

A new software for astrometry and photometry in the AO era

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In collaboration with
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Davide Massari (INAF-Bologna)
...et al.

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Motivation: why do we need a new software?

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We need high-precision astro/photo-metric measurements, but...

- PSFs are becoming complex, difficult to be described analytically
- PSFs varies across the an image in a way that it is difficult to predict a priori
- PSF reconstruction -> complex, time consuming. Need to be validated

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The community is aware of these issues:

Laura Schreiber's talk

Davide Massari's talk

Carmelo Arcidiacono's talk

Andrea Grazian's talk

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A possible solution

A software that

- A. extract purely *numerical* PSFs in different regions of the image
- B. use these PSFs to extract position and magnitude of all sources
- C. iterates A and B to improve on PSF models, astrometry and photometry

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SUPERSTAR

SUPERSTAR FLOW CHART

Original
image

-

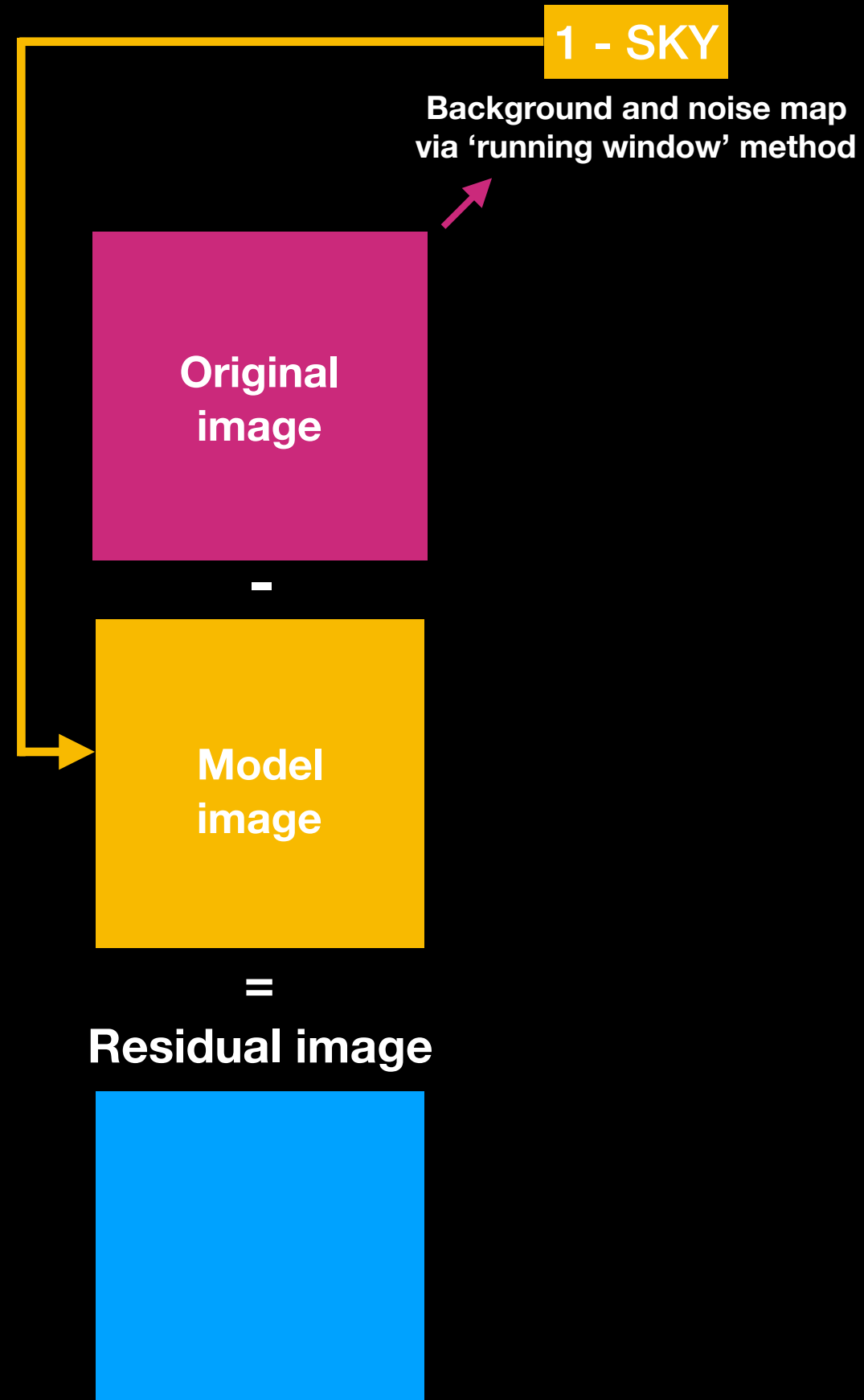
Model
image

=

Residual image



SUPERSTAR FLOW CHART



SUPERSTAR FLOW CHART

1 - SKY

Background and noise map
via 'running window' method

Original
image

-

Model
image

=

Residual image

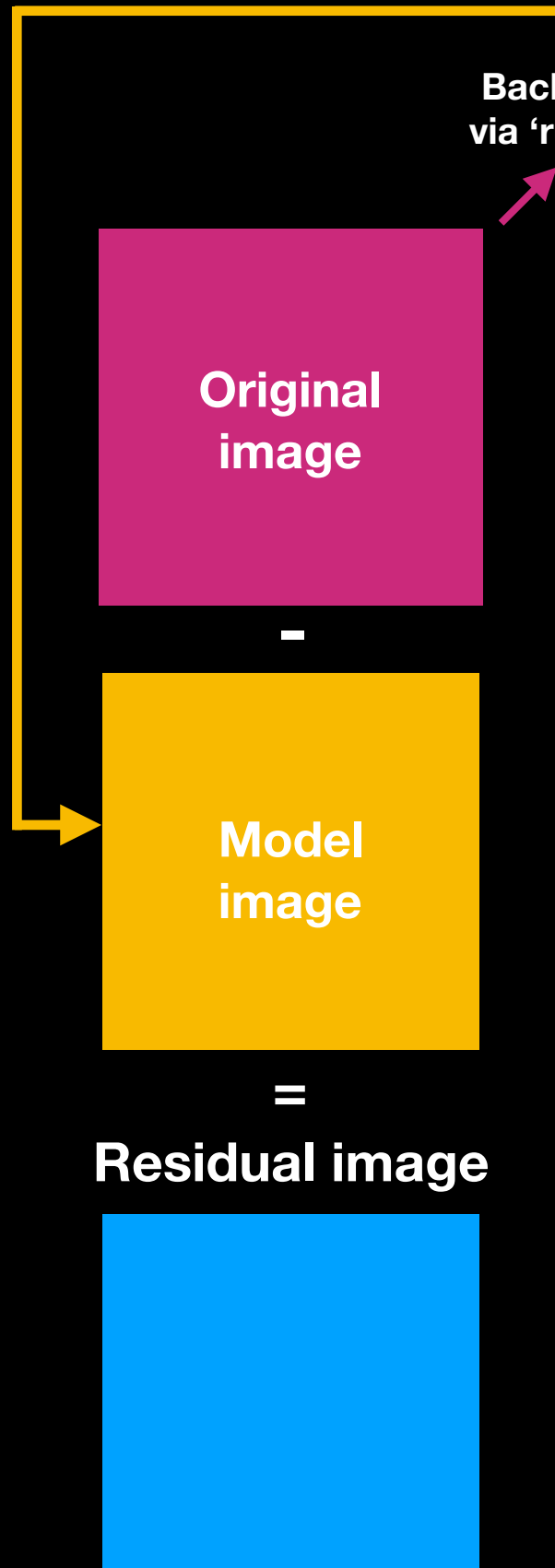
2 - SOURCE FINDER

Look for candidate stars in the residual image

S/N based

First estimate of position and fluxes

Flag "isolated" stars



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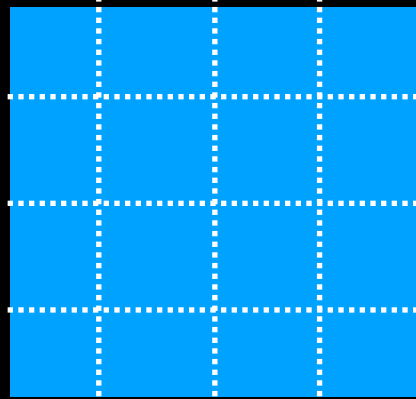
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Model
image

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Residual image

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3 - ePSF MODELLING

based on Anderson & King 2000,2006
stacking isolated, high S/N stars on a *fine* grid
multi-kernel smoothing
re-centering

ePSF NUMERICAL MODELLING

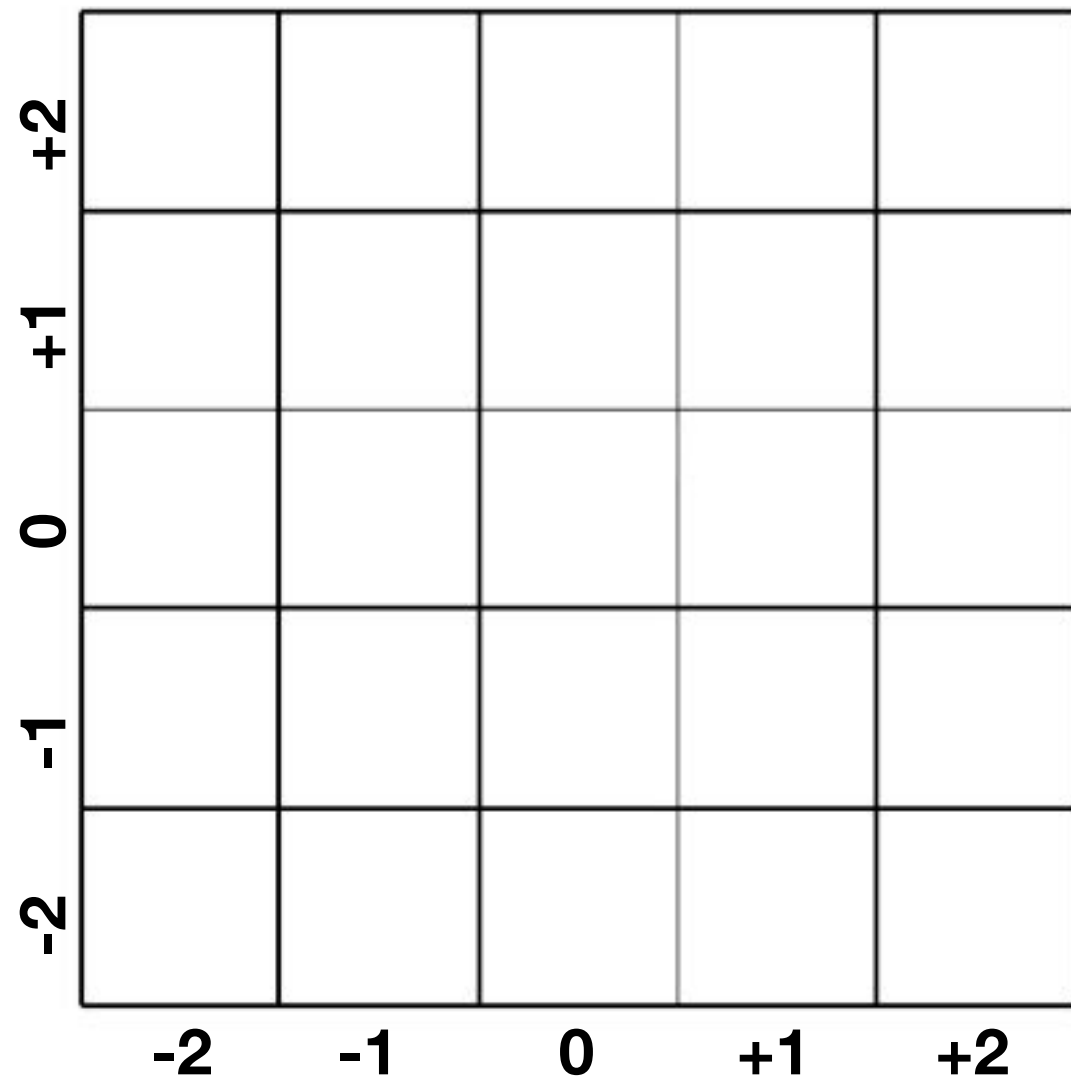
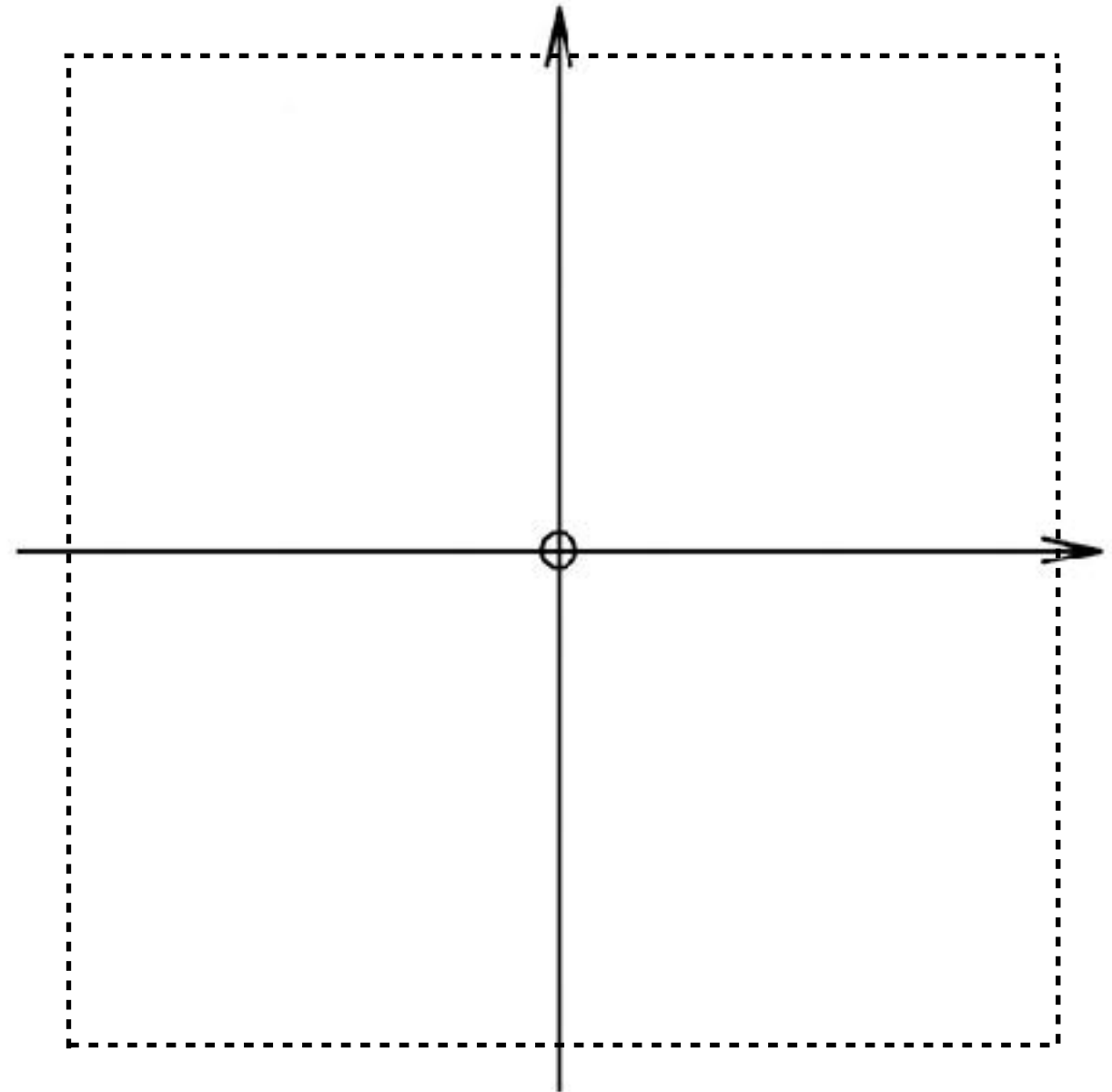


IMAGE FRAME



PSF FRAME

adapted from Anderson & King 2000

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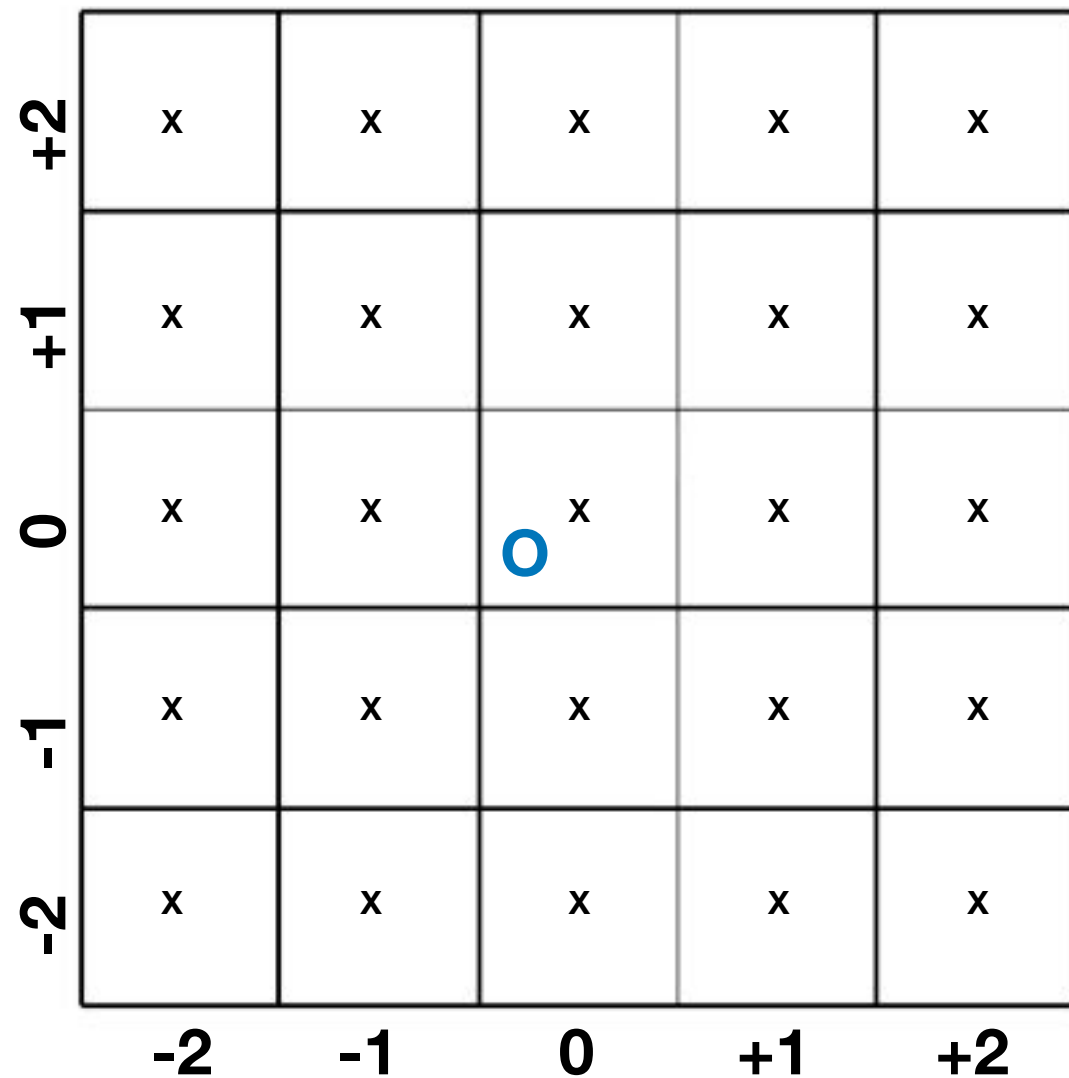
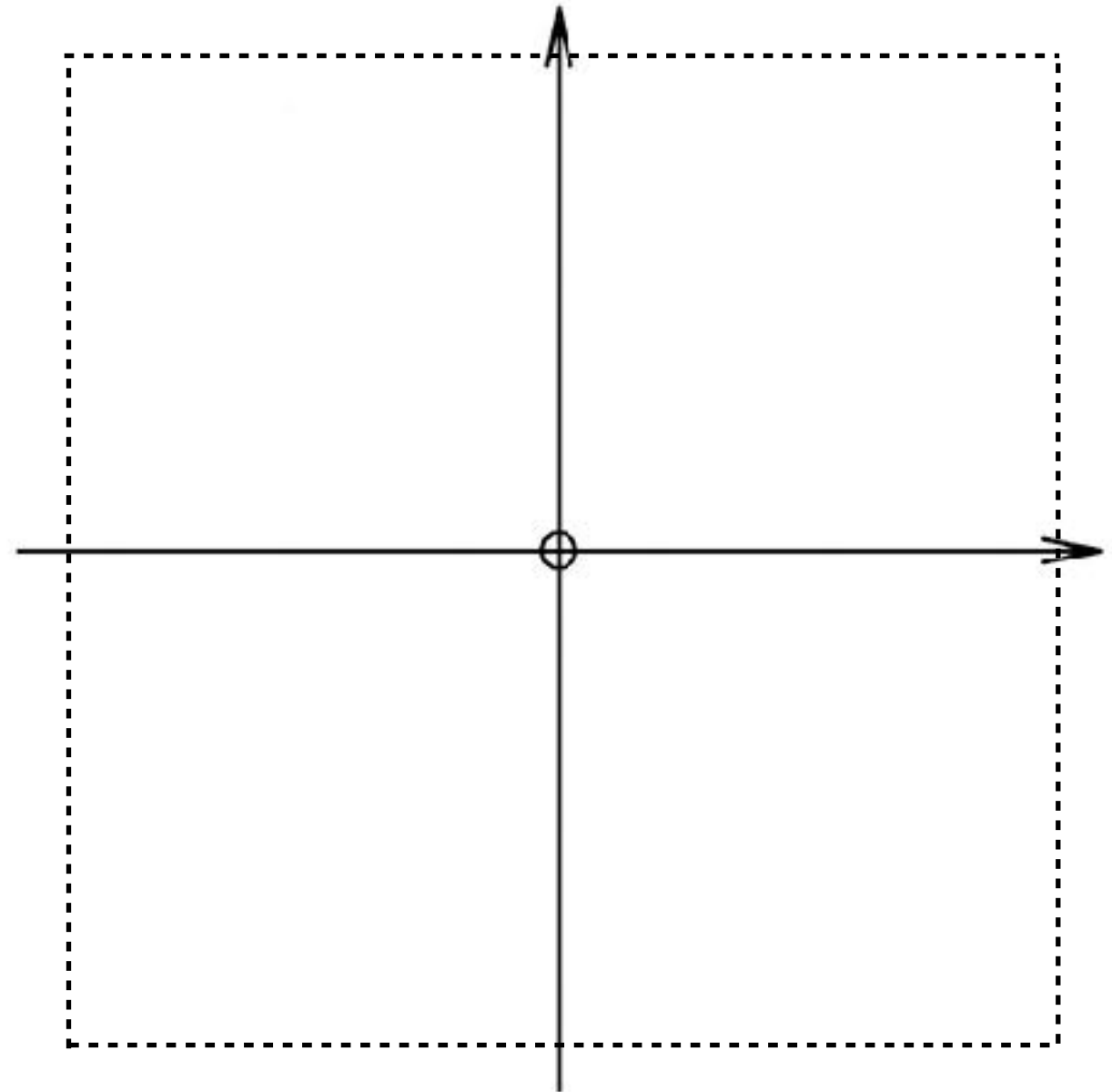


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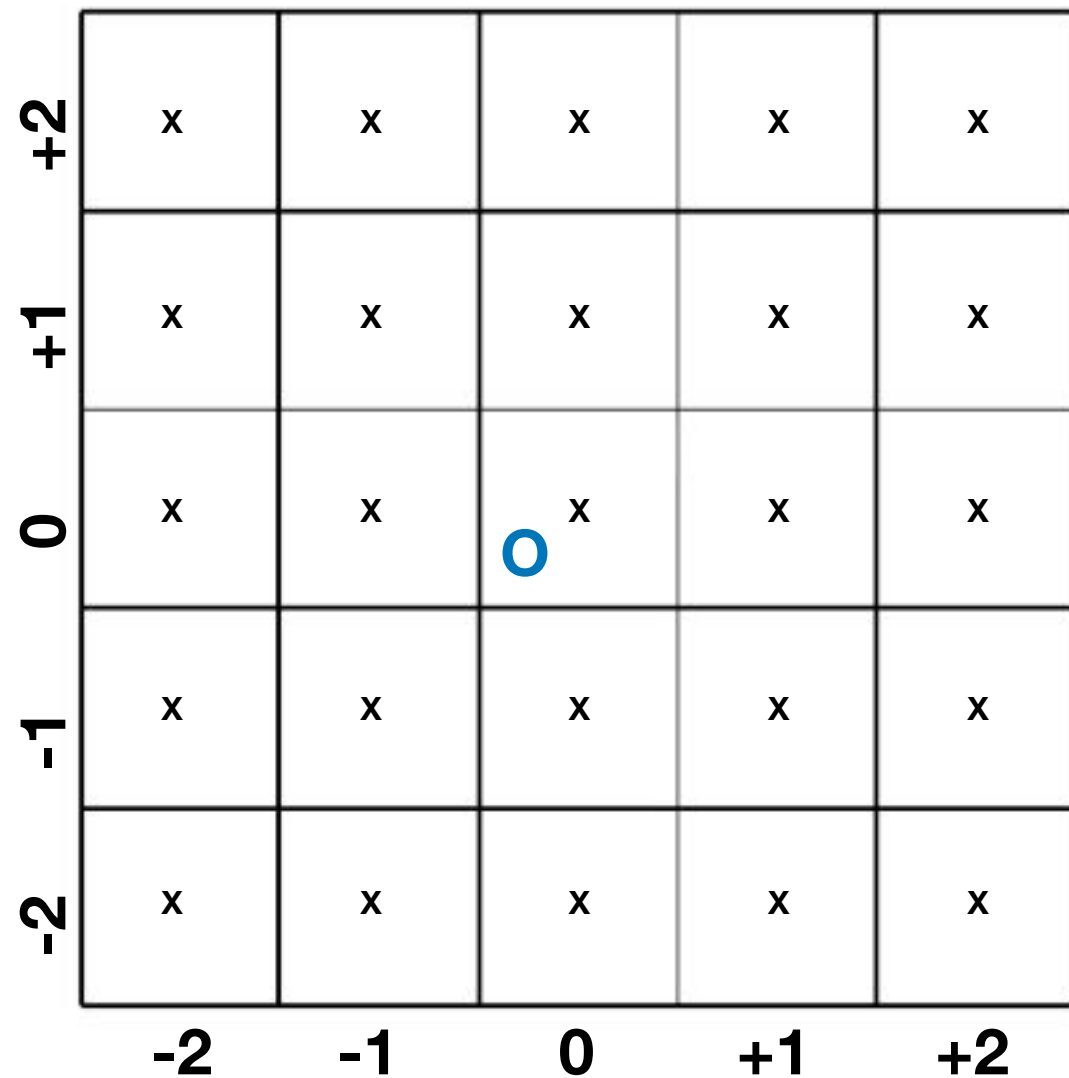
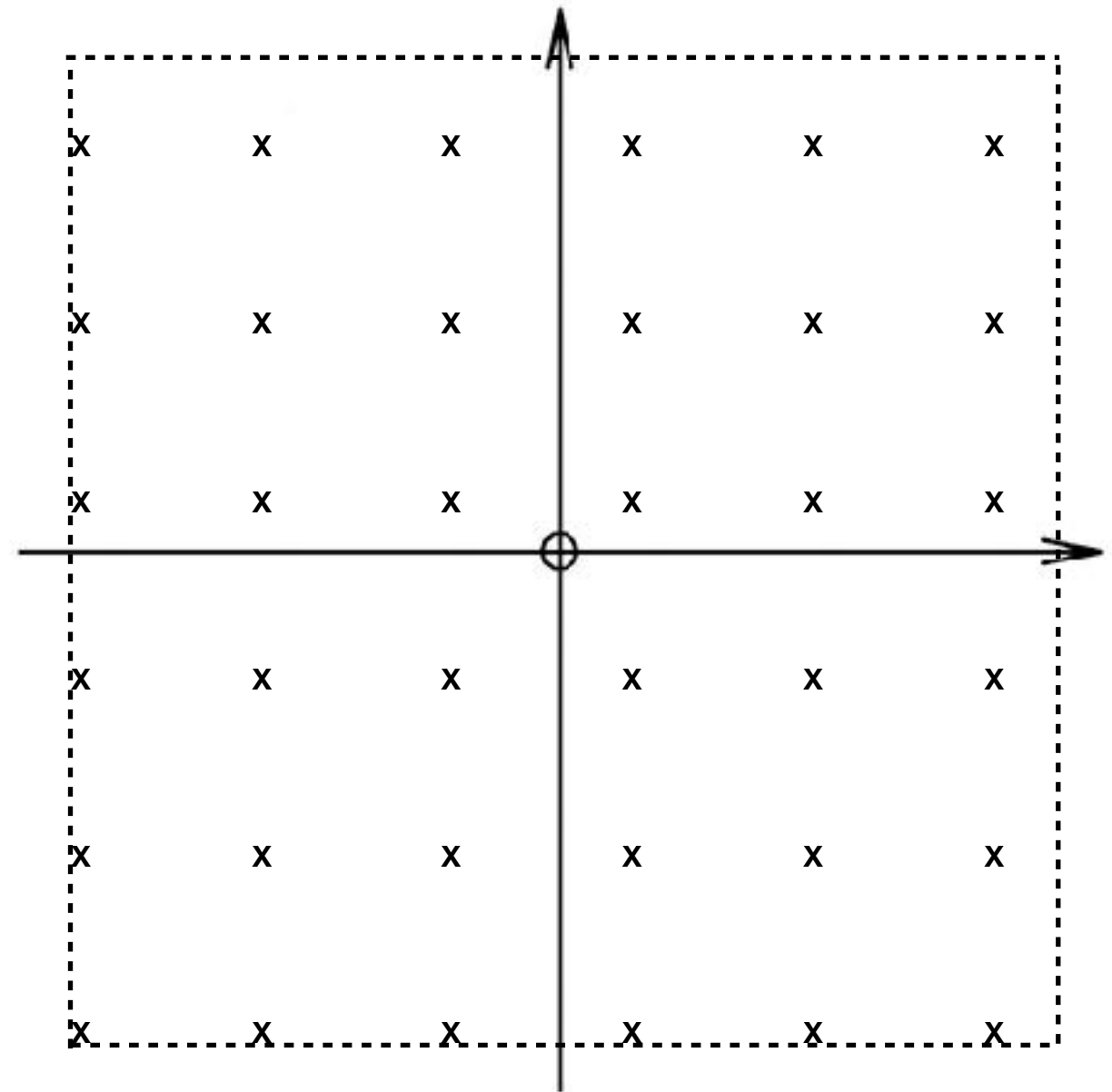


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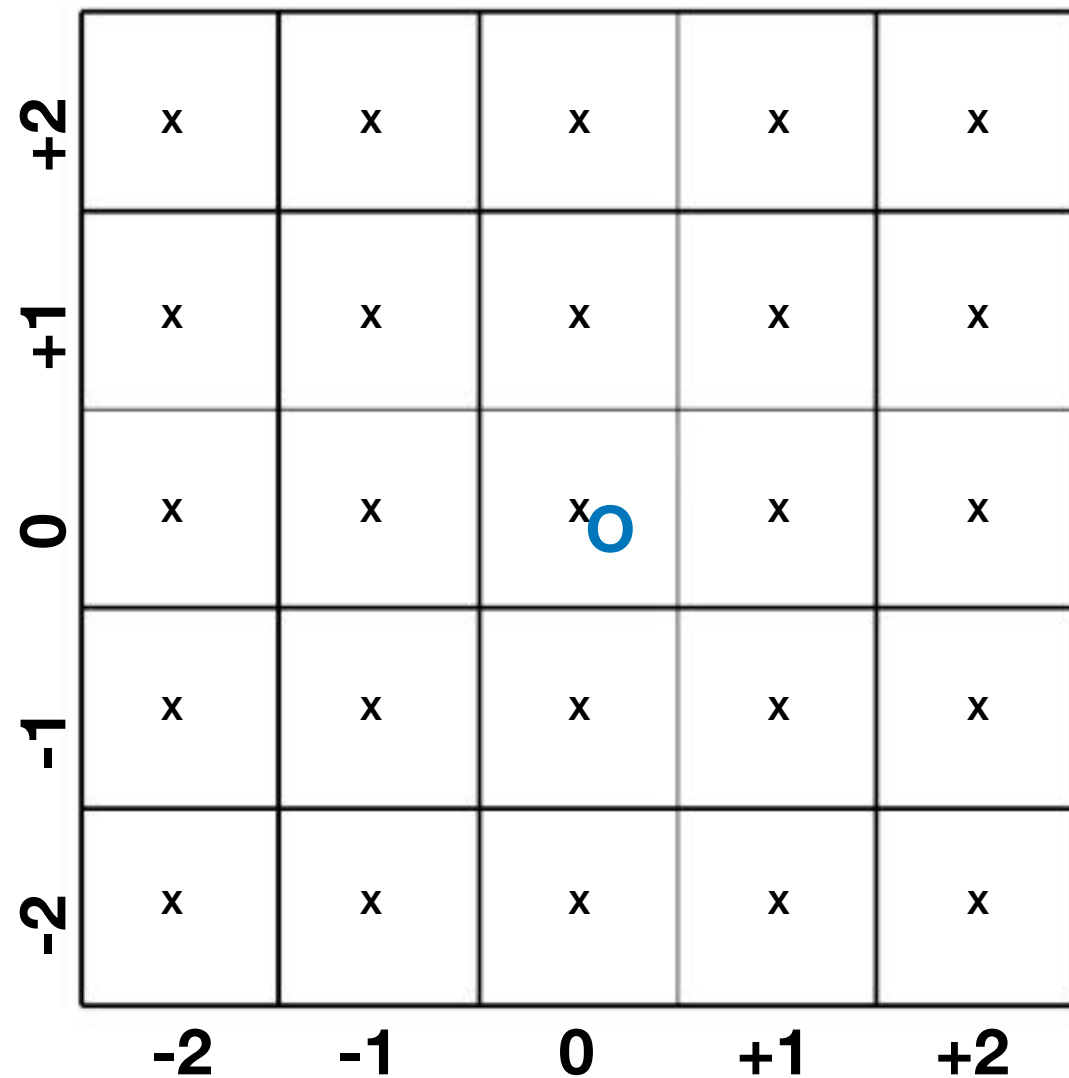
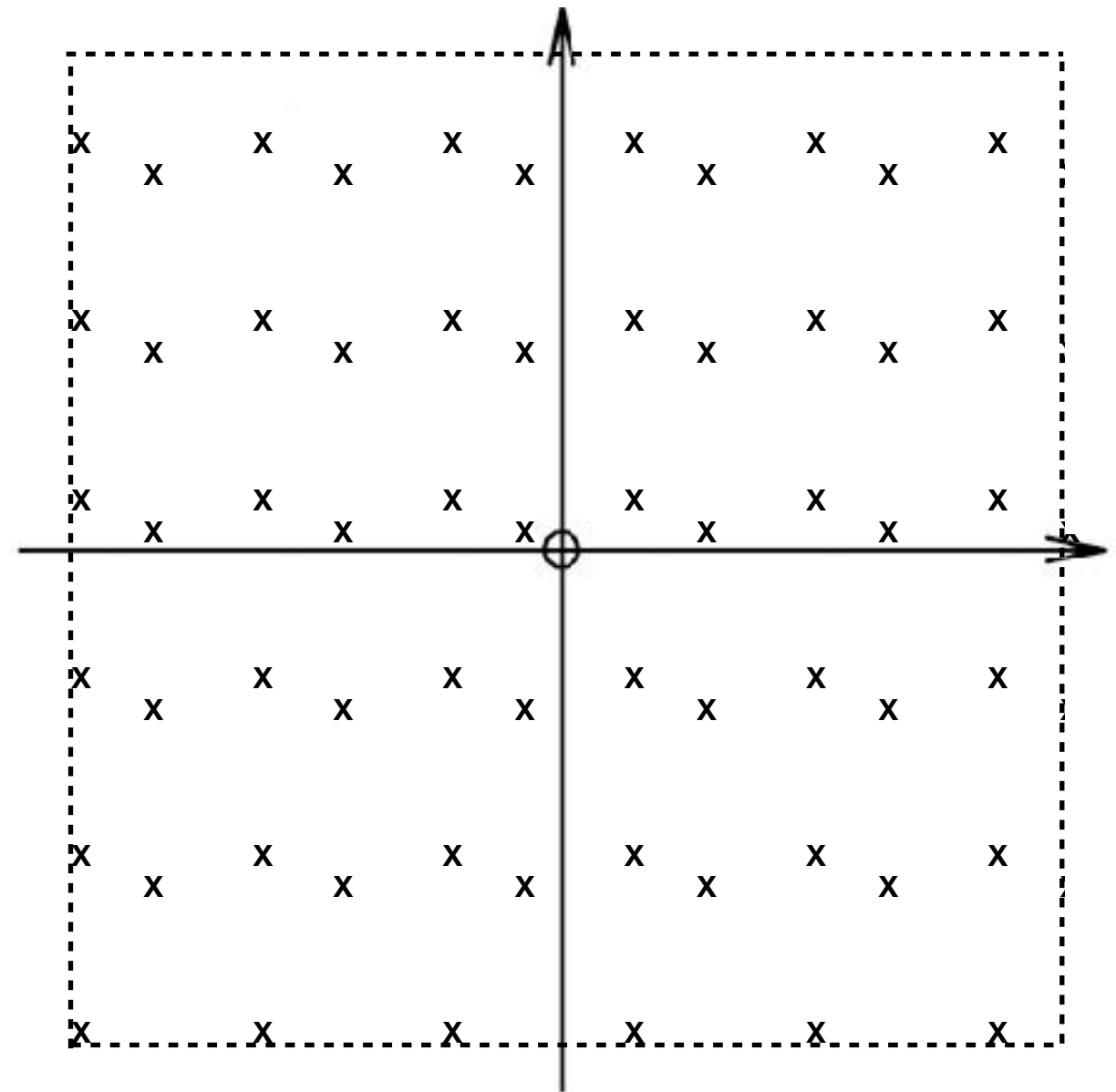


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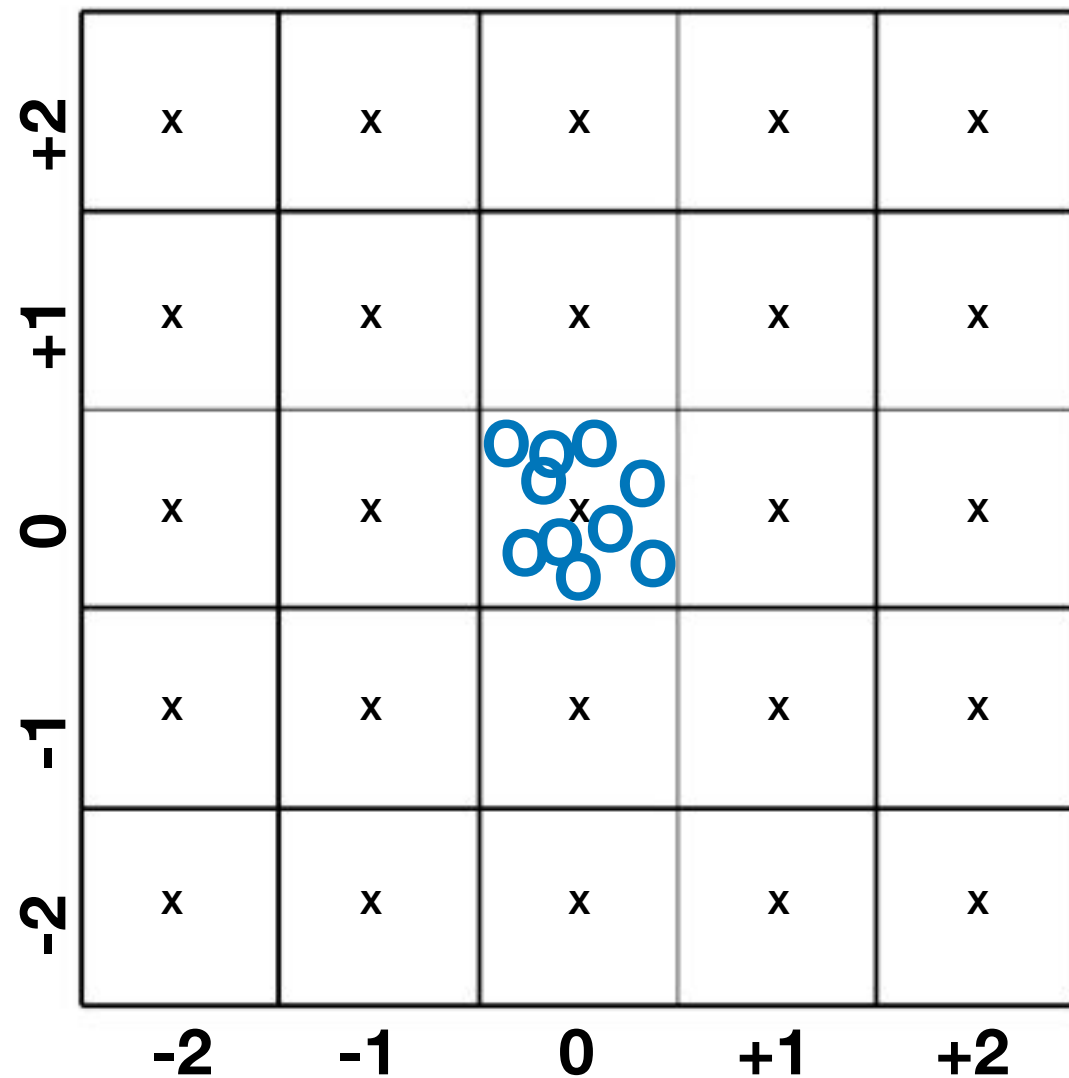
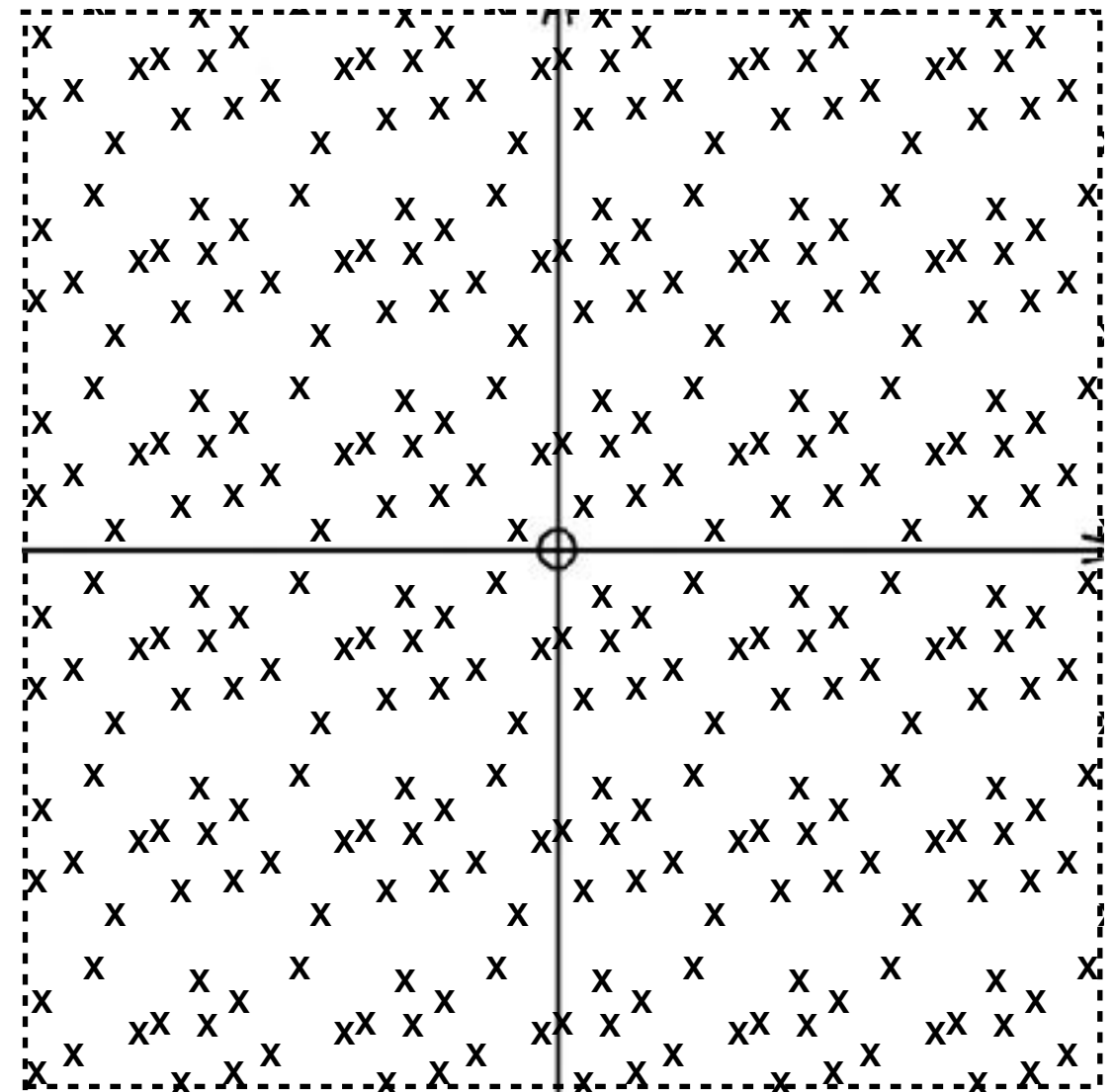


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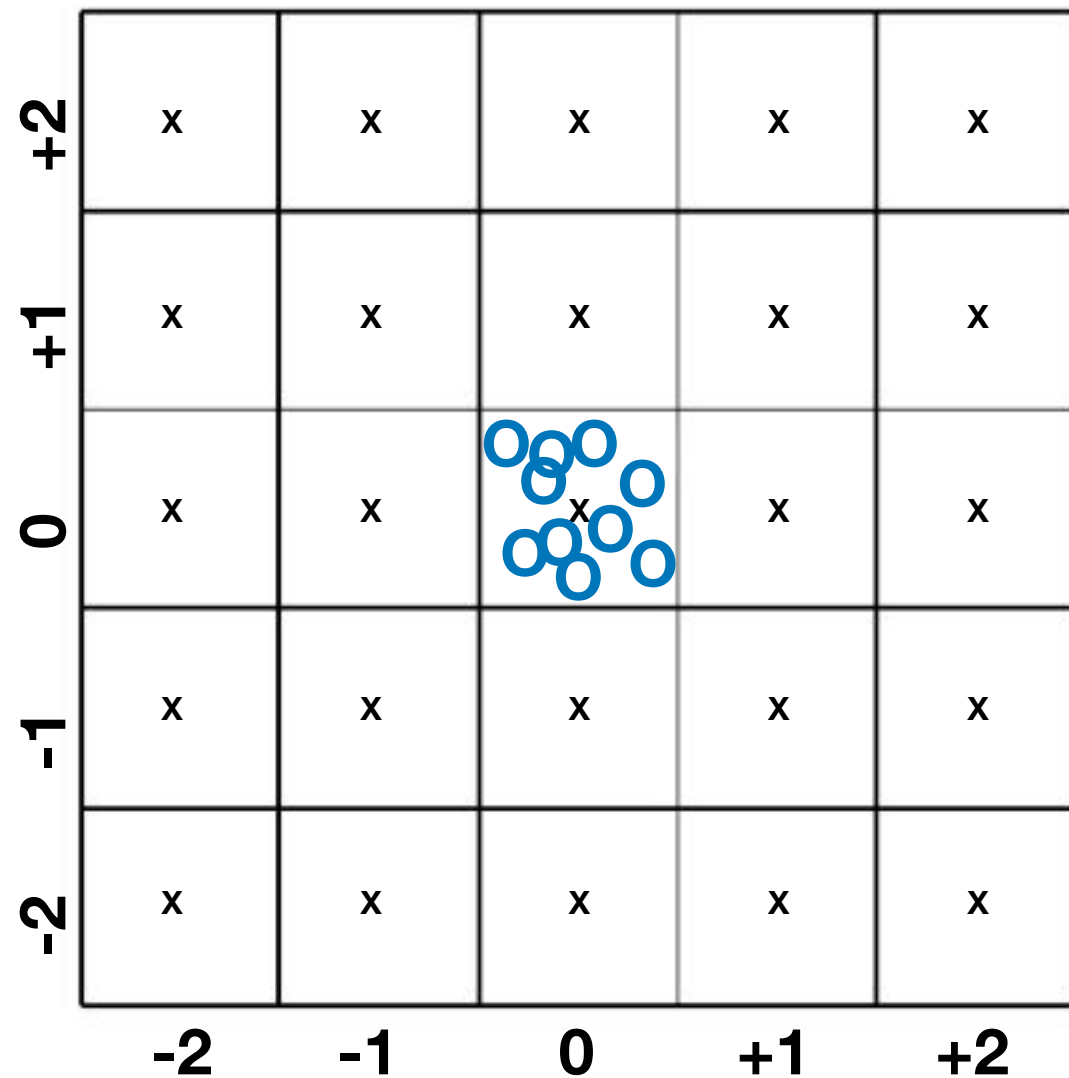
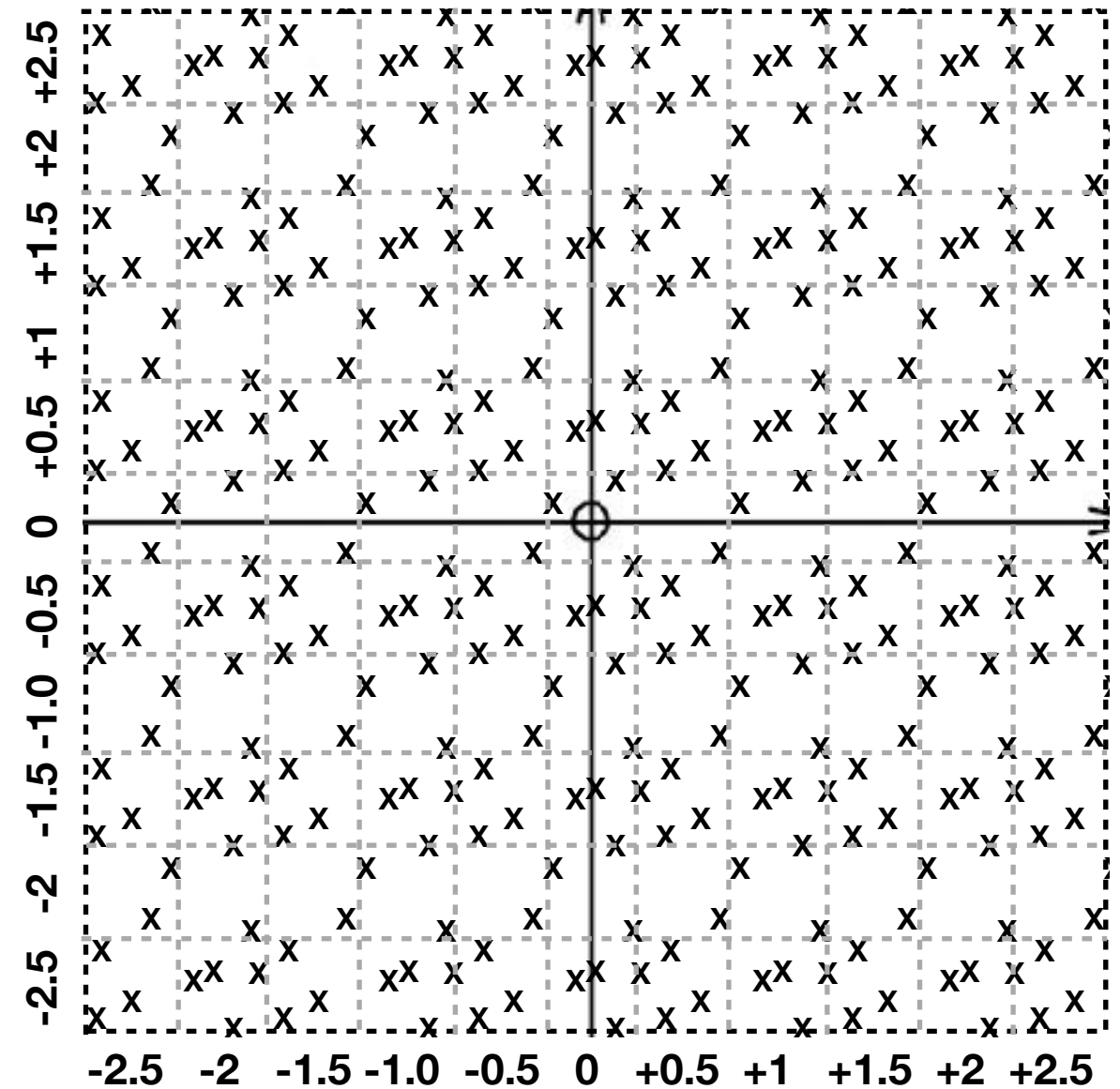


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Background and noise map
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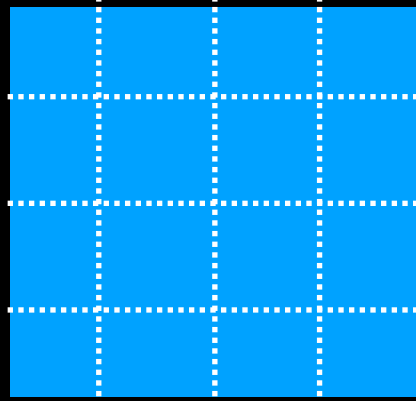
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image

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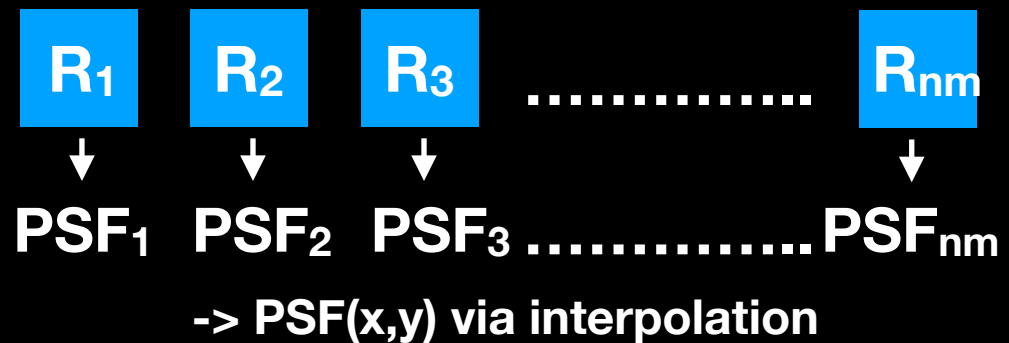
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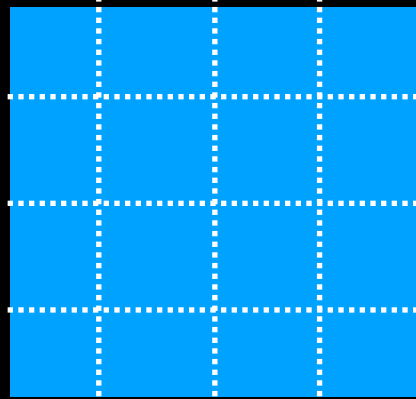
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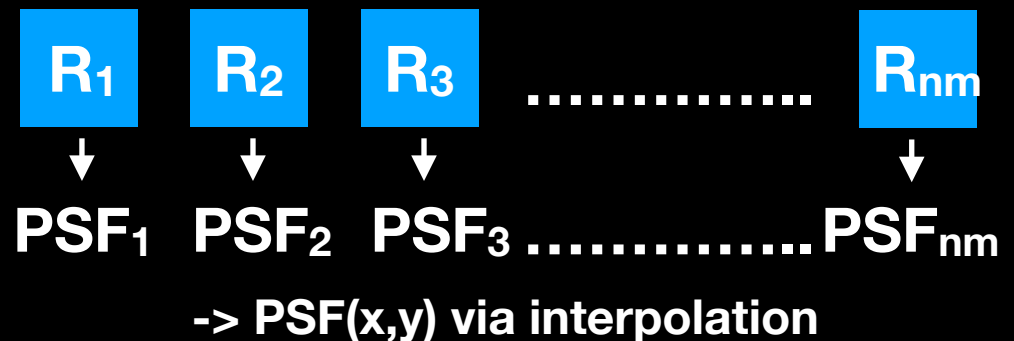
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4 - ePSF FITTING

group finder (DAOPHOT)
correlation coefficient (StarFinder)
least-square fitting (single or multiple stars)
top-down approach (StarFinder)

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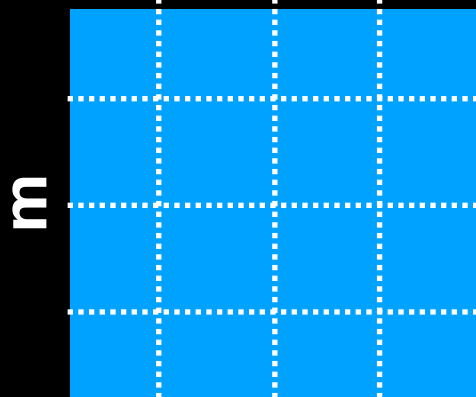
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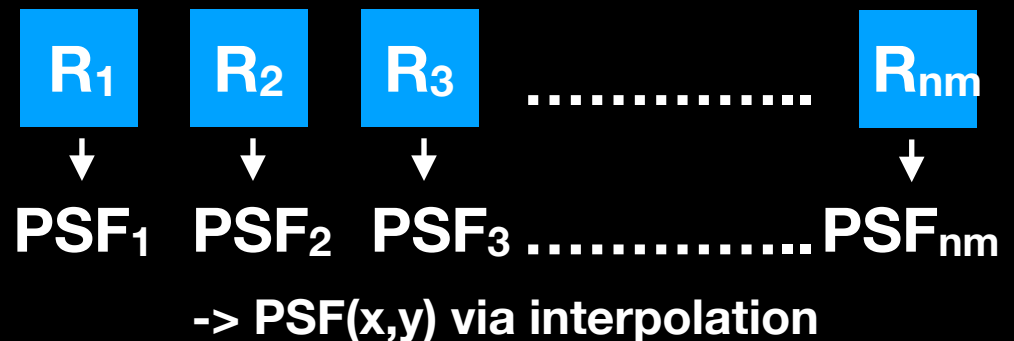
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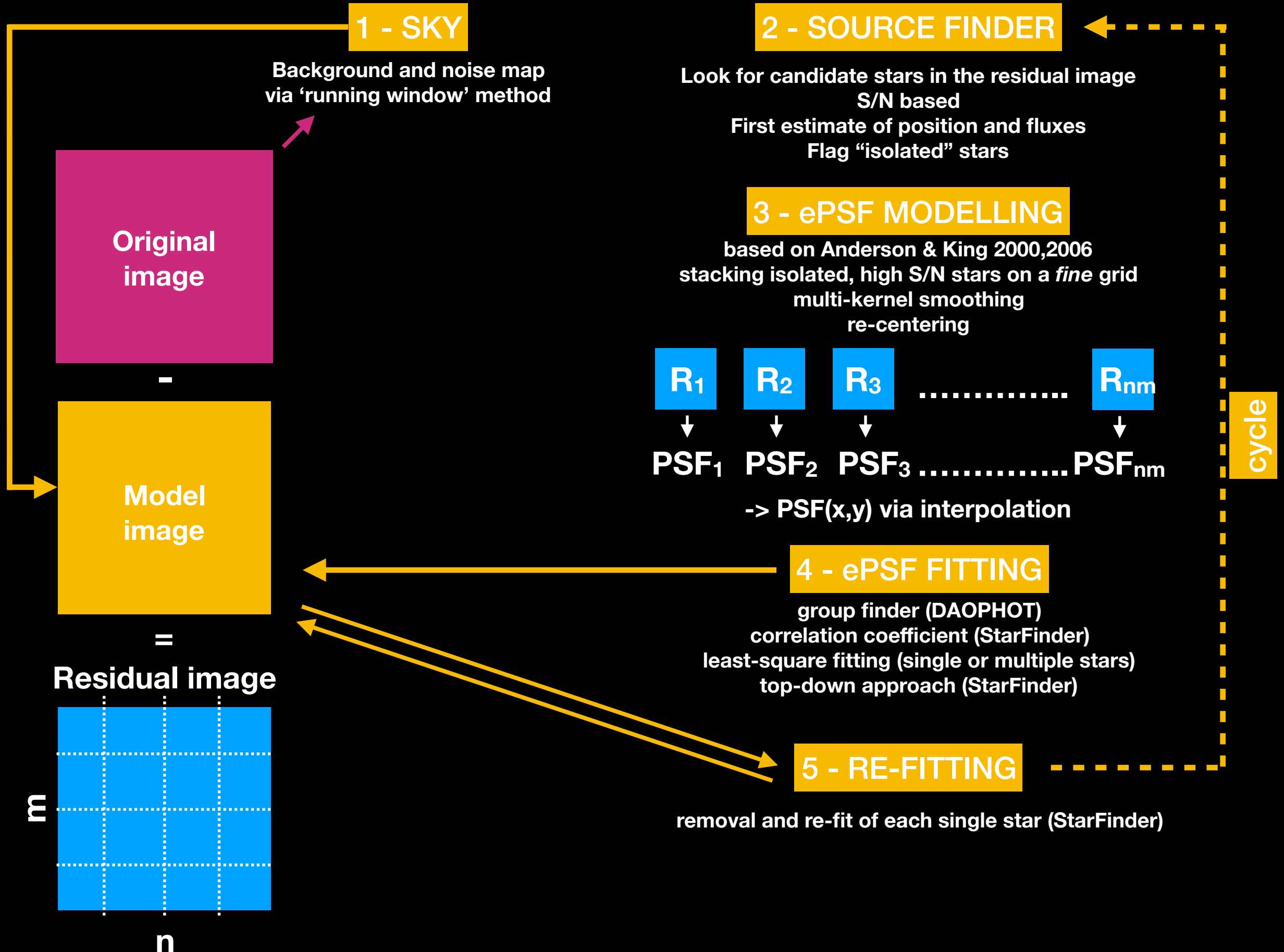
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5 - RE-FITTING

removal and re-fit of each single star (StarFinder)

SUPERSTAR FLOW CHART



SUPERSTAR OUTPUTS

catalogues

- initial estimates for (x,y,mag)
- final (x,y,mag) and corr.coefficients

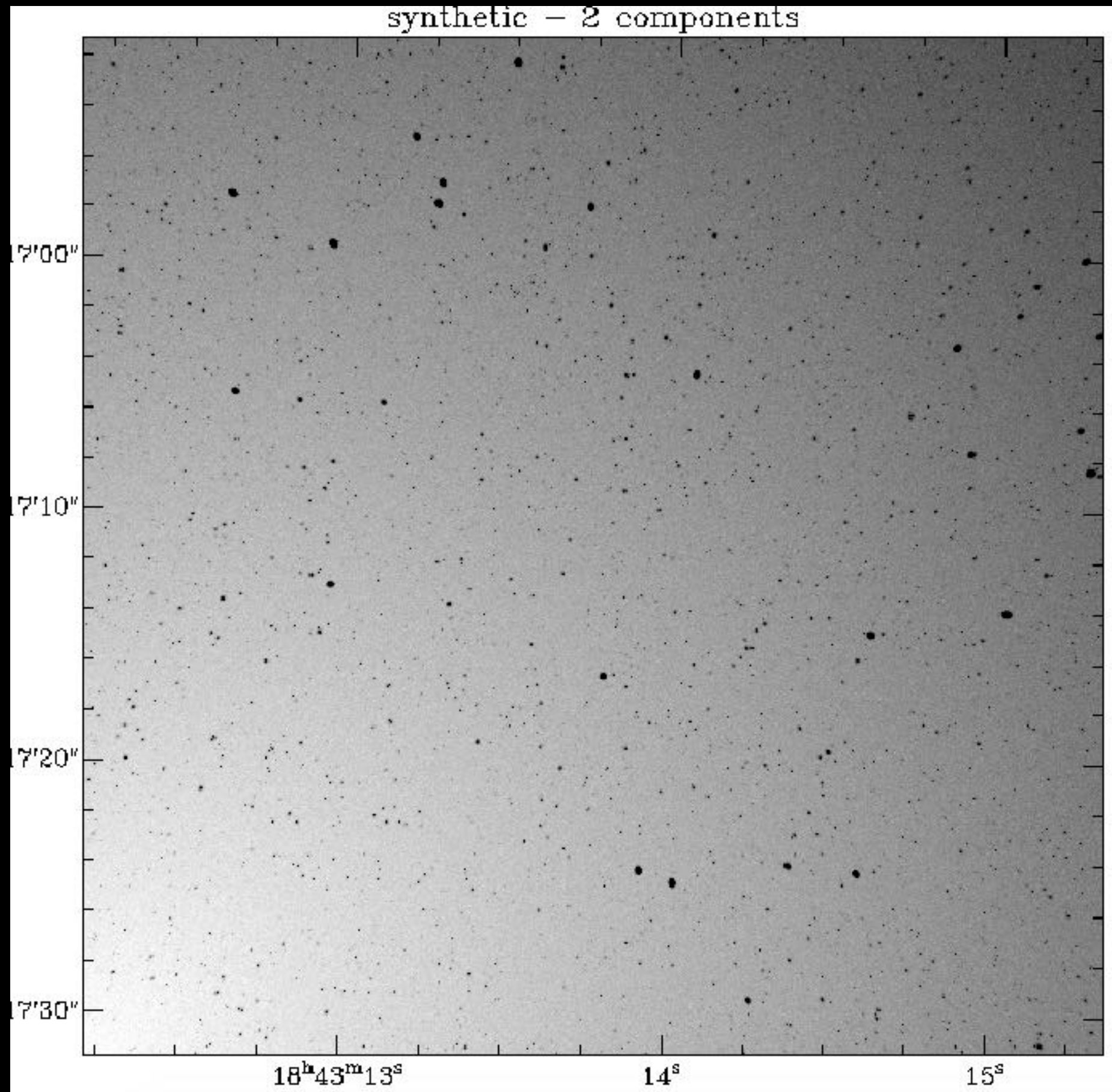
images (fits format)

- residuals (data-model)
- modelled sky background
- modelled sky noise
- initial (x,y) of all sources (1-0 map)
- final (x,y) of all sources (1-0 map)
- (x,y) of sources used to extract ePSF (1-0)

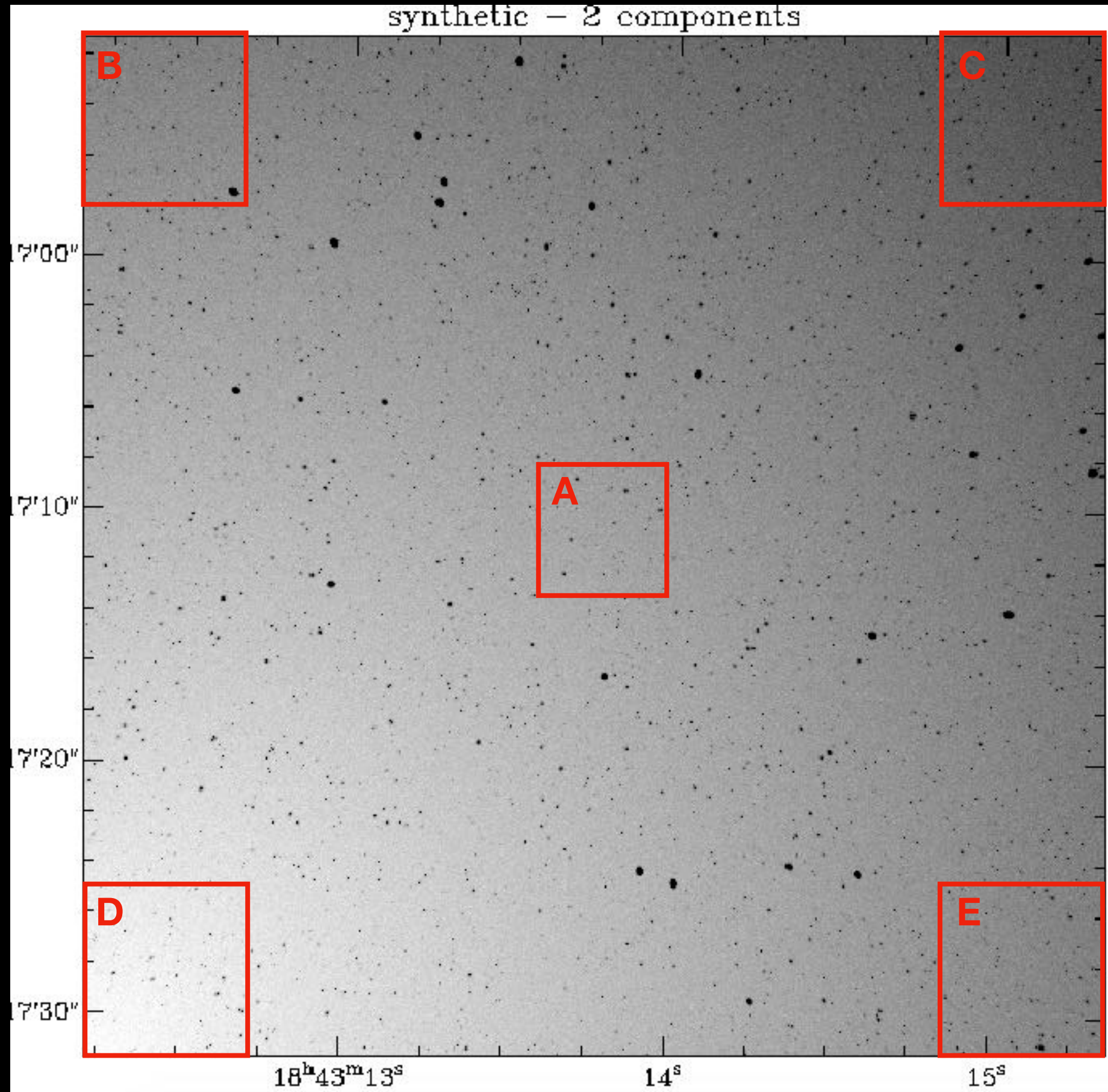
datacube (fits format)

- ePSF in the various regions

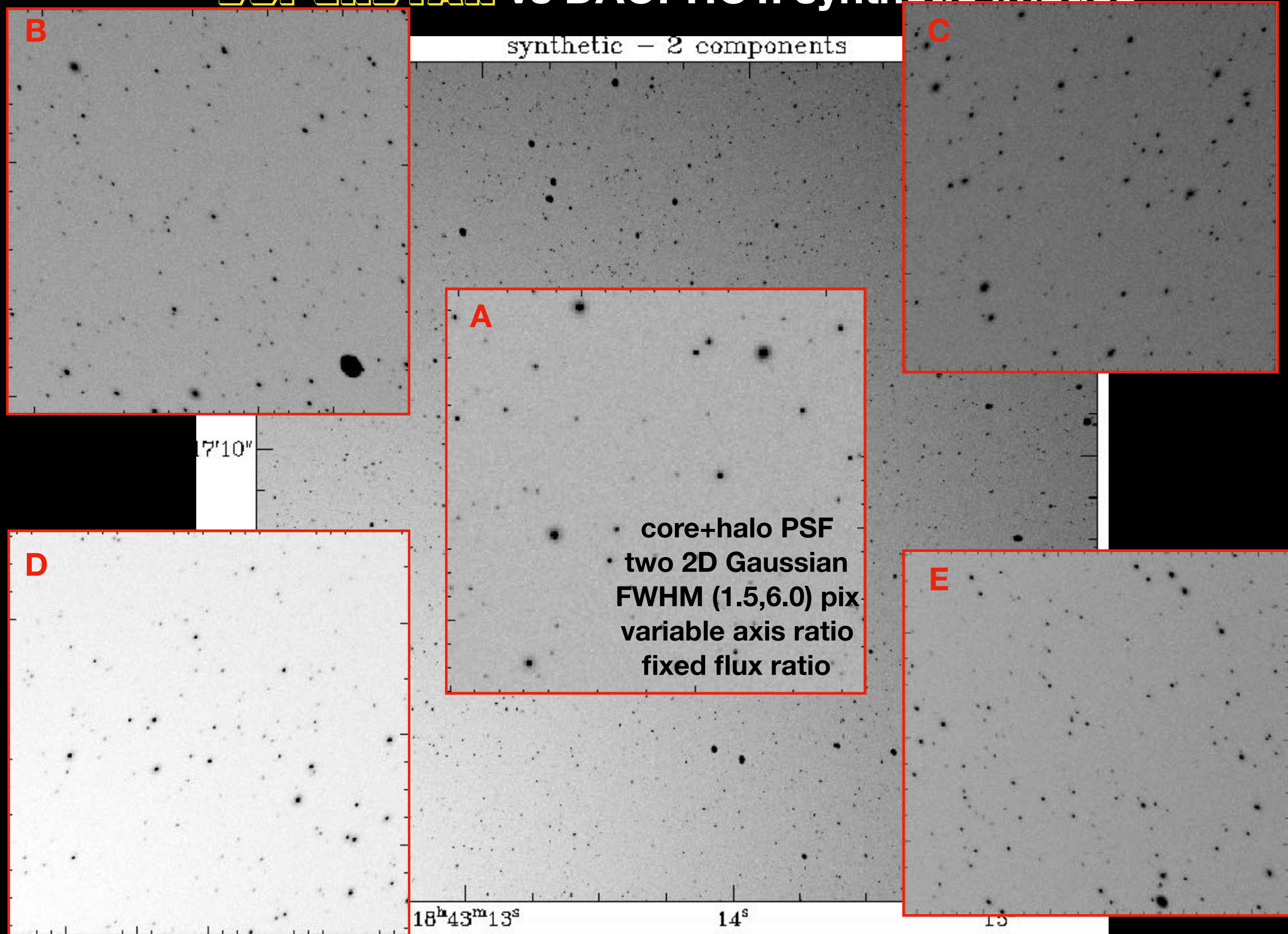
SUPERSTAR vs DAOPHOT: synthetic images



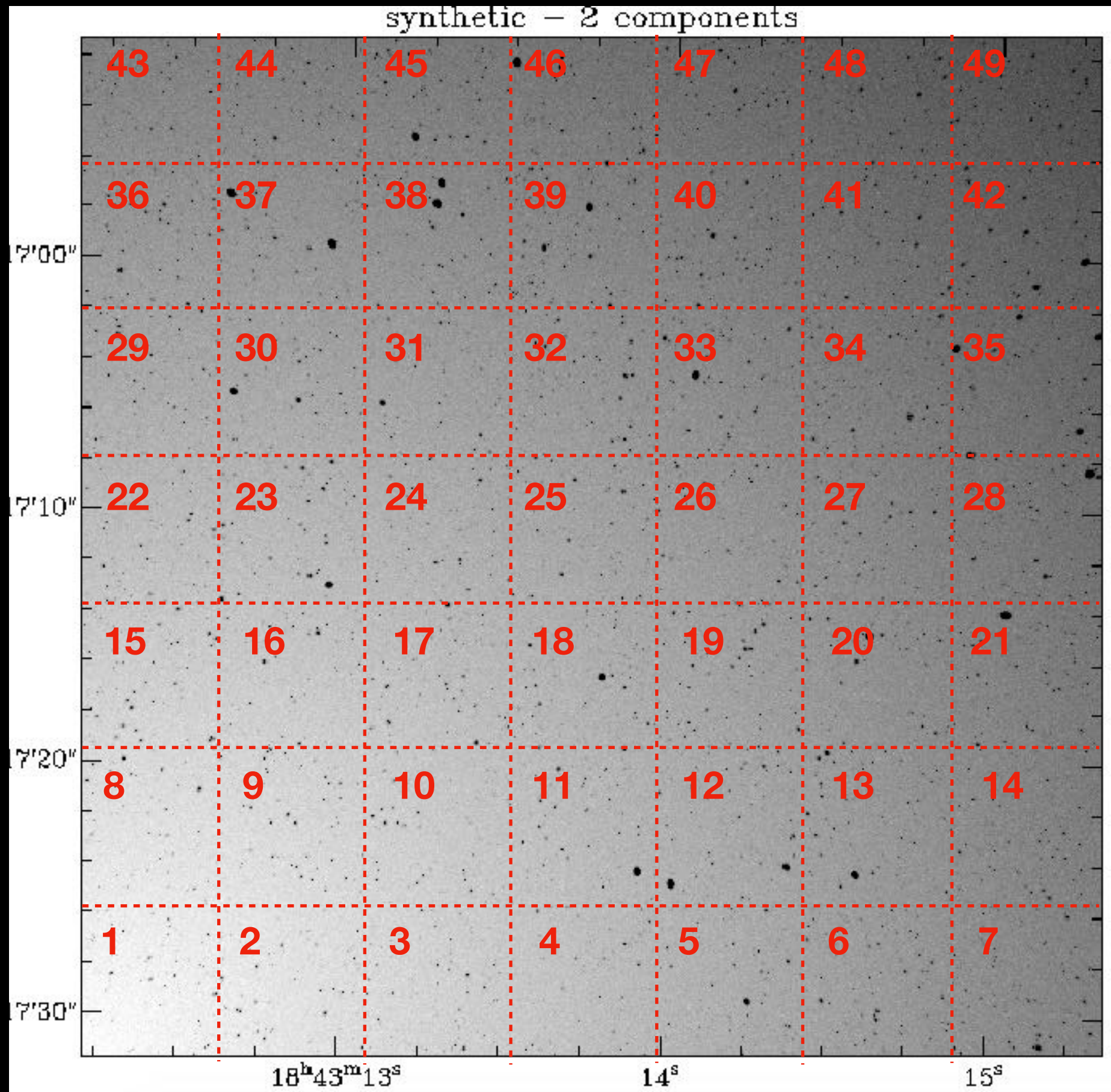
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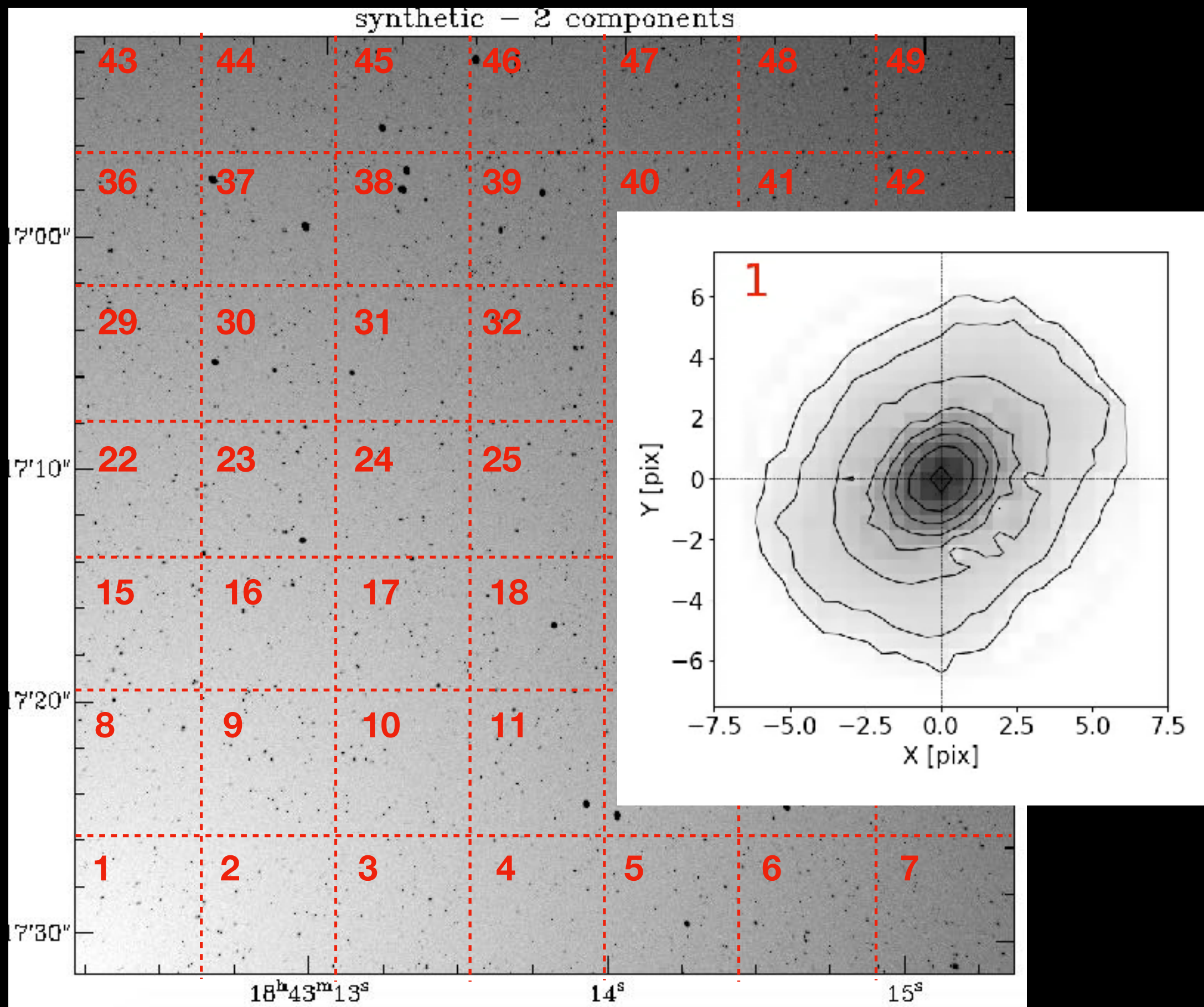
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SUPERSTAR vs DAOPHOT: synthetic images



Original

STAR vs DAOPHOT: synthetic images

DAOPHOT

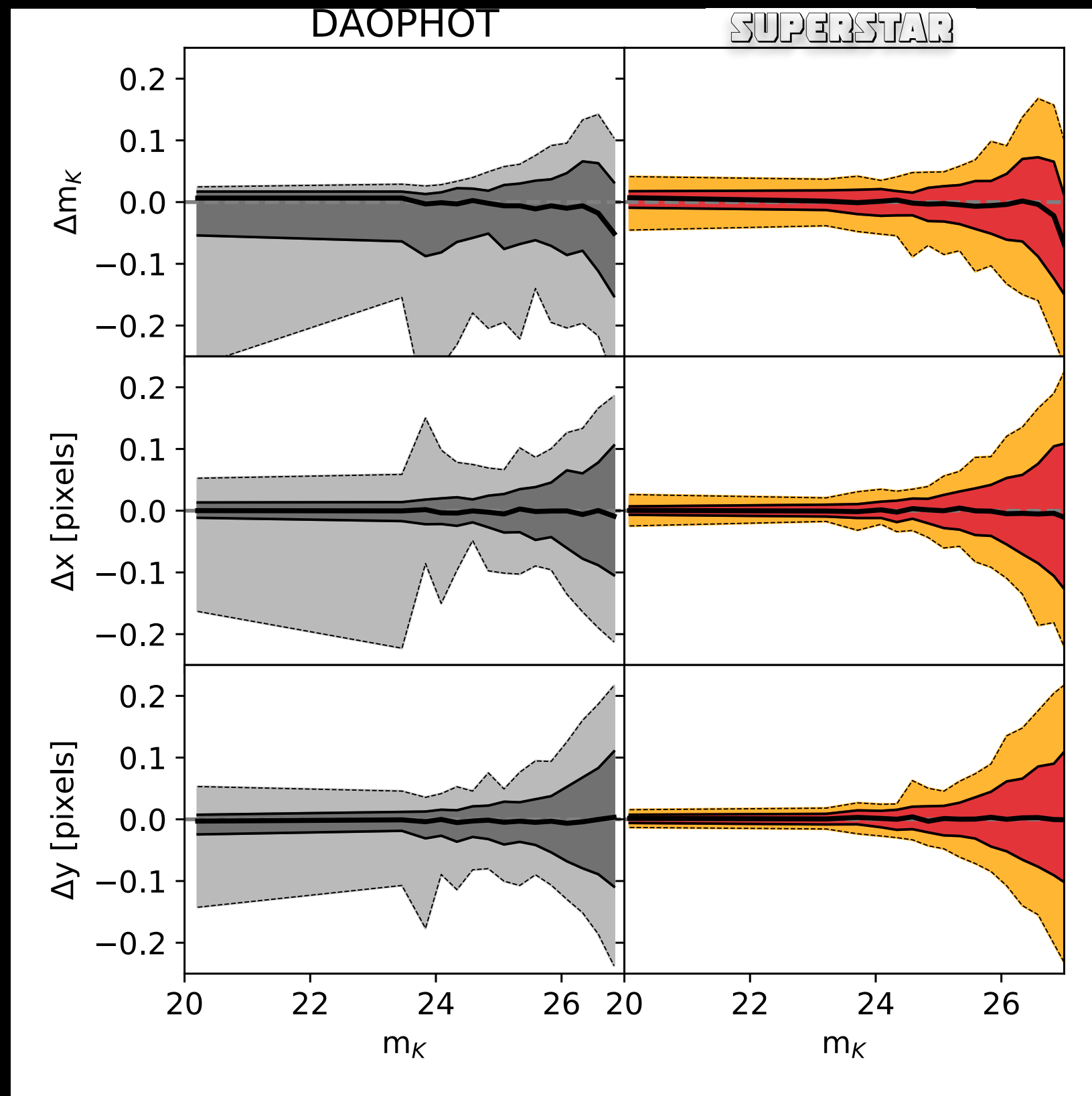
SUPERSTAR

Original

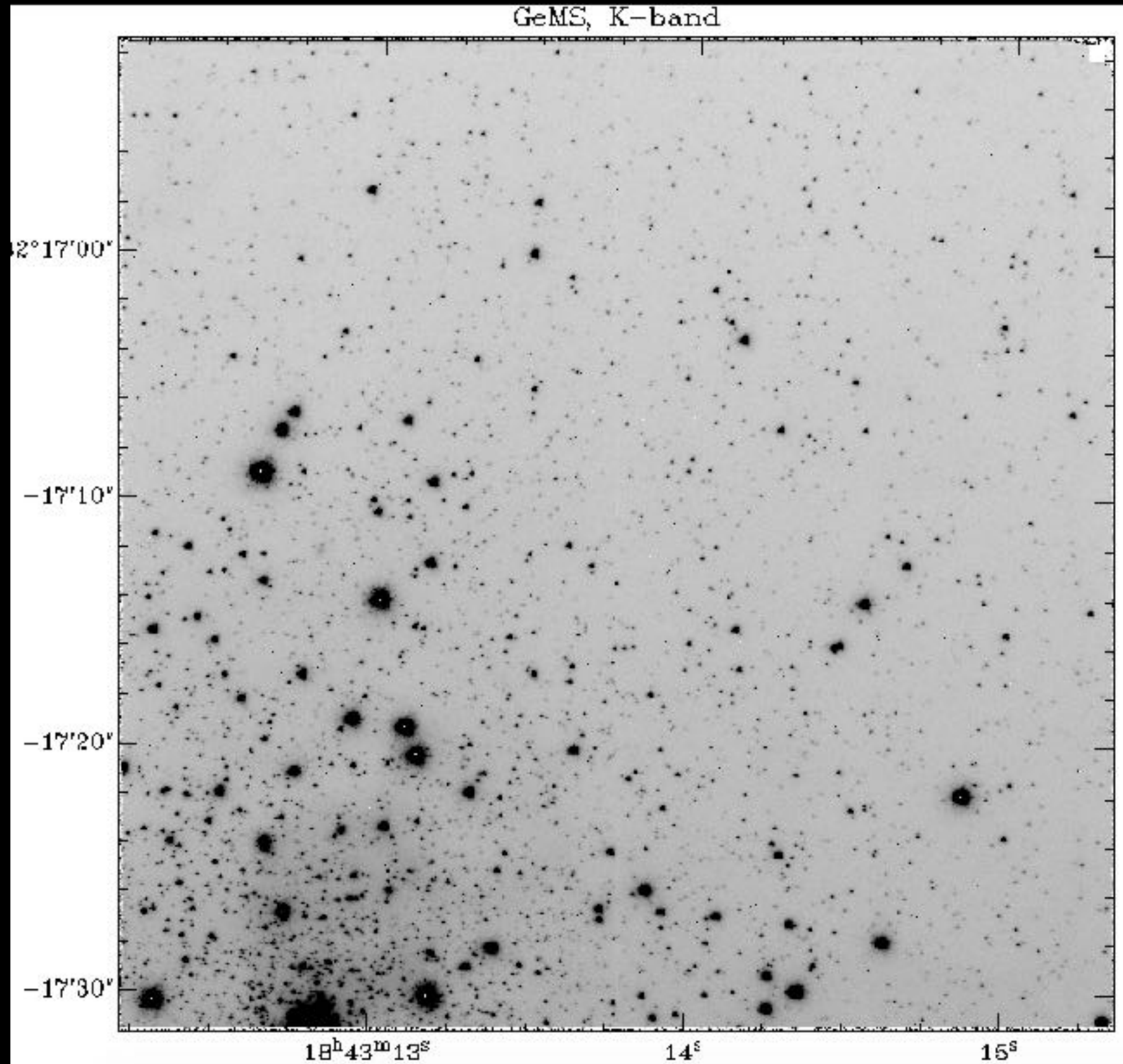
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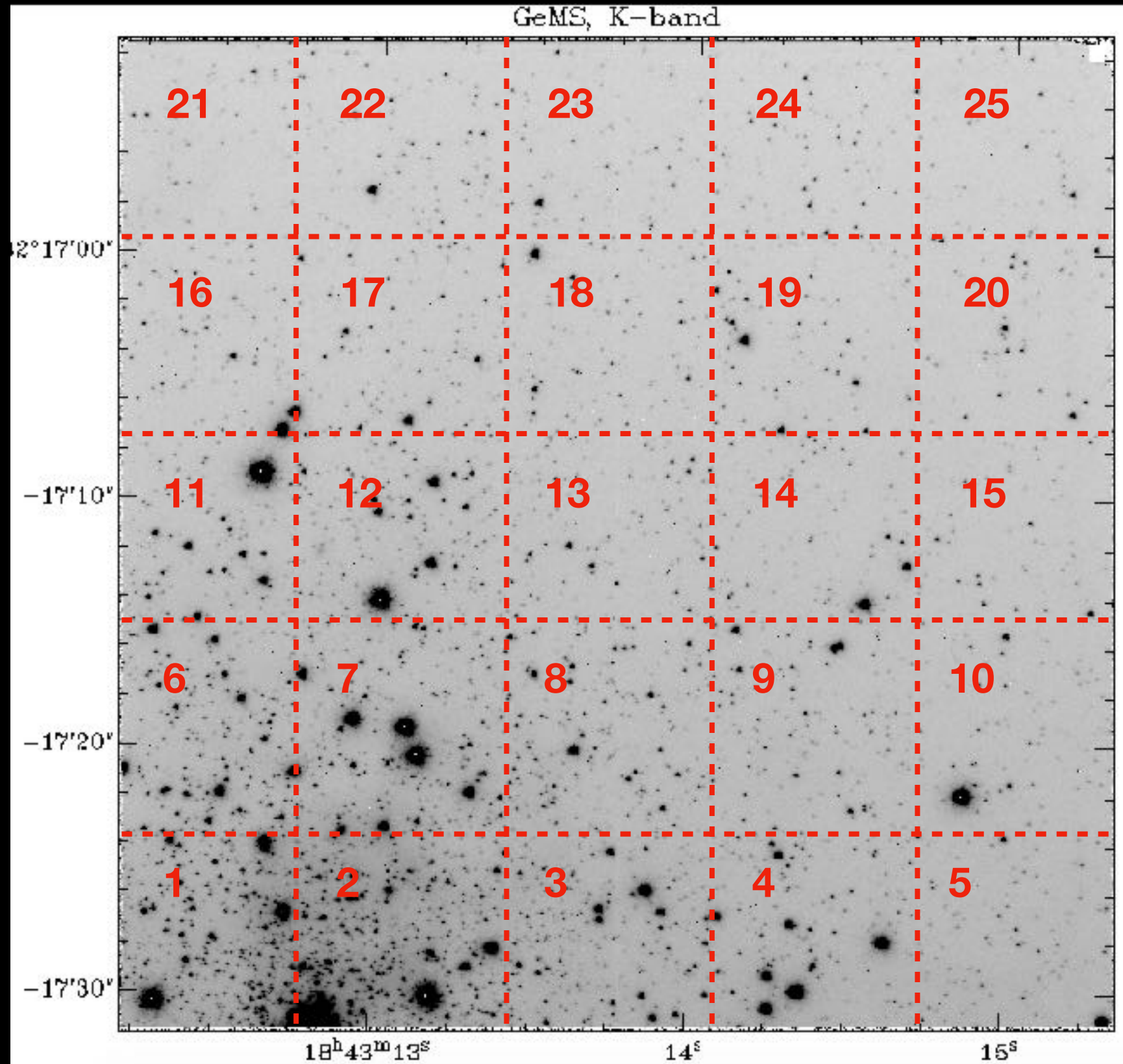
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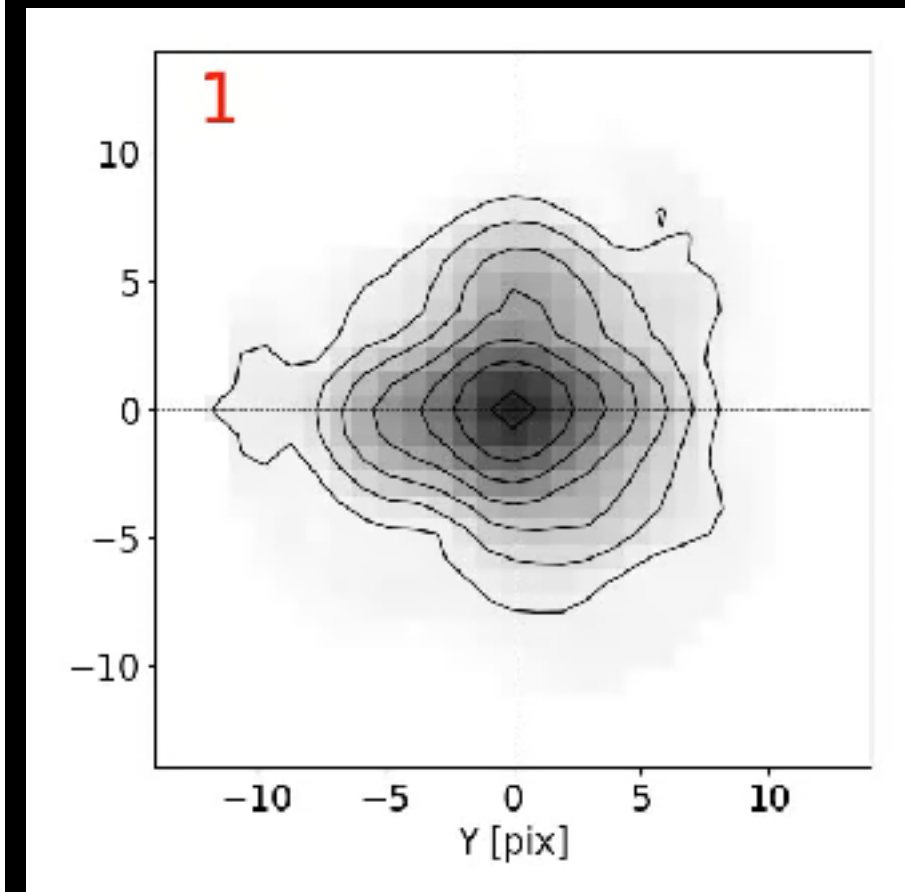
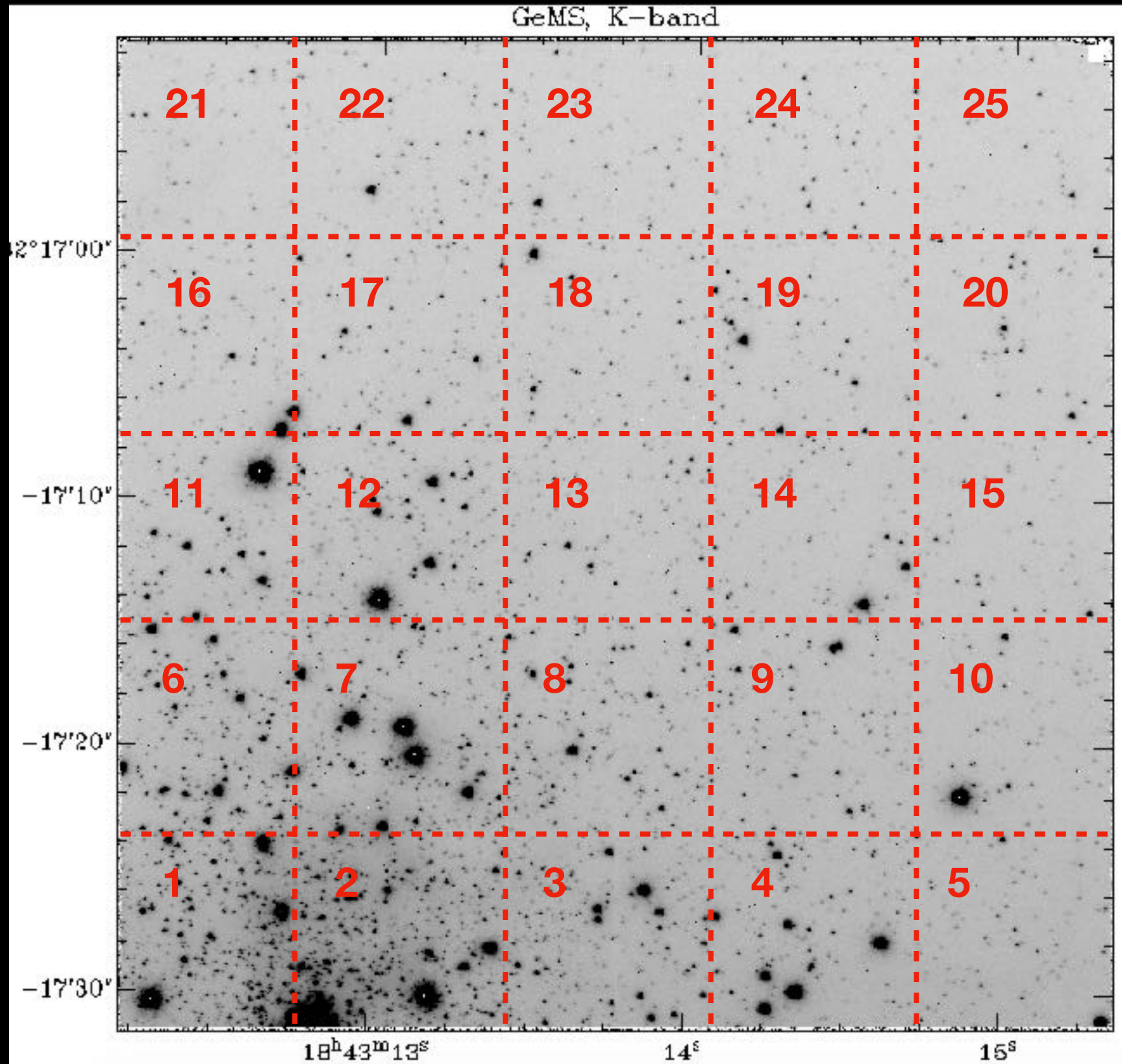
SUPERSTAR on GeMS data (NGC 6681)



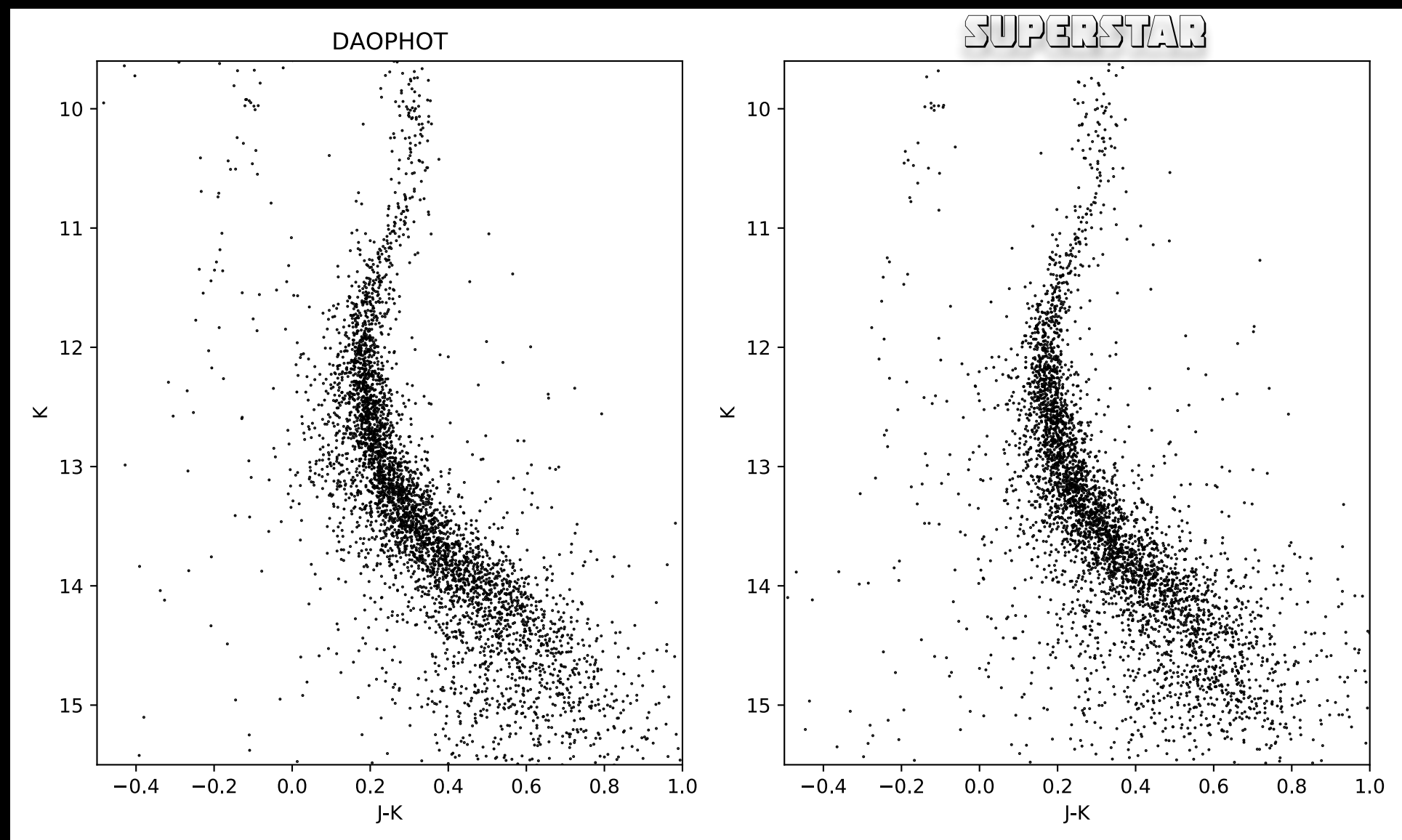
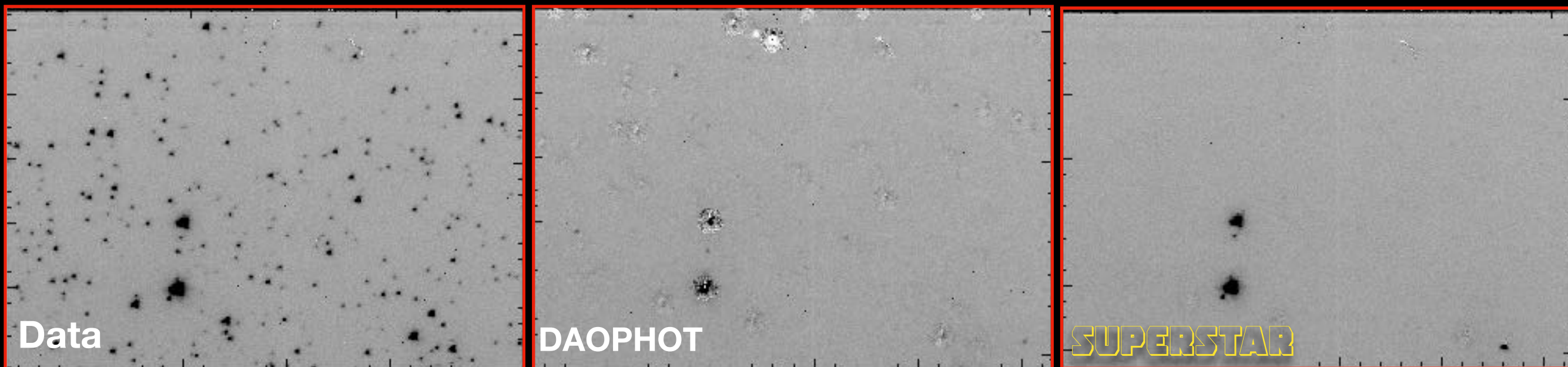
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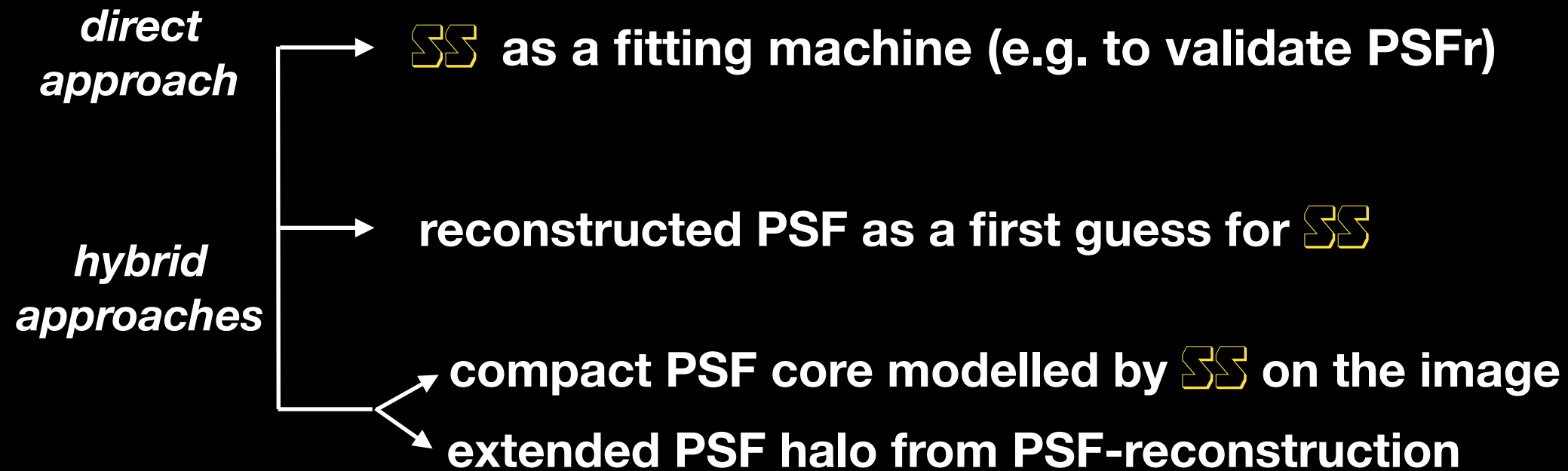


Synergy with PSF-reconstruction

SUPERSTAR takes as an input external PSFs (cubes) in fits format

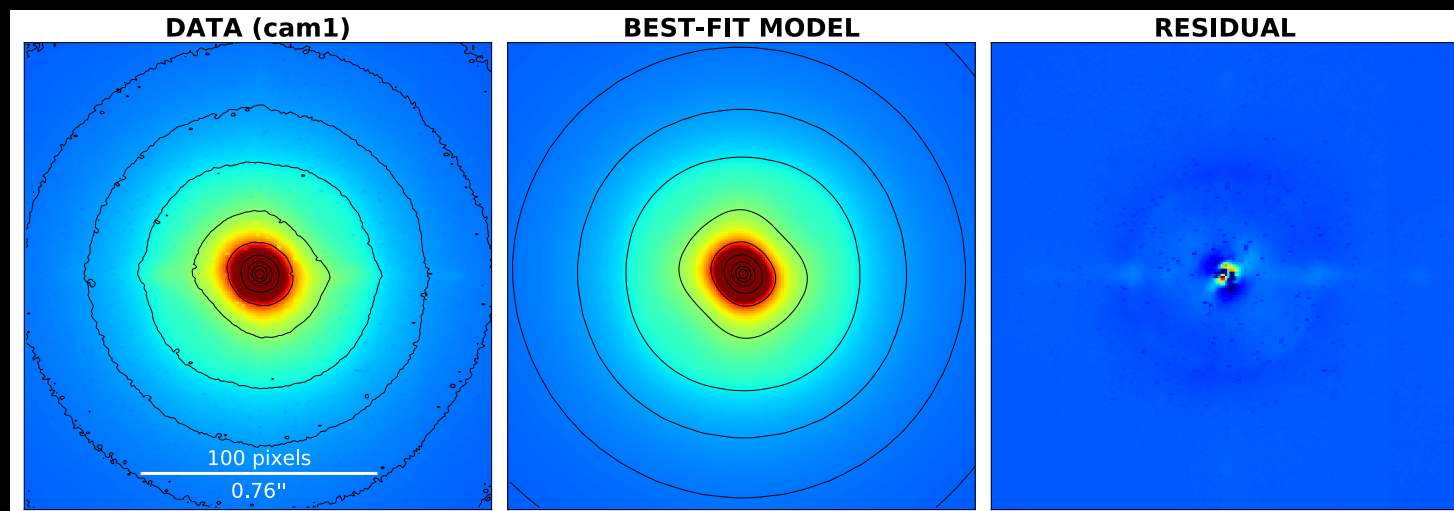
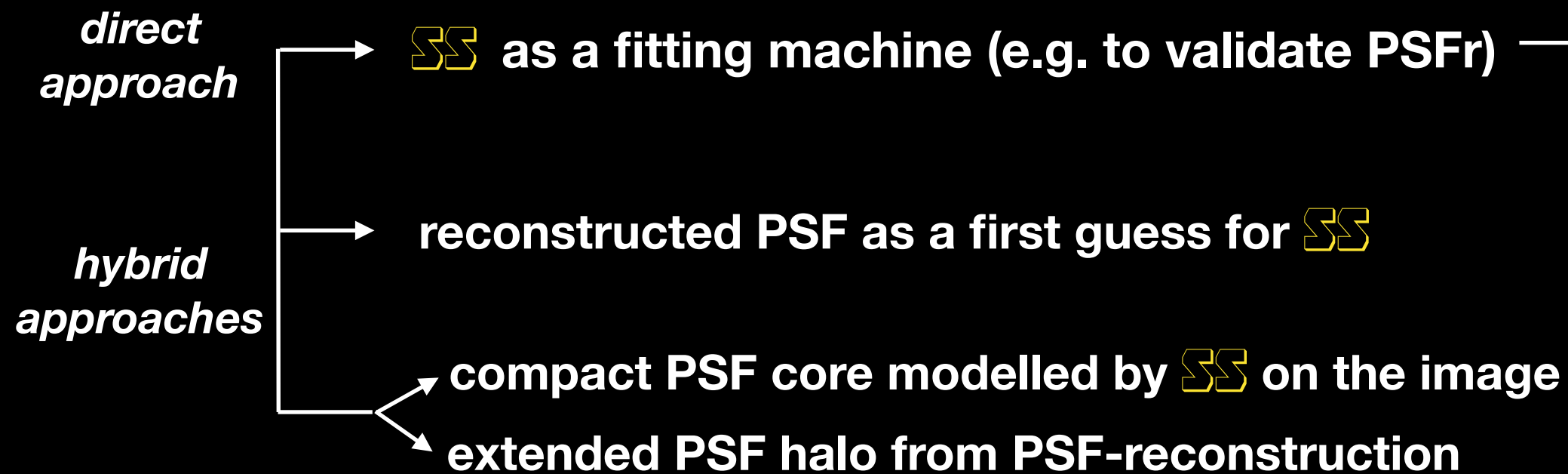
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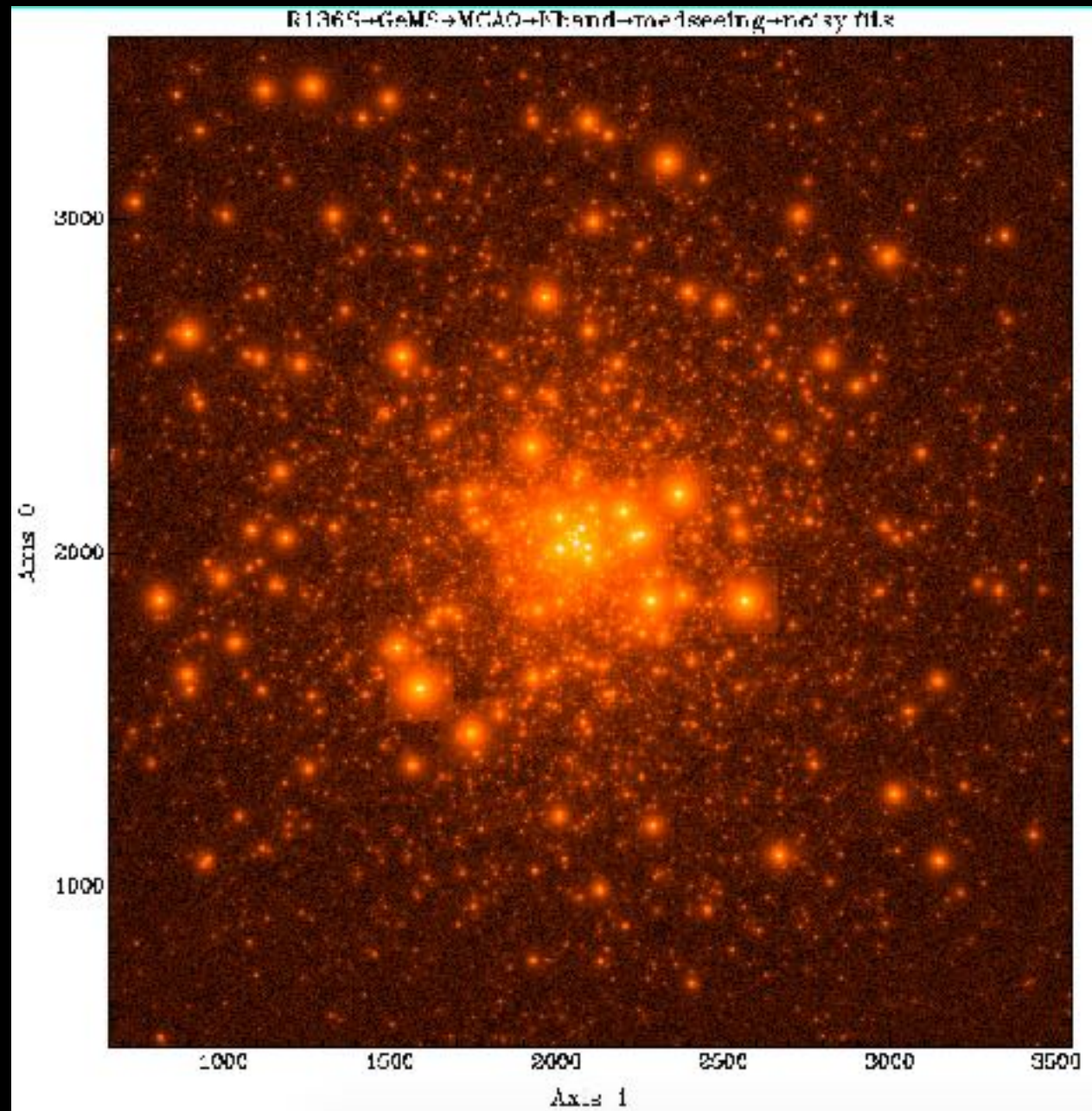
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See talk by **Davide Massari**

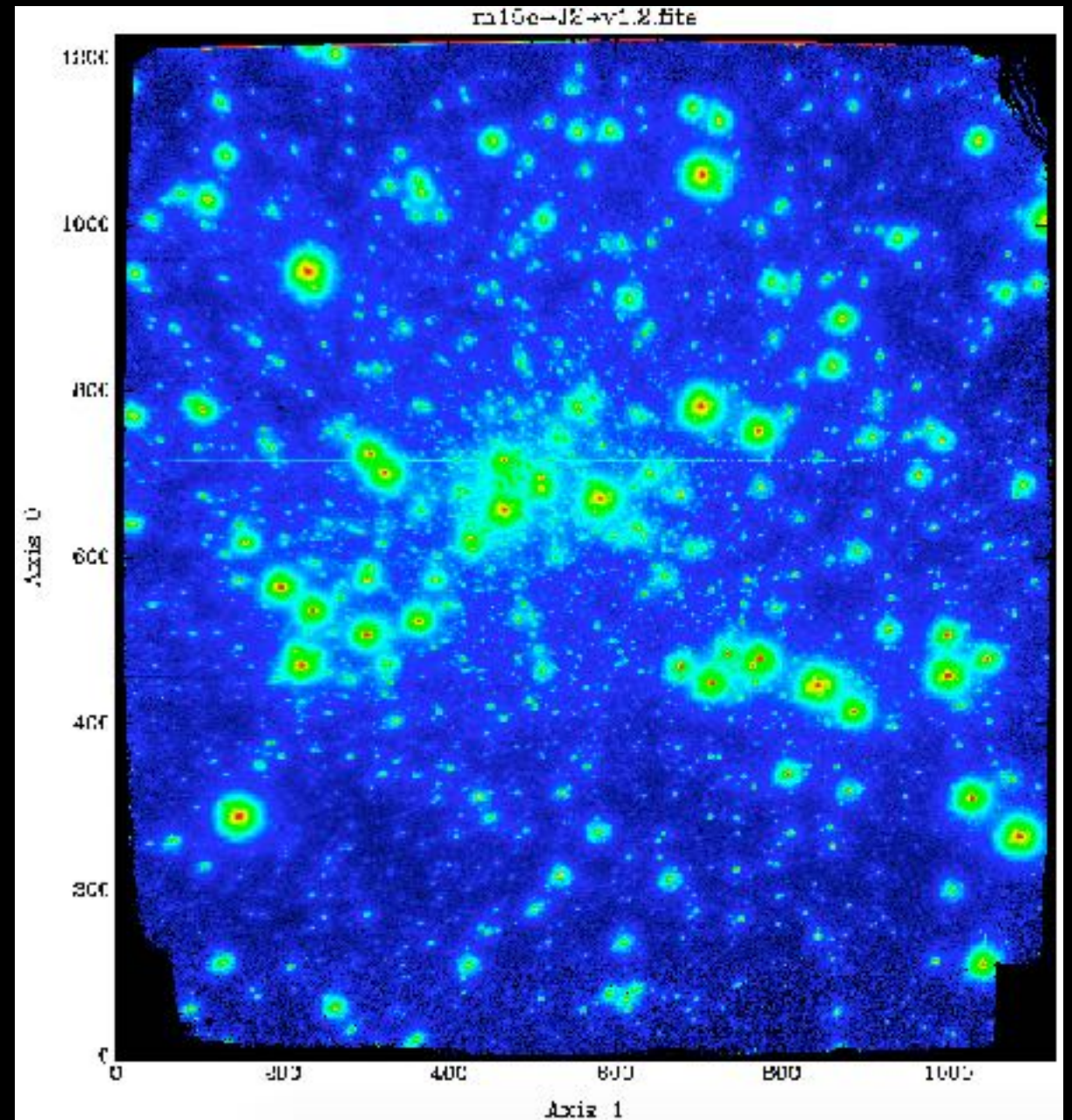
Work in progress

SUPERSTAR on simulations



core of a GC with GeMS
H,J,K, different seeing and exp.time
(collaboration INAF/LAM)

SUPERSTAR on real data



core of M15 with PISCES@LBT
(with C. Arcidiacono)