

What Comparing HST and JWST Images Reveals About Stellar Clusters Without Labels

Conference ML4Astro 3

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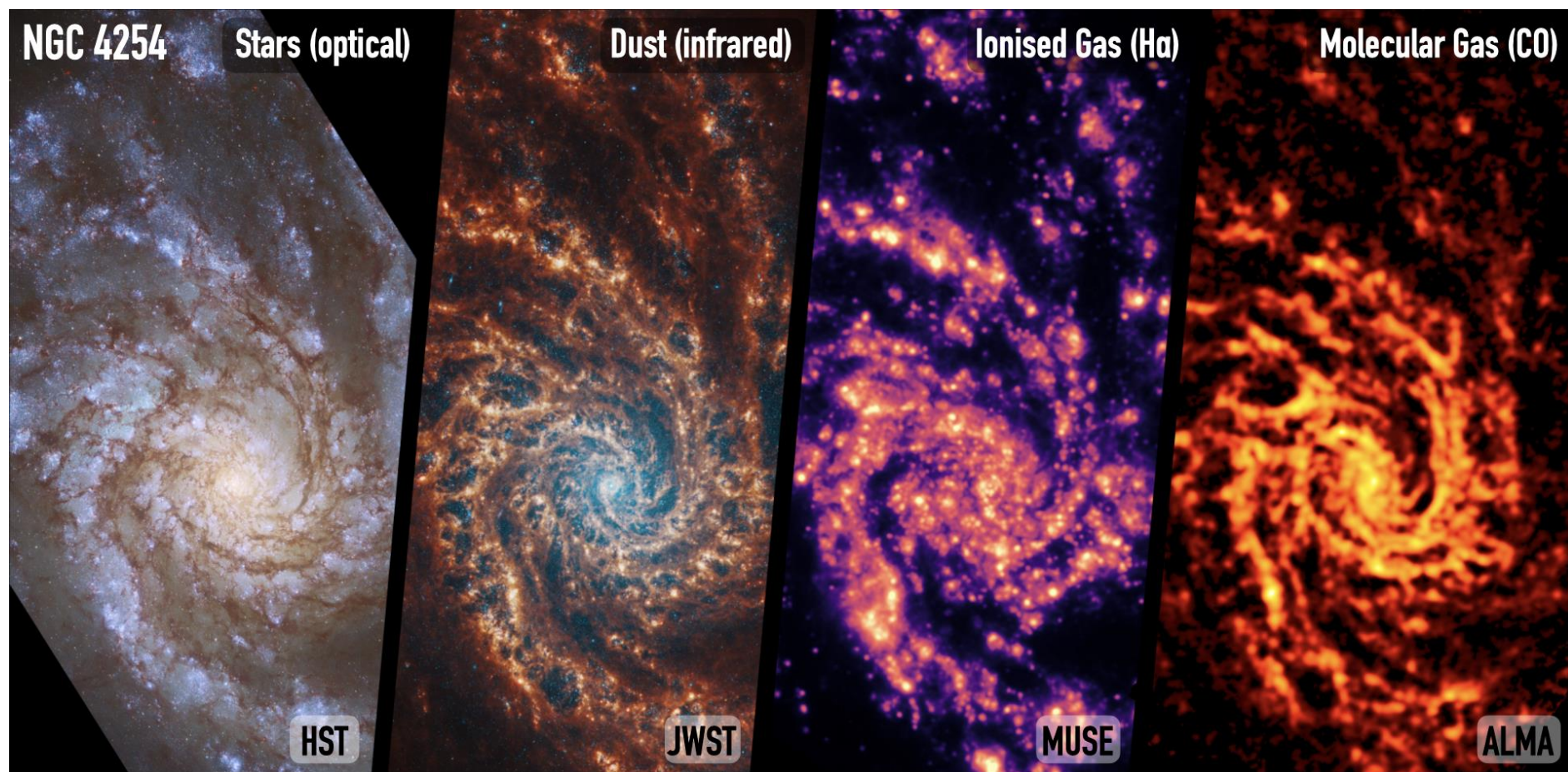


Westerlund 2 (Hubble), NASA

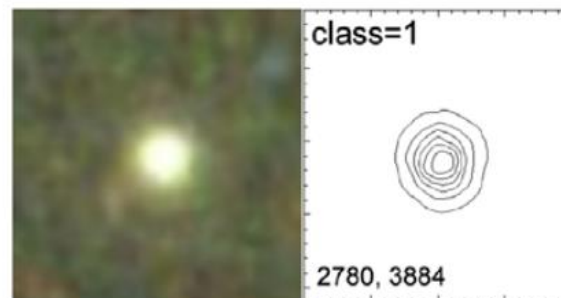
31 August 2026

PHANGS

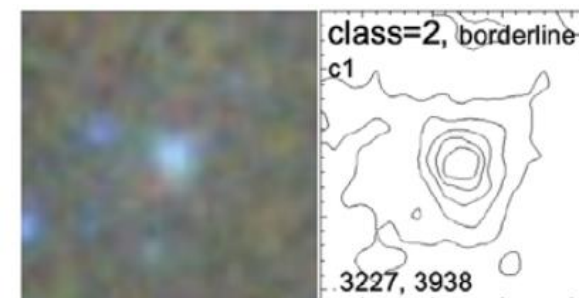
- 38 galaxies observed around a wide range of instruments and wavelength.
- 95,992 stellar clusters and compact associations (classes 1, 2, 3)
- 35,071 stellar clusters (classes 1 and 2)
- Two cycles of observations (cycle 2107 – cycle 3707)



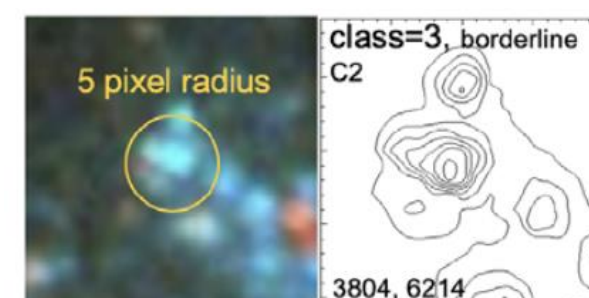
Symmetric 1



Asymmetric 2

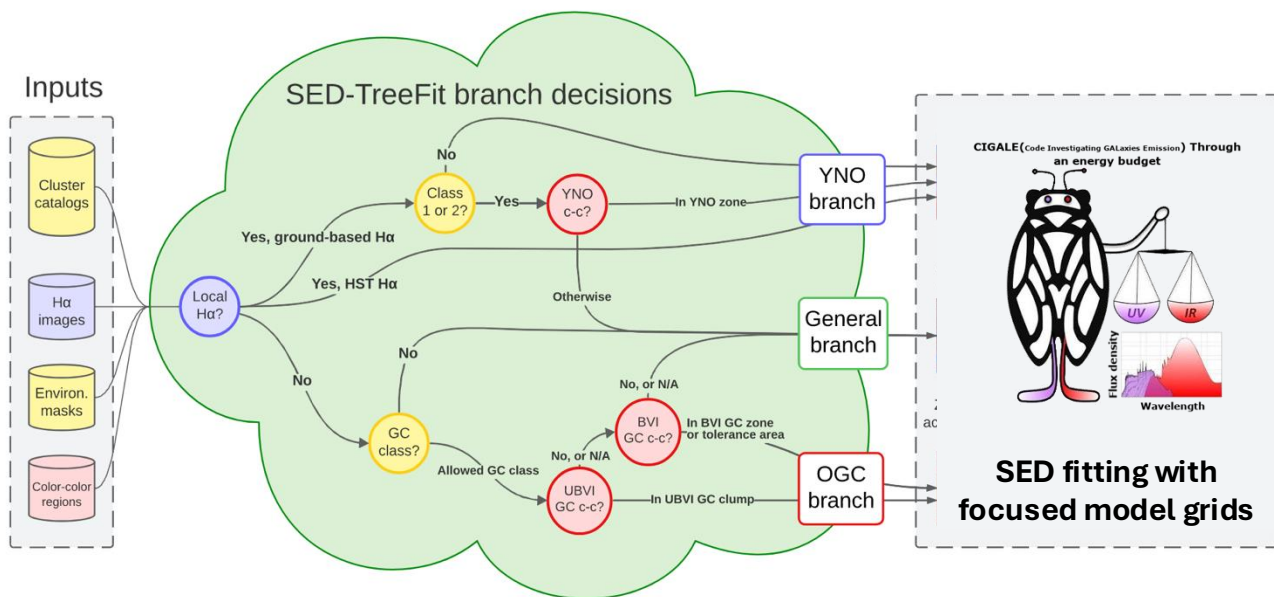


Compact association 3



Cluster in nearby galaxies:

Determination of age

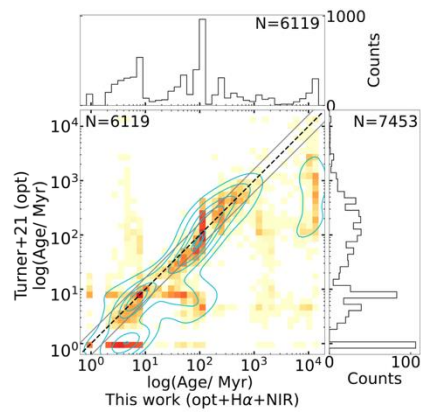


Thilker et al. 2025

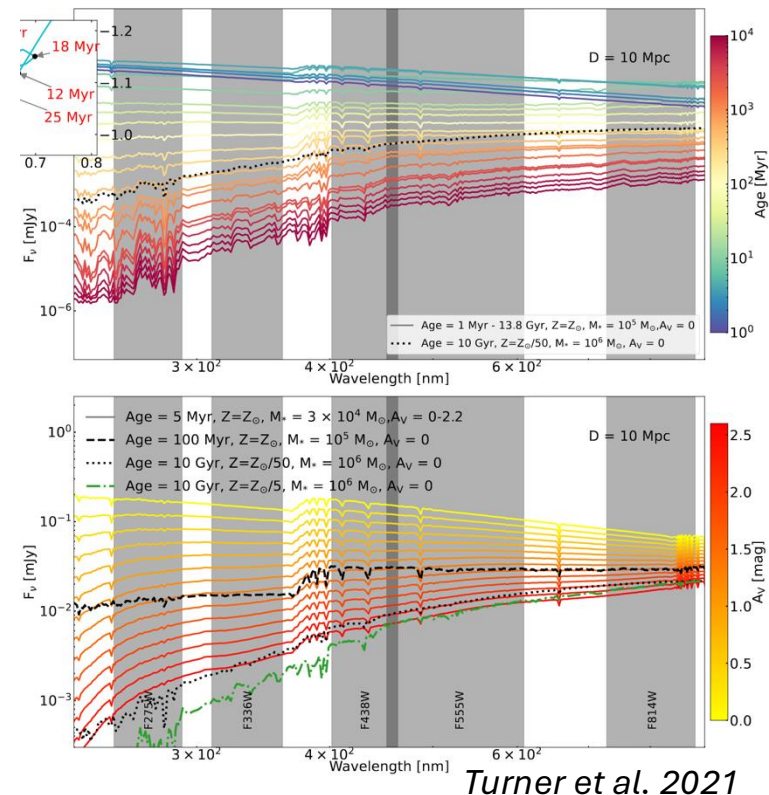
SoTA age determination algorithm

Problems:

- Current age determination is messy with arbitrary choices
- Age problem is multiple degenerate
- No good agreements between methods

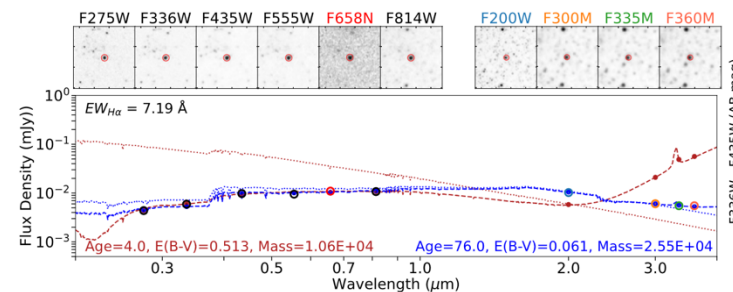


Henny et al. 2025



Turner et al. 2021

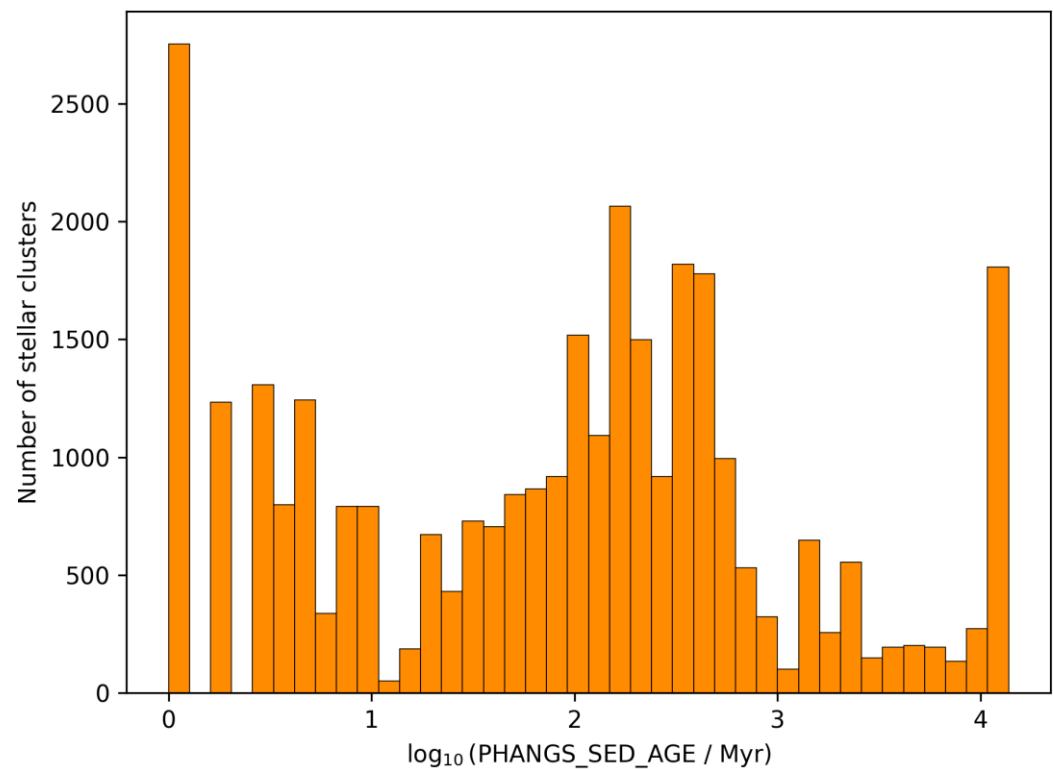
Degeneracies



Henny et al. 2025

Filter dependence

Dataset



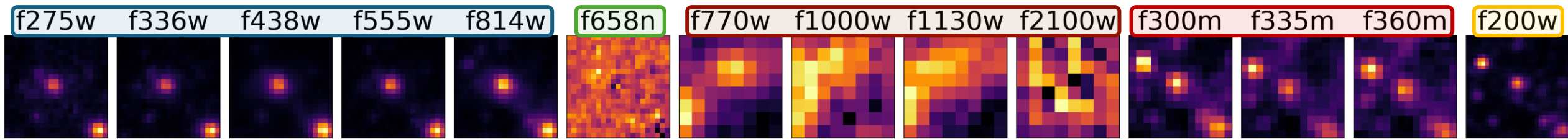
Age distribution

Poor label quality

Instruments	pixel size (arcsec)	Cycle 2107	Cycle 3707
HST	0.04	f275w, f336w, f438w, f555w, f814w	
HST H α	0.04	(F658n), (f657n)	f657w
JWST NIRCам SW	0.031	f200w	(f200w)
JWST NIRCам LW	0.063	f300m, f335m, f360m	f300m, f335m
JWST MIRI	0.11	f770w, f1000w, f1130w, f2100w	f770w, f2100w

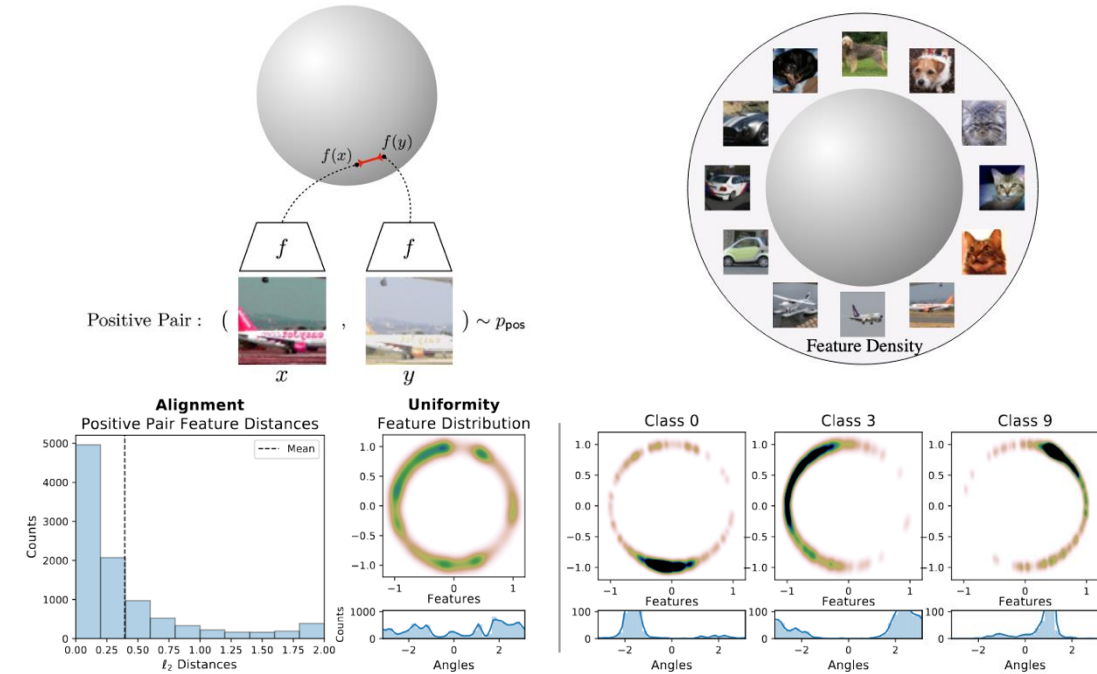
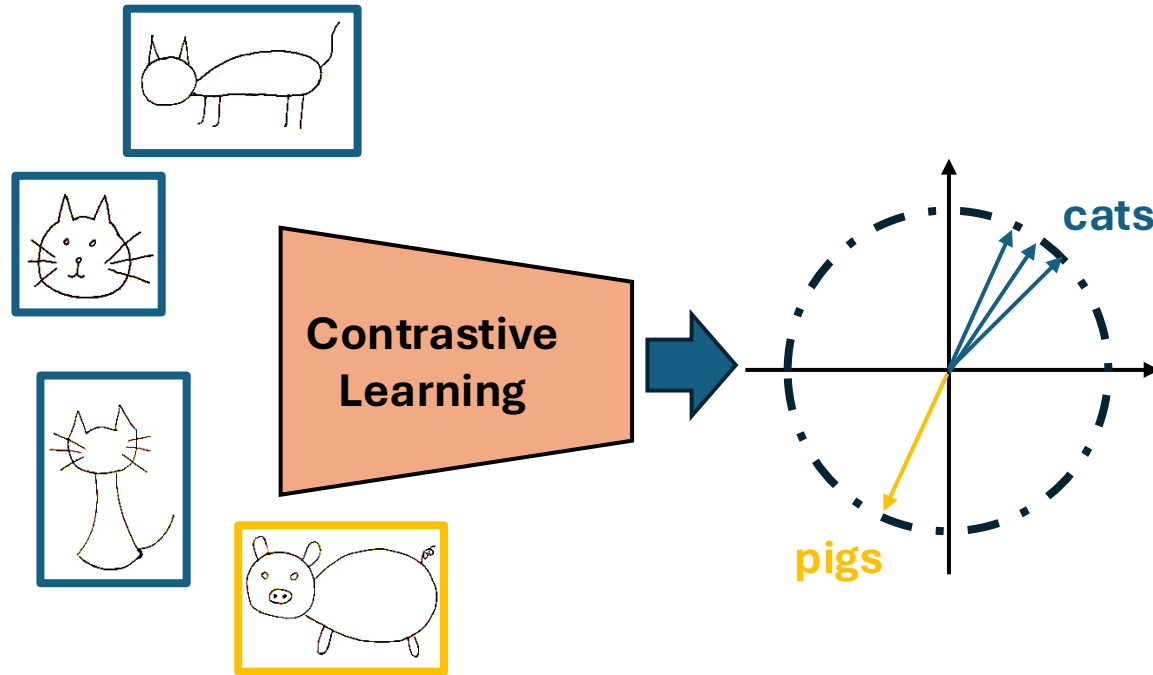
Age distribution

Missing Modality problem

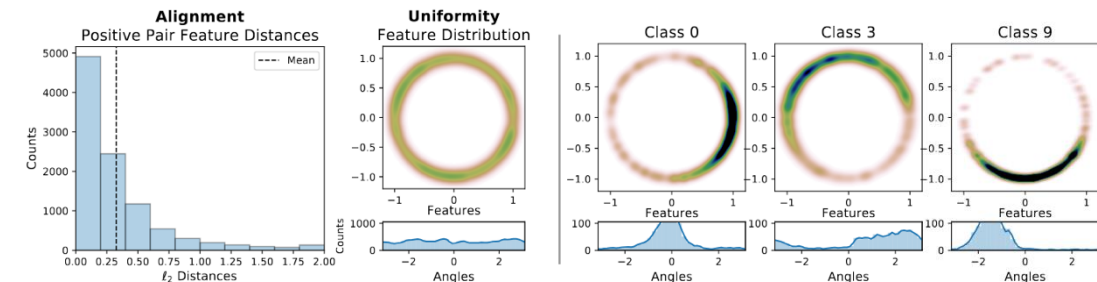


Unsupervised Contrastive Learning (1/2)

In contrastive methods applied to joint embedding architectures, the output embeddings for a sample and its distorted version are brought close to each other, while other samples and their distortions are pushed away.



(b) Supervised Predictive Learning.



(c) Unsupervised Contrastive Learning.

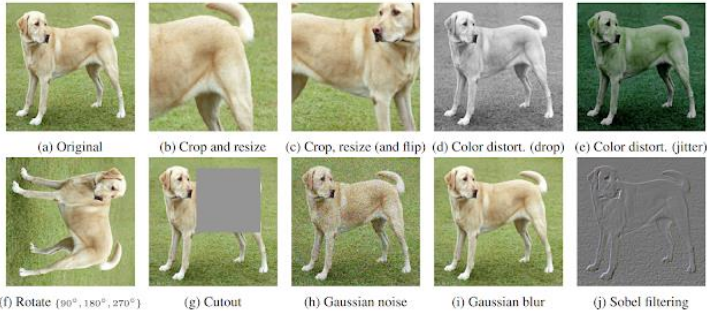
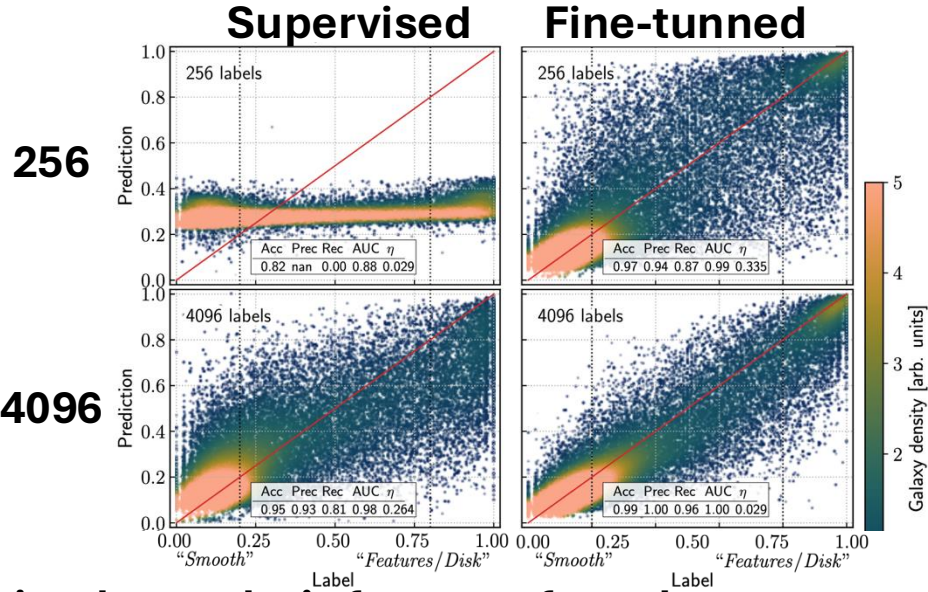
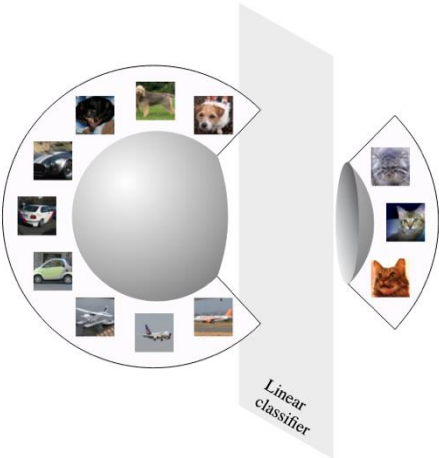
Wang & Isola 2022

Unsupervised Contrastive Learning (2/2)

Multiple algorithm: MoCO, SimCLR, CMC, CLIP...

One loss:
$$\mathcal{L}_{\text{InfoNCE}} = -\mathbb{E}_{x, x^+, x_i^-} \left[\log \frac{\exp(f(x)^T f(x^+) / \tau)}{\exp(f(x_i)^T f(x_i^+) / \tau) + \sum_i \exp(f(x)^T f(x_i^-) / \tau)} \right]$$

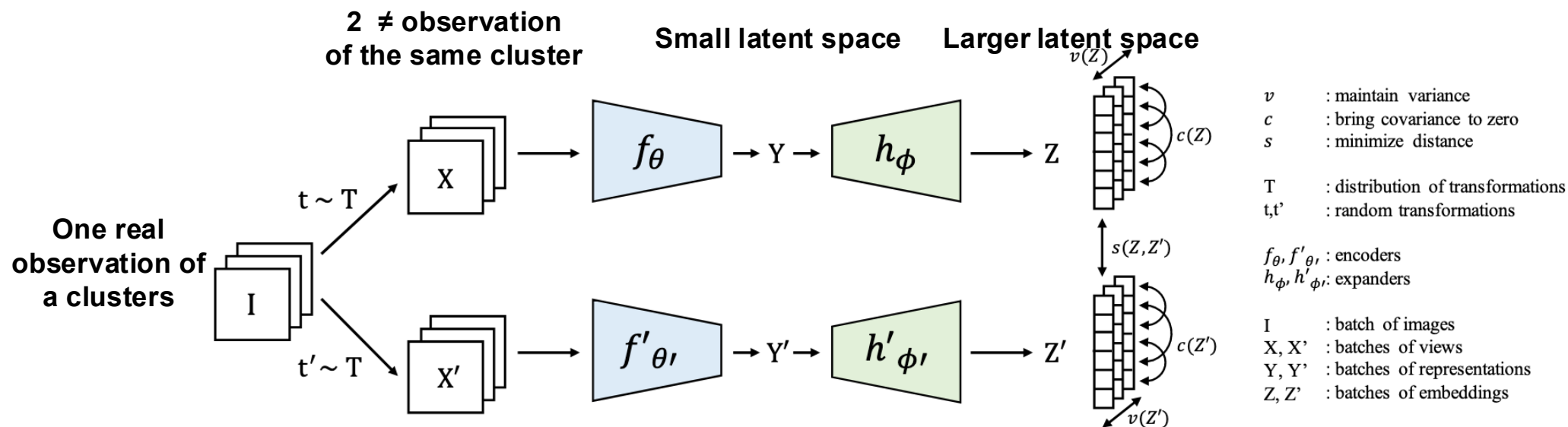
Pros	Cons
- Simple - Clean theoretical grounding - No need for label - allow to marginalize over known nuisance effects.	- Need negative pairs - Need large Batch (<4096) - False negative Pairs - Sensitive to hyperparameters



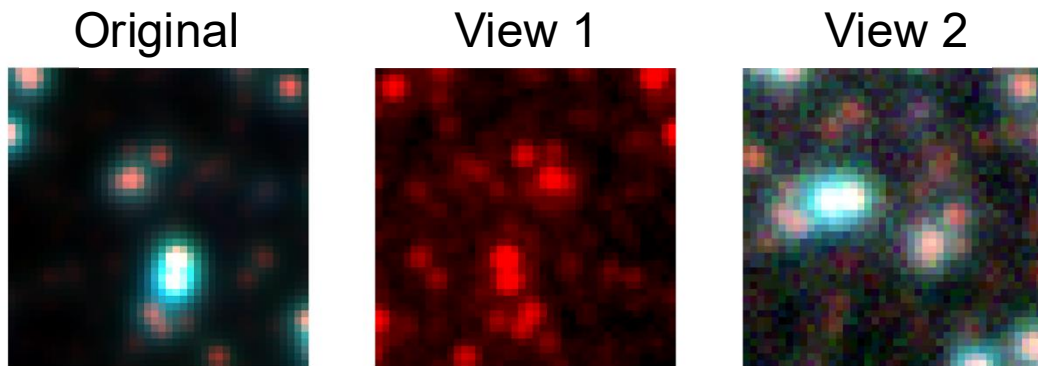
Fine-tuning reuses the pre-trained encoder's features for a downstream task

VICReg

VICReg: Variance-Invariance-Covariance Regularization for Self-Supervised Learning, *Bardes et al. 2022*



$$\mathcal{L}_{\text{total}} = \mathcal{L}_{\text{inv}} + \mathcal{L}_{\text{var}} + \mathcal{L}_{\text{cov}}$$



Advantages:

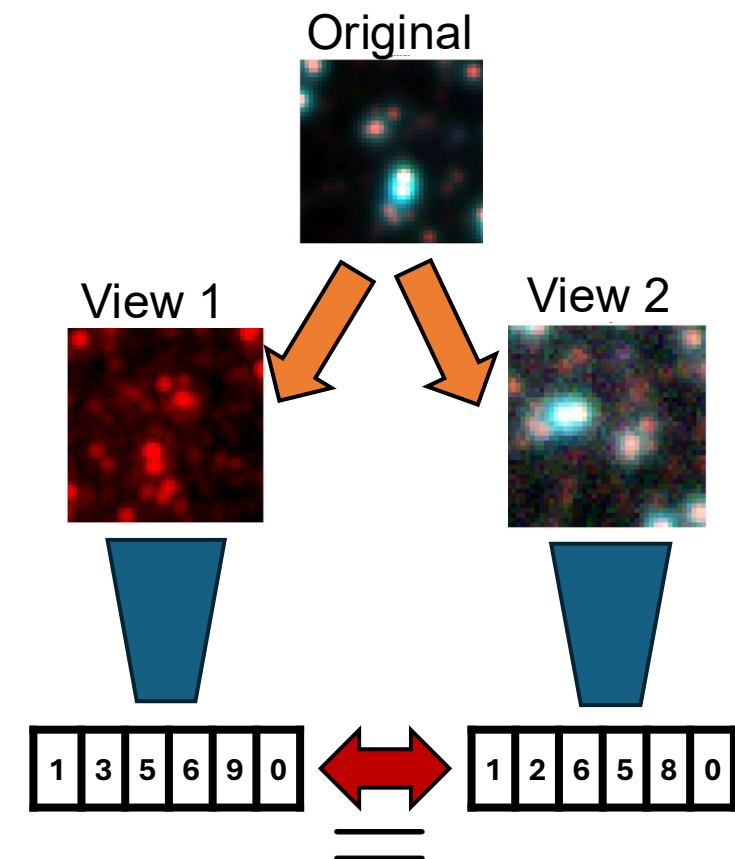
- **No negative Pair**
- Possibility to have different branches and input data
- No memory bank, No large batch needed
- Very stable
- No batch wise or feature normalization

VICReg loss

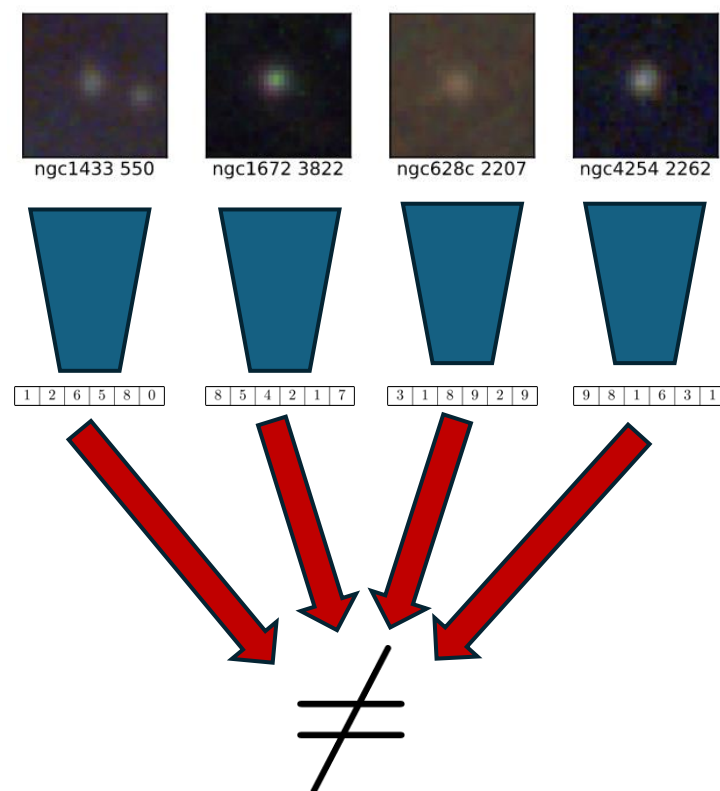
Loss to minimize:

$$\mathcal{L}_{\text{total}} = \mathcal{L}_{\text{inv}} + \mathcal{L}_{\text{var}} + \mathcal{L}_{\text{cov}}$$

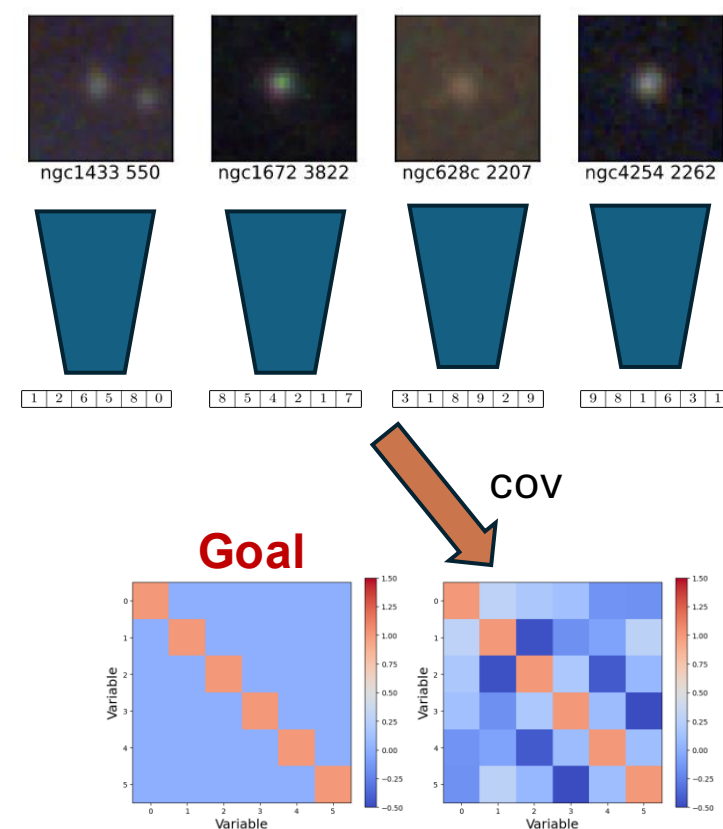
Invariance (-)



Variance (+)



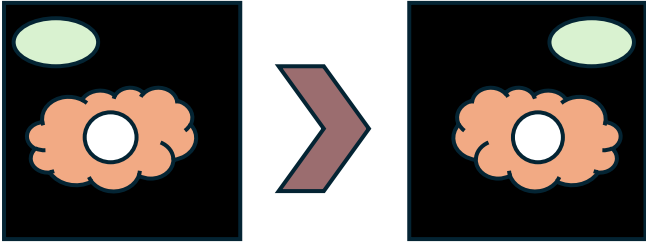
Covariance (-)



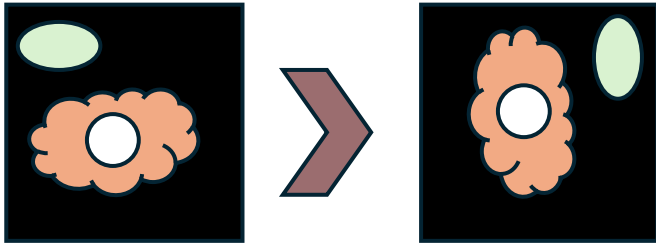
Augmentation

Geometric augmentation

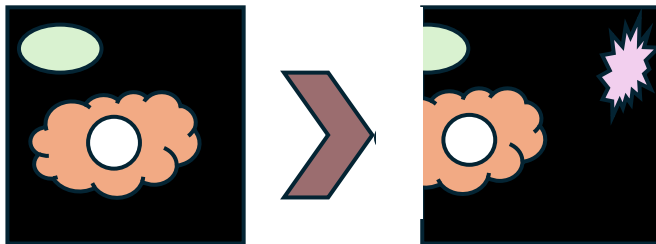
Flip (v/h)



Rotation ($n \times 90^\circ$)

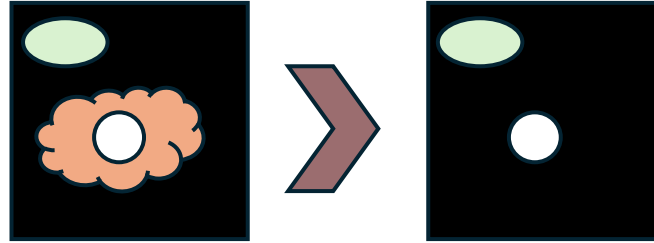


Translation



SED augmentation

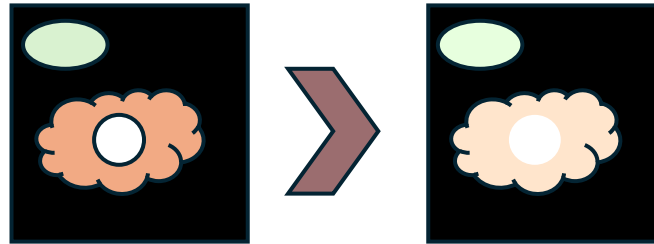
Channel Dropout



Ablation / Patch



Flux scaling

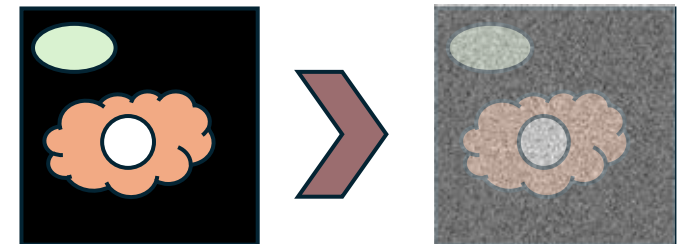


Galaxy augmentation

Poisson Noise



Gaussian Noise

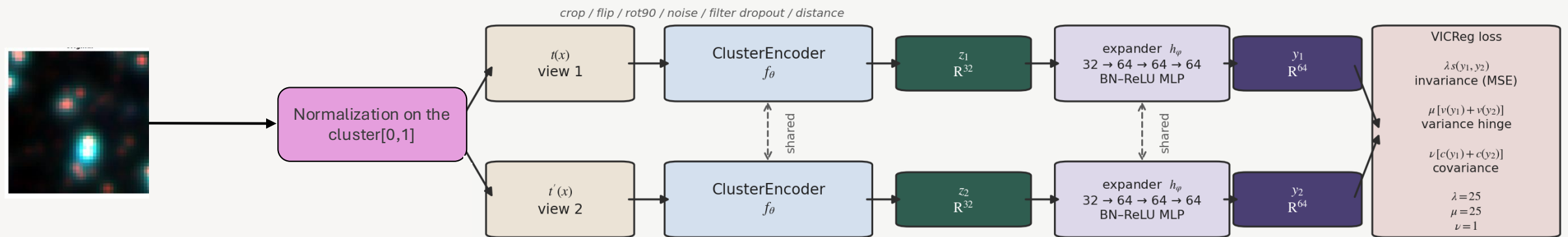
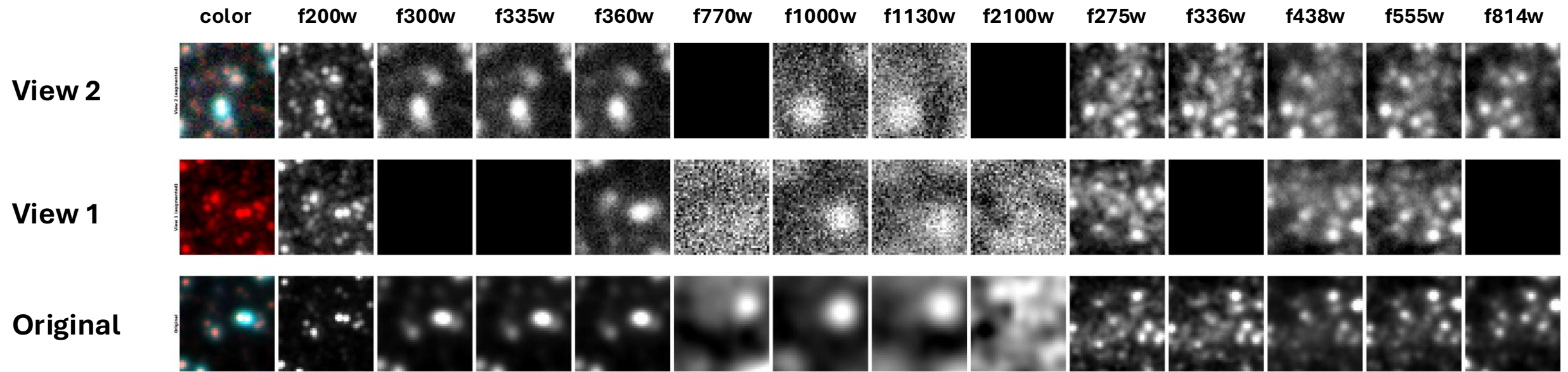


Distance simulation

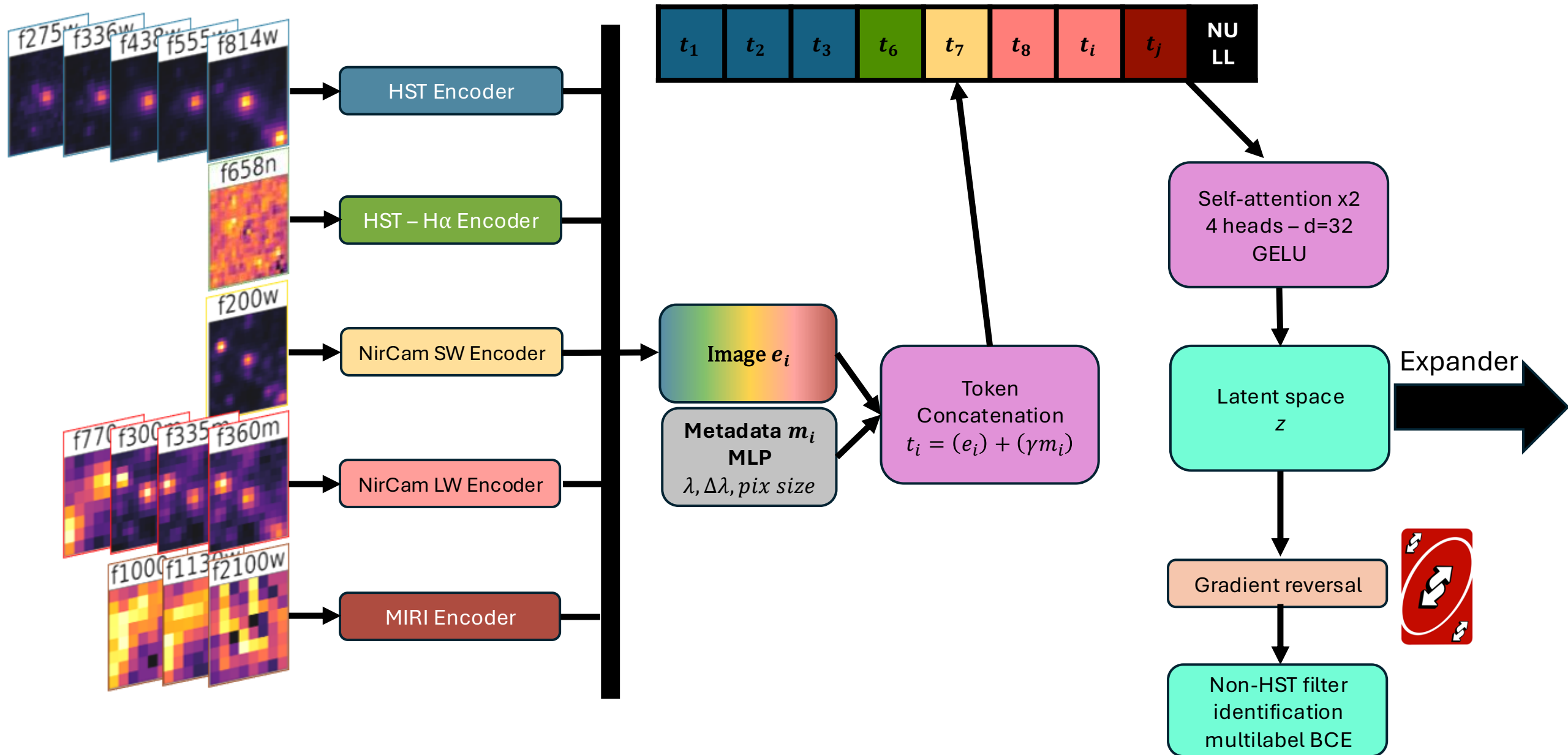


Augmentations create two views of the same object, so the model learns features invariant to nuisance transformations

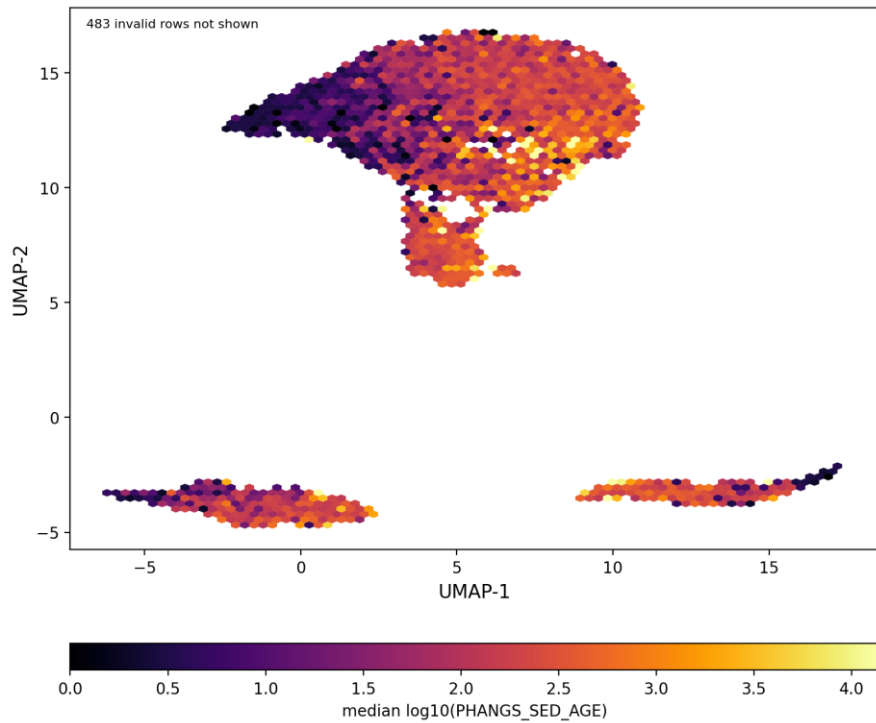
Example of augmentation



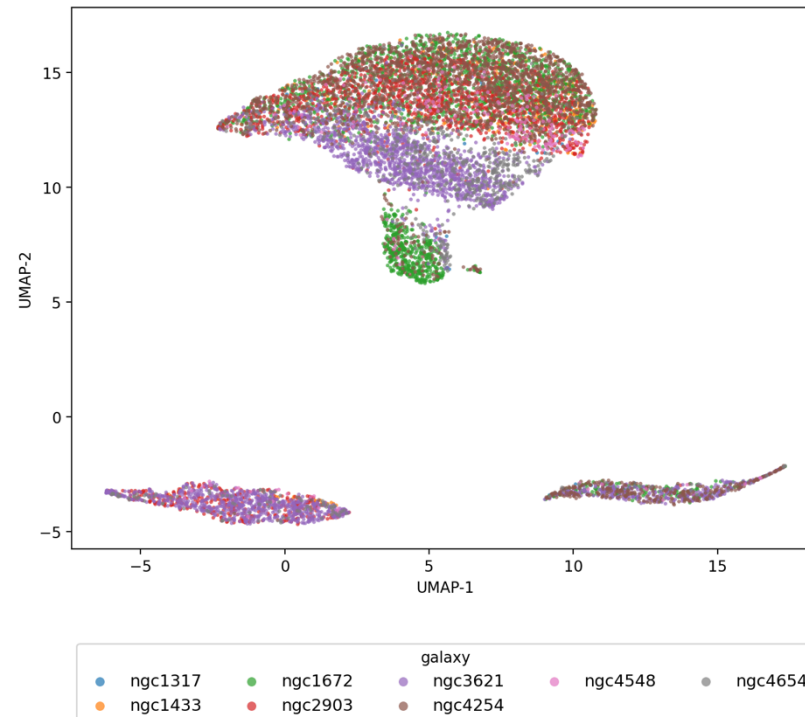
Encoder architecture



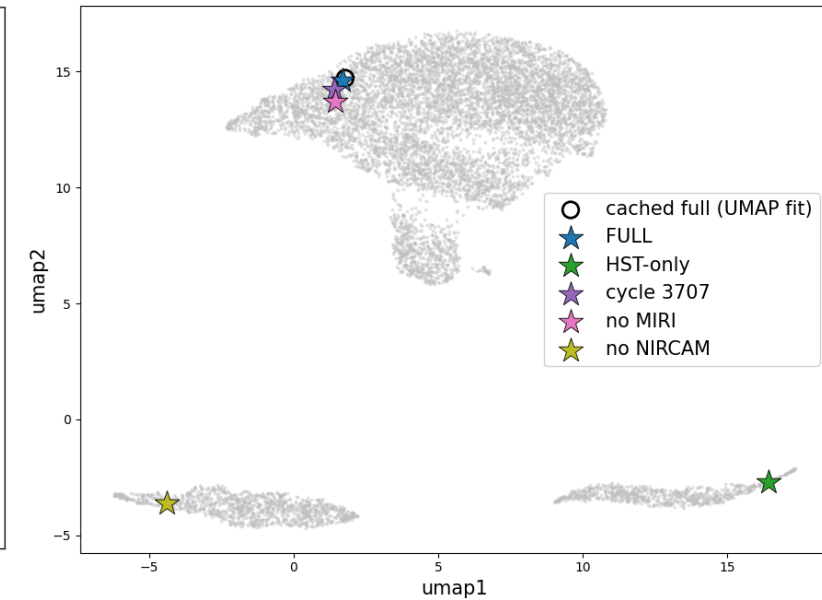
Results – UMAP



Age Structuration



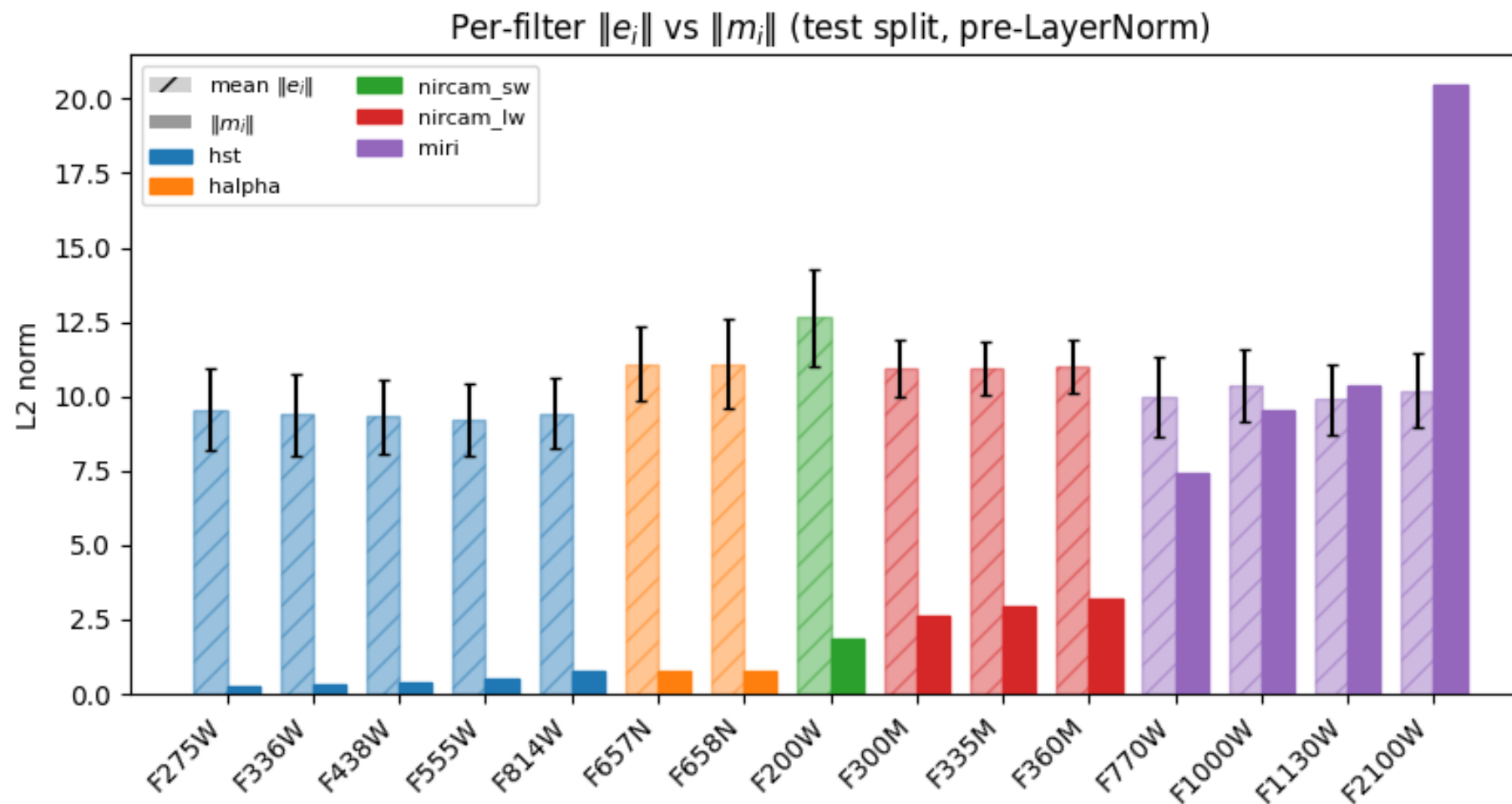
Galaxy Structuration



Ablation filters study

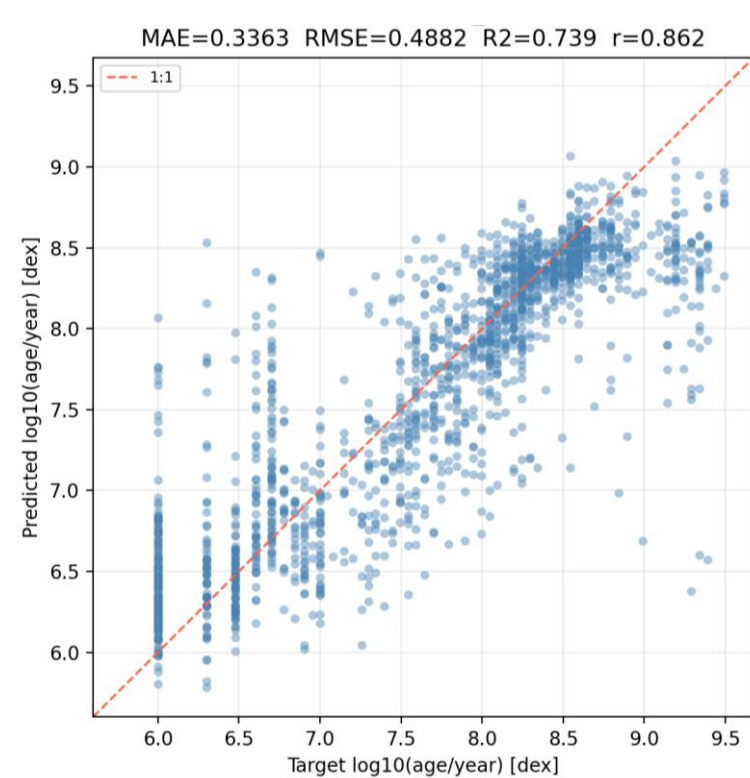
Results – Features importance

Ratio between the norm of the vector that come from the image $\|e_i\|$ and the metadata $\|\gamma m_i\|$

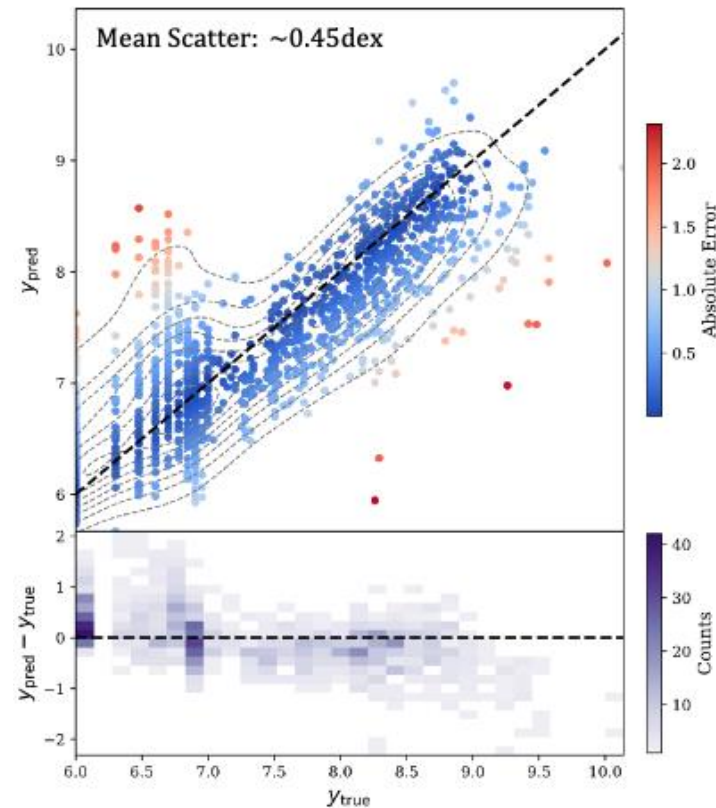


Candebat et al in prep

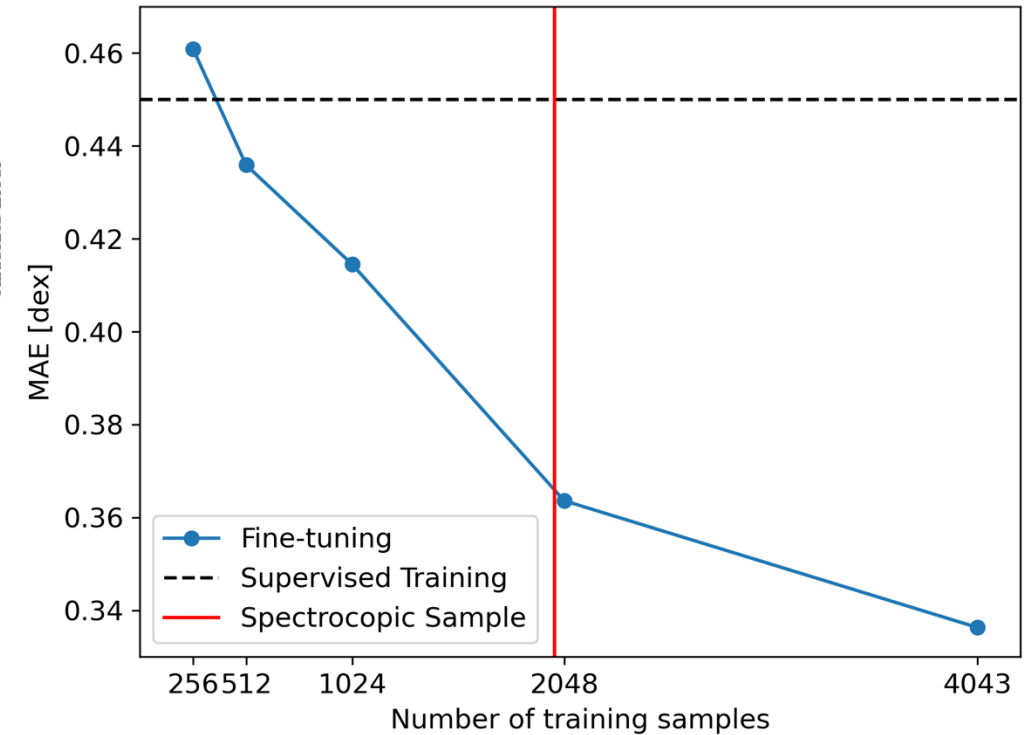
Results – fine-tuning



Fine-tuned Training
4,043 sources



Supervised Training
9,000 of the brightest sources
Viaña et al. 2026

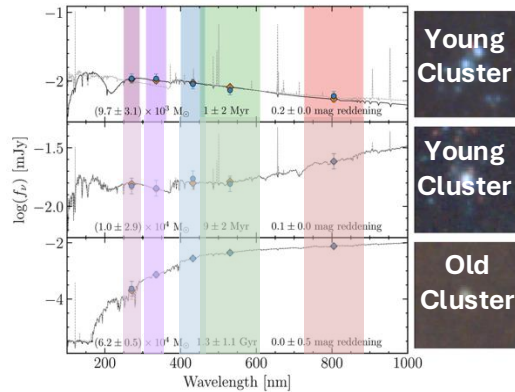


Fine-tuned Evolution

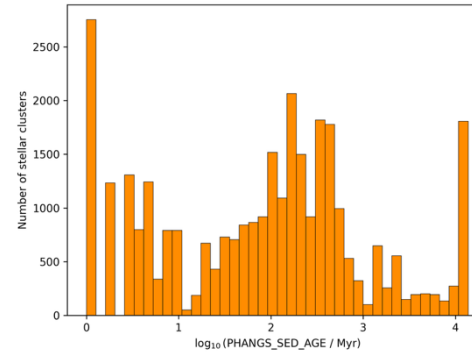
Candebat et al in prep

Conclusion

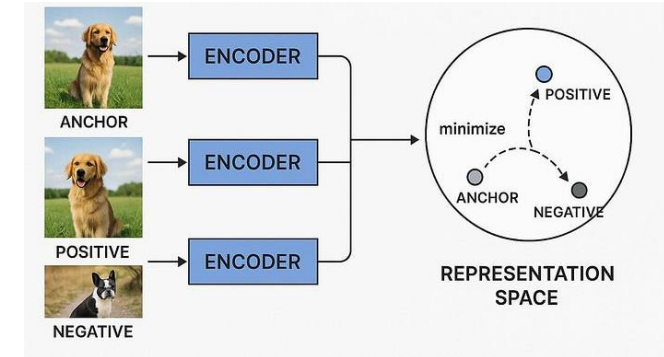
Stellar cluster age is important to understand ISM and galaxy evolution in nearby galaxies.



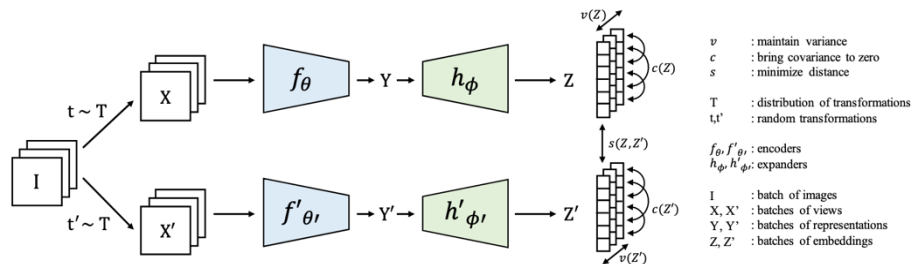
Stellar cluster PHANGS dataset is becoming bigger, but labels are currently unreliable



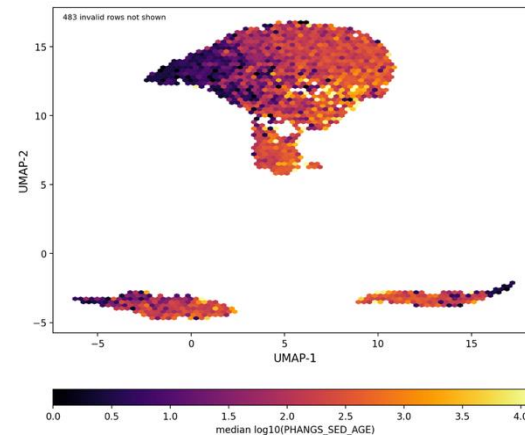
Contrastive Learning overcome the need of labels the dataset



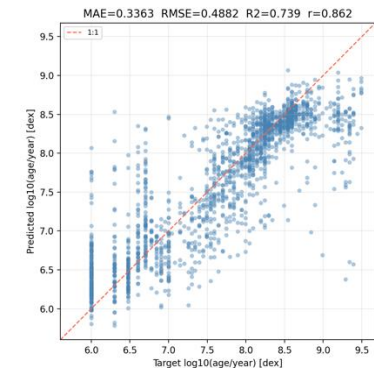
VICReg offers a compelling and simple solution by defining which transformations the network must be robust to.



The network learned what age is



Fine-tuning gives better results on the benchmark, but this must be confirmed

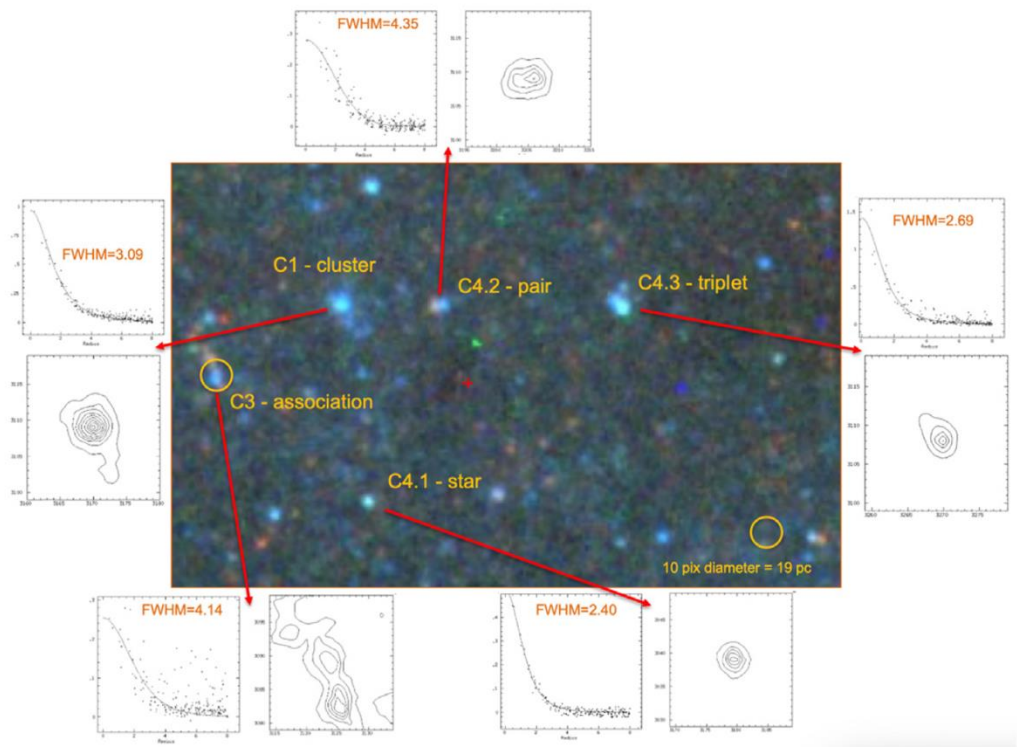




Thanks !!!!

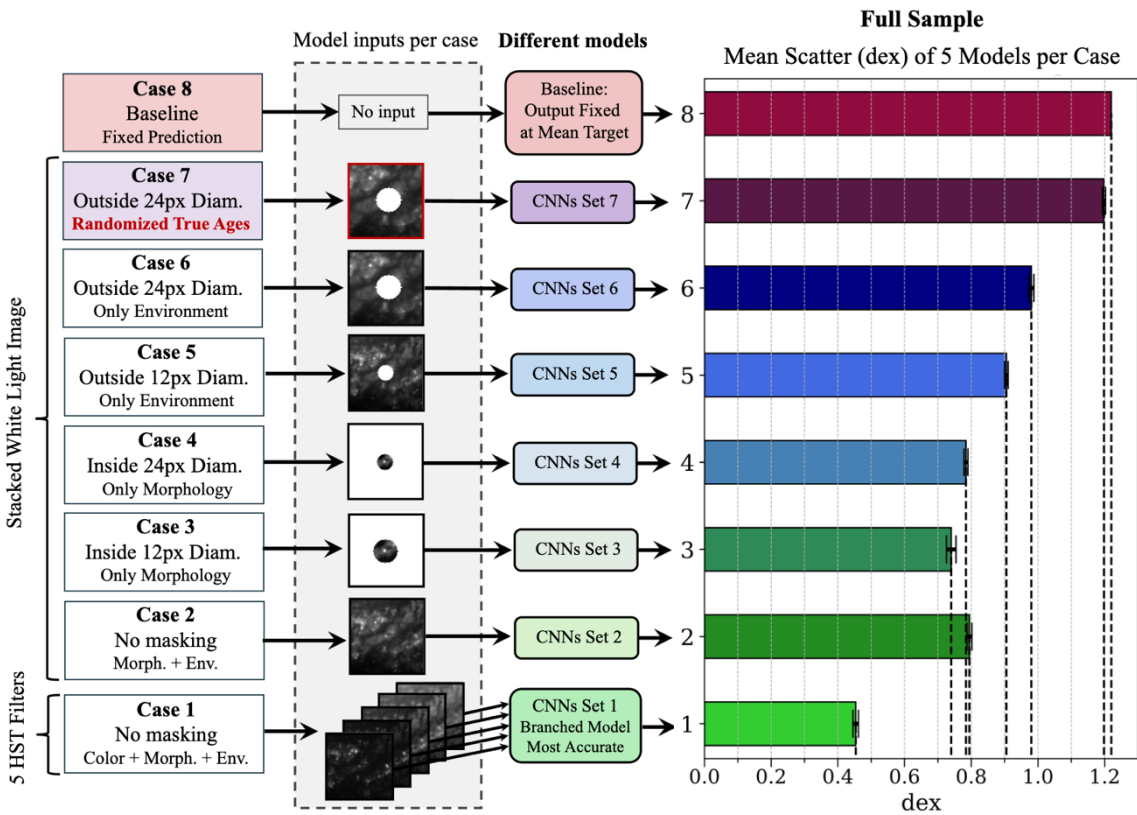


Machine Learning for Stellar Cluster



Whitmore et al. 2021

Detection of Stellar Clusters

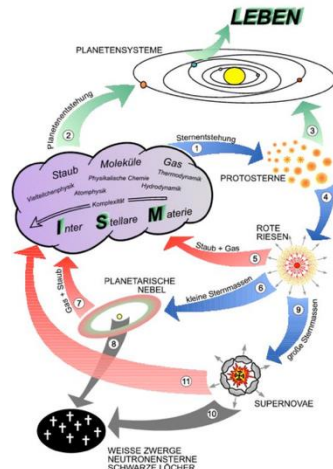
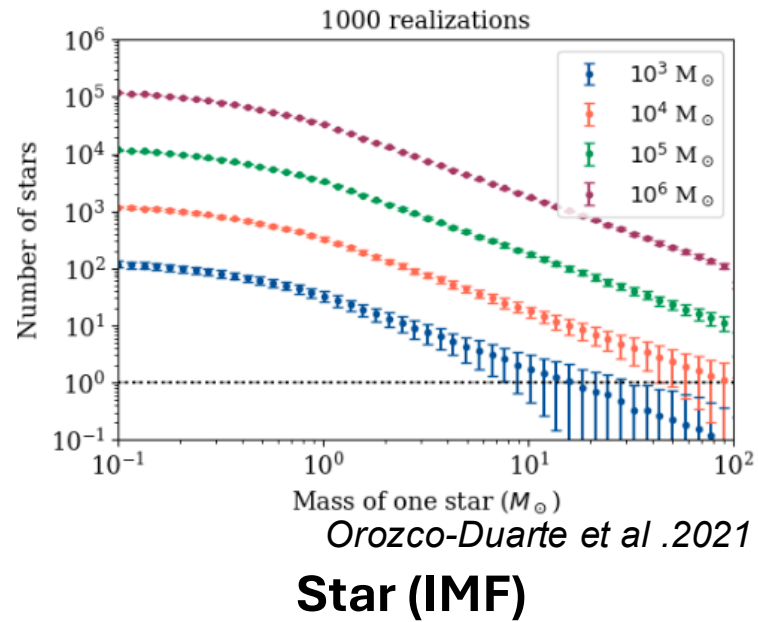


Viaña et al. 2026

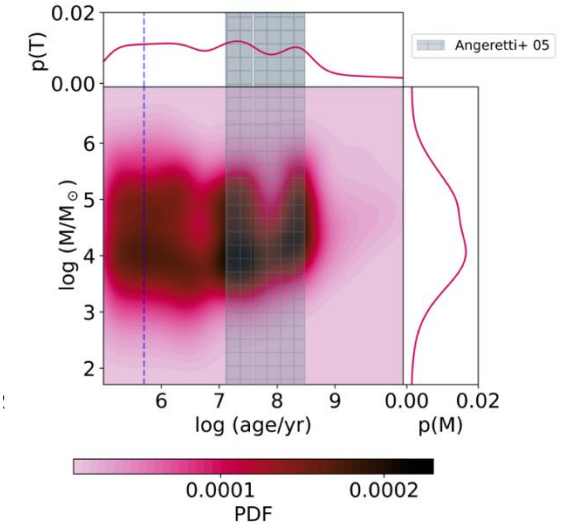
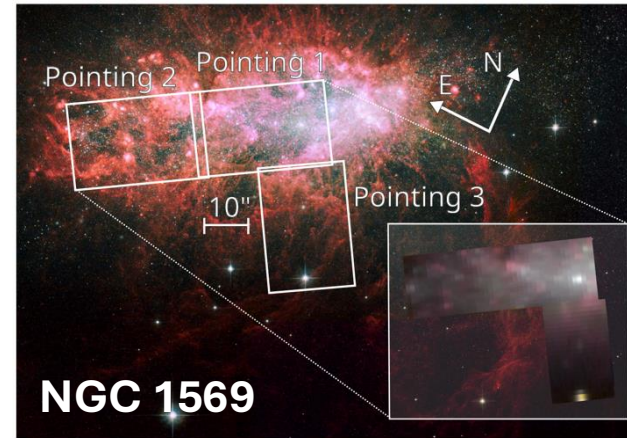
Age estimation (supervised learning)

Why study stellar cluster ?

SFR: Star Formation Rate
GMC : Giant Molecular Cloud
IMF: Initial Mass Function
ISM: Interstellar Medium



Klassen
ISM

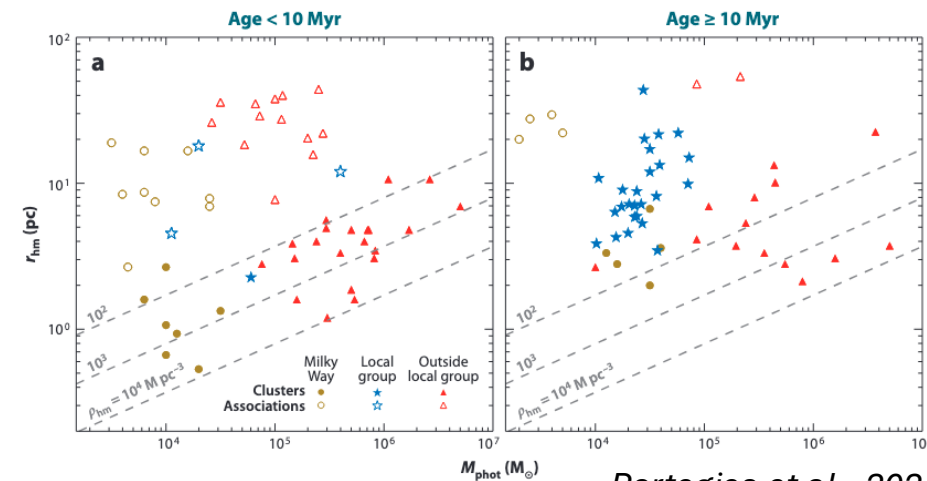
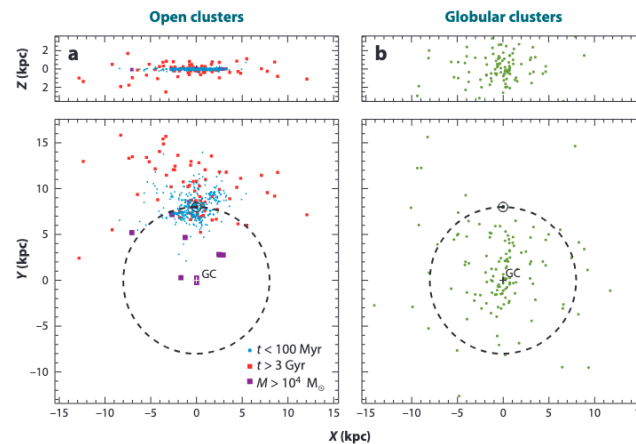


Björvinsson et al. 2026

Galaxies

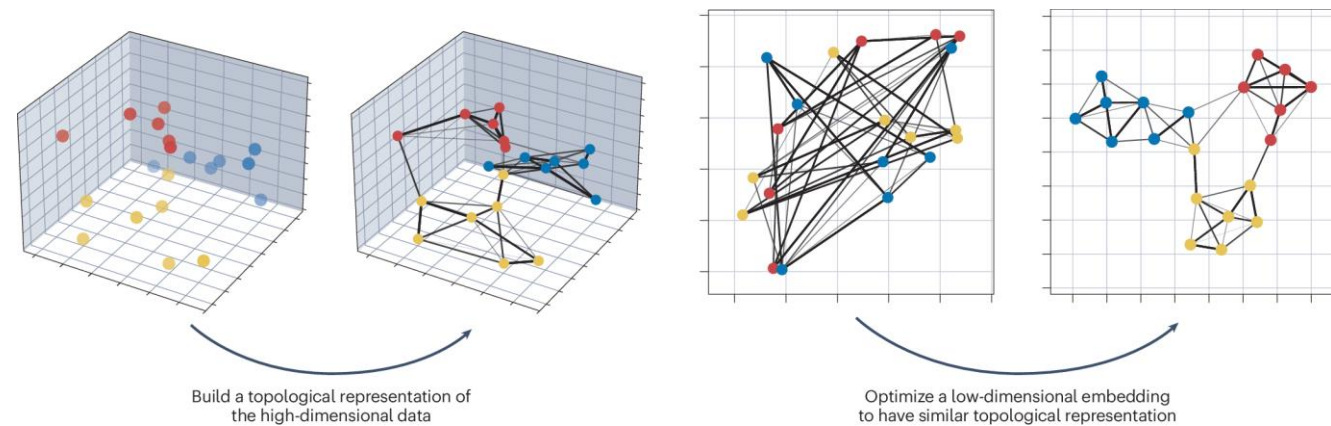
Problem in Milky Way:

- Low number, completeness
- Properties are not independent of galaxies



Portegies et al., 2025

Umaps

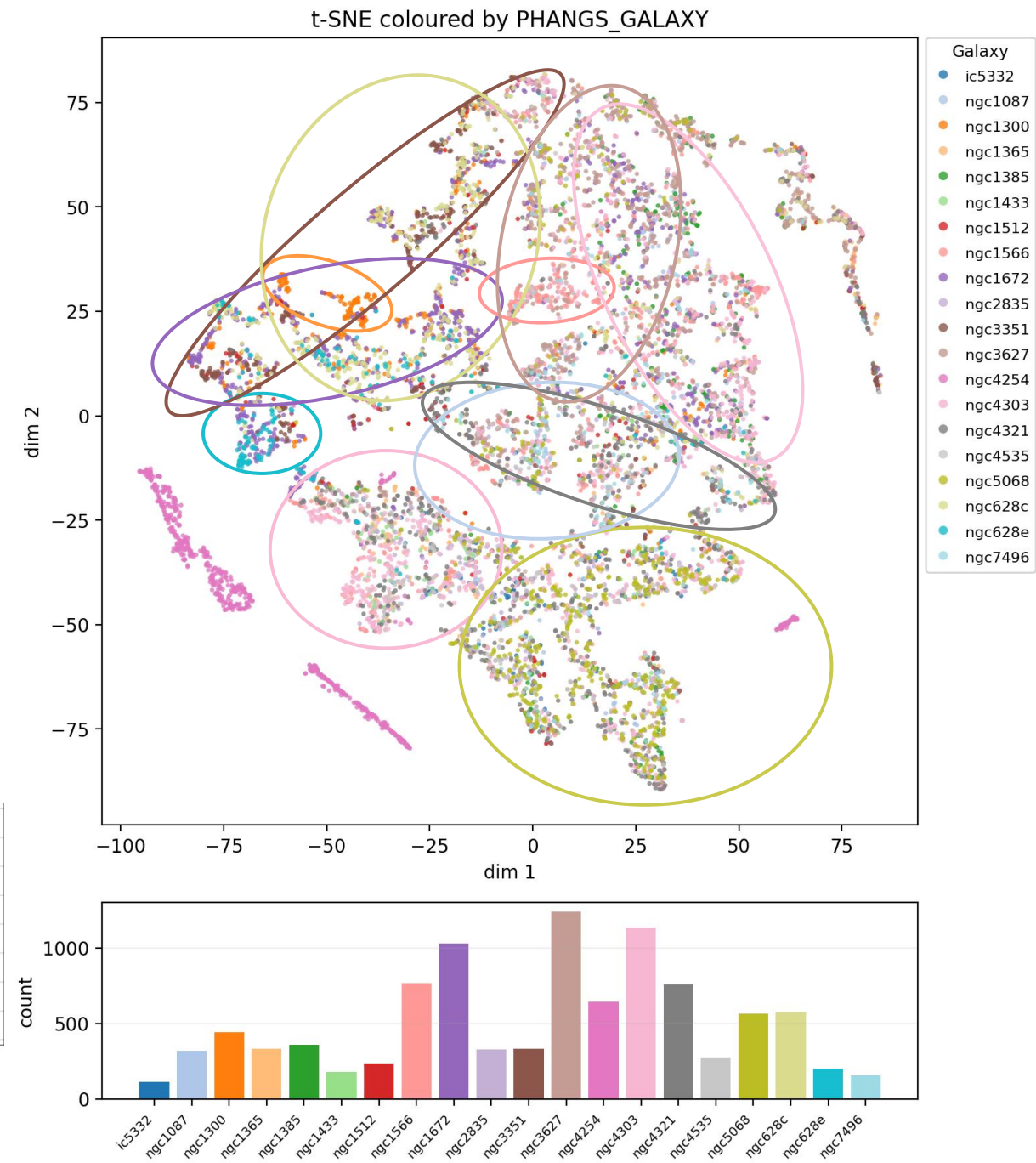


Problematic

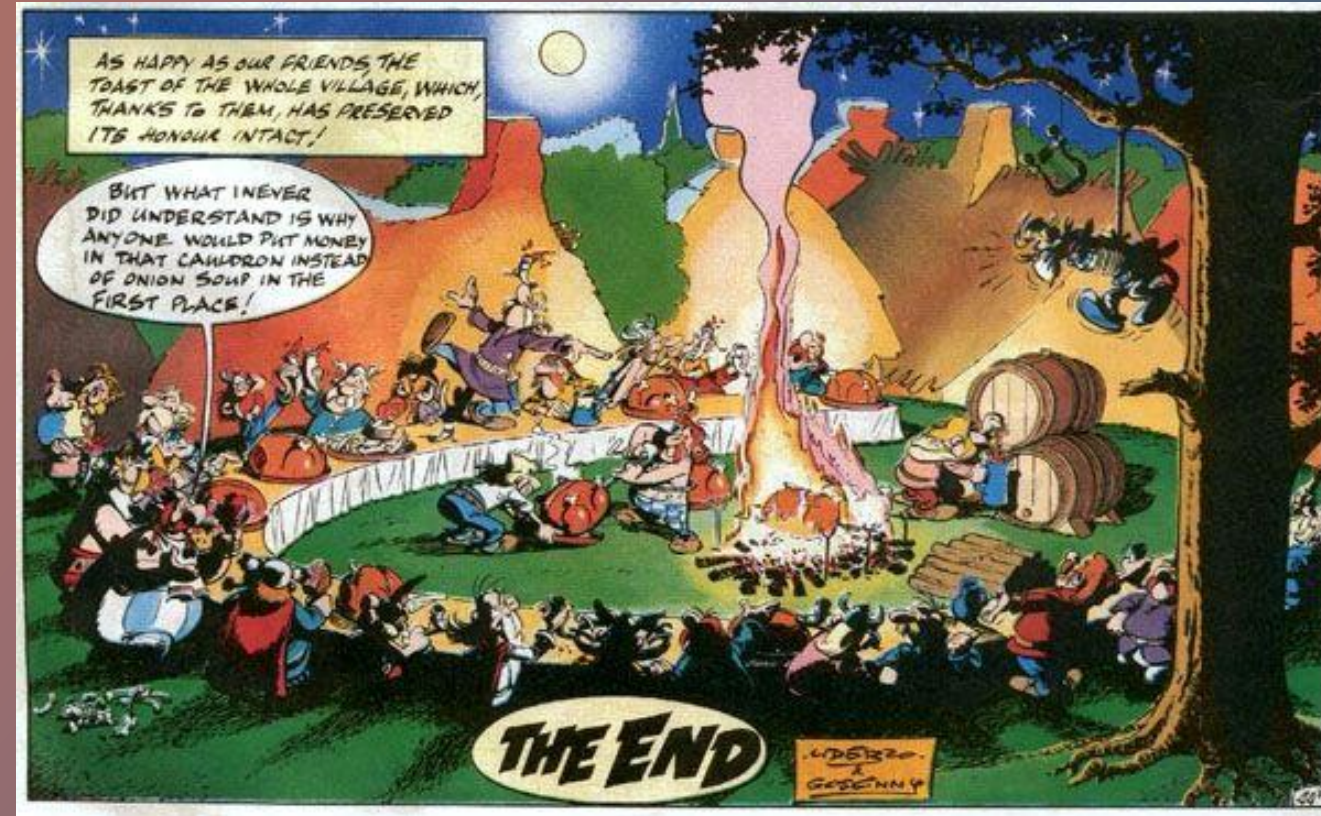
Contrastive Learning

My project

Results

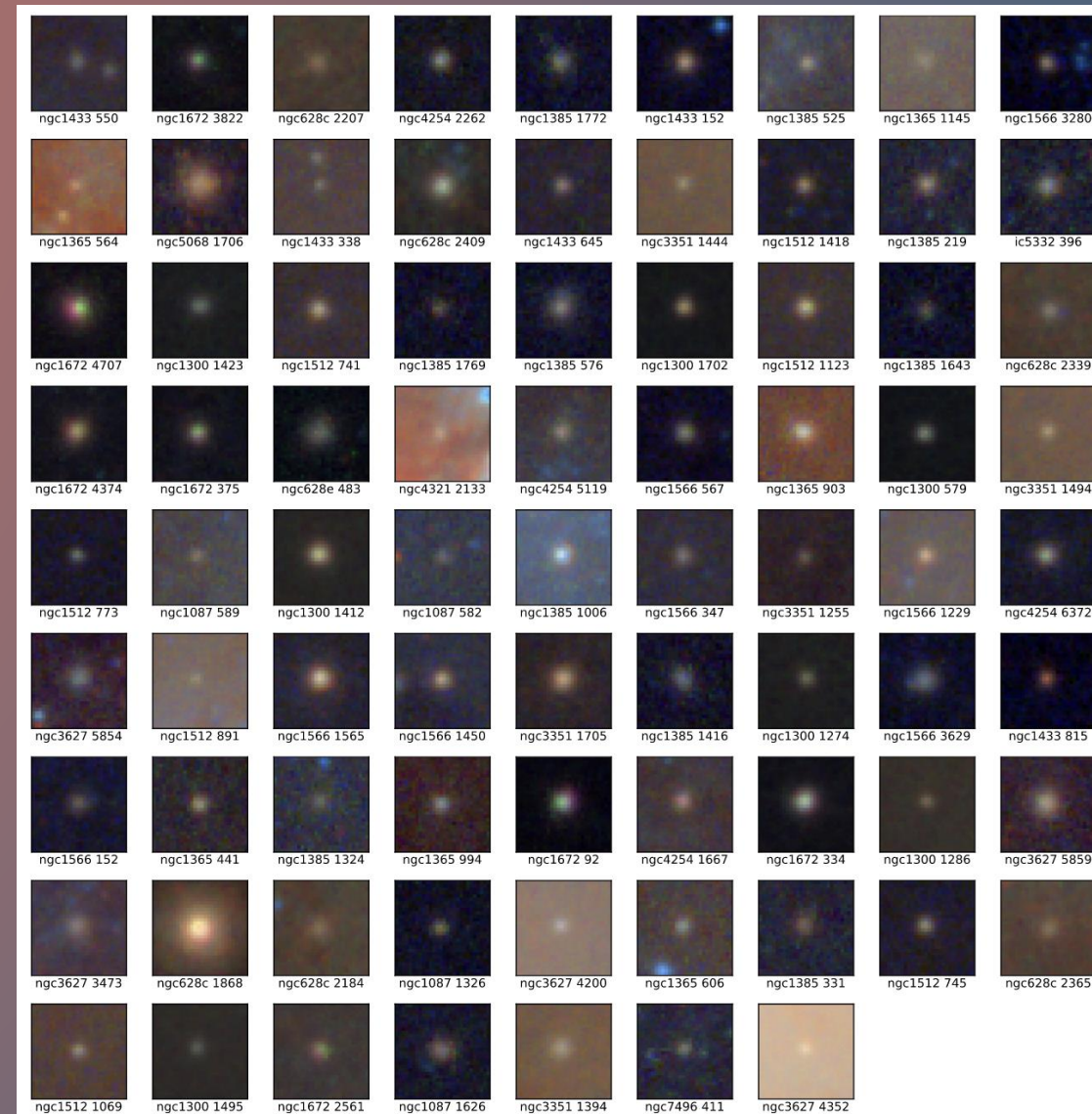


Conclusion



Asterix and Obelix and the cauldron

Project



Introduction

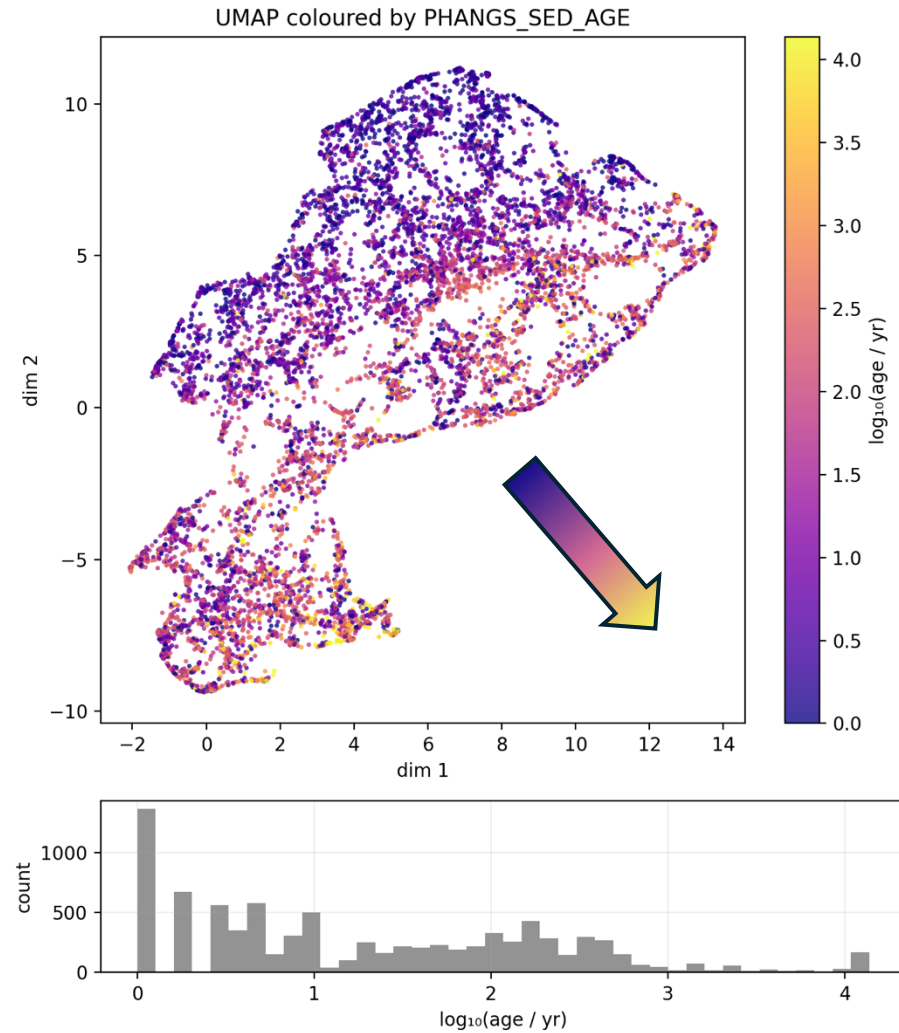
Motivation

Project

Long term goals

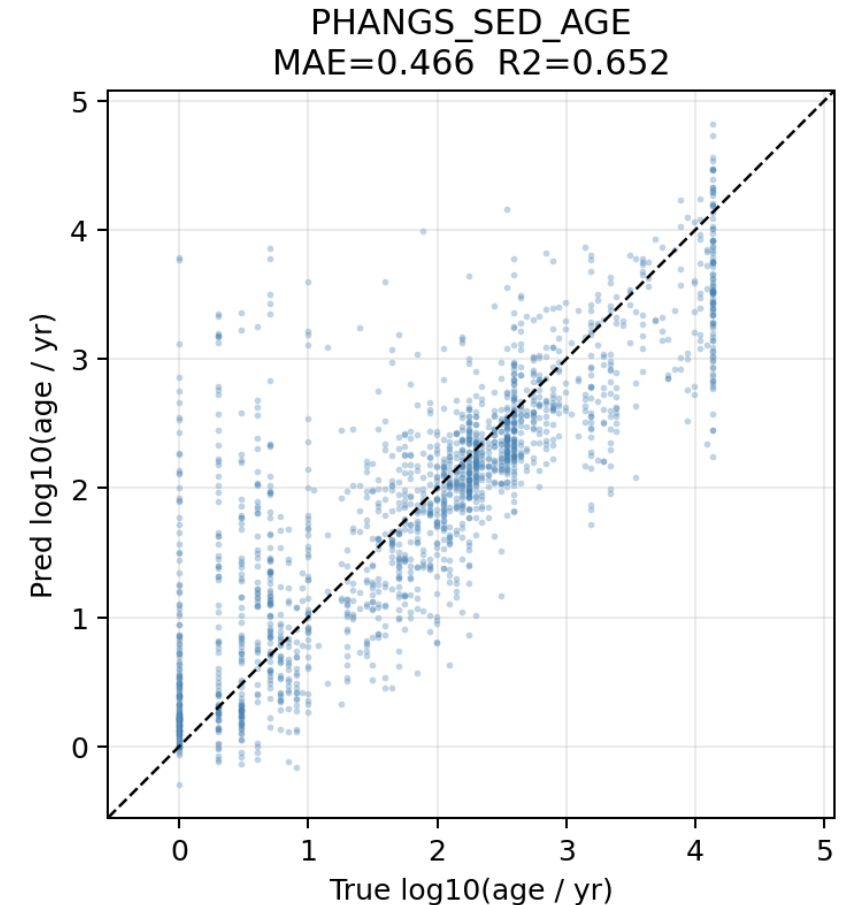
- 1. Study the embedding space**
- 2. Fine-tunes with high quality data**
- 3. Go to more complex parameters / quantities with nearby galaxies (M33 / LMC) as a fine-tuning dataset**
- 4. Make the Neural Network reliable with different combinations of filters (different cycle)**

Results – fine-tuning



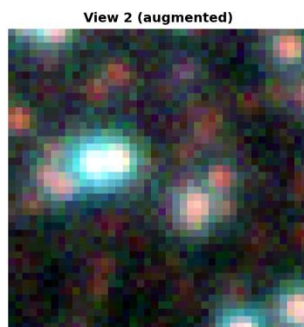
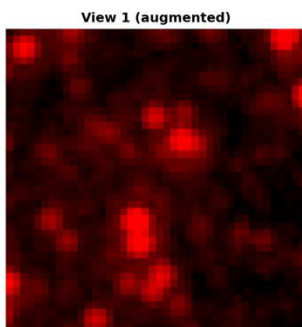
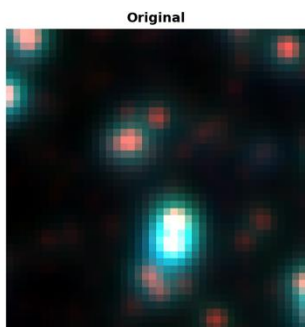
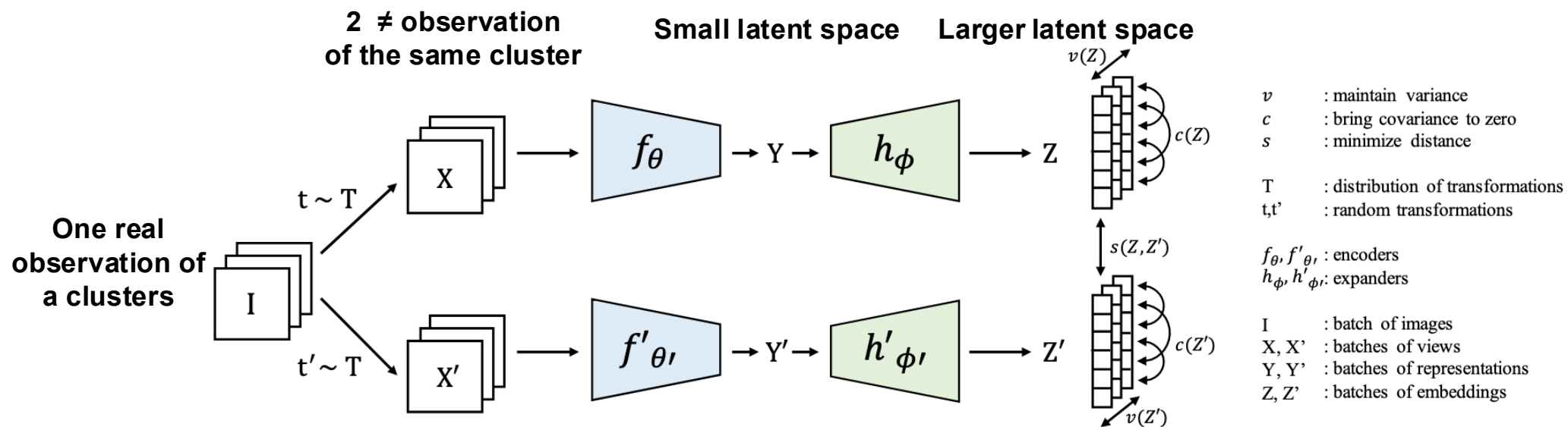
UMAP (Uniform Manifold Approximation and Projection) is a dimensionality reduction technique that preserves both local and global data structure

SimCLR fine-tune: final test predictions



Fine tuning

Neural Network



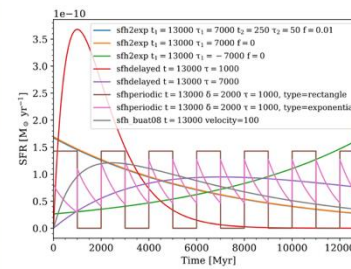
- **Invariance:** the mean square distance between the embedding vectors.
- **Variance:** a hinge loss to maintain the standard deviation (over a batch) of each variable of the embedding above a given threshold. This term forces the embedding vectors of samples within a batch to be different.
- **Covariance:** a term that attracts the covariances (over a batch) between every pair of (centered) embedding variables towards zero. This term decorrelates the variables of each embedding and prevents an *informational collapse* in which the variables would vary together or be highly correlated.

SED fitting

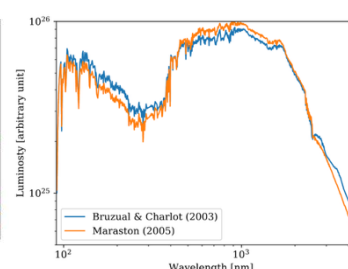
SFH: Star Formation History
SSP: Single Stellar Population
Z = Metallicity
IMF: Initial Mass Function
E(B-V) : reddening

1 - Create a model:

1. SFH



2. SSP (Z + IMF)

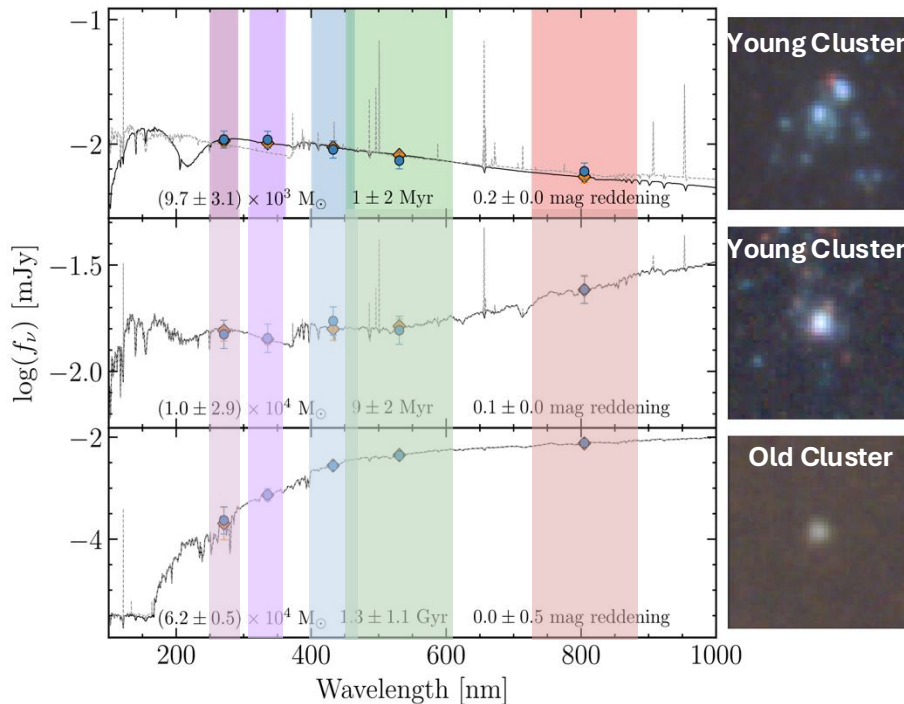


3. Interactions:

- Dust contribution
- Nebular emission
- Attenuation

Parameters:

- Age
- Mass
- E(B-V)

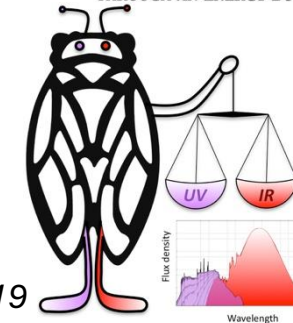


Turner et al. 2021

2 - Fit the model to the data:

These models can be used to evaluate physical properties based on the likelihood.

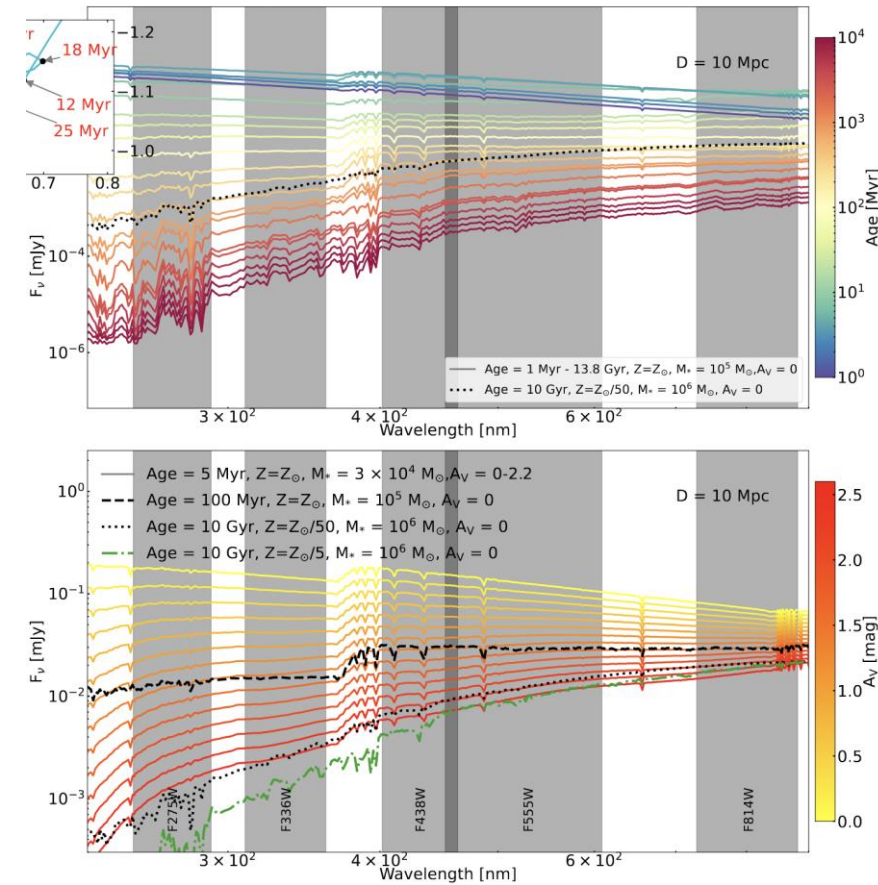
CIGALE (CODE INVESTIGATING THE GALAXIES EMISSION)
THROUGH AN ENERGY BUDGET



Boquien et al. 2019

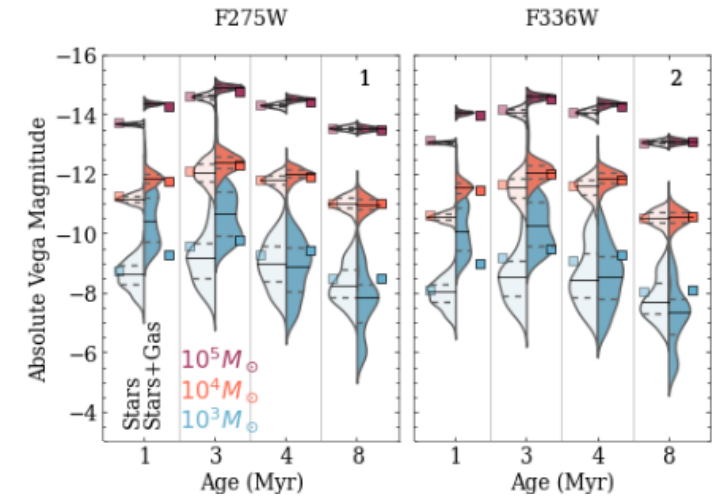
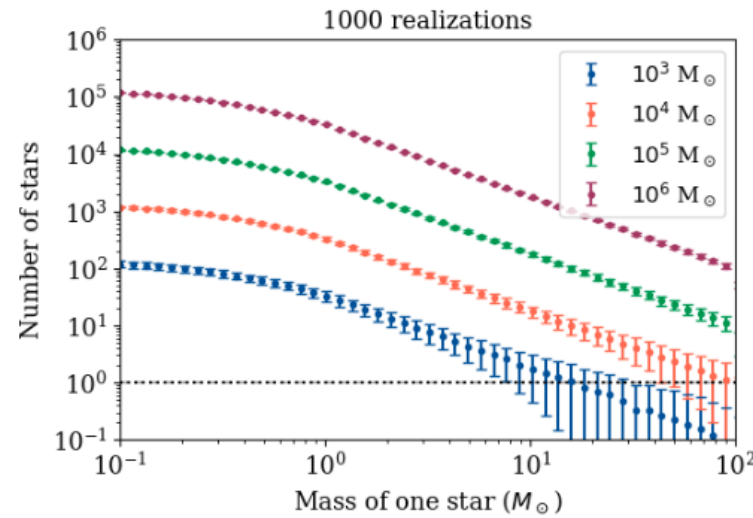
Problems

Degeneracies

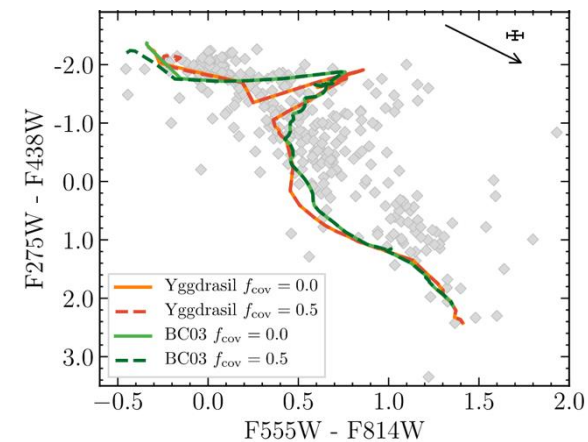


Thilker et al. 2025

Model assumptions (IMF, component contribution, model, ...)



Orozco-Duarte et al .2021



Turner et al .2021