# Turbulence parameter estimation with Paranal Observatory wavefront sensors

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1

### Estimation of r0 and L0

- Site evaluation and characterization
- Optimization of AO systems, including temporal updates
- Predictions of point spread functions (with or without AO)
- Optimization of fringe-trackers for optical interferometry
- Addressed by many dedicated experiments
  - Balloons, DIMM, MASS, SLODAR, SCIDAR, ...
- Advantages of estimation using Shack-Hartman WFS
  - Ubiquity in large telescopes → make use of existing infrastructure
  - Spatio-temporal synchronism
  - Identical turbulence path (including dome seeing) of the observations
- Previous work
  - Single sensor: Schöck+2003, Fusco+2004, Jolissaint+2018
  - Multiple sensor: Wilson+2002, Guesalaga+2017, Ono+2017

### Classic approach

- Simulate the WFS by generating a Zernike to slopes matrix (H<sub>//</sub>) and invert it obtaining the slopes to Zernike matrix (H<sup>+</sup>).
- For each WFS measurement recover the estimated Zernike coefficients (b) and then compute the variances <b<sup>2</sup><sub>i</sub>>
- Denoise the variances via temporal correlation (Fusco method)
- Select a "good range" of radial orders to fit (start after focus, but where to end?)
- Fit the von Kármán model (i.e., definition of r0 and L0) to denoised variances and recover r0 and L0.
- Operating solution in NAOS (Fusco+2004)



### Our approach

- Validate estimates from simulation (OOMAO, DASP, AOTools)
- Assume von Kármán turbulence
- Assume geometric Shack-Hartmann wavefront sensor
  - NACO like (14x14 sub-apertures, 8 m) + noise
- We have information on
  - Phase screen (assumed independent)
  - Estimated Zernike coefficients
  - True Zernike coefficients
  - True undetected (very high order) Zernike coefficients

### Cross-coupling is unavoidable in model fitting

- A Shack-Hartmann is a "gradient" sensor
- The Zernike gradients matrix is non-orthogonal ightarrow cross-coupling
- r0 and L0 are estimated using Zernike variances
- Diagonalizing the Zernike co-variance matrix (using Karhunen-Loève basis) would not solve the problem
- → No fitting functions for the r0 and L0 exist in this basis
- → Statistical independence versus geometric coupling?...
- Cross-coupling is unavoidable in r0 and L0 joint estimation with model fitting
  - Other (far less simpler, untested) options might exist...

## Onset of cross-coupling [phase screens]

- r0/L0 estimation is done in the low Zernike radial order range (r~2 to r~12)
- Aliasing strongly affects large radial orders (r~21 for our simulation)
- Cross-coupling has localized effects across "all" radial orders
- Cross-coupling is the dominant effect in r0/L0 estimation.



### Overcoming cross-coupling

 Include cross-coupling and noise in the model for measured variances

$$\left\langle b_{i}^{2}\right\rangle = \left\langle a_{\parallel i}^{2}\right\rangle + \sigma_{\mathrm{cc},i}^{2} + \sigma_{\mathrm{n},i}^{2}$$

- true variances, noise and cross coupling
- It turns out that the cross-coupling contribution is analytic (cf. Conan 2000, Takato+1995)

$$\sigma_{cc,i}^{2} = \sum_{j=J+1}^{M} \sum_{j'=J+1}^{M} c_{ij} \langle a_{\perp j} a_{\perp j'} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{ij} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\parallel i} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2 \sum_{j=J+1}^{M} c_{j'i} \langle a_{\perp j} a_{\perp j} \rangle c_{j'i}^{t} + 2$$



but a function of r0 and L0 → iterative method

### Iterative method

- Iteration zero is classic approach, obtain biased estimates of r0 and L0
- Remaining iterations include cross-coupling correction

$$\hat{\mathbf{p}}^{k} = \operatorname*{arg\,min}_{\mathbf{p}} \sum_{i=5}^{J(r)} \left\{ \log \left[ (\langle a_{/\!\!/}^{2} \rangle_{\mathrm{vK}} + \sigma_{\mathrm{n},i}^{2})(\mathbf{p}) \right] - \log \left[ \langle b_{i}^{2} \rangle - \sigma_{\mathrm{cc},i}^{2}(\hat{\mathbf{p}}^{k-1}) \right] \right\}^{2}, \ k = 1, .$$

- estimating improved r0, L0 and noise  $\sigma^2$  at each k
- [Alternative of joint estimation not obvious.]









L0 = 4 m, 8 m, 16 m, 32 m

r0 = 10 cm

SNR (@ r=9) = 10



#### Increasing SNR will not help [it is a bias]



Figure 8. Fried parameter estimations as a function of SNR(r = 9), for reconstructions with r = 9 and  $r_0 = 10$  cm. Note that the k = 3 curves overlap.



Figure 9. Outer scale estimations as a function of SNR(r = 9) for reconstructions with r = 9 and  $r_0 = 10$  cm.

Cf. Andrade+ 2019 ("*Estimation of atmospheric turbulence parameters from Shack–Hartmann wavefront sensor measurements*", MNRAS, 483, 1192) for a detailed presentation.

### What about real data?

#### Shack-Hartman WFSs at Paranal: +13!



### Shack-Hartman WFSs at Paranal

- SAXO
  - 40x40 WFS, visible, control in Karhunen-Loève modes
- CIAO #1-#4
  - 9x9 WFS, K-band, control in Karhunen-Loève modes, Coudé focus (rotation)
- NAOMI #1-#4
  - 4x4 WFS, visible, control in Zernike modes, Coudé focus (rotation)
- AOF #1-#4
  - 40x40 WFS, visible, Karhunen-Loève modes

## Estimating r0 and L0 from real data

- Open loop
  - Pros: simple
  - Cons: uses science time
  - Method
    - Slopes to Zernike matrix is a geometric model
    - Convert to Zernike coefficients
    - Apply fitting to variances
- Closed loop
  - Pros: runs parallel to science
  - Cons: complex combines voltages + slopes
  - Method
    - Define where to work (DM or WFS)
    - Convert voltages or slopes
    - Convert to Zernike coefficients
    - Apply fitting to variances









### Future prospects & challenges

#### • Short term

- Work on closed loop data issues...
- Run pipeline on archived data
- Paranal turbulence parameters
  - How does the estimation change with WFS characteristics?
  - How does r0 and L0 change from telescope to telescope?
  - Can we have a picture of these parameters on the mountain top (position/height)?
  - Non-stationarity effects, SPARTA implementation, etc
  - → more news in Adaptive Optics Week 2020
- Telemetry data curation
  - document, archive, distribute, standards → DADS is the way forward

#### Adaptive Optics Workshop Week @ Porto 2020 Porto, Portugal -- 30th March to 3rd April

