

# PyXim – A fast, GPU accelerated, differentiable HxRG simulation framework

Leander Lacroix

llacroix@ip2i.in2p3.fr

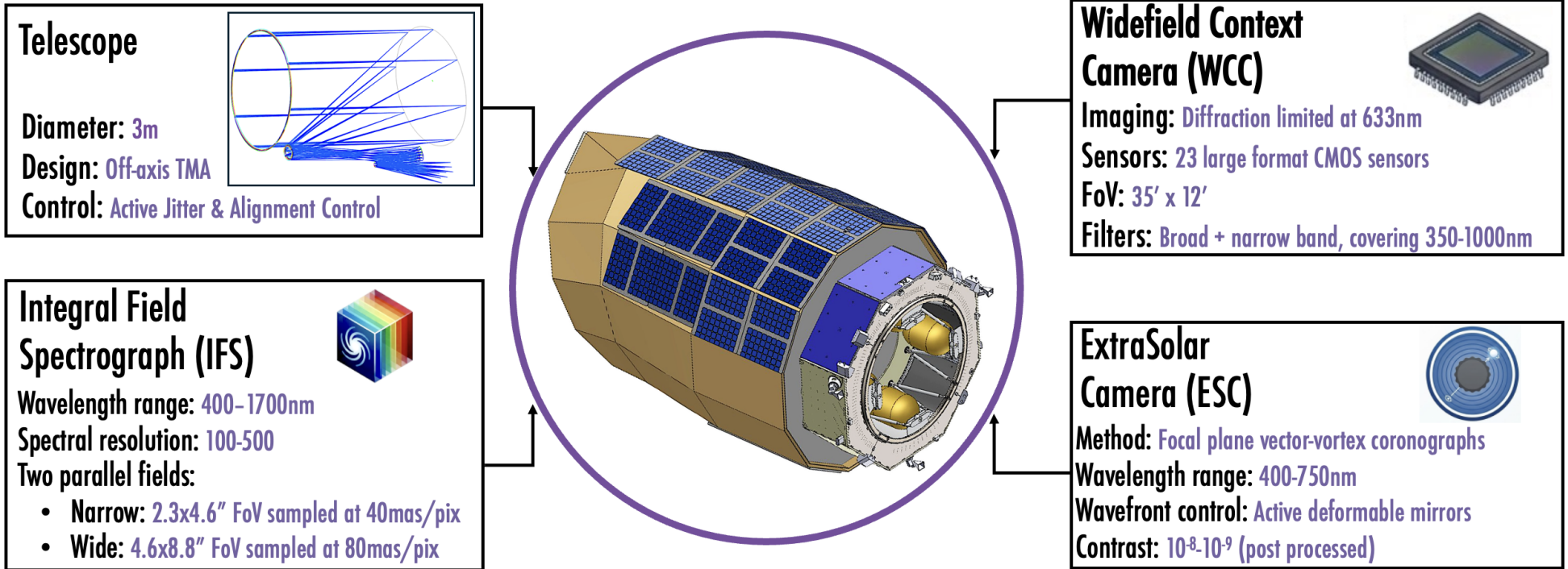
Institut de Physique des 2 Infinis, Lyon, France

IRIS workshop 2026 @ INAF OAS Bologna, Italy



# Context

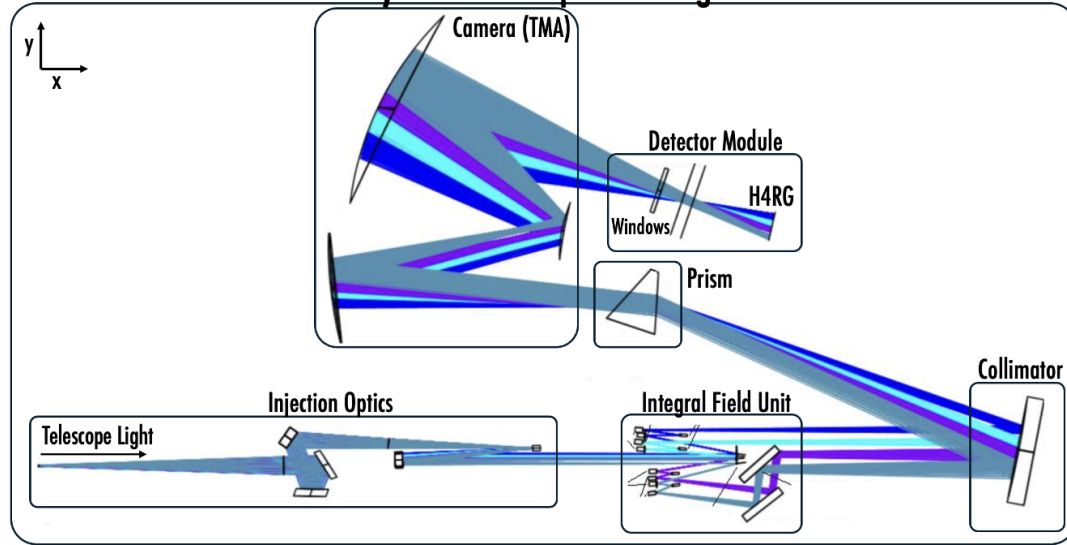
## The Lazuli Space Observatory



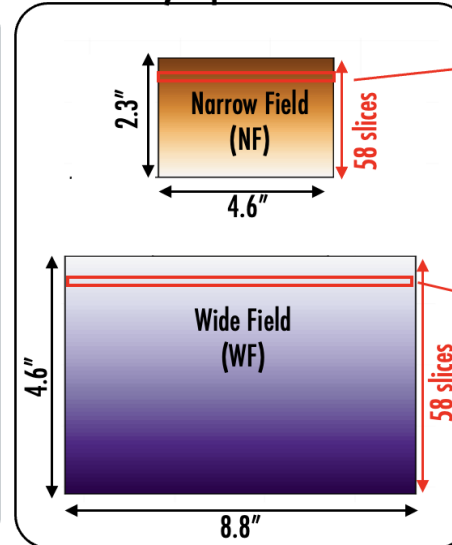
(figure taken from Roy et al., 2026)

# Integral Field Spectrograph

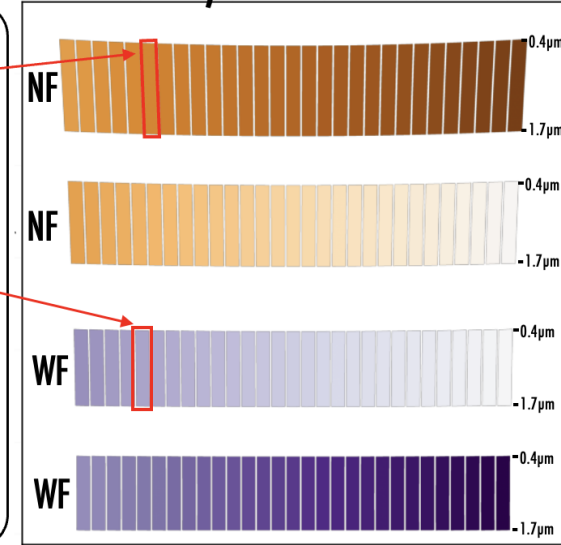
a) Lazuli IFS Optical Design Overview



b) Input Fields



c) Detector



(figure taken from Roy et al., 2026)

Detector used: **H4RG-10**, HgCdTe w/  $\lambda_{\text{cutoff}} = 1.7 \mu\text{m} @ 120 \text{ K}$

Our team in Lyon: calibration & flux inference pipeline

Lead by M. Rigault

# PyXim

- Specialized CMOS simulation framework:
    - ROIC → HxRG
    - Absorber → HgCdTe (could extend to HyViSI)
    - ASIC → SIDECAR/ACADIA/whatever
    - Sample-Up-the-Ramp mode only (no CDS nor guide mode)
  - Written in Python/JAX
    - Just-in-time (JIT) compilation: *near-native performance*
    - Accelerator support (GPUs): *massive parallelism*
    - Automatic differentiation: *differentiable modeling*
      - Test/prepare flux inference pipeline
- Goals:**
- Test/prepare detector characterization campaign
  - Full forward modeling fit

# JAX & JIT

## NumPy



- Eager execution
- Pure precompiled C ufuncs (tight loops, BLAS/LAPACK)
- Minimal runtime overhead
- Ubiquitous & simple

## Jax - w/ JIT



- Delayed execution (tracing)
- Graph & operation fusing
- Compilation to native binary (via OpenXLA → LLVM)
- **Removal of Python from the hot path**

**Pros:** Optimized & parallelized computations → Perfect for APS simulations

**Cons:** 🗡️ JAX - The Sharp Bits 🗡️

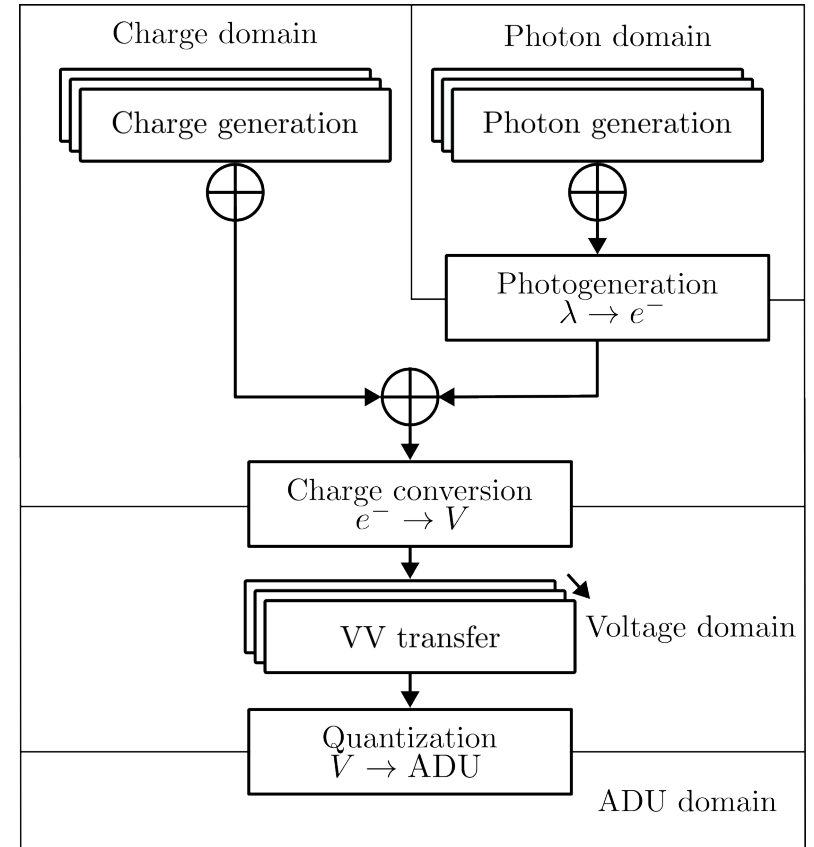
**NumPy optimizes *individual* operations**

**JAX optimizes *whole* programs**

# PyXim - Simulation flow

- 4 domains:
- Photon
  - Charge
  - Voltage
  - ADU

- Models:
- Photons
  - Charges
  - Domain  $\rightarrow$  domain
  - $\rightarrow$  Photogeneration
  - $\rightarrow$  Charge conversion
  - $\rightarrow$  Quantization
  - $V \rightarrow V$



# Model definition

## Declarative

```
[Photogeneration]
model_name = 'FPNPhotogenerationModel'
shot_noise_model = 'Poisson'

[Photogeneration.fpn]
init = 'from_gaussian_dist'
resolution = [1016, 1016]
seed = 1337
Pn = 0.01

[[Illumination]]
label = 'flat'
model_name = 'FlatfieldIlluminationModel'
flux = 3200.0

[[ChargeGeneration]]
label = 'dark'
model_name = 'DarkCurrentModel'
rule = 'rule22'

[[VVTransfer]]
label = "dc_offset"
model_name = 'DCOffsetModel'
enabled = true
dc_offset = 0.01

# kTC noise
[[VVTransfer]]
enabled = true
label = 'reset_noise'
model_name = 'ResetNoiseModel'
seed = 0
```

## Imperative

```
# Define an illumination model, here a simple flatfield with around 800 incident photon/seconds
illum_model = FlatfieldIlluminationModel(flux=850.)

# Add 10 e- readout noise
readout_noise_model = SimpleReadNoiseModel(noise_std=10.*sensor.sn_gain)

# Add an ad-hoc 100 e- DC offset
dc_offset_model = DCOffsetModel(dc_offset=100.*sensor.sn_gain)

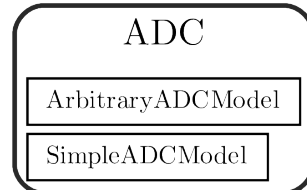
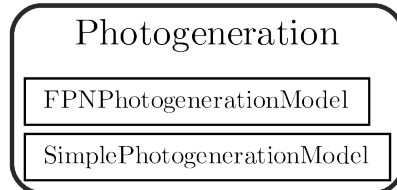
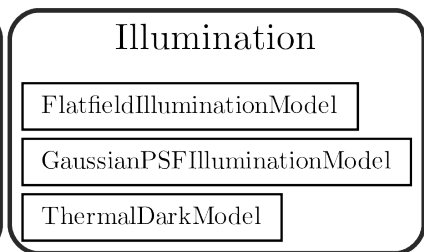
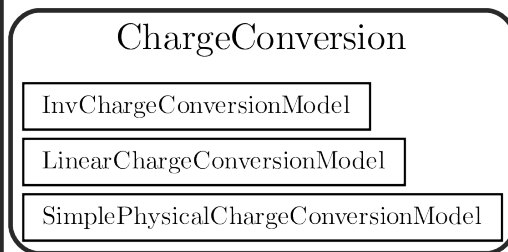
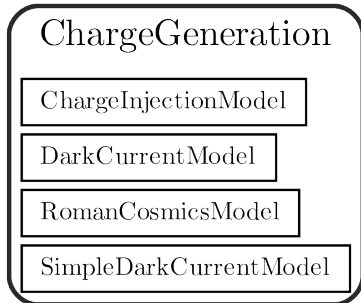
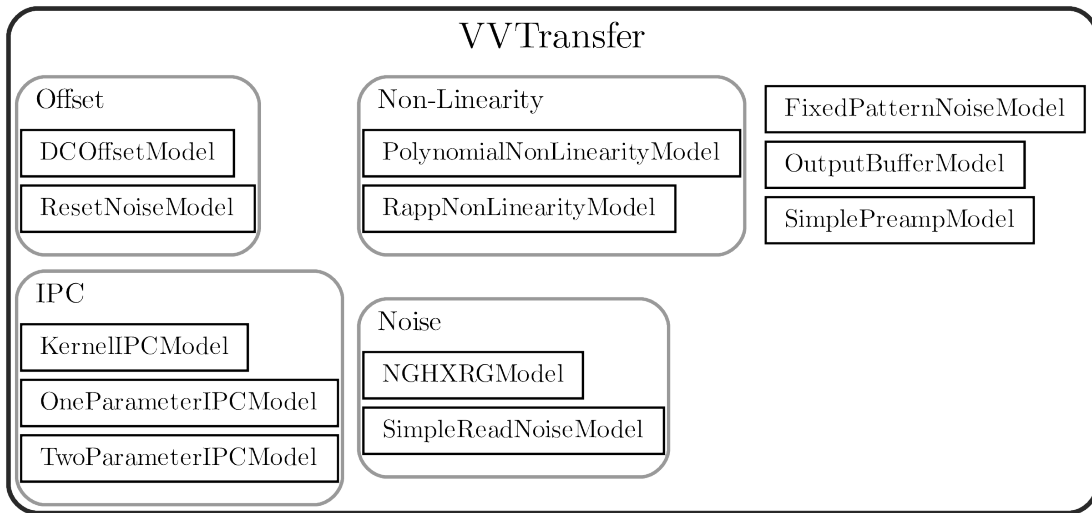
# Our FPN-modulated photogeneration model
photogeneration_model = FPNPhotogenerationModel(
    fpn=FixedPatternNoise.from_gaussian_dist(0.01, sensor.resolution, key=jax.random.key(1337)))
```

2 equivalent definition modes:

- Declarative – From text file (.toml)
- Imperative – From code (Python)

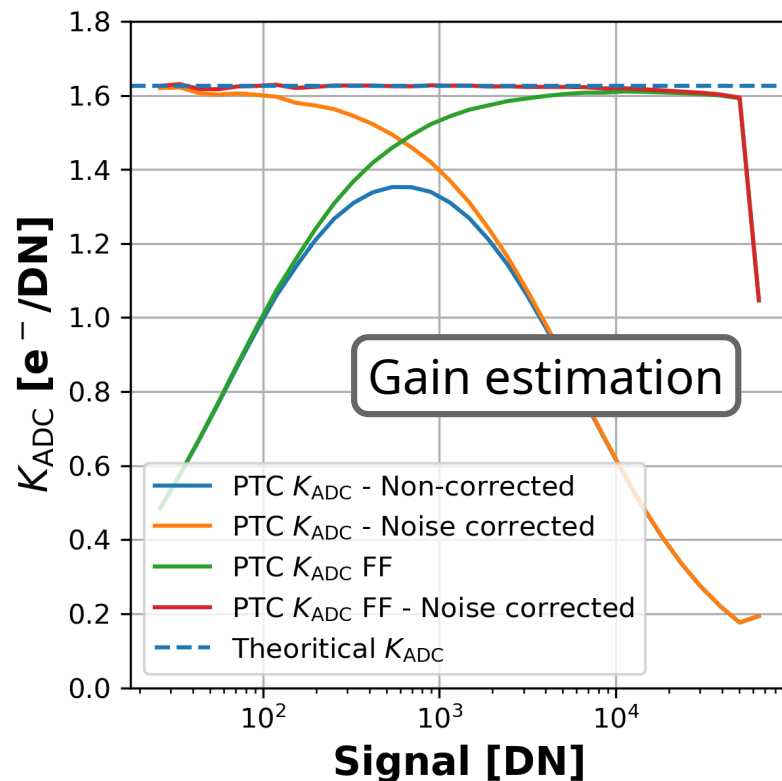
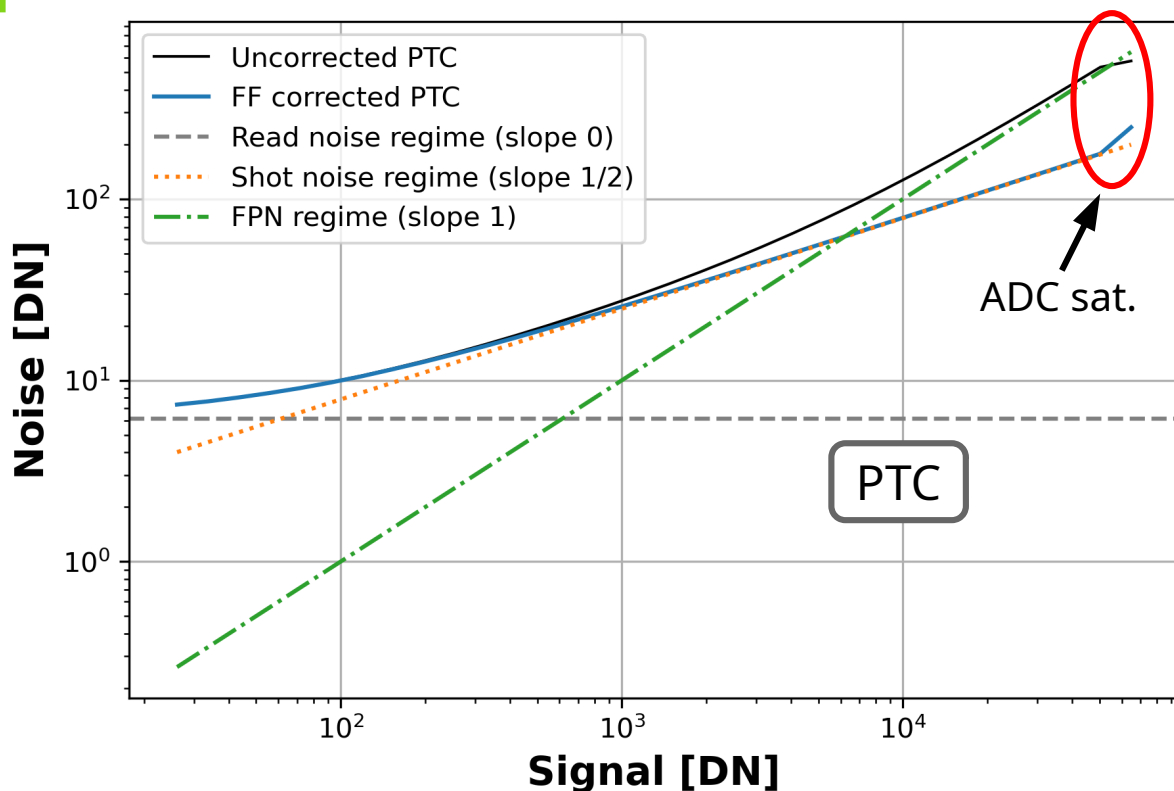
**Both** exposes the **same** set of functionality

# Model catalog



Plugin architecture w/ lazy loading

# Feature gallery - Sanity check

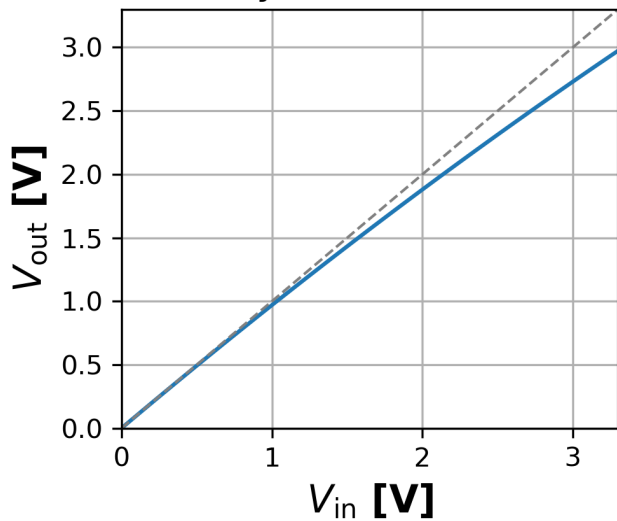


Simple model: readout noise + FPN  $\rightarrow$  follows theory perfectly!

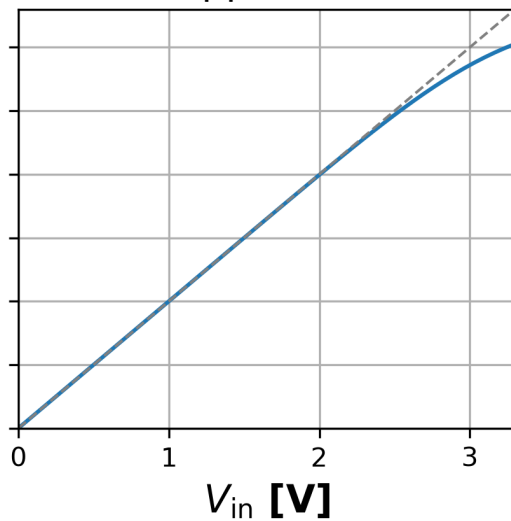
# Feature gallery – Classical nonlinearity

## V/V nonlinearity

Polynomial model

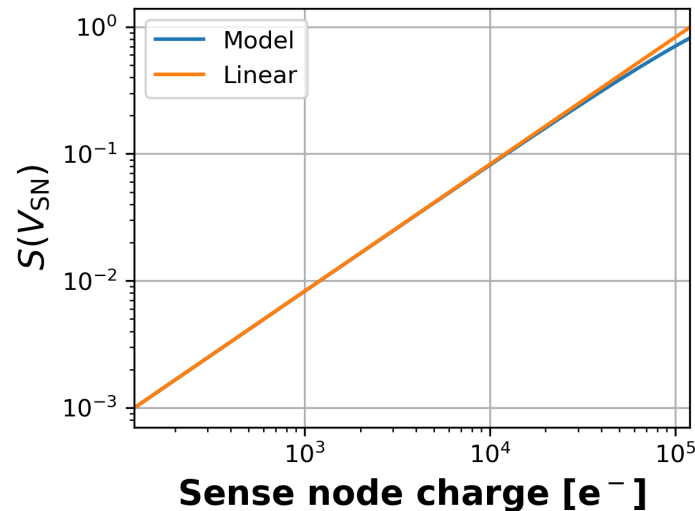


Rapp model



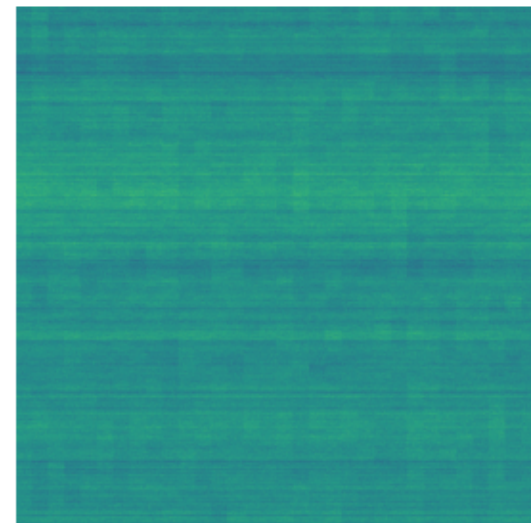
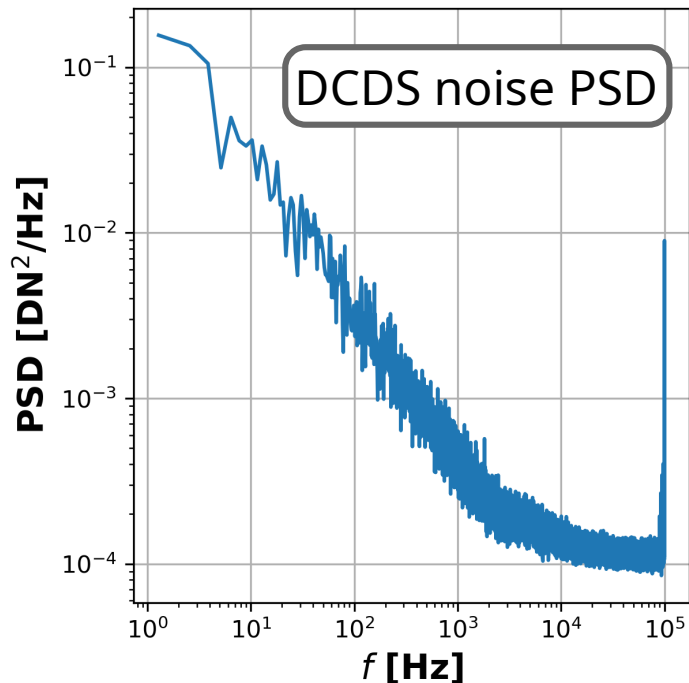
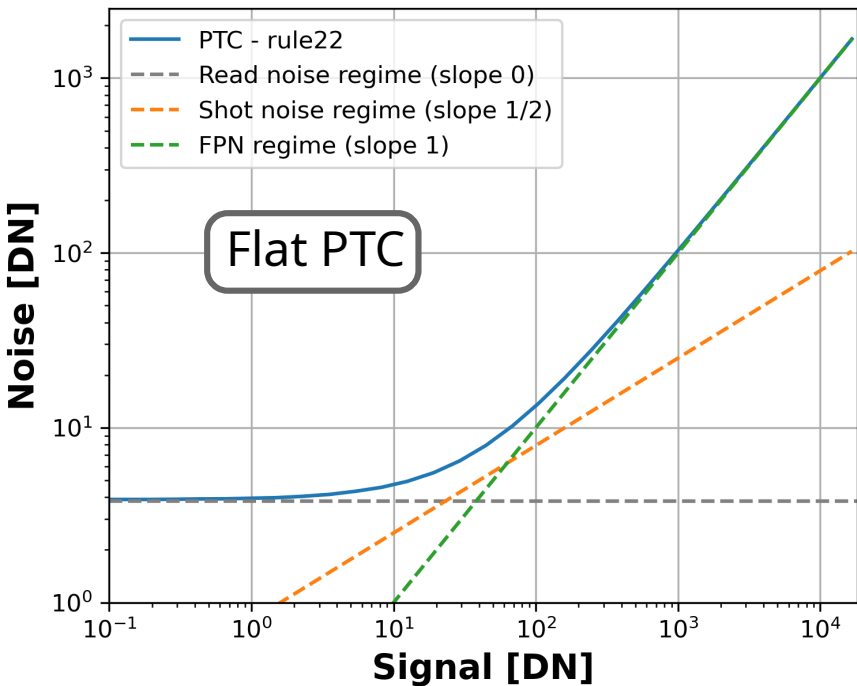
- Per pixel
  - Per column
  - Per channel
  - Frame
- 4 granularity: → Composable

## V/e<sup>-</sup> nonlinearity



- Transimpedance amplifier NL
- This plot:
- Small signal model
  - Assumes abrupt P<sup>+</sup>N junction

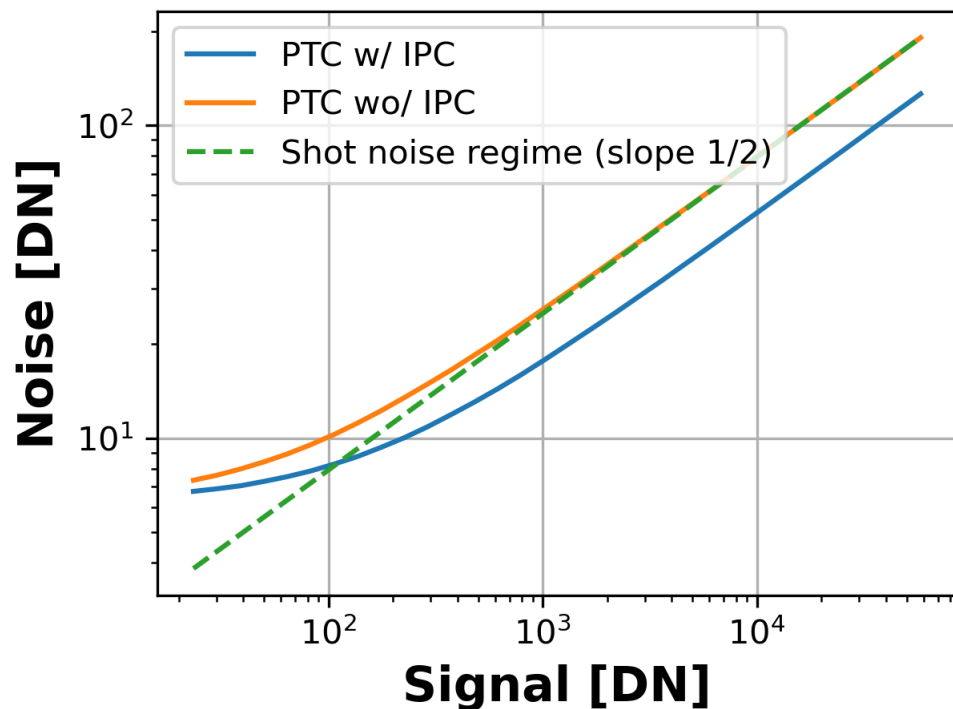
# Feature gallery - Dark + NGHXRG



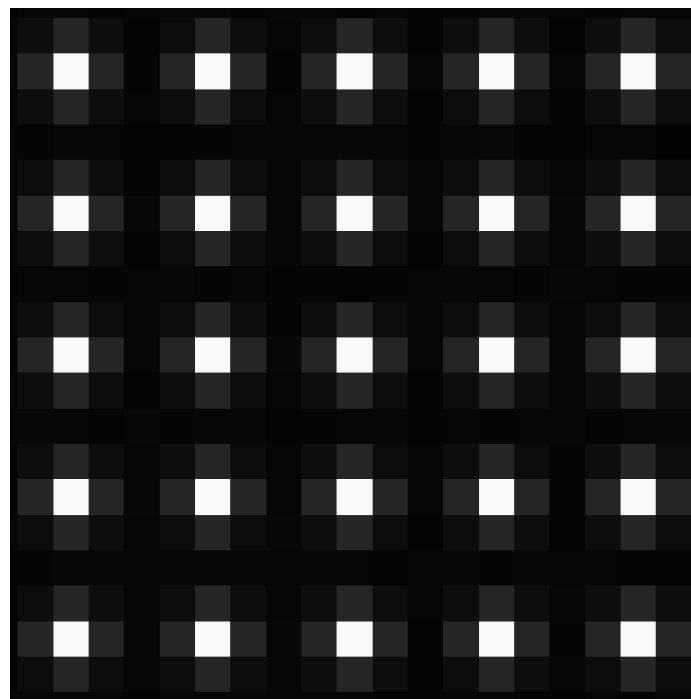
DCDS frame  
(4k - 32 chan.)

- Dark model: Rule07 & Rule22 + DFPN
- NGHXRG (Rauscher, 2015) adapted into PyXim

# Feature gallery – Inter Pixel Capacitance

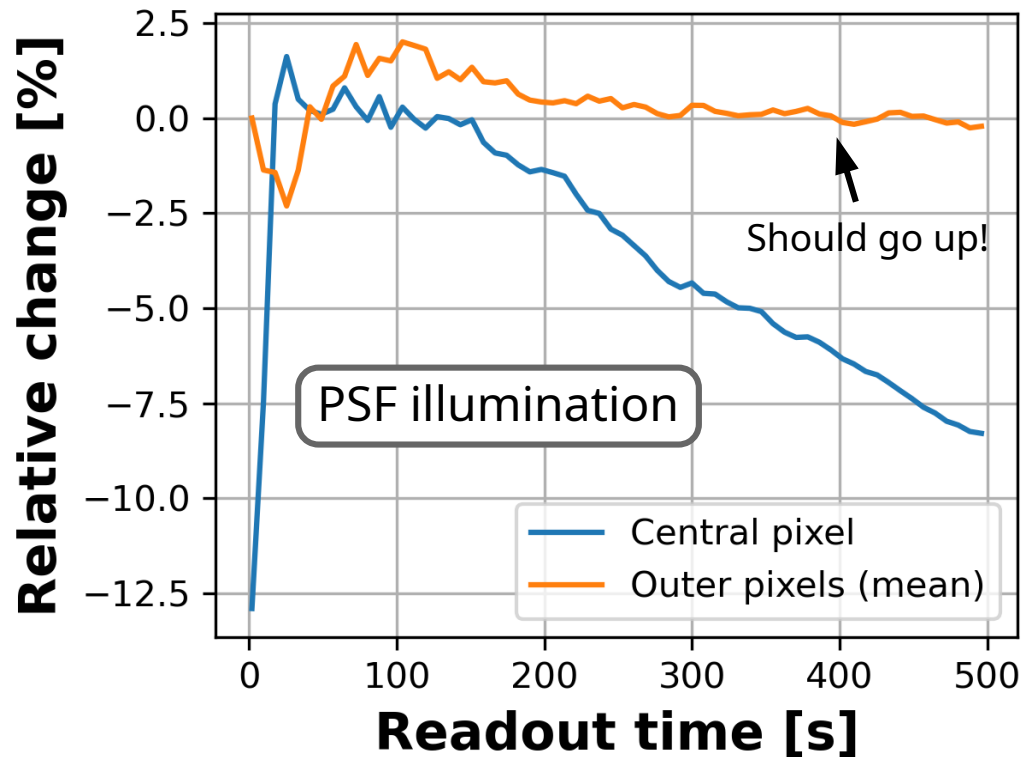
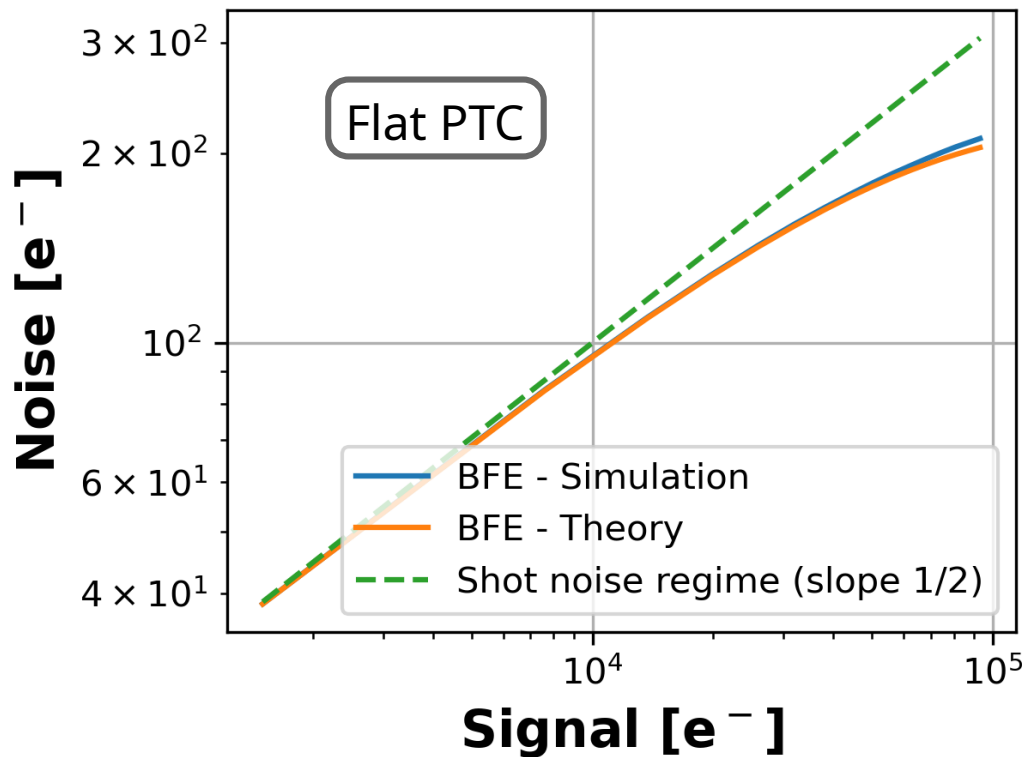


PTC variance deficit due to IPC  
(exaggerated kernel)



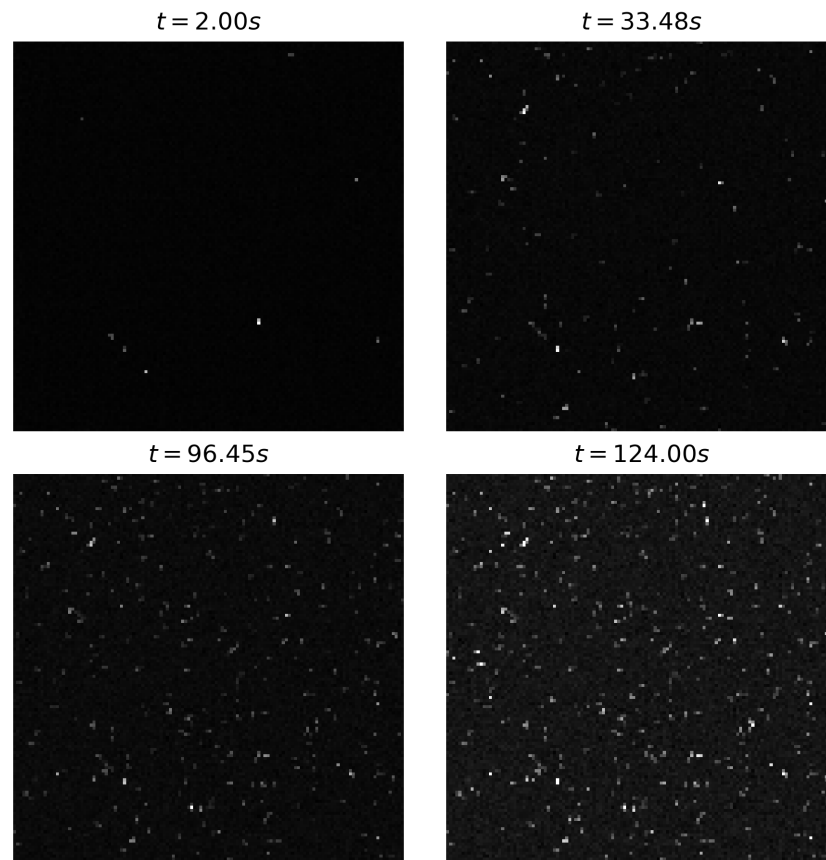
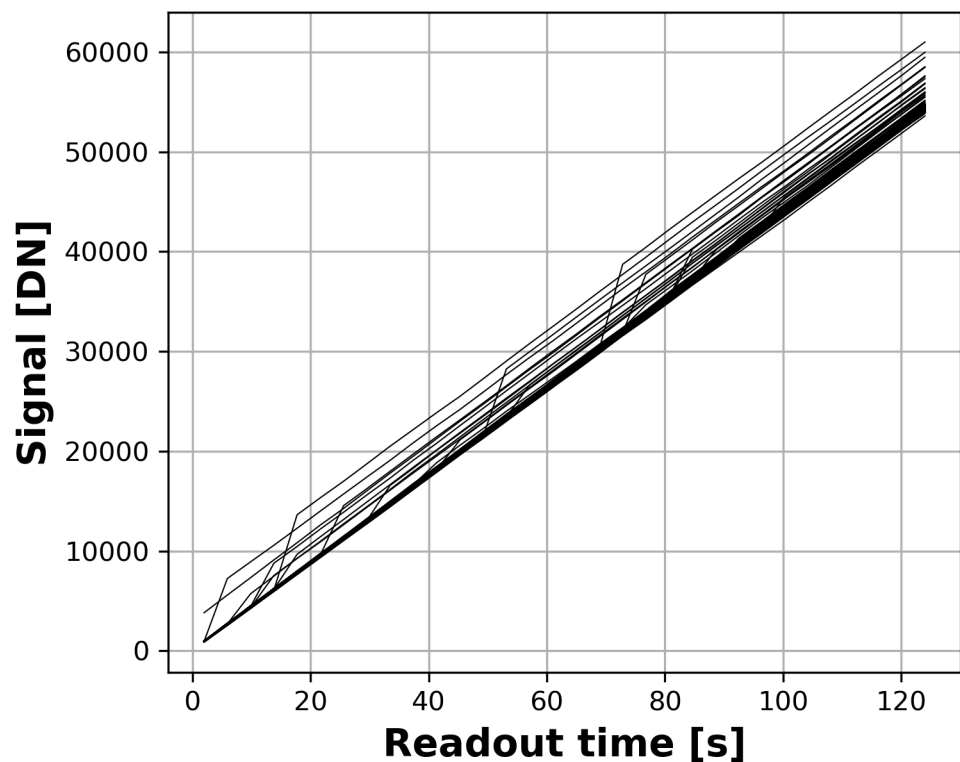
$V_{\text{RESET}}$  point grid to estimate  
IPC kernel

# Feature gallery - Brighter-Fatter effect



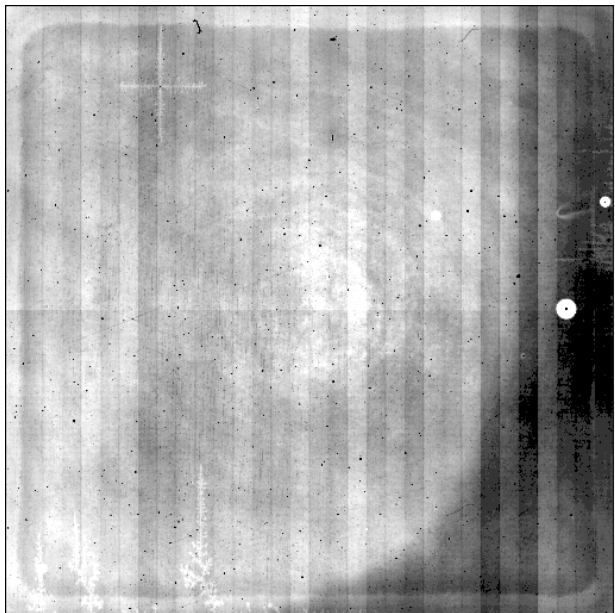
→ Flatfield formulation only! (Astier et al., 2019)  
As in Solid-Waffle (Hirata & Choi, 2020)

# Feature gallery - Cosmics

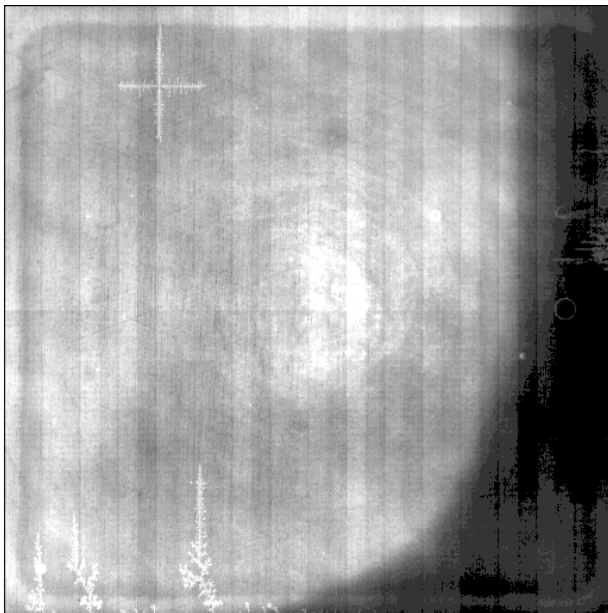


Adapted from Roman-STScI-000502

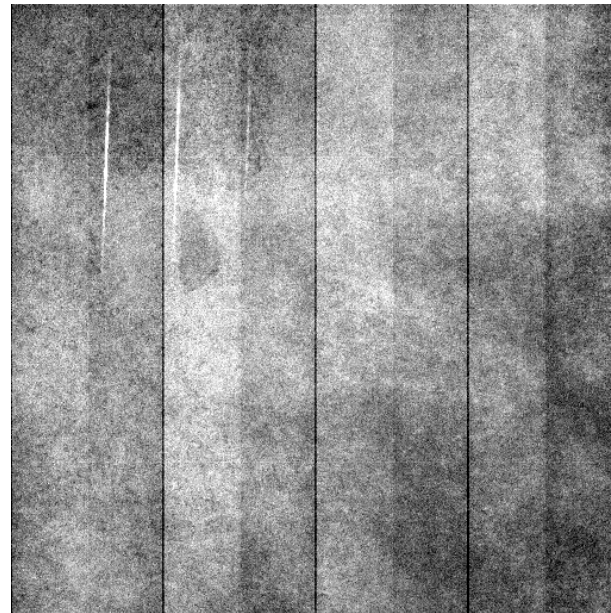
# Feature gallery – Lazuli IFS



**Roman flat**



**PyXim flat**

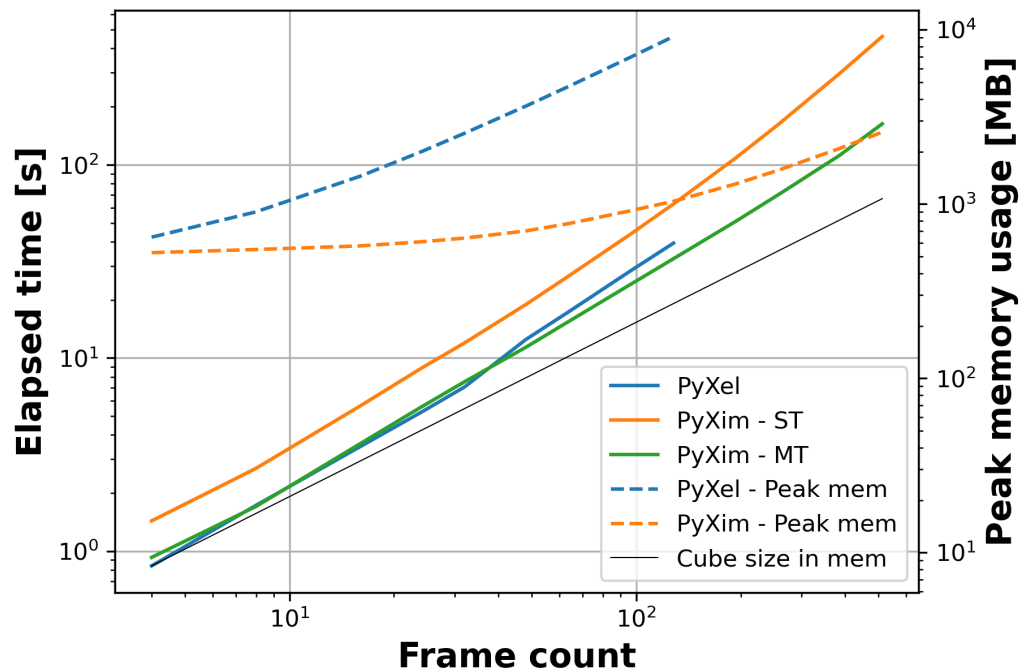


**PyXim Lazuli IFS  
(magnified)**

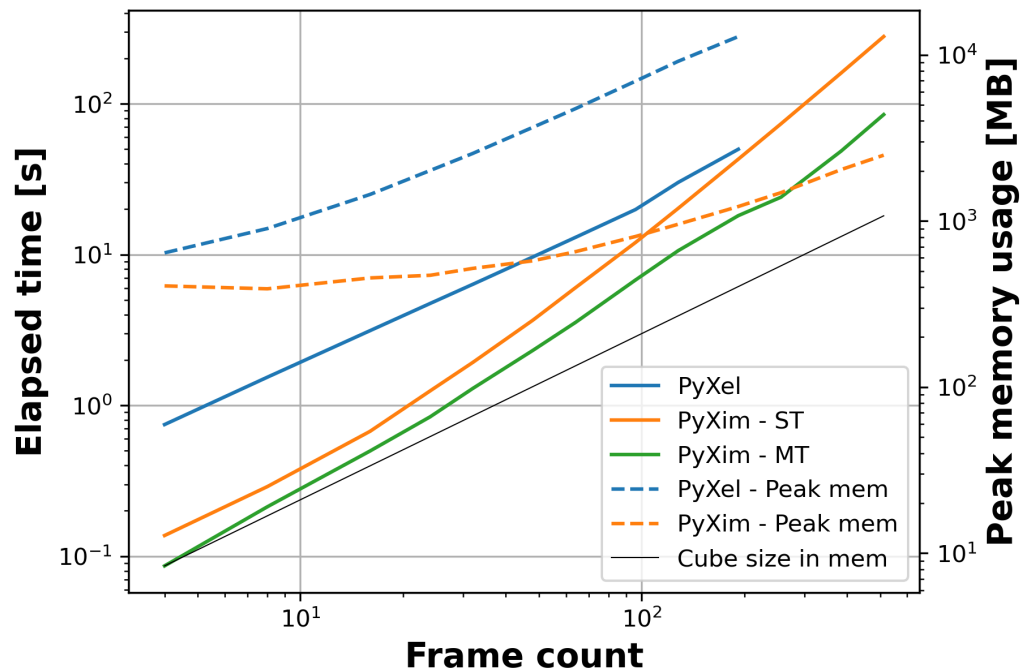
→ Offset & FPN components extracted from Roman (public WFI Triplet Test Data)

# Comparison to PyXel - Simple model

Shot noise model: Poisson



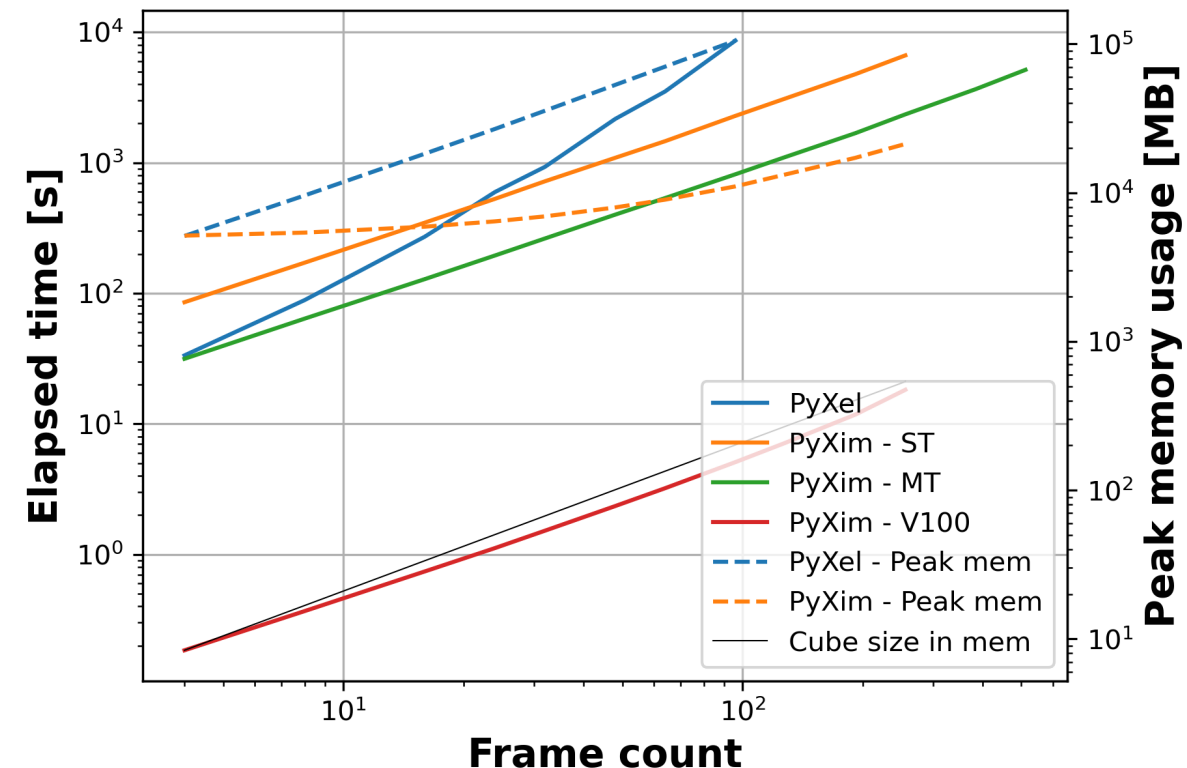
Shot noise model: Normal



Simple model: — 1024 x 1024  
— FPN  
— Gaussian read-out noise

Hardware used:  
Intel Core i7-1165G7 (2.8 GHz) – 4C/8T  
(PyXel version: 2.16.2)

# Comparison to PyXel - Complex model



Complex model:

— 4096 x 4096

— Dark (rule 07)

— Reset noise

— Polynomial non-linearity

— NGHXRG noise mode (32 channels)

→ On V100: 256 frames in 18s

Hardware used: — Intel Xeon Silver 4210R (2.40 GHz) – 10C/20T

— Nvidia V100 32 GB

# Forward modeling

## Classic inference pipeline

- Characterize non-ideal behaviors
- Correct raw from them
- Fit for flux

## Forward modeling

- Define model
- Fit model nuisance parameter spaces
- Fit for flux

- JAX: Automatic Differentiation (gradient, Jacobian, Hessian)
  - Gradient: 1 model evaluation
  - Enables classic ML optimization algorithms  
(Conjugate Gradient, BFGS, ...)
- Forward modeling fit → non-linear maximum likelihood estimation

**Pros:**

- Automatically account for bias sources
- Fisher matrix

**Cons:**

- Model dependent
- Computationally expensive

# Breaking one degeneracy at a time

Breaking degeneracies calls for different datasets:

- $V_{\text{RESET}}$  sweeps (up to  $V_{\text{DSUB}}$ )
  - SF/column/output buffer/preamp transfer functions
- $V_{\text{RESET}}$  point grid → Characterize IPC
- Flat ramp to saturation → BFE, full well
- Shorted inputs → Preamp noise
- Dark flats → Dark contribution, noise, amp/mux glow
- Low THD sinusoidal in ASIC → ADC nonlinearities
- CV PN-junction relationship → Photodiode characterization

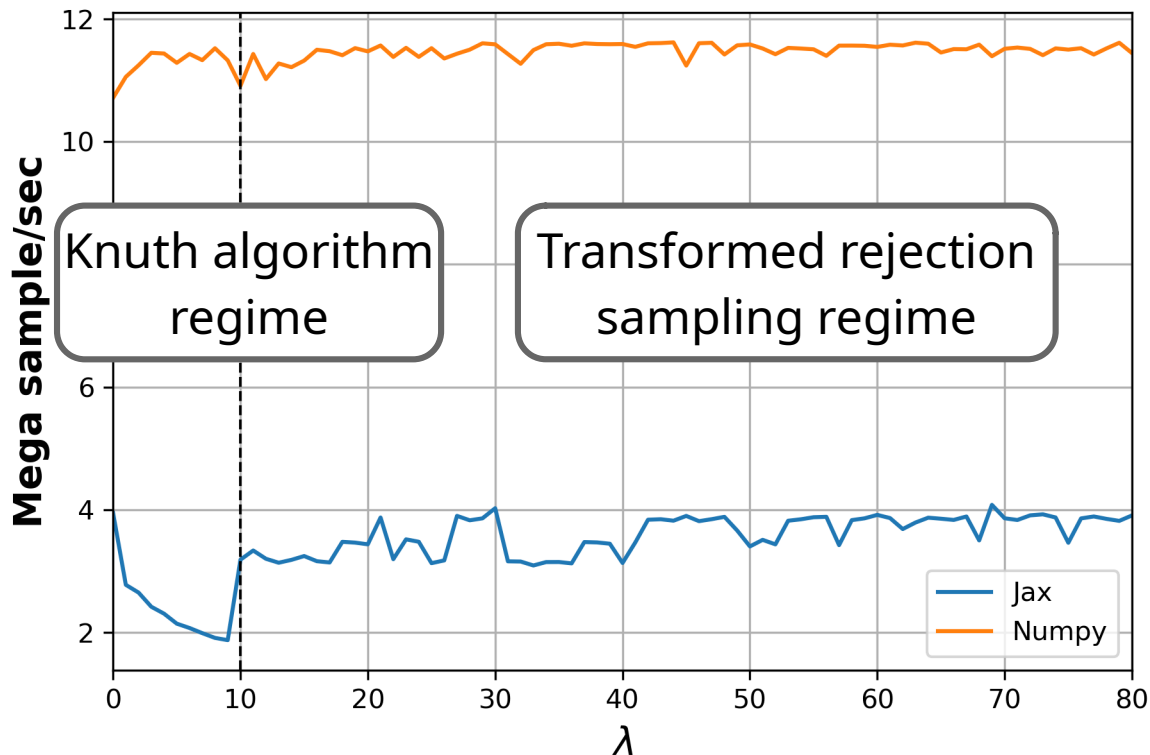
From there: fit for flux! (with nuisance parameters fixed)  
→ Forward modeling

# The future

- Extend model catalog
  - Crosstalk
  - Persistence/burn in/count rate non-linearity
  - ADC nonlinearities
  - Better sense node transimpedance amplifier models (saturation)
  - Pixel cosmetics
- Start experimentation with forward modeling
- **Write paper & release code!**

# Backup slides

# Poisson sampling benchmark



JAX: ~3/4 times **slower** than NumPy!

- Stochastic loop
- Branch heavy
- Key splitting cost

Hardware used: Intel Core i7-1165G7 (2.8 GHz) – 4C/8T