



Machine Learning and Deep Learning in Astroparticle Physics:

From Cosmic Rays to Neutrino and Gamma-Ray Astronomy

Yvonne Becherini, Laboratoire Astroparticule et Cosmologie,
Université Paris Cité

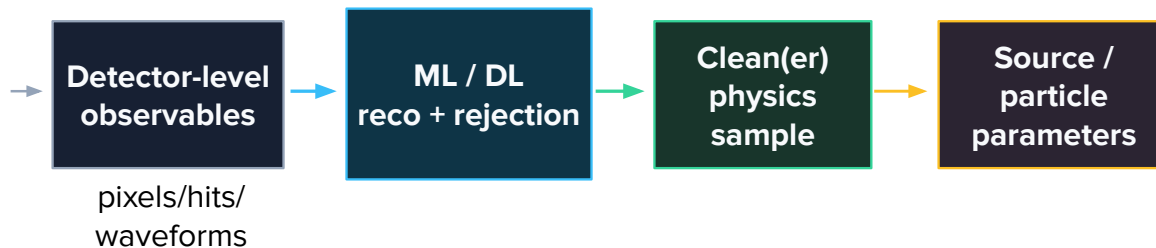
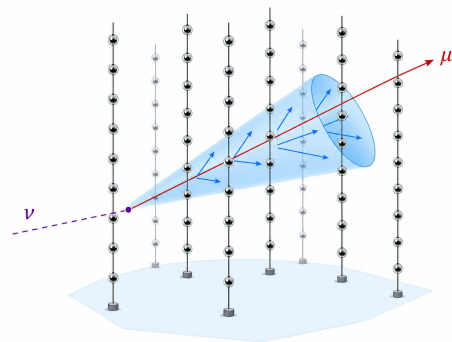


Extreme backgrounds → Focus on the low-level reconstruction and rejection part

ASTROPARTICLE PHYSICS

Often $S/B \ll 1$ already at event level

γ/hadron • ν/μ • rare showers



Sensitivity Gain: 1) reduce residual background while retaining signal $\Rightarrow S \approx N_{\text{sig}} / \sqrt{N_{\text{bkg}}}$
2) Angular and energy resolution

OBSERVATIONAL ASTROPHYSICS

Often starts closer to astronomical observables

images • spectra • light curves • catalogues

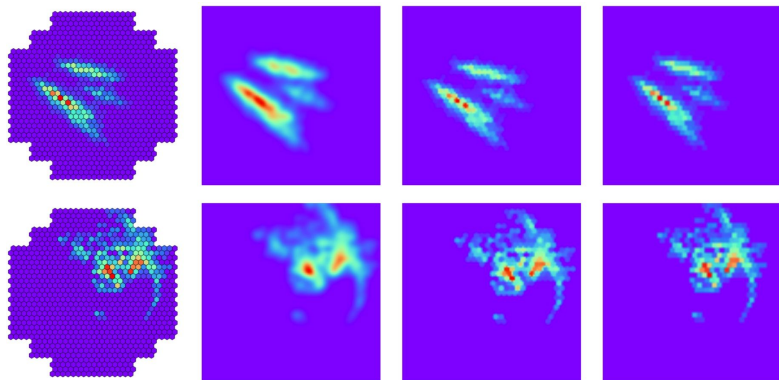
Observable

Physical
inference

Astroparticle ML historically enters earlier in the analysis chain: at reconstruction, classification and event selection.



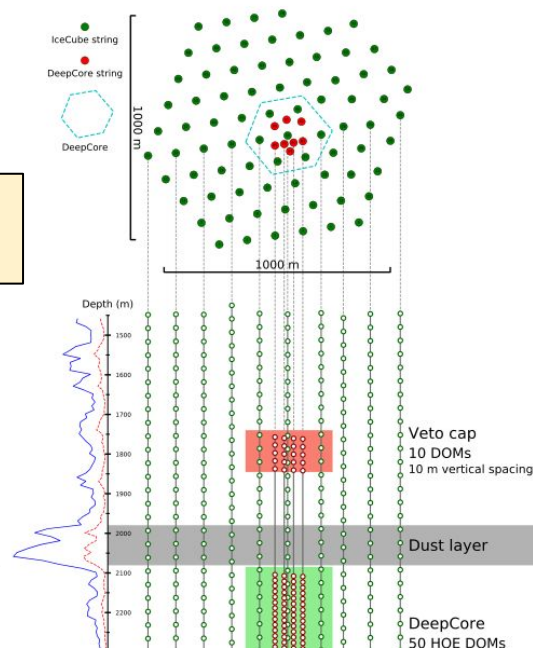
IACT camera
image-like shower view



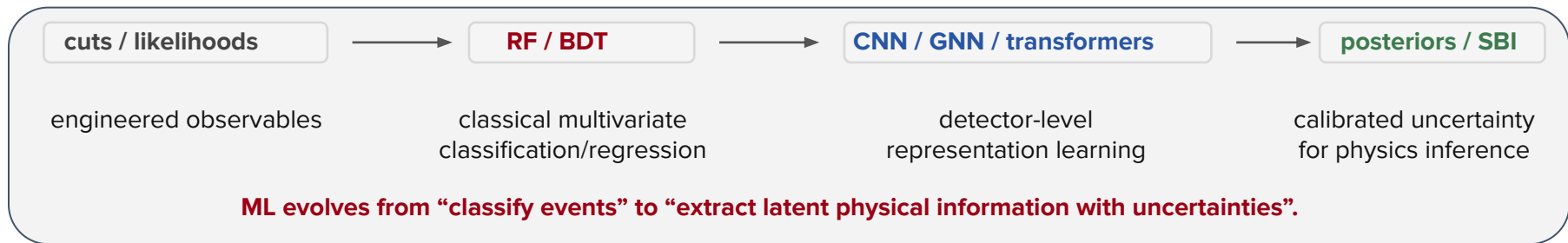
The detector determines the useful ML representation

Shilon et al. 2019, arXiv:1803.10698;
Abbasi et al. 2022, arXiv:2209.03042.

neutrino telescope
sparse 3D hits



CNNs are natural for camera images; GNNs and transformers become natural when the detector is irregular, sparse or time-resolved.



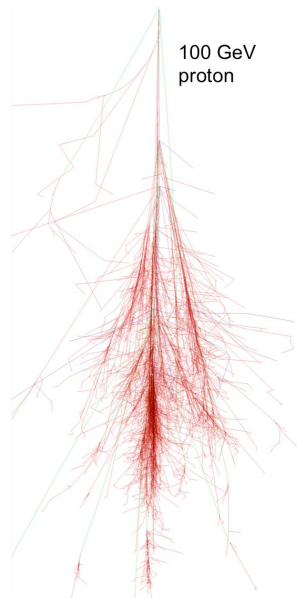
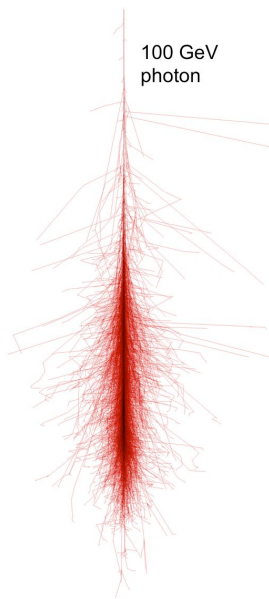
What becomes possible?

sensitivity gains

combine observables;
reduce background;
faint-source reach

hidden physical information

Shower maximum;
images/graphs learn
morphology and timing



Electromagnetic Showers (pair production in the Coulomb field of an atmospheric nucleus and bremsstrahlung)

- Highly beamed, compact, symmetrical, and extremely muon-poor.

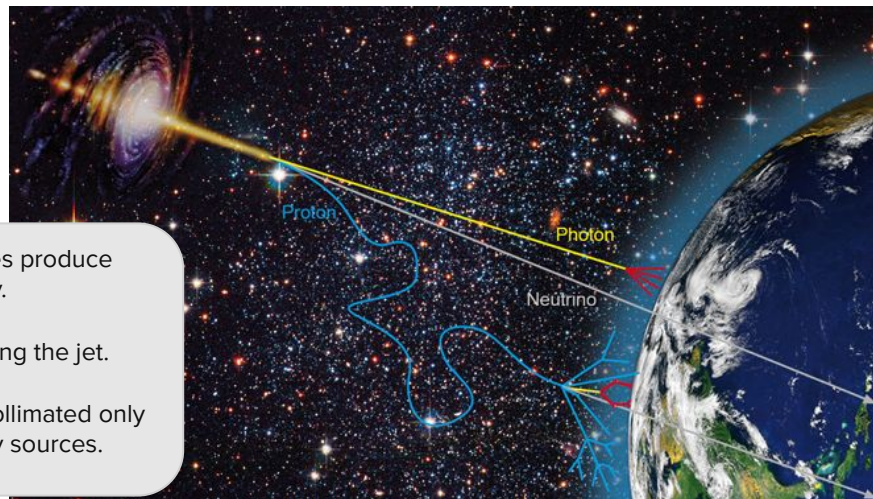
Hadronic Showers (Hadronic pN interactions)

- Complex multi-particle networks.
- Wider lateral footprint with significant muon, pion, and hadronic core components.

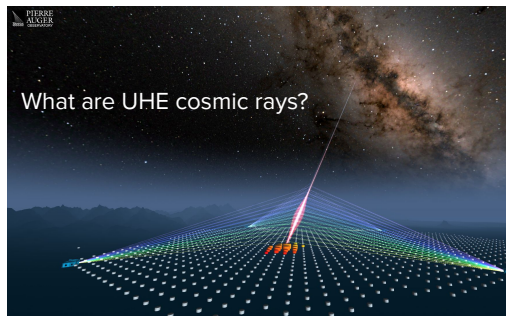
Protons accelerated at cosmic-ray sites produce secondary ν and γ -rays via pion decay.

Neutrinos and γ -rays stay beamed along the jet.

Protons are magnetically deflected, collimated only at the highest energies and for nearby sources.



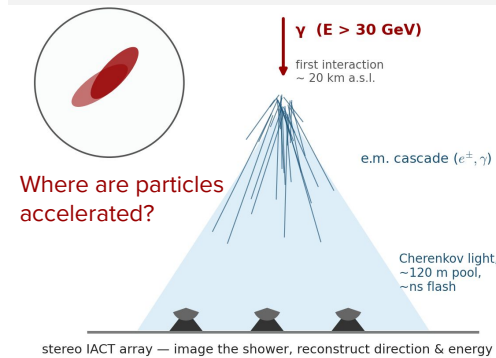
Pierre Auger Observatory



UHECR air showers: hybrid surface + fluorescence detector

hybrid cosmic-ray air-shower observatory

Imaging Atmospheric Cherenkov Telescopes

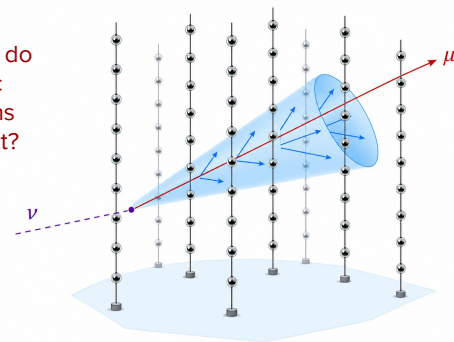


TeV γ rays: atmosphere as calorimeter, cameras as fast imagers

H.E.S.S. / MAGIC / VERITAS → CTAO

Neutrino telescopes

Where do
cosmic
hadrons
interact?



cosmic ν : sparse 3D arrays in ice or deep sea water

IceCube / KM3NeT / Baikal-GVD and next generation

What is measured

- ground footprint + ns traces
- fluorescence profile
- Xmax, energy, muon/EM content

- ns Cherenkov images
- stereo → direction, impact, energy
- morphology → hadron rejection

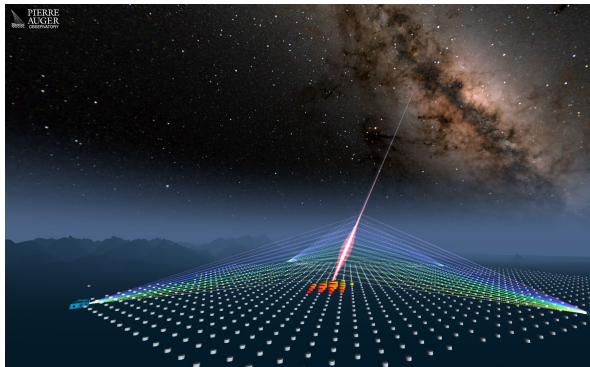
- Cherenkov light in ice / sea
- hits: position, time, charge
- track vs cascade topology

Physics goals

- composition above 10^{18} eV
- Galactic → extragalactic
- UHE photons and neutrinos

- TeV–PeV accelerators, PeVatrons
- leptonic vs hadronic emission
- AGN, SNRs, PWNe, EBL, DM

- astrophysical ν sources
- hadronic signatures of CRs
- γ – ν –CR connection



Surface arrays sample the shower at ground level:

- near-100% duty cycle, huge exposure
- indirect access to **mass composition**
- timing traces carry shower-development information

What Auger/TA-like arrays measure

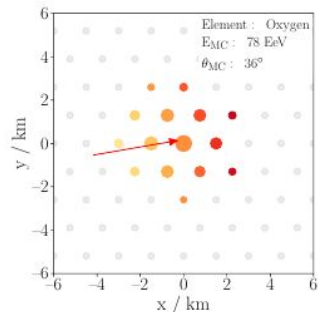
- lateral shower footprint
- time traces in each station
- signal risetime and curvature
- geometry + energy proxies



What are ultra-high-energy cosmic rays made of, and how does their composition evolve with energy?

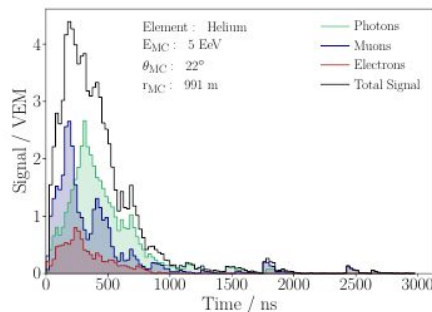
- The key observable is the atmospheric depth at which the shower reaches maximum development (X_{max}).
- X_{max} is strongly composition-sensitive
- X_{max} is measured with the fluorescence detector, but this has only about 15% duty cycle, while the surface detector operates nearly continuously.

Case-study question: can surface-detector traces recover information normally associated with fluorescence X_{max} ?



LSTM

learns time-trace features
per WCD station



hexagonal CNN

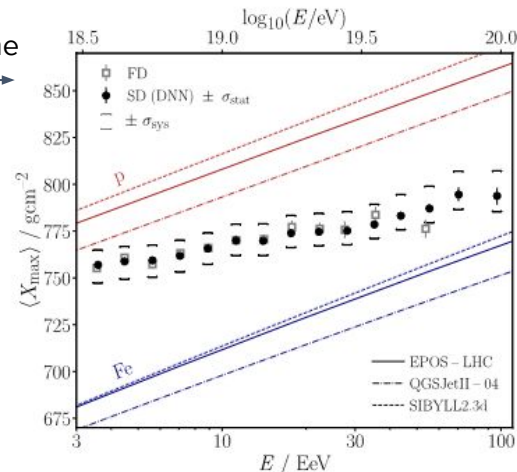
uses triangular/hexagonal
array symmetry

- LSTM → converts each station waveform into learned feature channels; encodes the temporal structure of each station trace
- hexagonal CNN → learns the spatial correlations of those features across the shower footprint.

Trained on simulations (MC ≠ data), calibrated on hybrid Fluorescence Detector data

Pierre Auger Coll., JINST 16 (2021) P07019;
Phys. Rev. Lett. 134 (2025) 021001.

close to the
ground →



≈10×

100 EeV

more statistics
than FD Xmax
sample

composition reach
at extreme energies

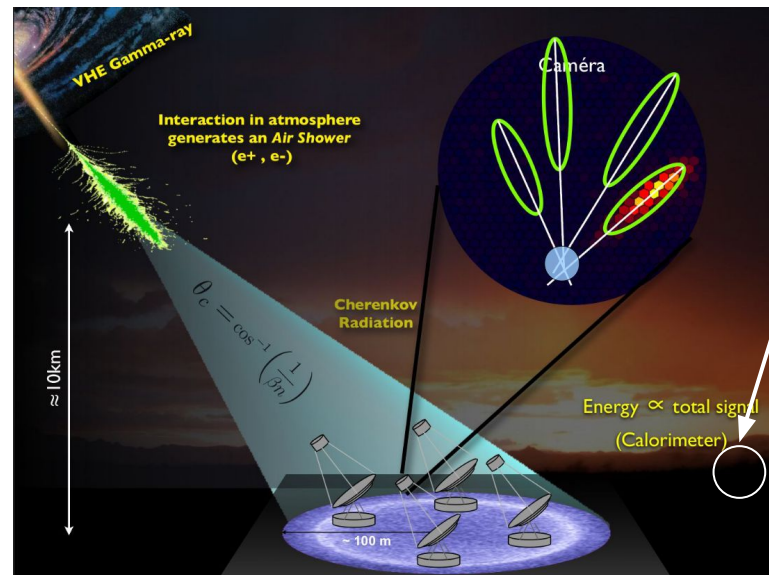
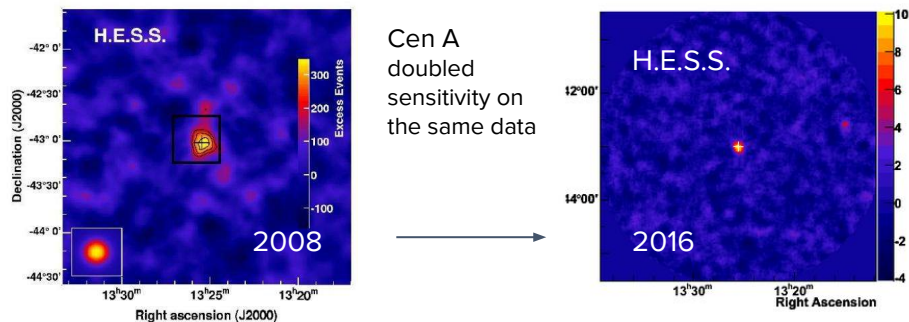
From a set of telescope images, we wish to infer the particle type, its energy and its direction

The dominant challenge is $\gamma \ll$ hadronic cosmic-ray background.

Classical approach

- Reduce each image to hand-engineered quantities:
 - width, length, intensity
 - impact-related parameters
 - stereo quantities
- Then use **Random Forests/BDTs/multivariate classifiers**.

Better gamma/hadron separation $\rightarrow$ better sensitivity to faint sources.



Becherini et al, *Astroparticle Physics*, Volume 34, Issue 12, July 2011, Pages 858–870

What DL tries to exploit



Beyond engineered features:

pixel-level morphology and timing

multi-telescope information fusion

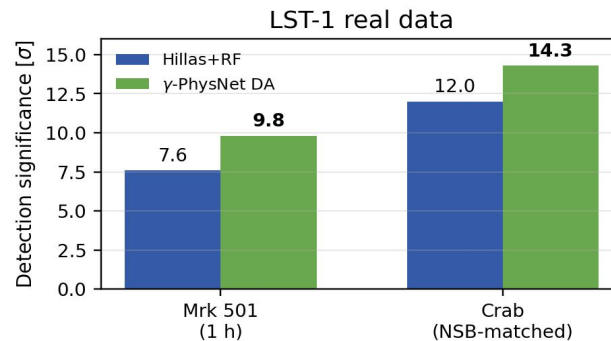
multi-task reconstruction: γ/h , energy, direction

The high bar:

DL competes not only with Hillas+RF, but with mature likelihood/template chains

So the relevant metric is not only AUC on MC, but stable gain on real data. (Domain shift)

Clear real-data example: LST-1 CTAO



Tangible observational gain, but depends on matching MC to data.

LST-1 real data: Vuillaume et al. 2021, PoS ICRC2021 703, arXiv:2108.04130 (Mrk 501); Dellaiera et al. 2024, arXiv:2403.13633 (Crab, NSB tuning).

Most supervised ML chains in astroparticle physics are trained on Monte Carlo simulations.

$p_{\text{MC}}(x)$

$\neq$

$p_{\text{data}}(x)$

Sources of domain shift

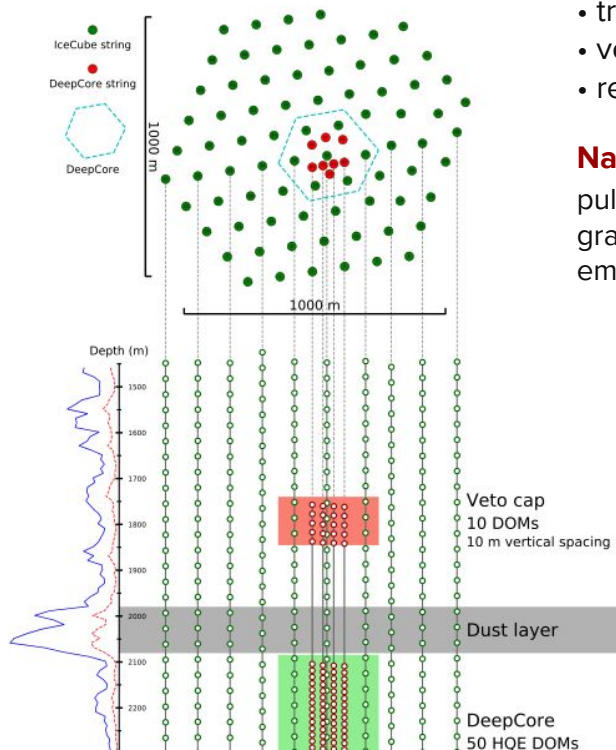
- night-sky background and atmosphere
- detector ageing / calibration
- hadronic interaction models
- trigger and selection effects

Methods entering the field

- data/MC validation on standard candles
- domain adaptation
- systematic-aware training
- uncertainty calibration

A major barrier to adoption in IACT analyses:

mature reconstruction chains are robust on real data, while DL gains can degrade under domain shift.

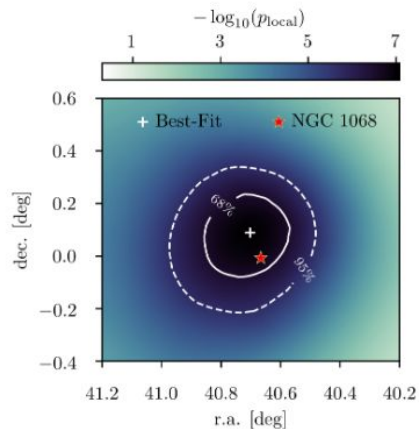


Different detector language, but same goals

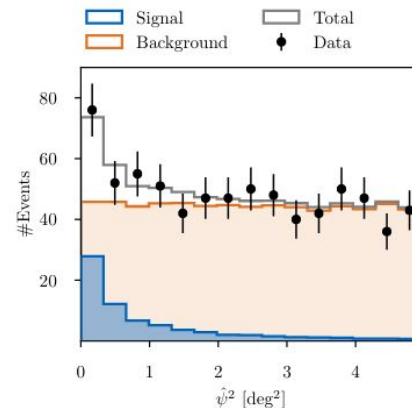
- atmospheric background rejection
- track /cascade classification
- vertex, direction and energy reconstruction
- real-time event selection for follow-up

Natural representations

pulses →
graph nodes/point cloud/time-aware
embeddings



- Gradient boosted decision tree for angular errors (so standard ML)
- CNN for energy reconstruction (DL)



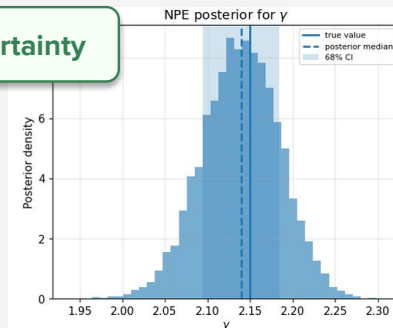
“Evidence for neutrino emission from the nearby active galaxy NGC 1068” Science, 2022

From point estimates to posteriors

classical output
E, direction, class

physics output
 $p(\theta|\text{detector data})$

usable uncertainty



Pre-trained/foundation models for Data Filtering

- TabPFN for tabular data
- Fine-Tuned DINOv2 on H.E.S.S. images

Simulation-Based Inference

Representation Learning

raw detector
hits

learned event
embedding

- Learned embeddings can be reused across analyses
- Promising for low-statistics and transient searches
- Still needs physics-aware validation

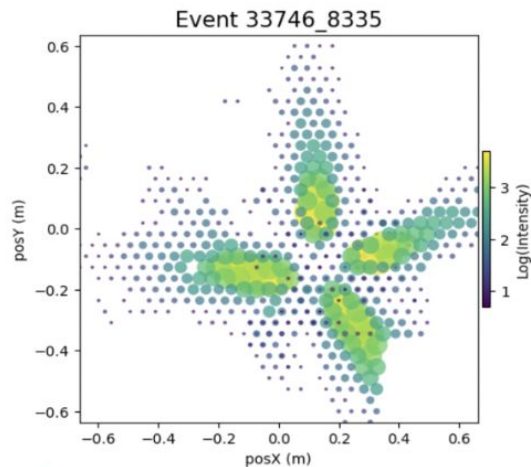
classification

energy /
direction

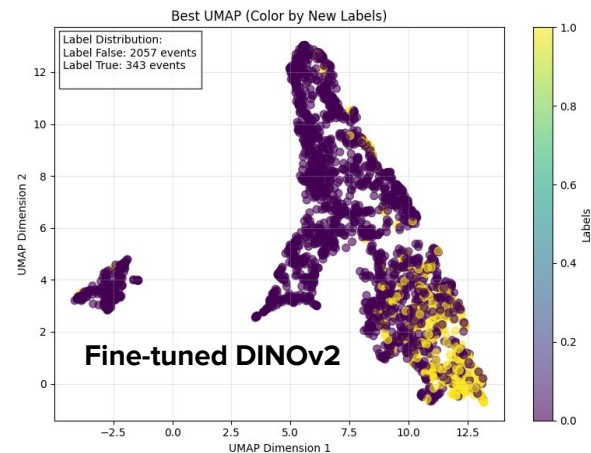
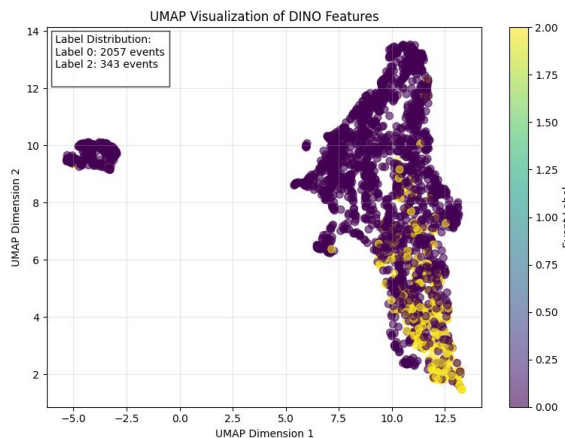
anomaly search

source
association

DINOv2 on real H.E.S.S. data to see if we can distinguish gamma rays from hadronic showers with no supervision

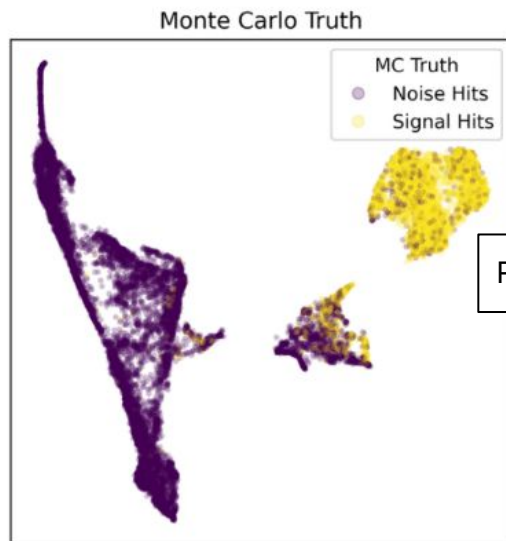


Frozen DINOv2 features

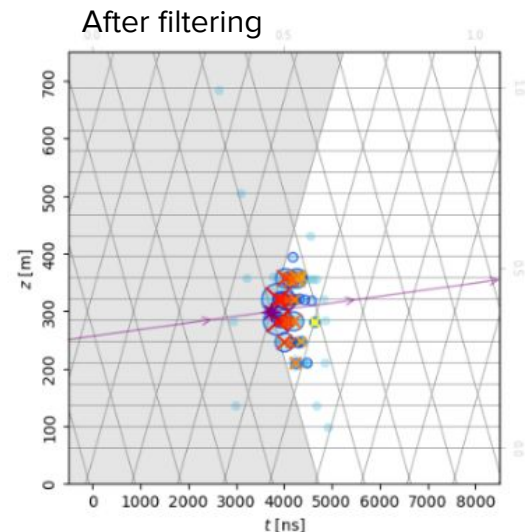
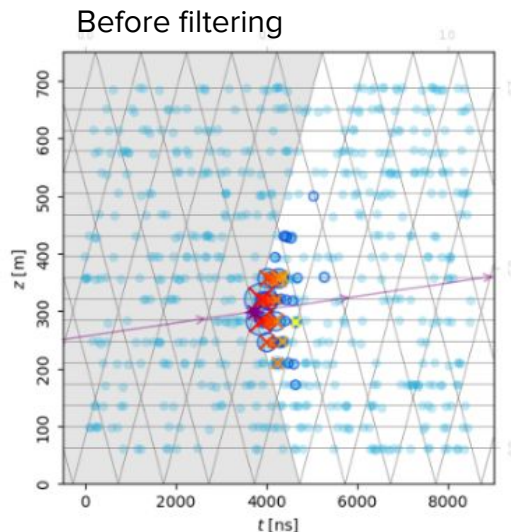


G. Aractingi, G. Jeannin
Master internships

- GNN to filter out K40 background from data to accelerate the track reconstruction procedure
- PMT hits are nodes (position, time, charge); physically motivated space-time compatibility defines the edges. **Sparse + irregular geometry $\rightarrow$ GNN.**
- Exploit unlabelled data/semi-supervised learning $\rightarrow$ reduce simulation dependence
- Binary classifier sees physics events and pure background events
 $\rightarrow$ the network learns the representation of the hits



Preliminary

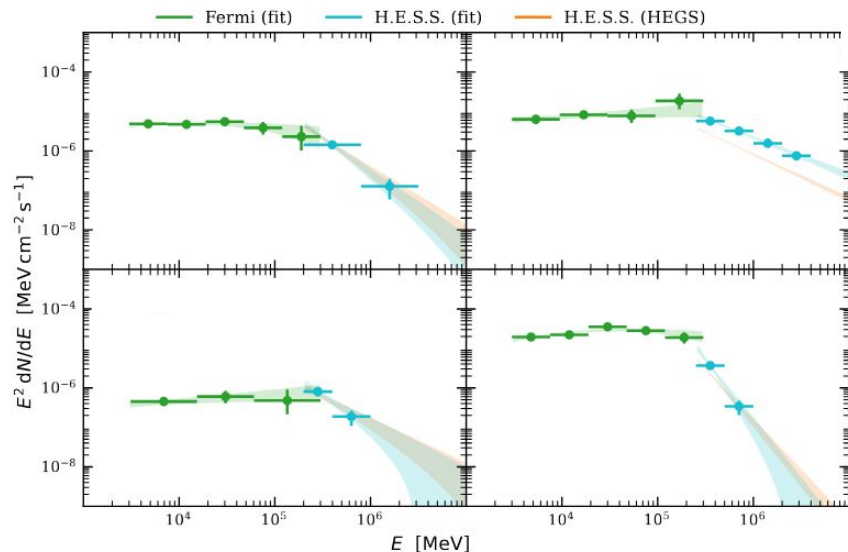


Max Eff, PhD Thesis

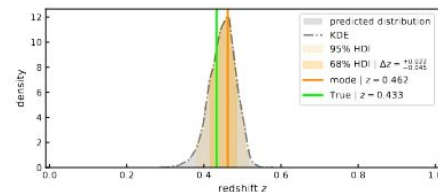
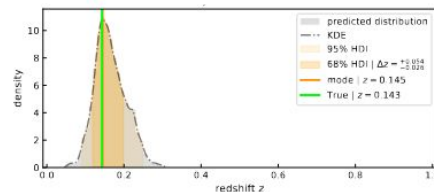
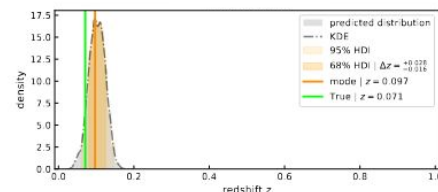
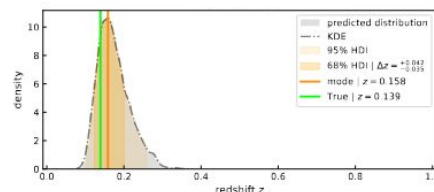
Goal: Estimate BL Lac redshifts from **EBL-attenuated inverse-Compton SEDs**, using supervised ML trained on a large set of physically motivated synthetic spectra.

Max Eff, PhD Thesis

Same inverse-problem logic, now at source level



Preliminary



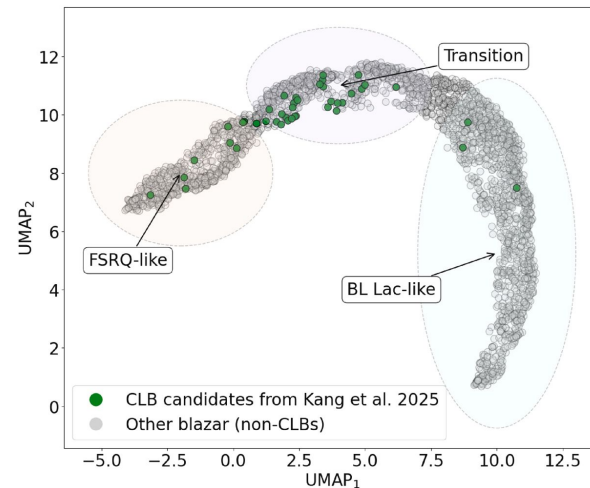
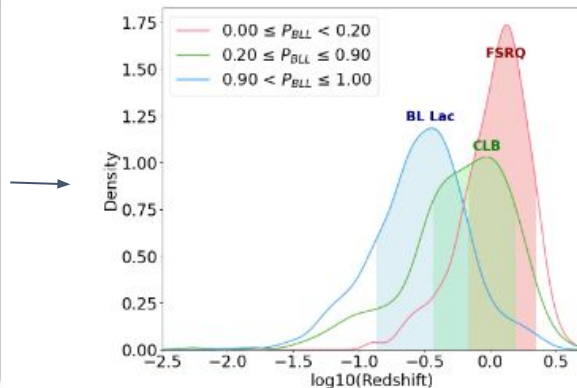
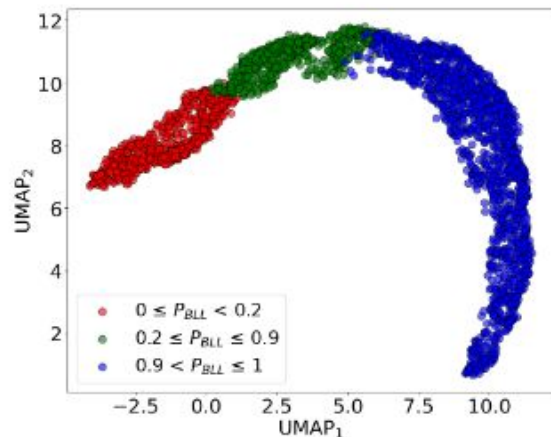
Simulation-based inference: the inverse mapping is learned from physically simulated SEDs, while the redshift posterior is obtained by Monte-Carlo propagation of the measured spectral uncertainties.



Next step: Neural SBI

- Classification of blazars from the Fermi 4LAC-DR3 catalogue, focusing on blazars of uncertain type.
- **TabPFN** as a foundation model for tabular data.
- **The result suggests a continuum between FSRQs and BL Lacs, with Changing-Look Blazars as possible transitional objects.**
- Here the ML output is not only a label.
A probability score plus latent-space structure becomes a way to discuss physical evolution.

Goal: Study blazar evolution through latent space investigation



Detector level: ML as reconstruction

- **Auger:** DL recovers X_{max} from surface traces, 10x the fluorescence statistics and composition reach to 100 EeV.
- **IACTs:** measurable gains on real data at low energies, but the baseline is mature likelihood chains and gains are sensitive to observing conditions.
- **Neutrino telescopes:** graphs and transformers match sparse 3D space-time data

Source level: the same inverse problem, one step up

- SEDs $\rightarrow$ redshift posteriors: simulation-based inference gives a distribution, not a point estimate.
- Catalogue features $\rightarrow$ latent space: classification becomes a way to discuss physical evolution, not just a label.
- Images $\rightarrow$ pre-trained foundation models: DINOv2 usable off the shelf where labels are scarce.

The common bottleneck is not architecture, it is the simulation gap

Every supervised chain here is trained on Monte Carlo. The interesting direction is reducing that dependence: domain adaptation, weak supervision from event-level labels, self-supervised pretraining on unlabelled data.

Thank you