









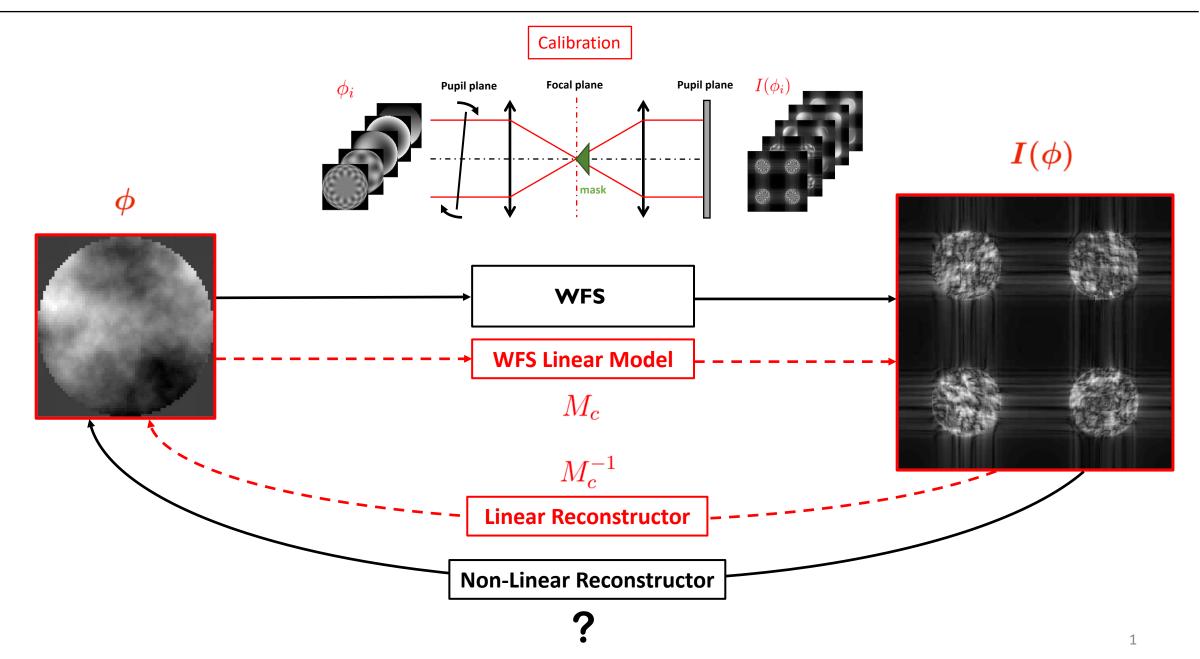
Using a modulation camera to control Pyramid Wavefront Sensor on the fly

Vincent Chambouleyron, Olivier Fauvarque, Pierre Janin-Potiron Benoît Neichel & Thierry Fusco





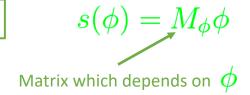
Towards a non-linear reconstructor?



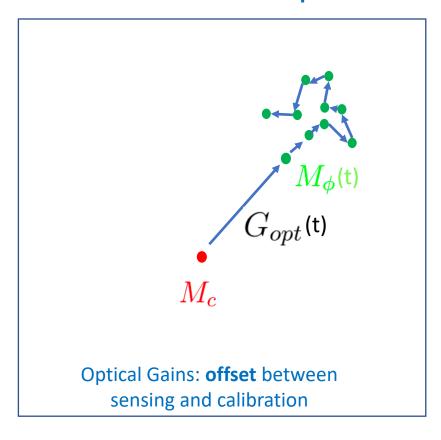
Towards a non-linear reconstructor?

$$s(\phi) = M_c \phi$$

Pyramid WFS = Linear Parameter-Varying System (LPVS)

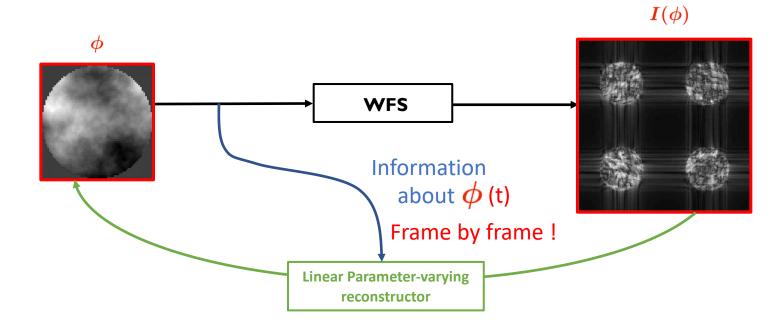


Interaction Matrix Space

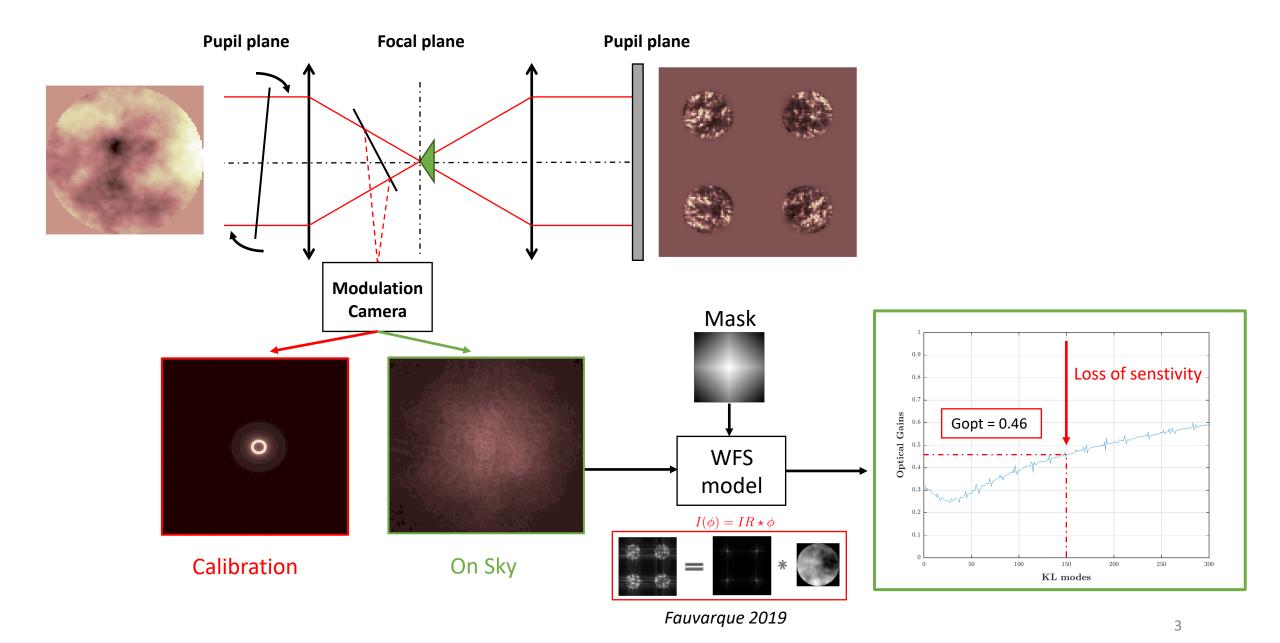


The **Reconstructor** need to be aware of the state of the system

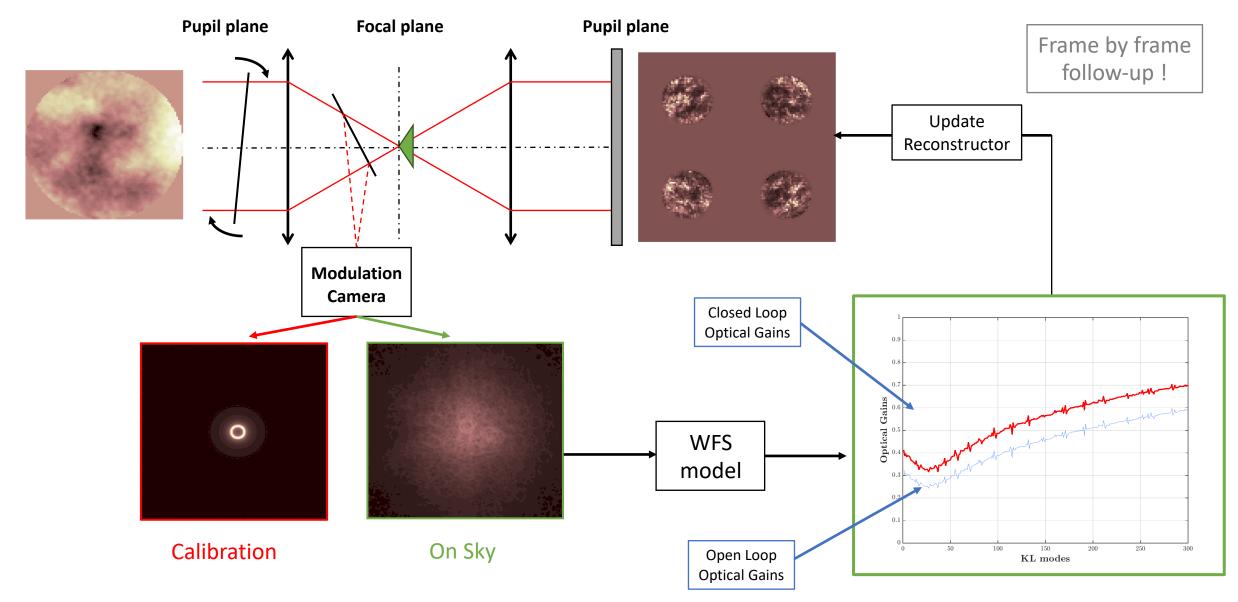
We need to perform **gain scheduling**



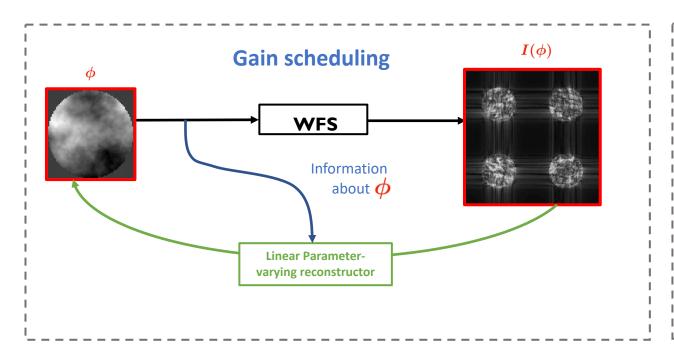
How to perform gain scheduling? One possible solution

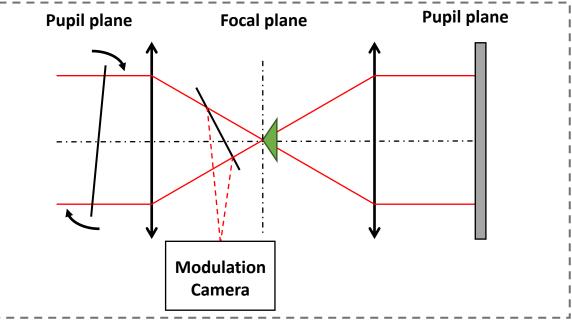


How to perform gain scheduling? One possible solution



How to perform gain scheduling? One possible solution





DRAWBACK: Steal photons on the way!

ADVANTAGE: Absolute measurements « Free from the loop »

NO PAIN

NO GAIN

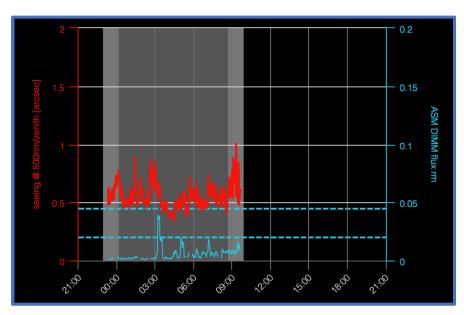
Applications

BOOTSTRAP

Open-Loop **Optical Gains** Fast Bootstrap Easier Bootstrap on strong turbulence Towards a non-modulated Pyramid?

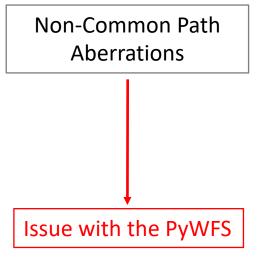
ENHANCEMENT OF CLOSED-LOOP ROBUSTNESS AND PERFORMANCE

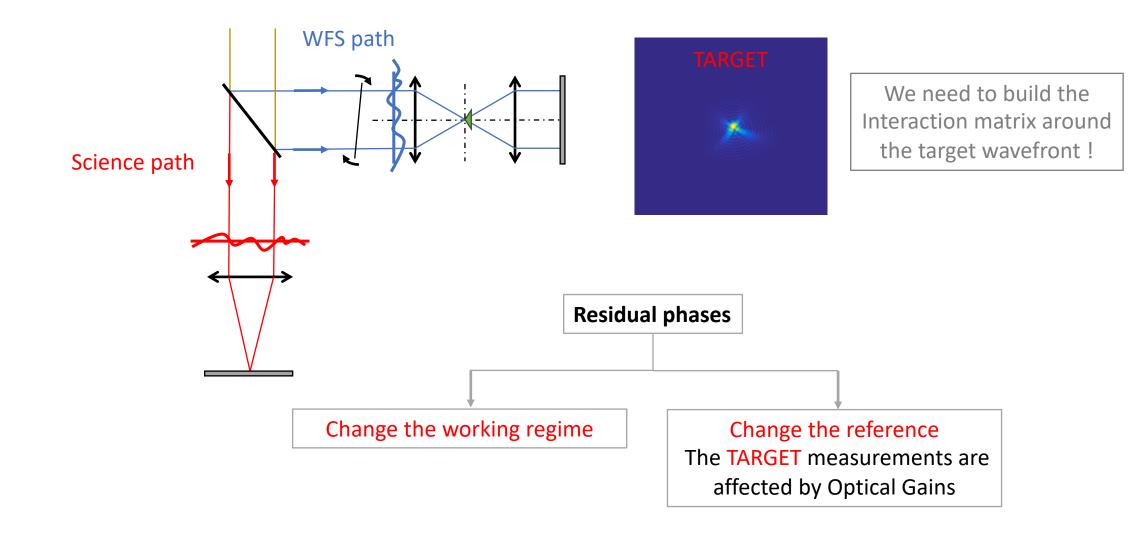
Strong variation of seeing during the night

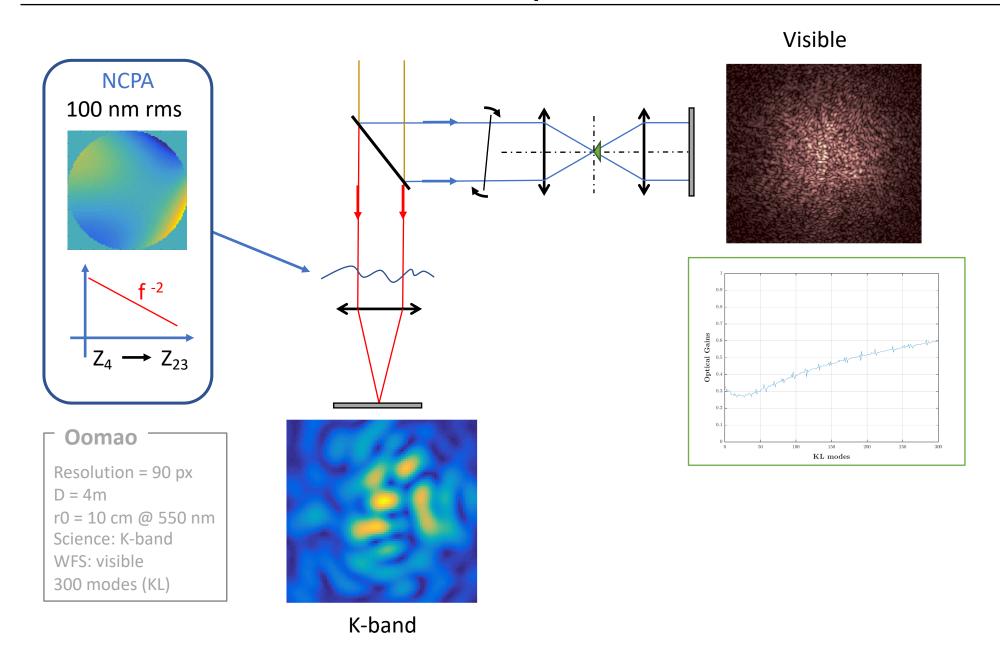


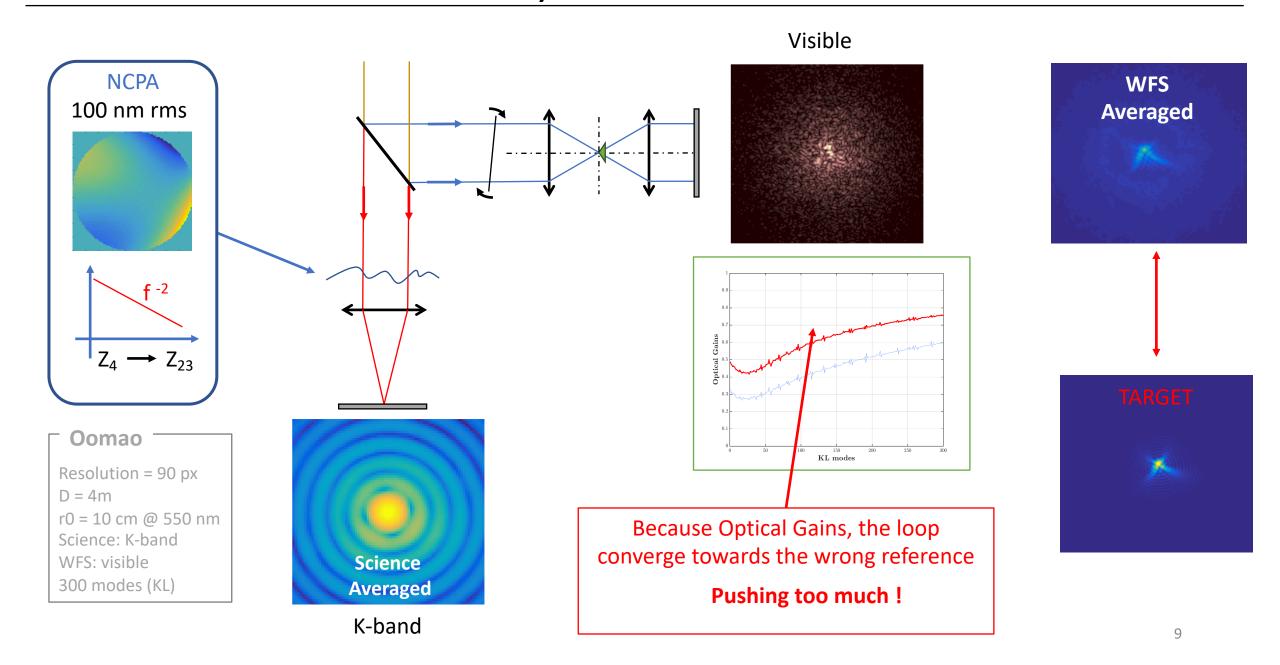
Seeing at Paranal October 21th 2019

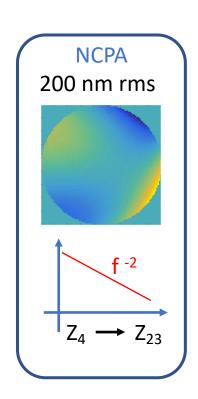
HANDLING NCPA

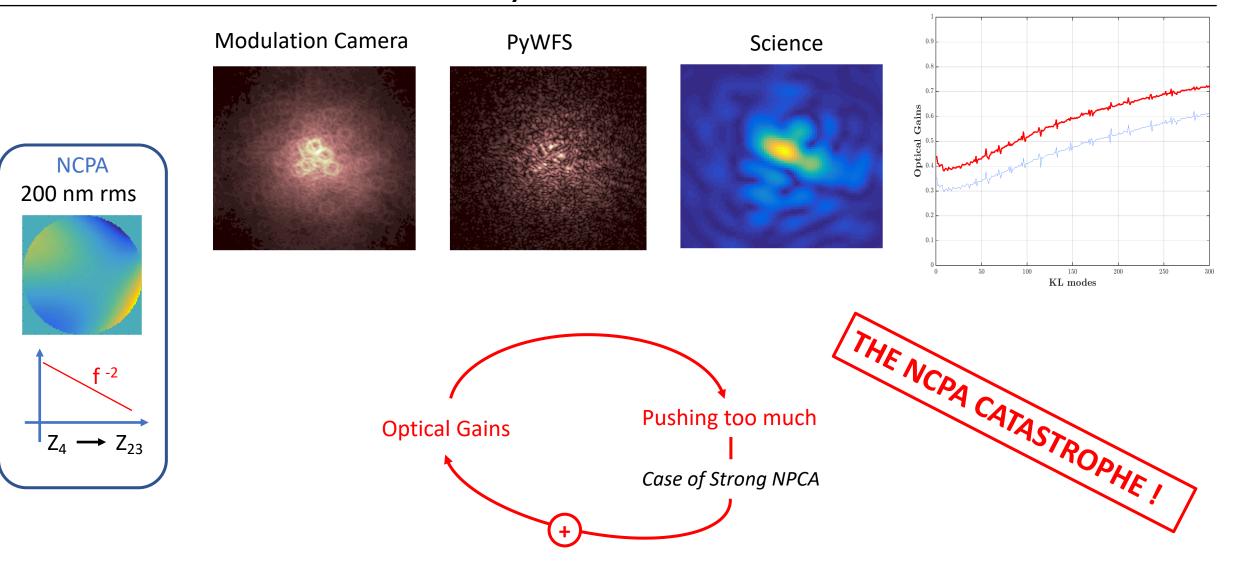


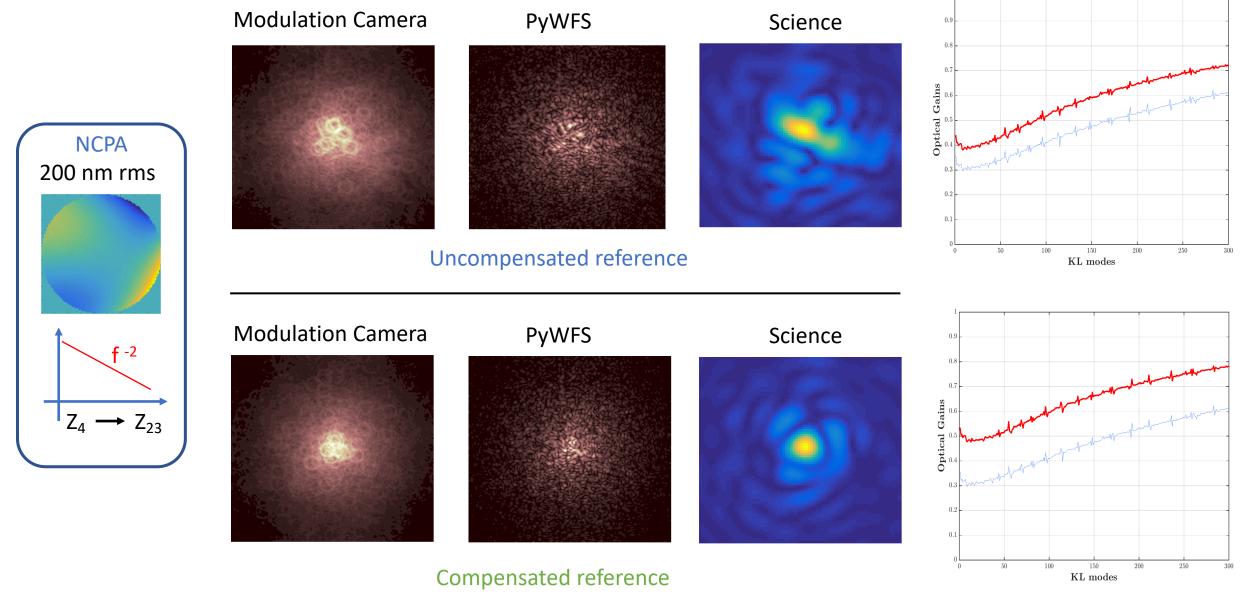


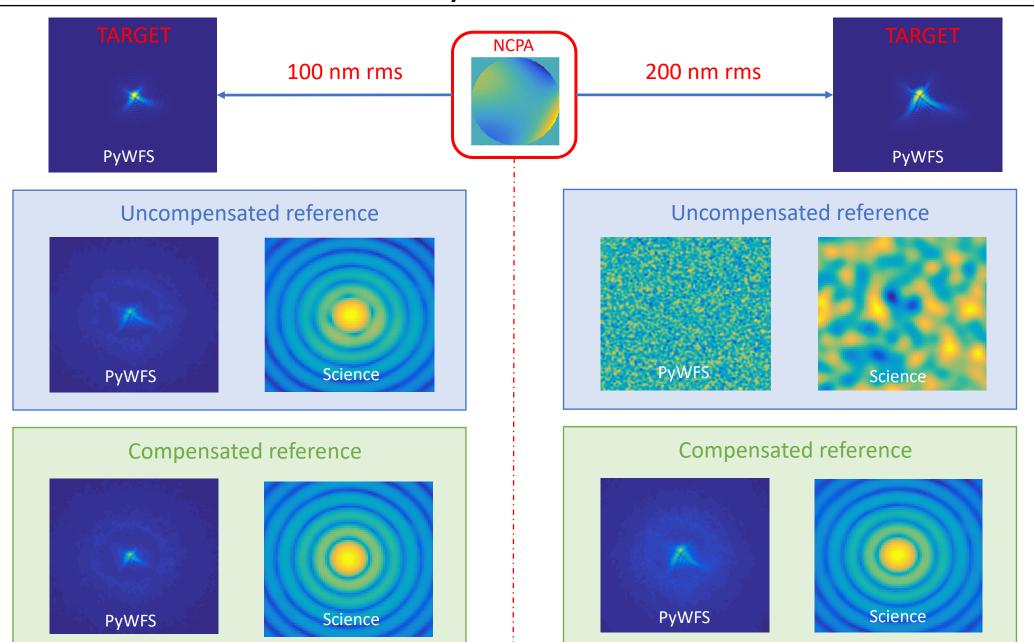




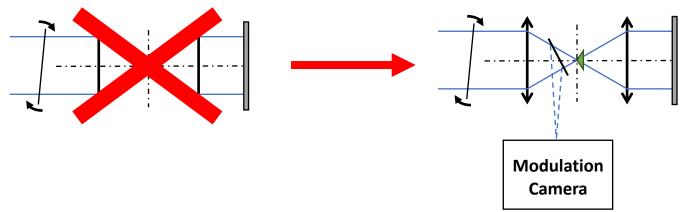






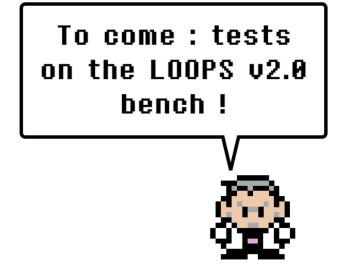


Conclusion



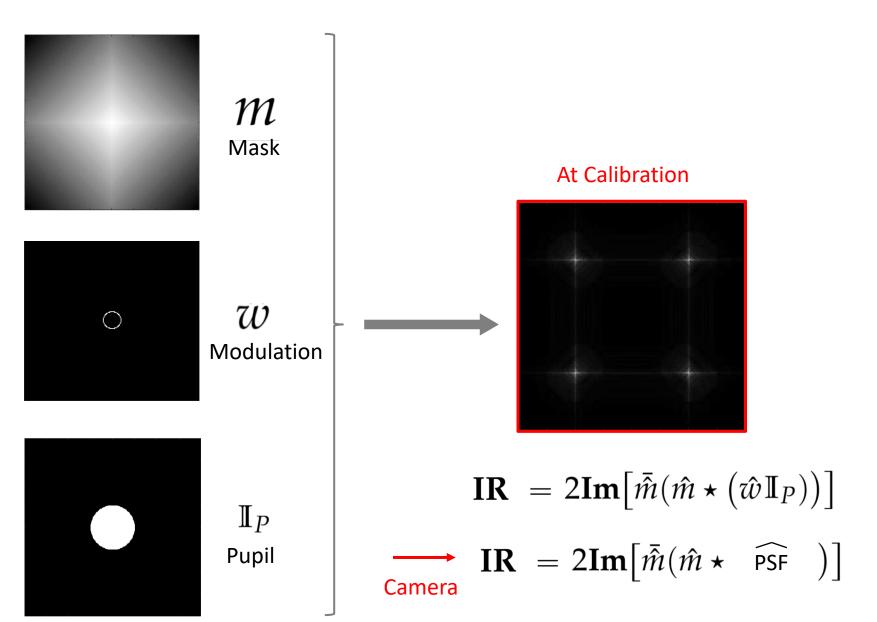
Some Questions

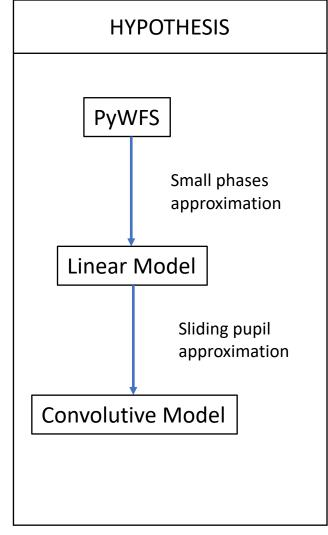
- Noise on modulation camera Impact on Optical Gains computation ?
- Can we use the modulation camera at another wavelength?



THANK YOU If you have it, use it!

ANNEX: The Convolutional Model – FAUVARQUE 2019





ANNEX: The Convolutional Model – FAUVARQUE 2019

