

# SKA Observatory Management and Control Software: the INAF contribution

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# The SKA software engineering group

PI 27 Planning - Hertogenbosch (NL) 3-7 March 2025

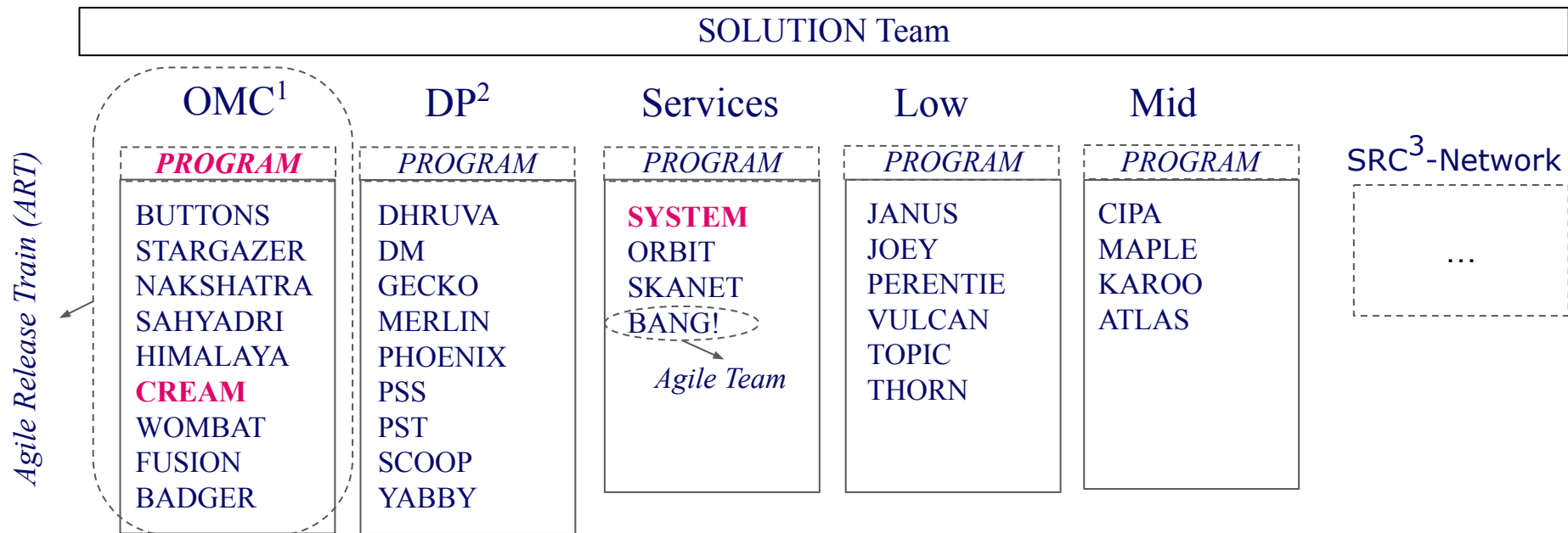




# The SKA software engineering group



- more than 200 people involved from 15 different countries
- organized with Scaled Agile Framework (SAFe)
- work is iteratively planned every 3 months (Program Increment - PI)



<sup>1</sup> Observatory Management and Control

<sup>2</sup> Data Processing

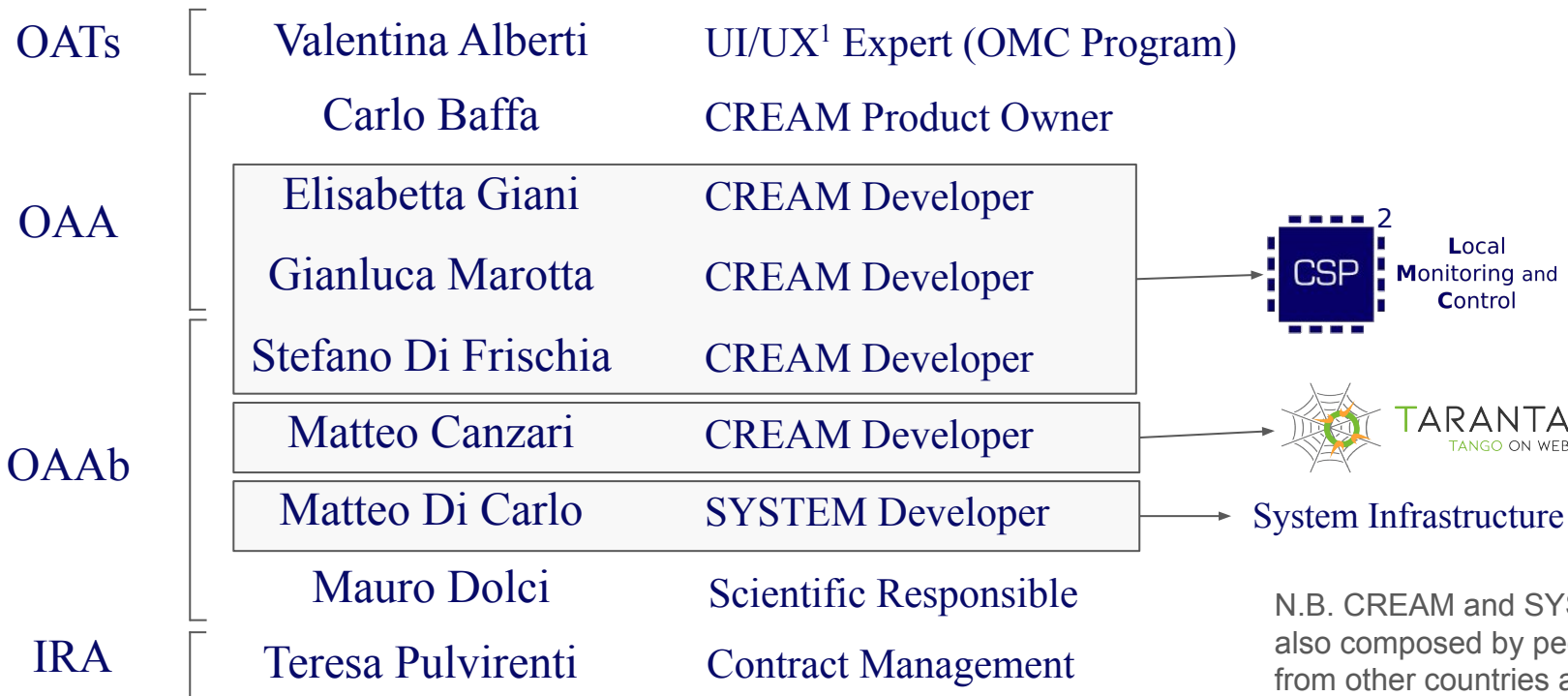
<sup>2</sup> SKA Regional Centers



# The INAF Group



Program Team



N.B. CREAM and SYSTEM are also composed by people coming from other countries and companies/institutions



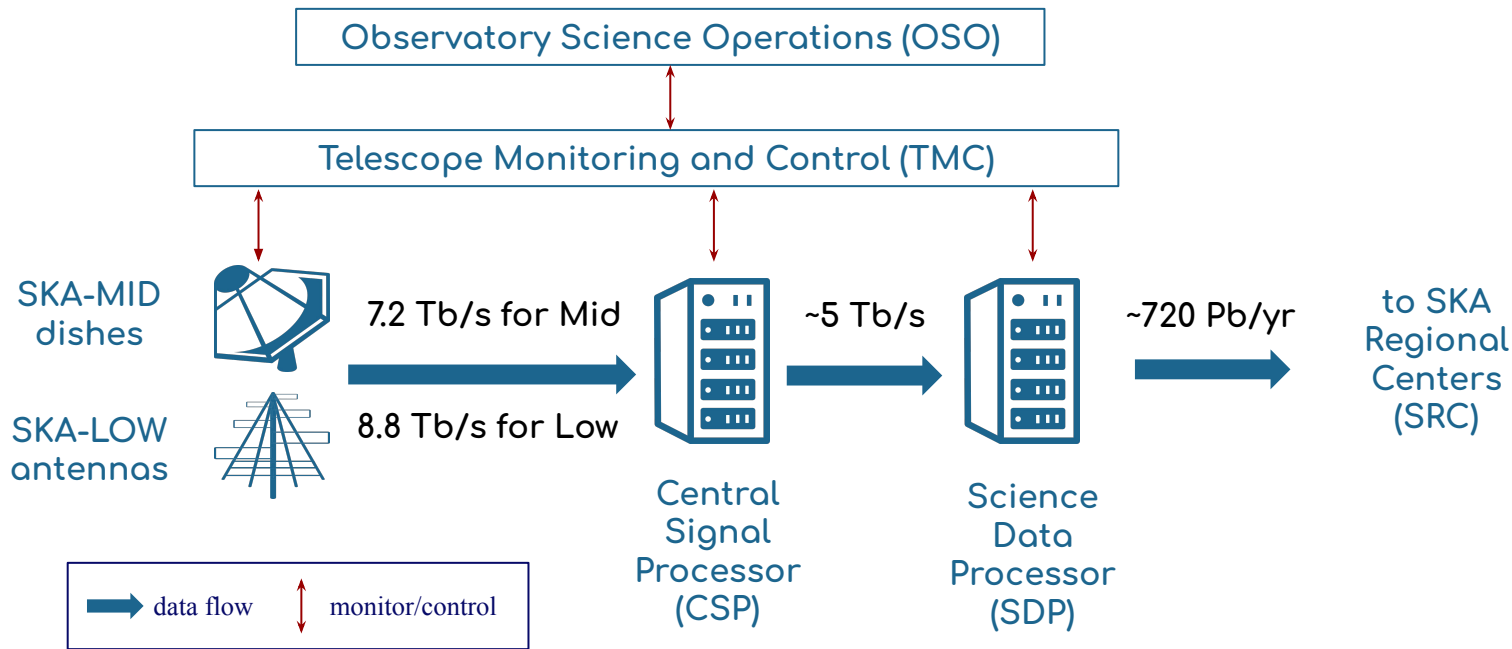
<sup>1</sup>User Interfaces/User eXperience

<sup>2</sup>Central Signal Processor



# The SKA Data Flow and Control System

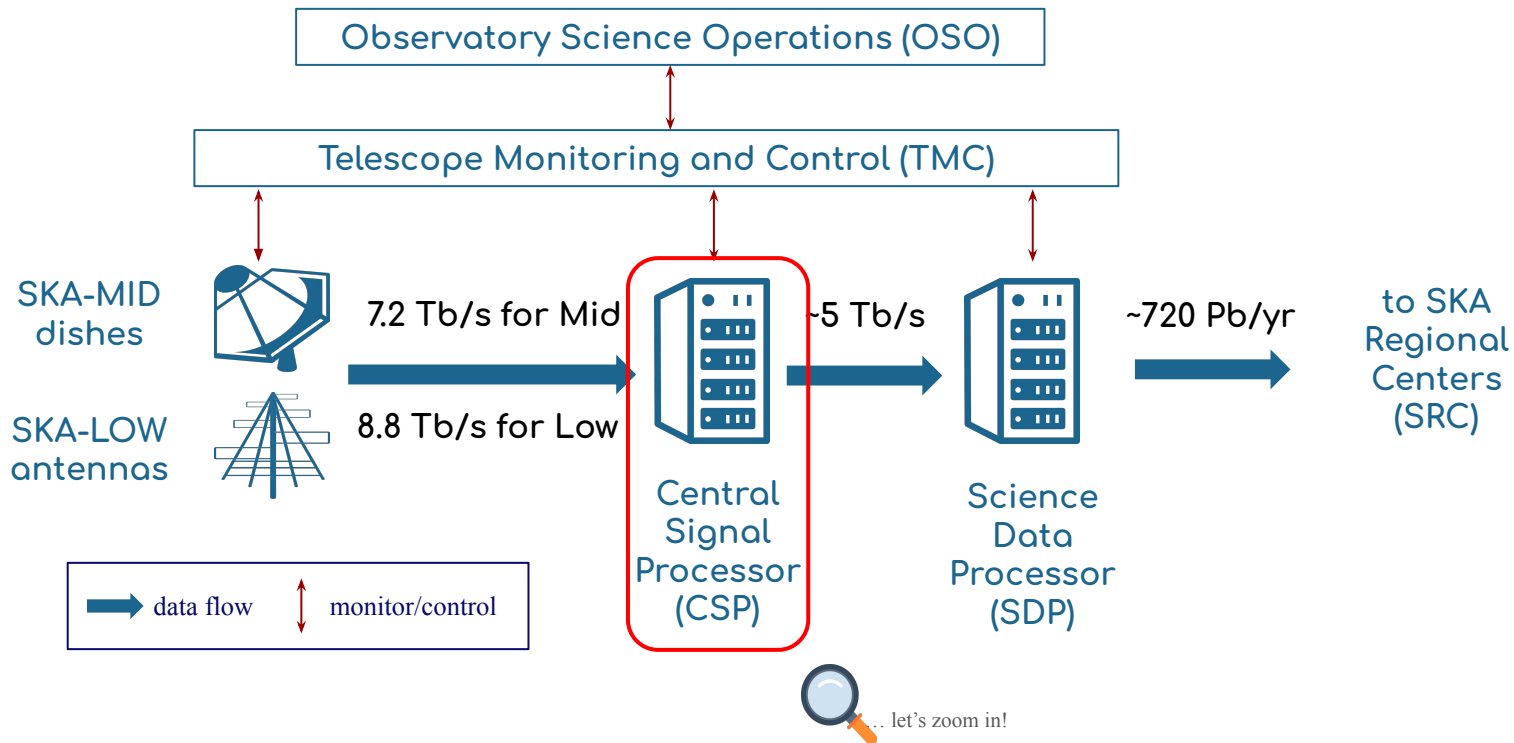
... a very simplified view





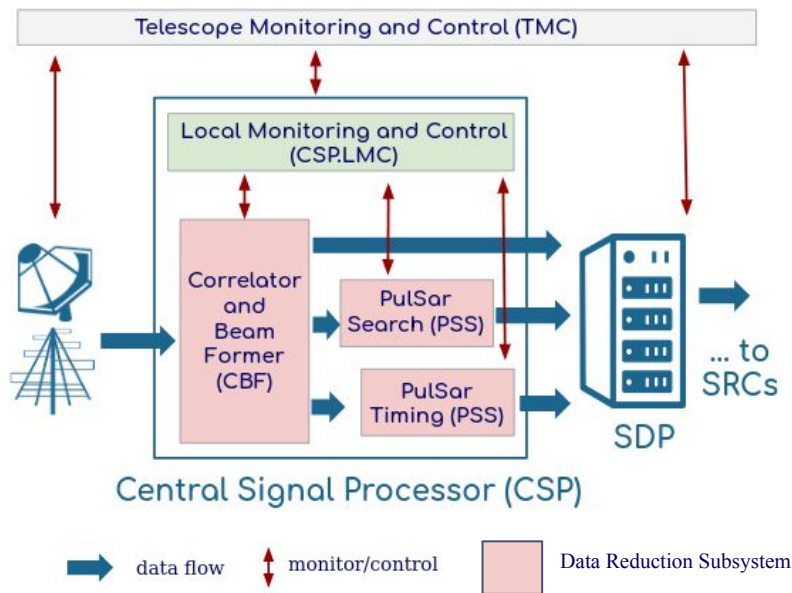
# The SKA Data Flow and Control System

... a very simplified view





# The Central Signal Processor



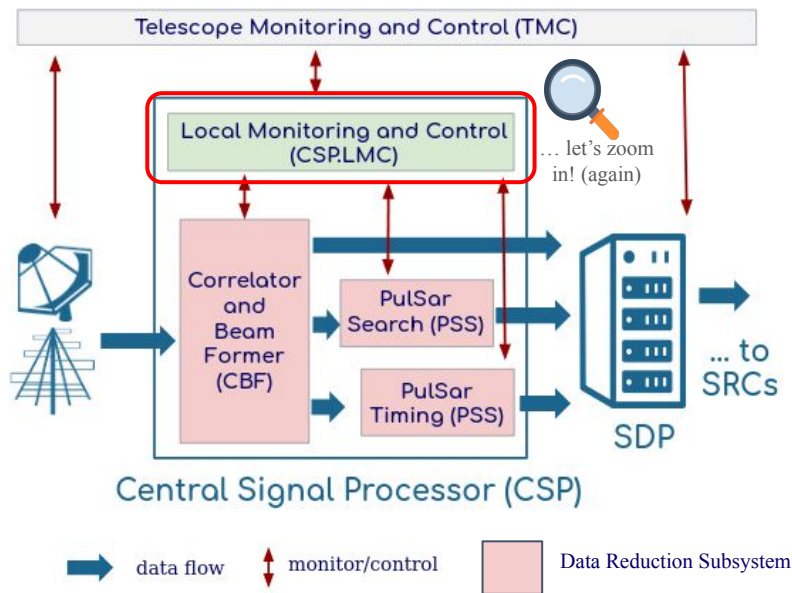
CSP is composed of three main subsystems:

- the **Correlator and Beam Former (CBF)**, to creates the visibilities and the data beams;
- the **Pulsar Search (PSS)**, to perform an all-sky pulsar search survey;
- the **Pulsar Timing (PST)**, to measures the frequency of the pulsar candidates

CSP.LMC provides the *interface* to TMC *without exposing CSP internal complexity*.



# The Central Signal Processor



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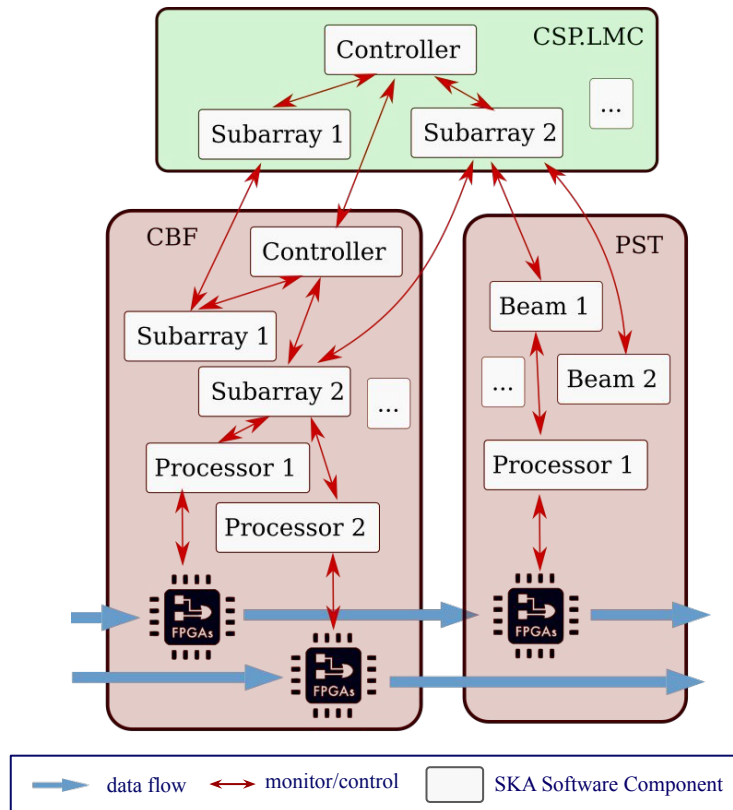
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CSP.LMC provides the *interface* to TMC *without exposing CSP internal complexity*.



# The CSP Local Monitoring and Control (CSP.LMC)

... a very simplified view



The CSP.LMC is composed by:

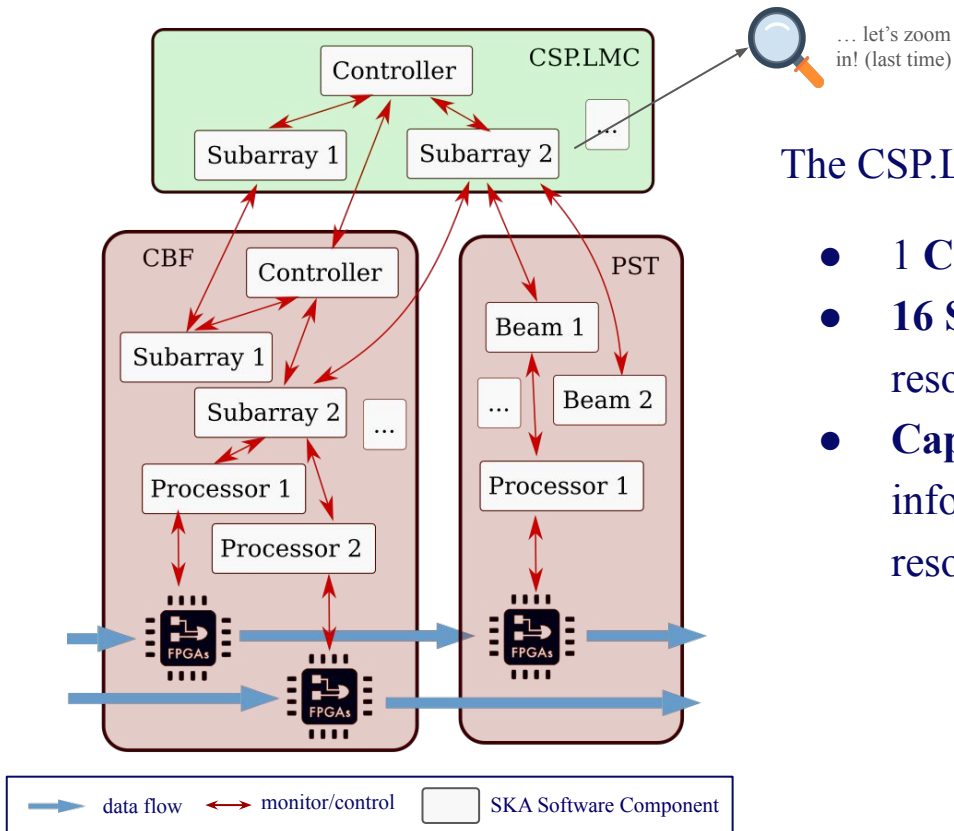
- 1 **Controller**, i.e. the primary point of access for CSP
- 16 **Subarray**, representing subsets of the telescope resources that can be used for one observation
- **Capability** devices, apt to monitor and report to TMC information and statistical data about specific CSP resources (e.g. CBF processors, PST Beams)





# The CSP Local Monitoring and Control (CSP.LMC)

... a very simplified view



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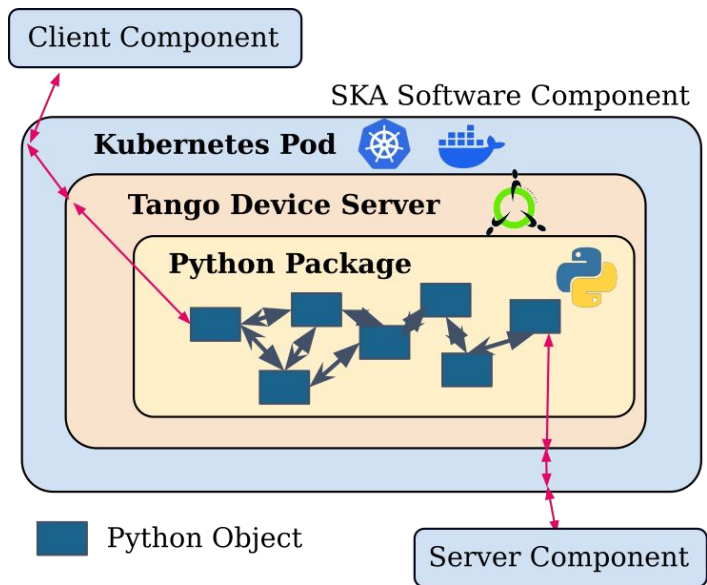
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# The SKA Software Component

Software is **executed** by a **Tango Device Server** process, that runs in a **Docker container** that is **orchestrated** in a cluster by **Kubernetes**



“a free open source device-oriented controls toolkit for controlling any kind of hardware or software and building SCADA<sup>1</sup> systems”<sup>2</sup>.



“is an open platform for developing, shipping, and running applications [...] enables you to separate your applications from your infrastructure”<sup>3</sup>”



“is a portable, extensible, open source platform for managing containerized workloads and services ...”<sup>4</sup>”

\* for simplicity only one server/client is reported

<sup>1</sup>Supervisory Control And Data Acquisition

<sup>2</sup><https://www.tango-controls.org/>

<sup>3</sup><https://docs.docker.com>

<sup>4</sup><https://kubernetes.io/docs>



# The contribution to TANGO Control System



The Tango Community has **more than 45 institutional** and **more than 15 industrial partners** from all over the World

INAF is member of the TANGO steering committee and active actor in the community



**TANGO collaboration meeting - hosted by INAF OAAb - May 2025**



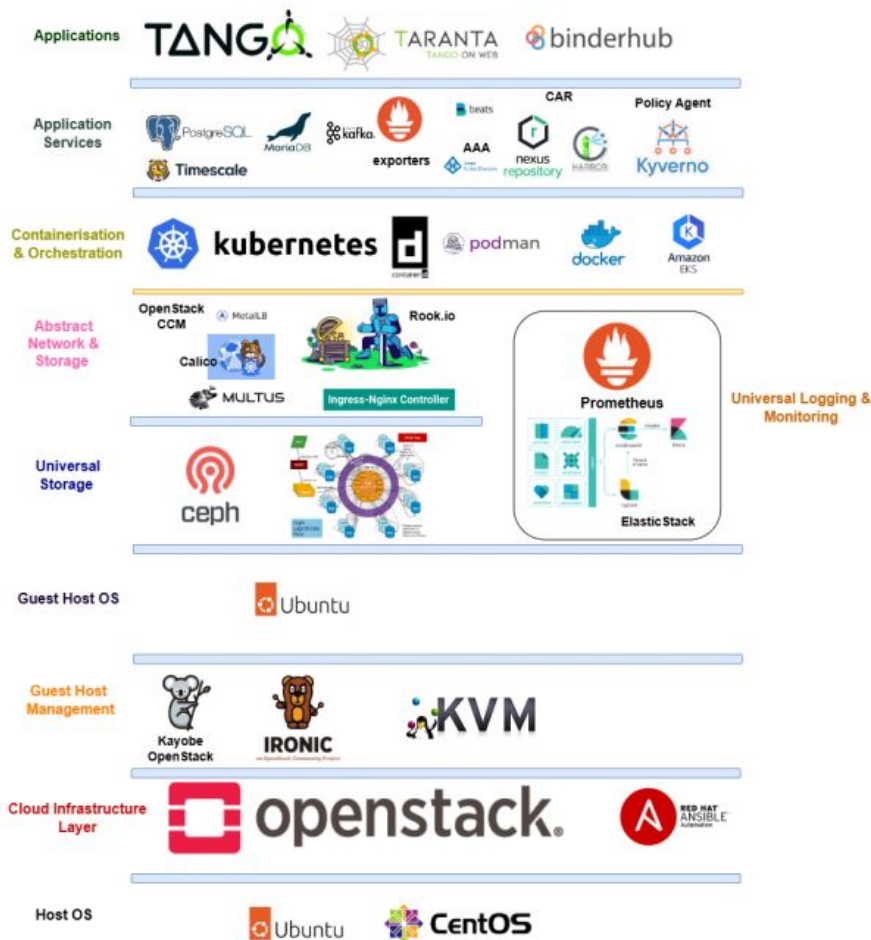
# The System Infrastructure

SKA Control Software is meant to be deployed with a large use of **cloud-native technologies**

The infrastructure is developed and maintained by System Team



Tools for *deploying, testing and monitoring* are provided to developers



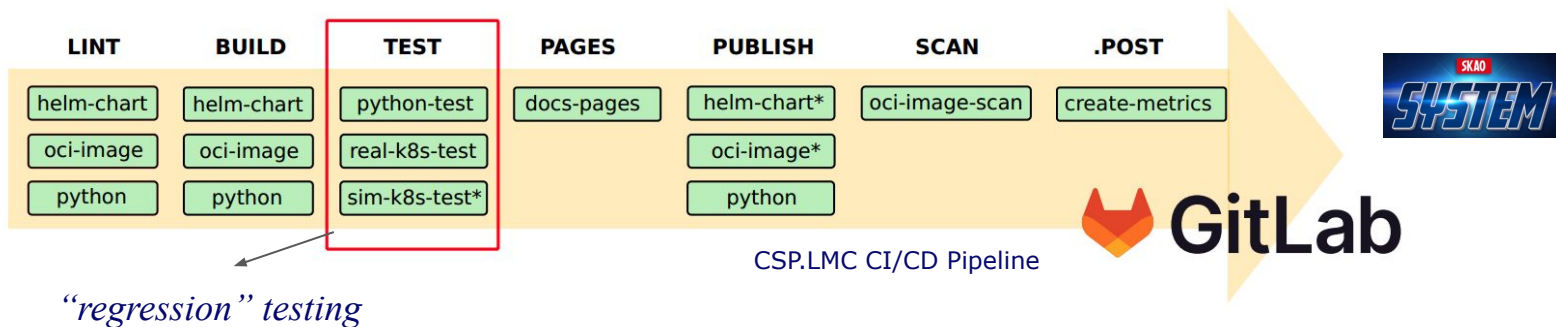


# Continuous Integration/Continuous Delivery/Deployment

Continuous Integration/Continuous Delivery/Deployment (CI/CD) refers to development practices:

- single source repository for each component;
- automated build;
- ^automated testing;
- ^**every commit** should build on an integration machine (with tango/kubernetes)

CI/CD practices are ensured by the use of **Gitlab pipelines**, based on System Team templates.





# Testing the SKA Software

“[Testing is] the process [...] to determine that they [software products] **satisfy specified requirements**, to demonstrate that **they are fit for purpose** and to **detect bugs**.”<sup>1</sup>

SKAO Software Testing Policy and Strategy - <https://developer.skao.int/>

- Individual teams are responsible for software component quality and testing strategy
- Verification Tests based on requirements are done by AIV teams
- A *Testing Community of Practice* gather developers from different teams to share knowledge and practices



Testing can represent a **considerable amount of time** of development (about 50% in CSP.LMC)

CREAM Team plays a pioneering role in SKA software testing, tackling “*test flakiness*” and “*unhappy-path testing*”



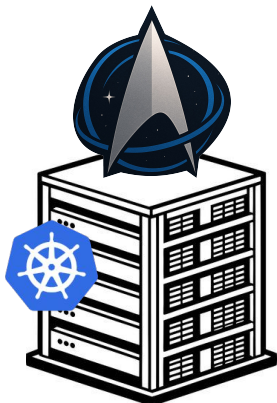
# HW Infrastructure for SKA Software @ INAF



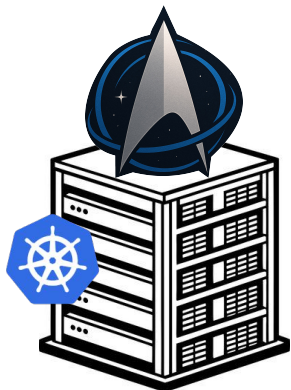
Finanziato  
dall'Unione europea  
NextGenerationEU



**Italiadomani**  
PIANO NAZIONALE  
DI RIPRESA E RESILIENZA



@INAF-OAA



@INAF-OAAb

## Federation Clusters

- made available free of charge
- provide kubernetes
- hosted and managed by INAF-OAA and INAF-OAAb members
- hosts Cream Team VMs for development
- hosts CSP.LMC CI/CD pipelines

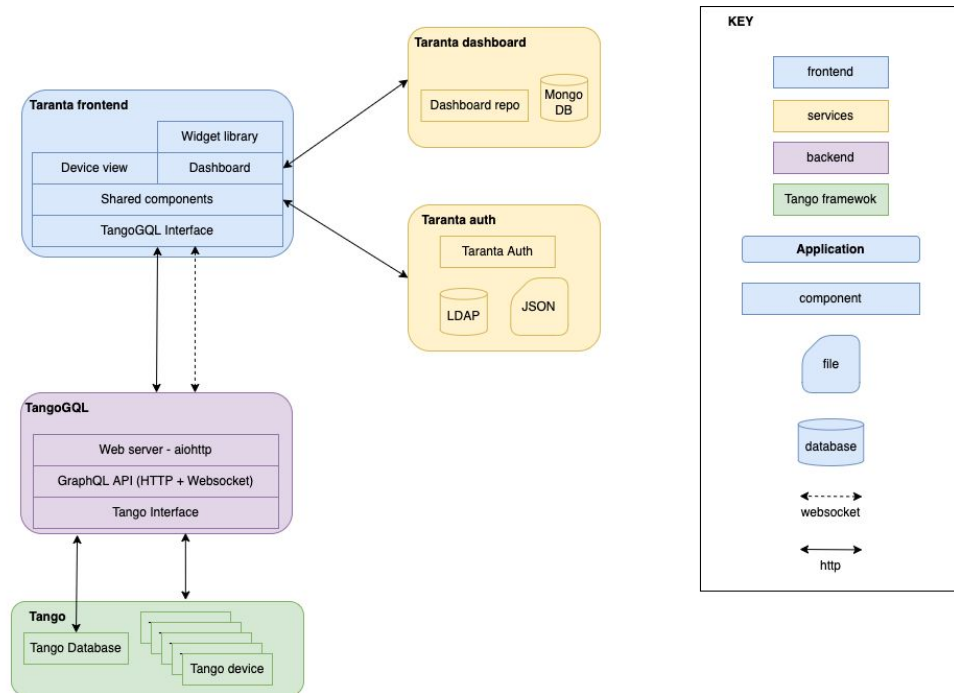


# Taranta: a web UI for Tango



Taranta offers a **no-code, web-based** approach for creating dashboards that integrate multiple *Tango devices*.

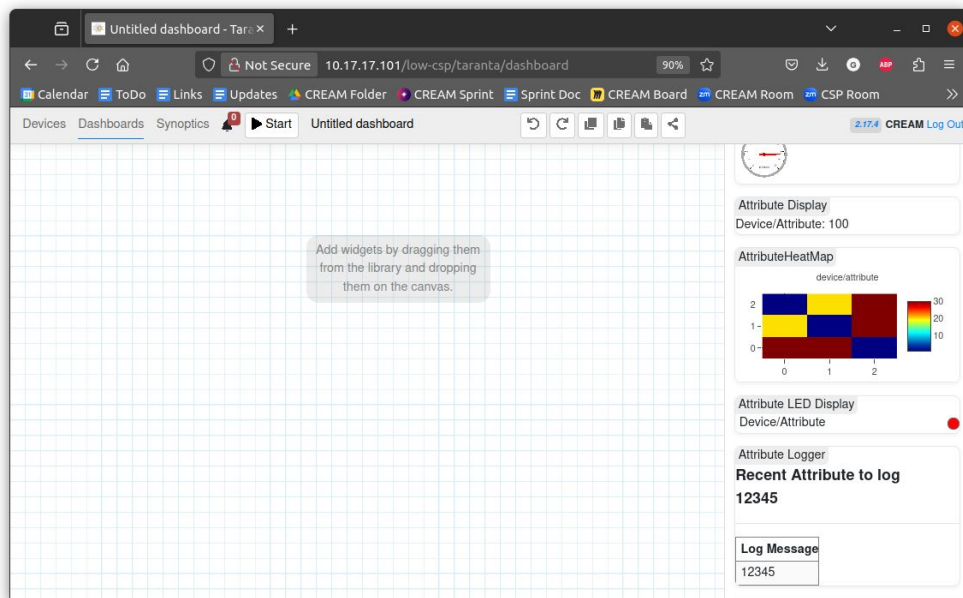
Taranta is developed by CREAM team in collaboration with MAX IV institute





# Taranta: a web UI for Tango

Taranta is largely used by teams for creating **engineering dashboards**

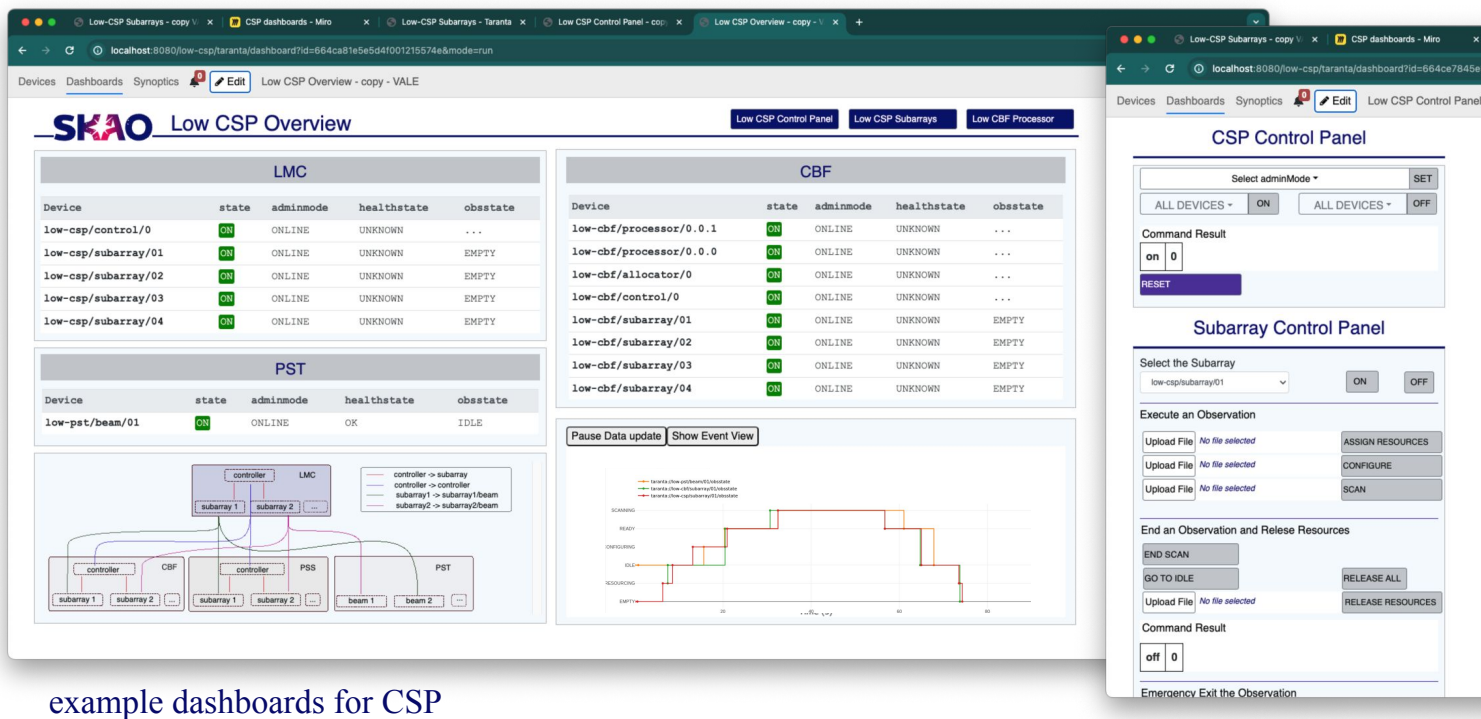


- simple to use (drag and drop)
- new functionalities based on user feedback
- possibility to create vectorial and synoptic dashboards with Inkscape





# Taranta: a web UI for Tango



example dashboards for CSP



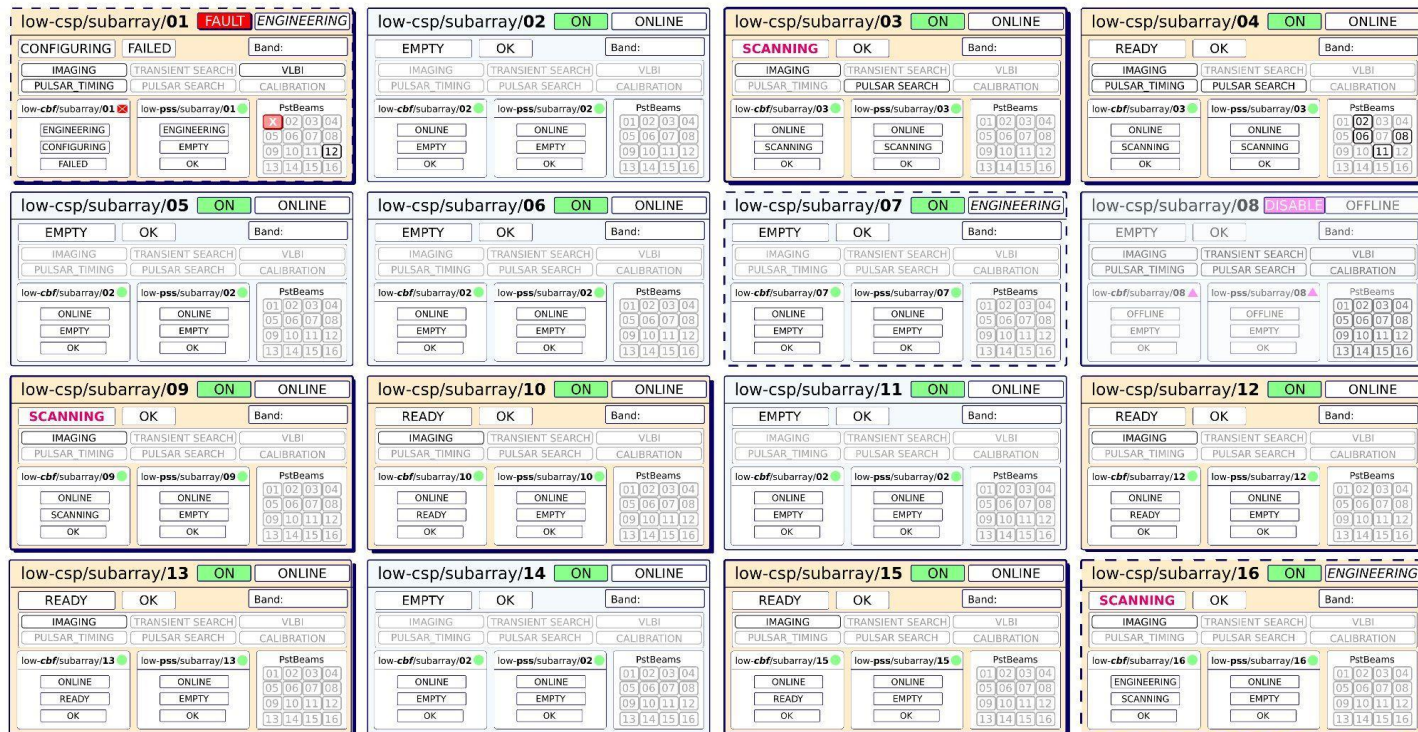
# Taranta: the “new” synoptic view



TARANTA  
TANGO ON WEB



Low Telescope - CSP Local Monitoring and Control - Subarrays Overview



a prototype  
synoptic for  
CSP



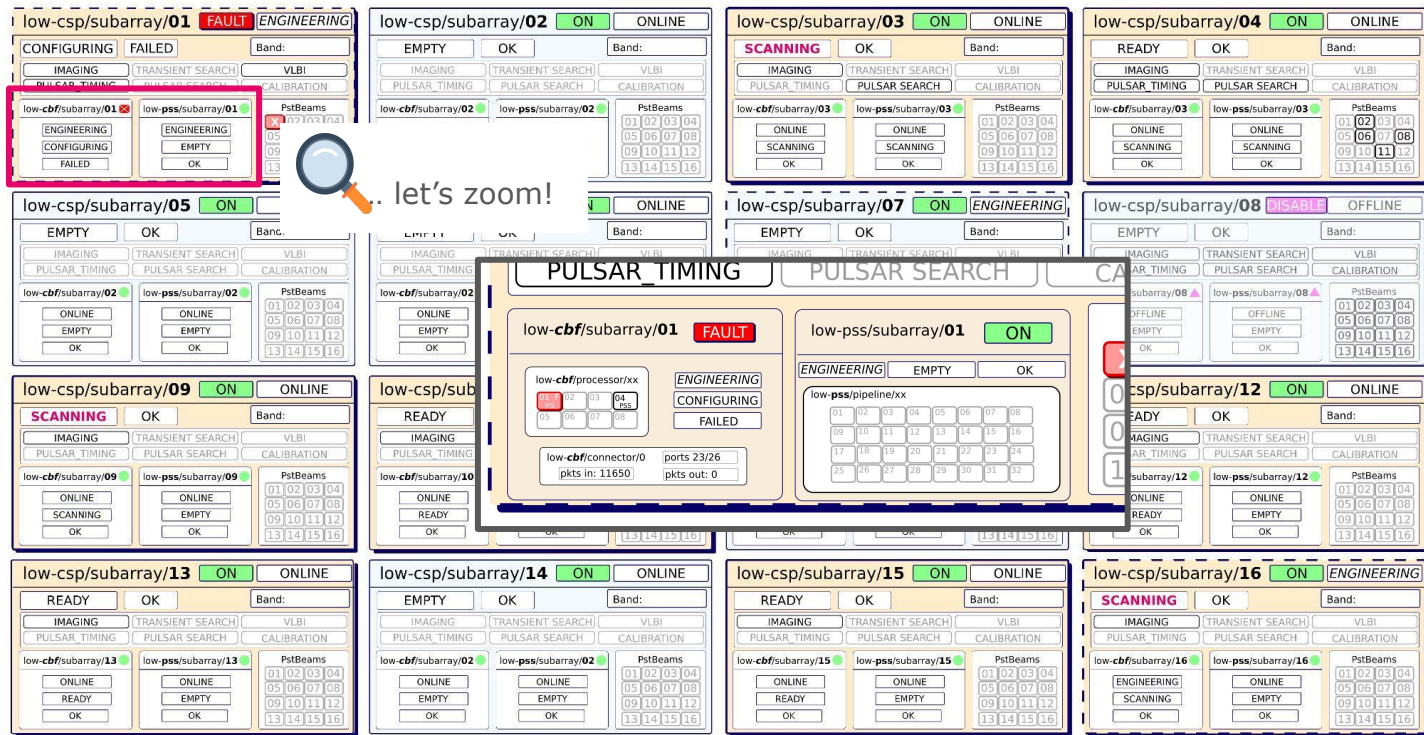
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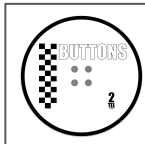
a prototype  
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# Collaborating over the world



OSO



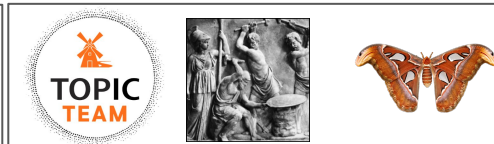
TMC



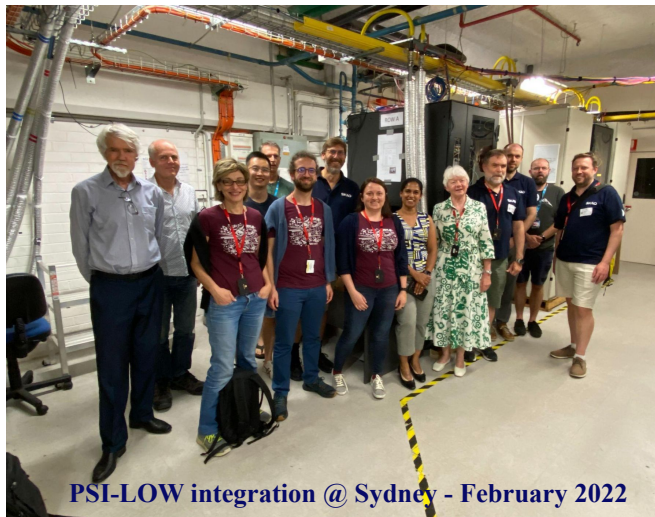
CSP SUBSYSTEMS



AIV



teams that interact with CREAM on a regular basis



PSI-LOW integration @ Sydney - February 2022



TMC Workshop @ Pune - May 2024



UI Workshop @ Australia - March 2025





# ...furthermore

- CSP.LMC developers are also in charge of PSS.LMC<sup>1</sup>



detection of first known Pulsar using CSP.LMC and PSS.LMC developed by CREAM TEAM

NOTE: PSS.LMC will control >1000 pulsar engines in the future

- Taranta developers will take over the SKA Alarm handling UI (IC@MS)

IC@MS  
logged as admin@gmail.com

Home Admin Configuration Logout

Search placeholder Search

Severity All State All Active since

Active alarms 16.05.2022, 08:40:09

Alarm	Severity	State	Active since	Description	Formula	Device
R3_BeamLoss	DEBUG	UNACK	Mon, 16 May 2022 08:07:06 GMT	The beam has been...	/S-37962/beamloss...	/S3/beamloss-01
R3_A1111111_CARBON_D100_AD_...alarm	ALARM	UNACK	Mon, 16 May 2022 08:09:22 GMT	Libera Interlock #14	R3-VACRUC-D2FE	/Libera/alarm-02
R3MAX_FORCE_Lock	ALARM	UNACK	Mon, 16 May 2022 08:09:54 GMT	ForceMAX #1 is locke...	/S-3086/forcemax...	/g30/watchdog-3...
R3_Energyspread	ALARM	UNACK	Mon, 16 May 2022 08:09:27 GMT	Energyspread too h...	/GCTU/CustomerAla...	/g30/watchdog-3...
R3_LOCK_R3_PSRB_HPS_FAULT	WARNING	UNACK	Thu, 12 May 2022 05:19:21 GMT	INTERLOCK_R3_PS...	R3-A111110CAB30...	/pps/interlock/alarm
R3_LOCK_EM_BUTTON_CAUSE_STOP	WARNING	UNACK	Thu, 12 May 2022 05:19:13 GMT		R3-A111110CAB30...	/pps/interlock/alarm



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**Thank you for your attention!**

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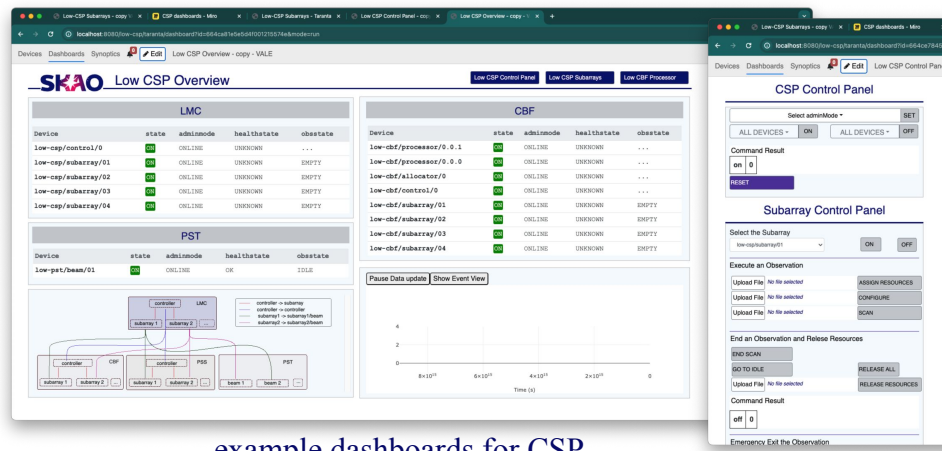


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SKAO

MAX IV



example dashboards for CSP

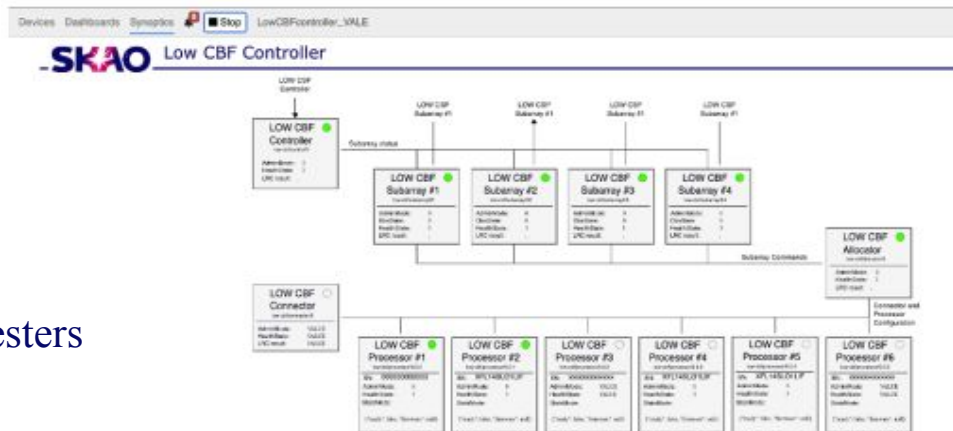
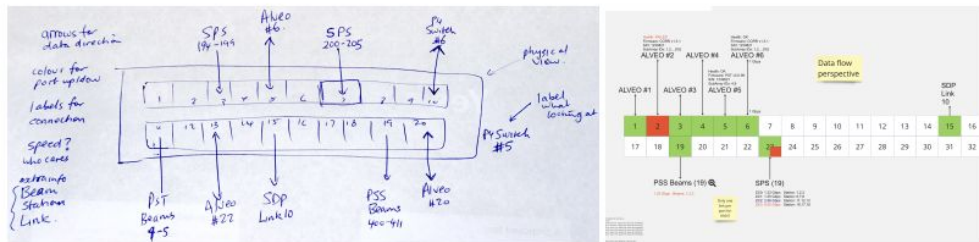


The new **synoptic view** enables the integration of **svg files** that reacts to the changes of the attributes of the TANGO Devices



# Creating engineering UIs: lean UX

The creation of User Interfaces for LOW-CSP has been experimented as a cross team collaboration using a **LeanUX** approach

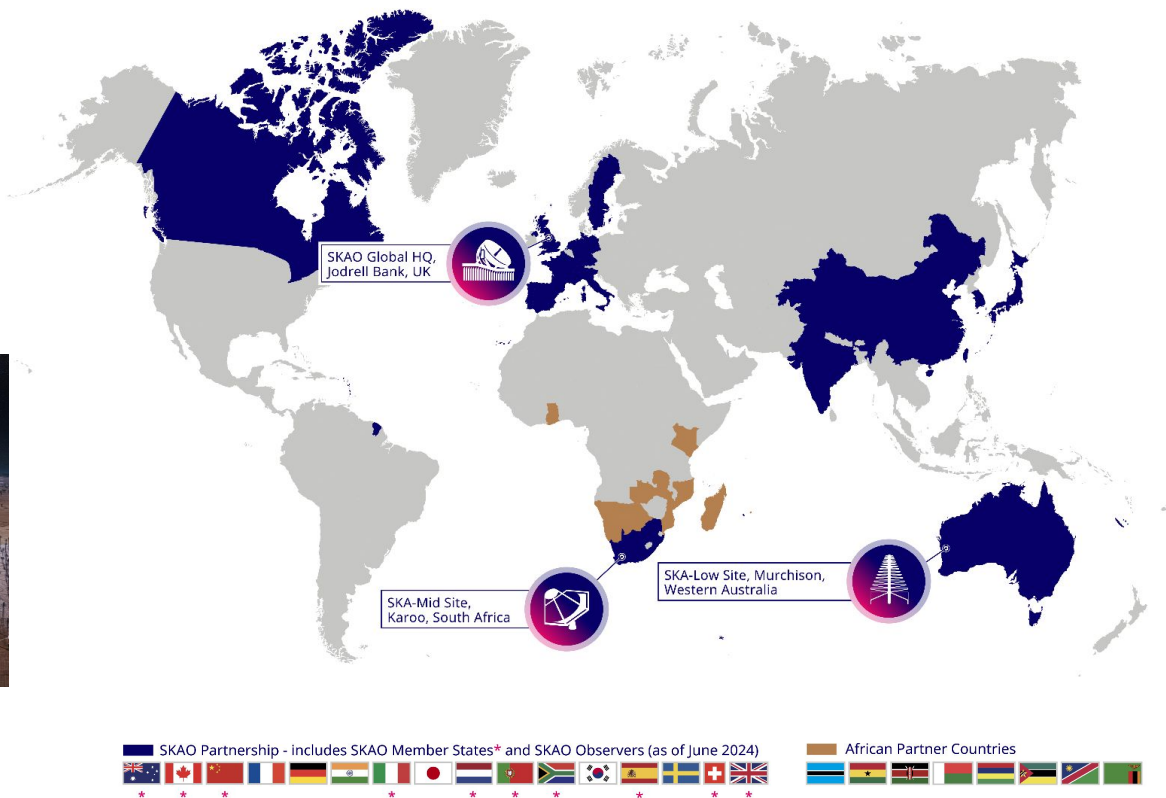


Taranta Users are both developer and testers



# The SKA Project

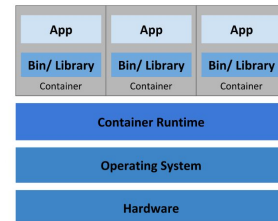
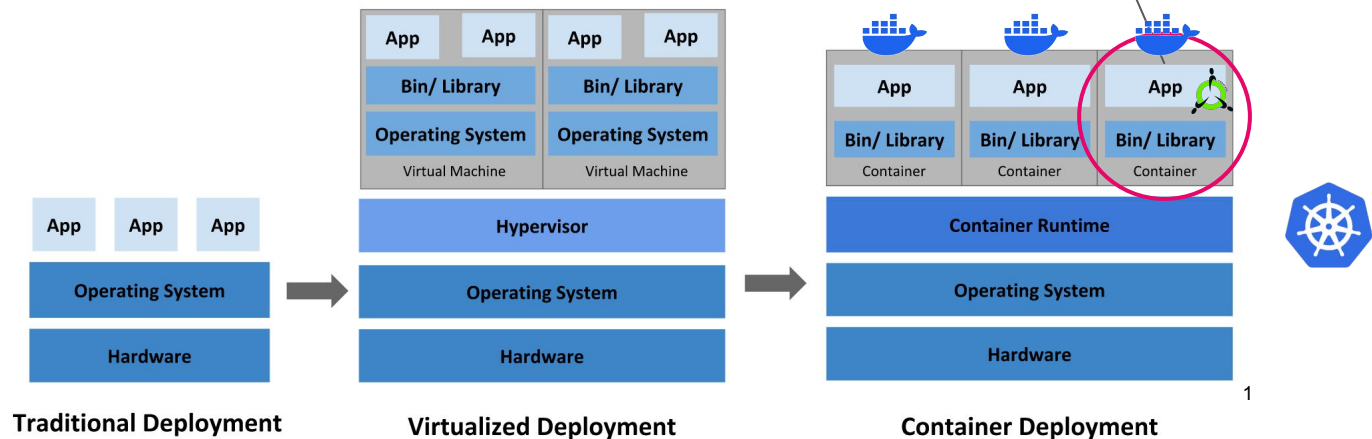
The Square Kilometer Array (SKA)  
is an international effort to  
construct the **two** world's *biggest*  
*radio telescopes*.



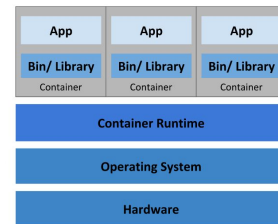


# Docker and Kubernetes

...a small digression



Container Deployment



Container Deployment

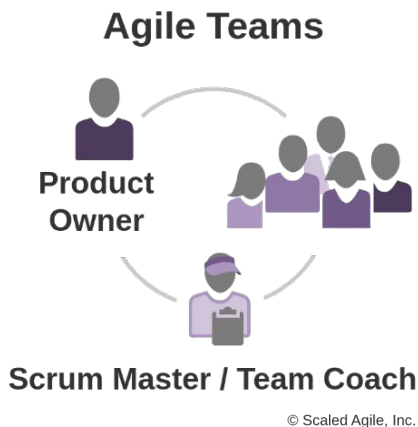
Kubernetes: 

- establishes the network between containers,
- allows shared storage,
- manage secrets,
- distributes workloads in cluster
- is self-healing,
- ensure scalability

<sup>1</sup><https://kubernetes.io/docs>



# The Agile Team



- each Agile Team is responsible for one or more SW Product;
- code is developed iteratively;
- Team plans the work within the ART<sup>1</sup> every 3 months (*Program Iteration - PI*);
- Team revise its PI plan every 2 weeks (*sprint*);
- the *Scrum Master* “helps implement and maintain Agile practices, [...] optimizes and improves team performance”<sup>2</sup>
- the *Product Owner* “contributes to the Vision and roadmap [...] and prioritize the team’s work”<sup>2</sup>.

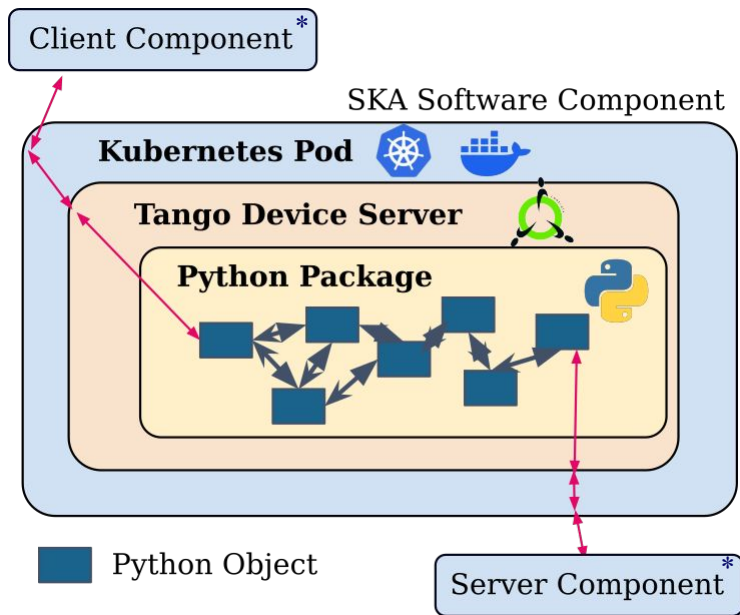


more about it: **tomorrow's** training session on “Agile Framework”  
conducted by Valentina Alberti and Matteo Di Carlo (**h14:00**)

<sup>1</sup> Agile Release Train    <sup>2</sup> <https://scaledagileframework.com/agile-teams/>



# Testing strategy of CSP.LMC



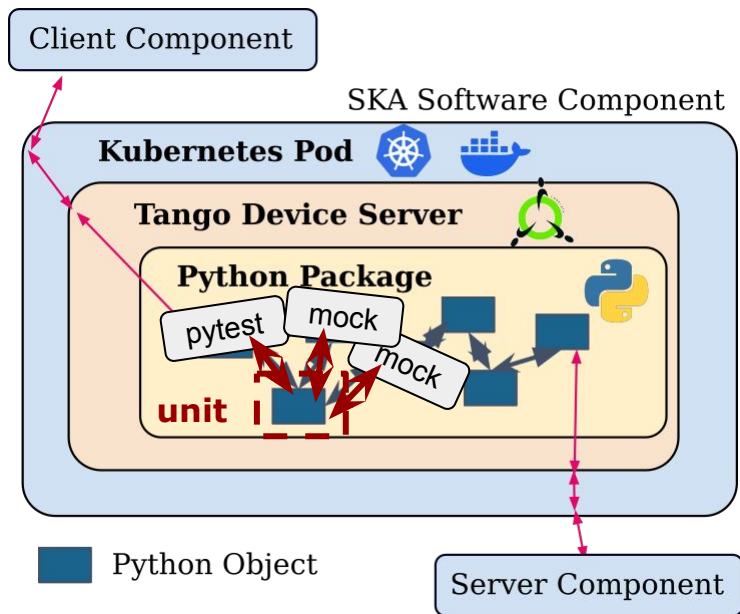
\* for simplicity only one server/client is reported



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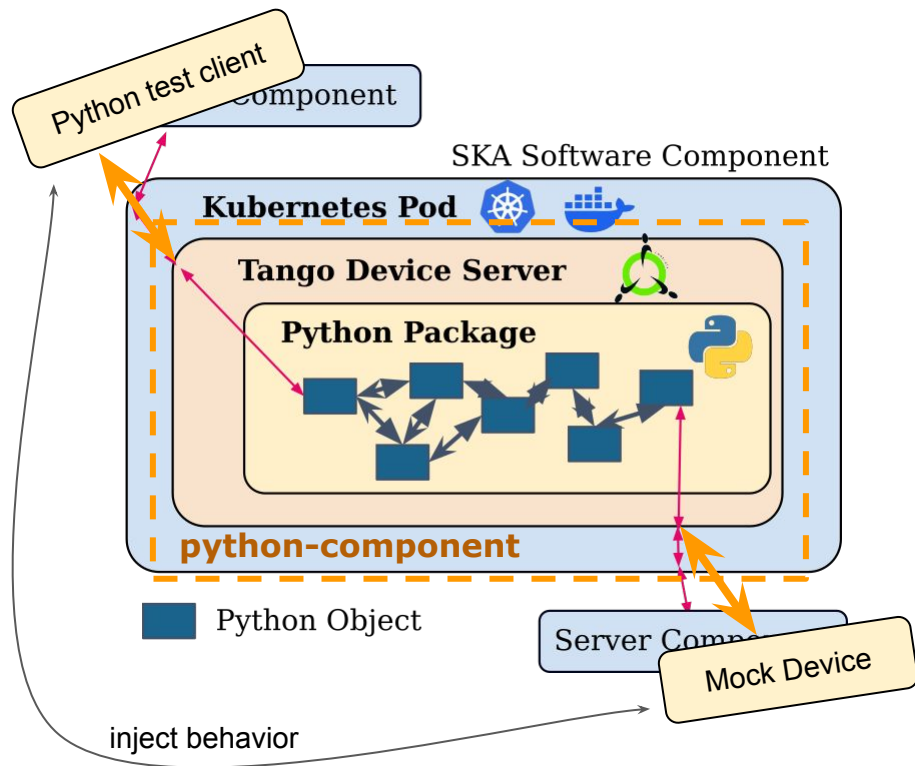
Tests are performed with a *multi-level strategy*:

- *unit* tests



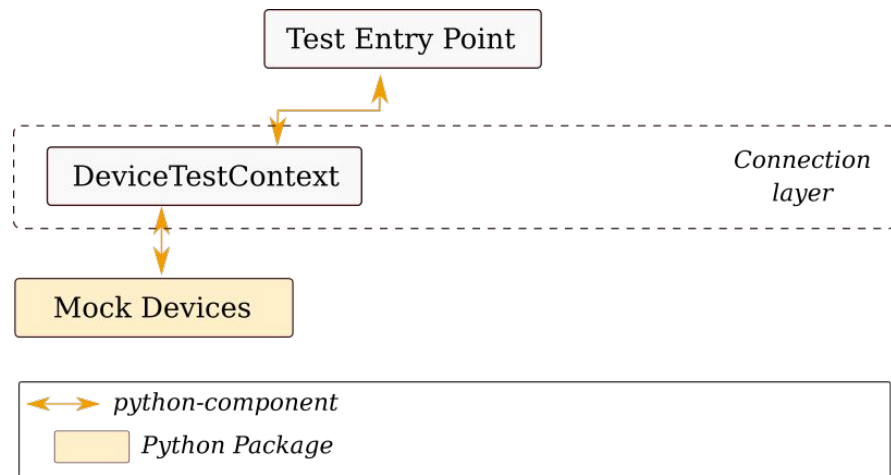


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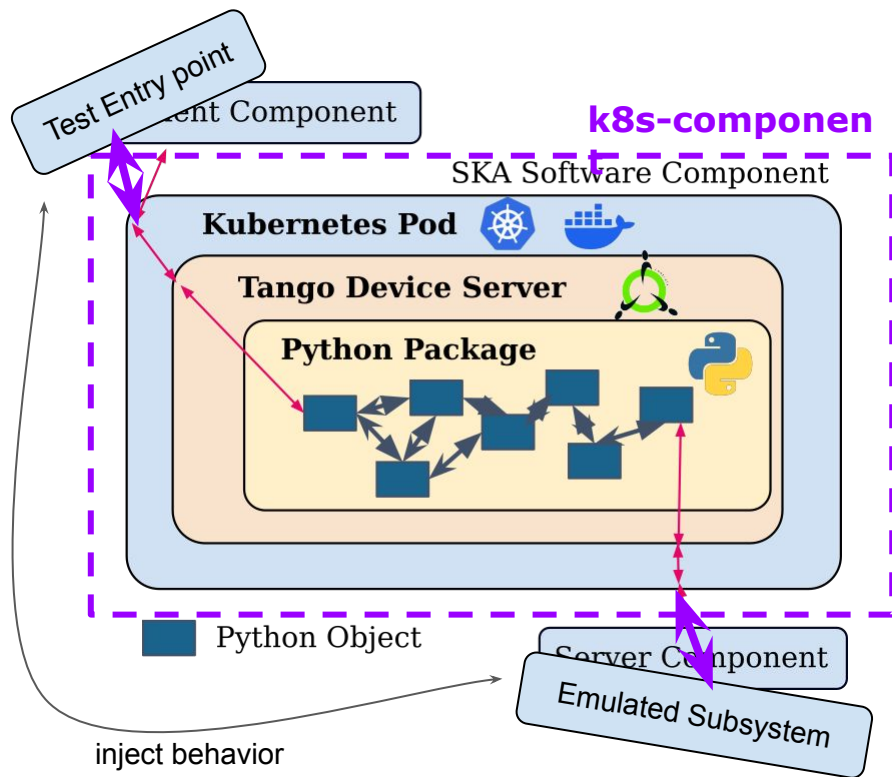
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- *python-component* tests



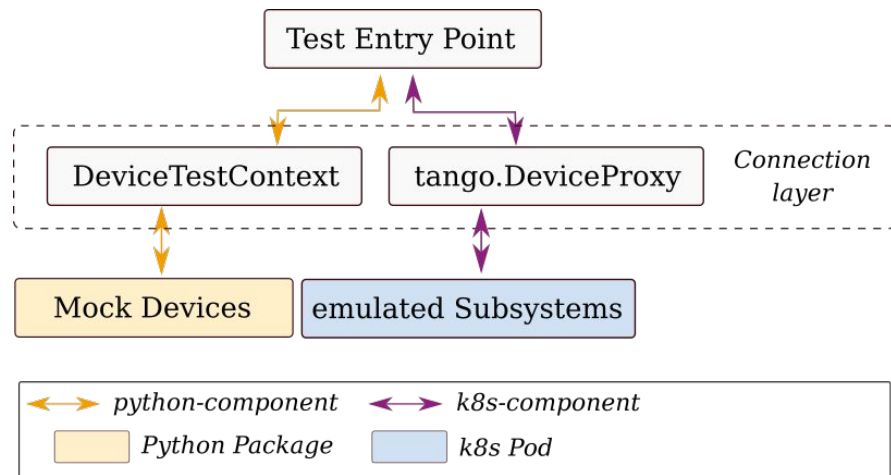


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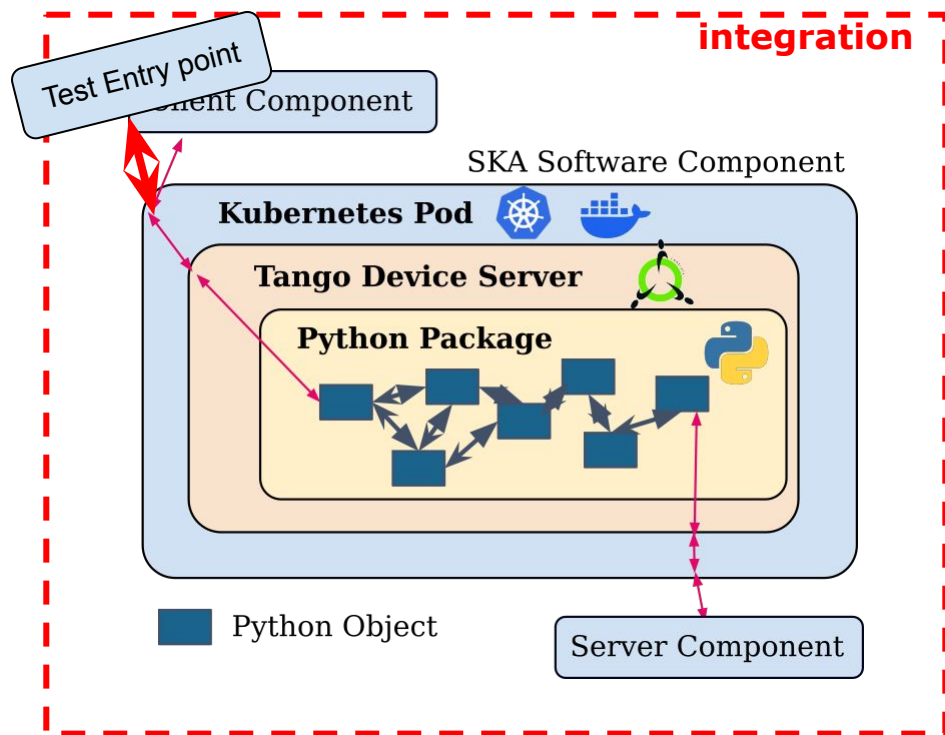
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- *python-component* tests
- *k8s-component* tests



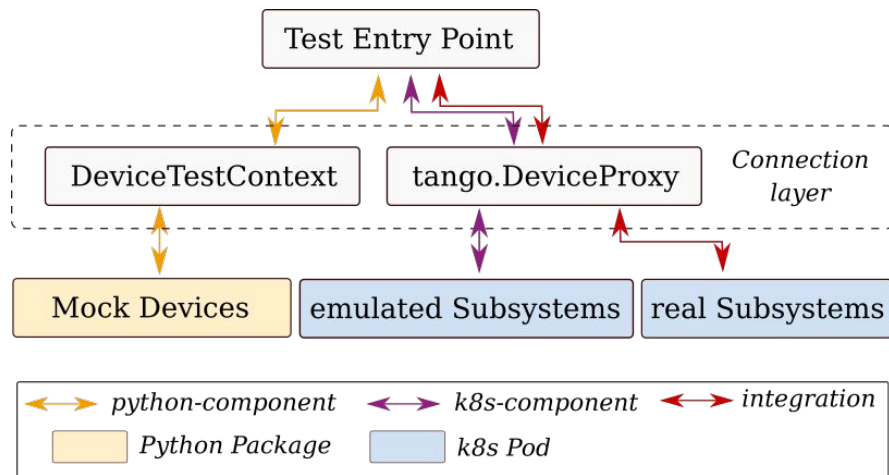


# Testing strategy of CSP.LMC



Tests are performed with a *multi-level strategy*:

- *unit* tests
- *python-component* tests
- *k8s-component* tests
- *integration* tests





# BDD testing

“The purpose of testing is to **increase confidence** for **stakeholders** through **evidence**”<sup>1</sup>

*Integration and component tests follow the Behaviour Driven Development (BDD) approach. They are written in the Gherkin language.*

✓	✓	<b>Given:</b> All subsystems are fresh initialized
✓	✓	<b>When:</b> On Command is issued on CspController
✓	✓	<b>Then:</b> CbfController longRunningCommandStatus is (0, COMPLETED)
✓	✗	<b>And:</b> CbfController state is ON
✓		<b>And:</b> CbfSubarray0 state is ON
Passed Failed		

Each “step” is translated to a specific Python function and can be utilised in different tests

Gherkin files can be used as **living documentation**

“regression” testing

A single failing test let the CI/CD pipeline to fail and prevent any MR to be effective!

<sup>1</sup>Dan North “We need to talk about testing”- dannorth.net



# “Test flakiness” and data mining

Tests **randomly fail** during CI/CD pipeline execution  $\longrightarrow$  “*test flakiness*”

test name	fail rate	num of execution	most failed step - mfs	mfs frequency
cspcontroller healthstate is unknown 1	0.9333	105	CspController HealthState is UNKNOWN	1.0
assignresources rejected on subarray01 without pst beams	0.6667	6	All subsystems are fresh initialized without PST beams	1.0
csp controller reports simulationmode	0.6667	111	CspController SimulationMode is FALSE	1.0
obsstate subscription on subarray01	0.0631	111	All subsystems are fresh initialized	1.0
state subscription on controller and subarray01	0.0541	111	CspController state is subscribed for archiving	0.5
configure rejected on ready subarray01 with pst beams	0.0472	106	All subsystems are fresh initialized with PST beams	1.0
configure rejected on idle subarray01 with pst beams	0.036	111	All subsystems are fresh initialized with PST beams	1.0
assignresources rejected on subarray01 with pst beams	0.036	111	All subsystems are fresh initialized with PST beams	1.0
all commands on subarray01 with pst beam	0.036	111	All subsystems are fresh initialized with PST beams	1.0
csp controller reports healthstate	0.027	111	All subsystems are fresh initialized	1.0

*an example of test statistics: the 10 most failing tests*

data mining on test result helps in providing:

- better metrics on test quality;
- hints on “deeply hidden” bugs



*Predictive maintenance* also for software?



# About Tango Controls



"Tango Controls is an object oriented, *distributed control system framework*."

- it is built around the concept of **devices**, that run into device servers
  - each device has *state machine, commands , pipes and attributes*
- each Tango system has a centralised **database** that:
  - stores configuration data to start up device servers;
  - acts as a name server storing the dynamic network addresses;
- uses CORBA (synchronous) and ZMQ (asynchronous) to communicate between device server and clients;
- kernel written in C++;
- can be programmed in C++, **Python** or Java.

