

EMU and Euclid: Detection of a radio-optical galaxy clustering cross-correlation signal between EMU and Euclid

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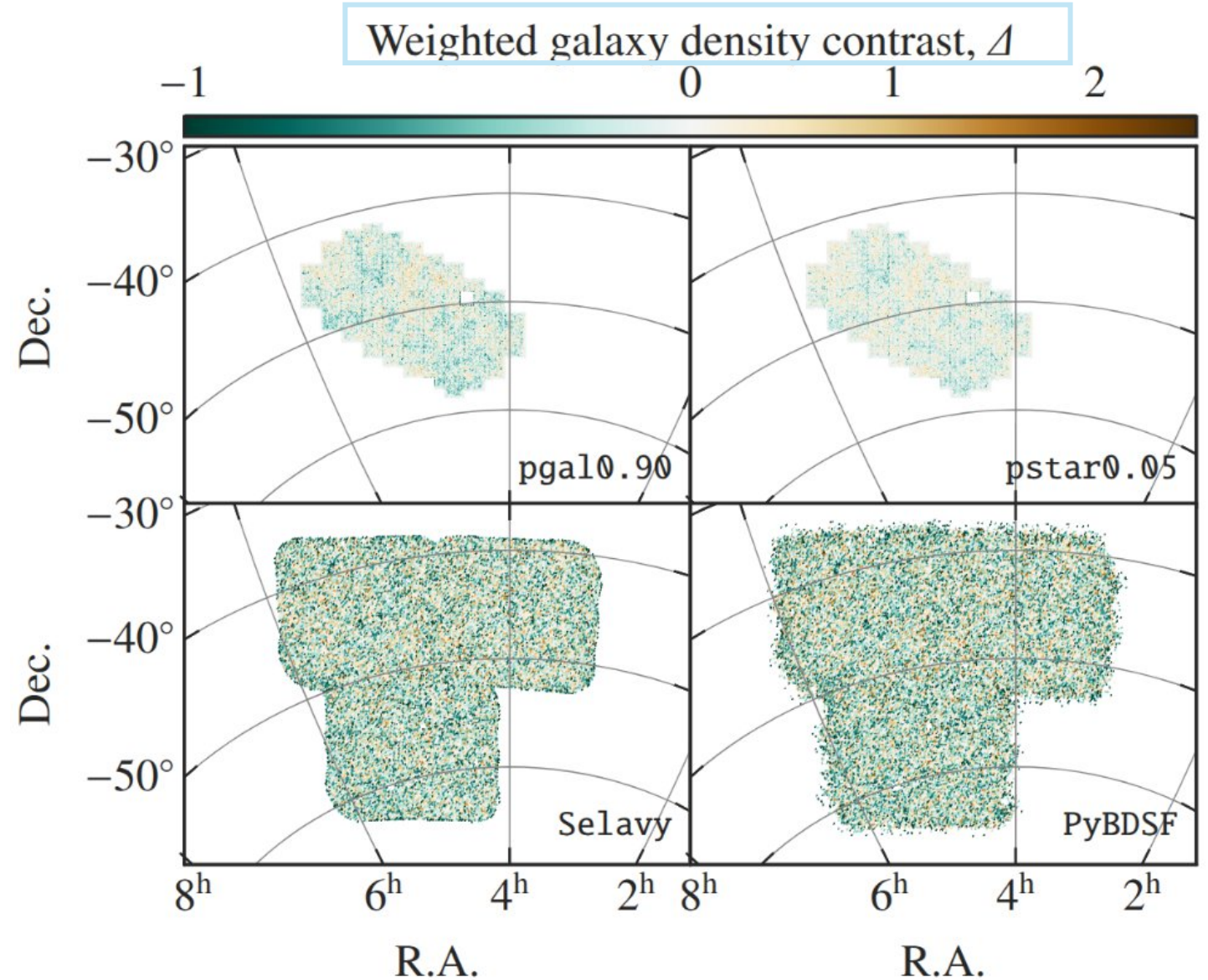
Data sets

- *Euclid Deep Field South* ($p_{gal}0.90$ and $p_{star}0.05$)
- *Evolutionary Map of the Universe (EMU) Main Survey* data:
 - Survey of radio sources in the Southern Hemisphere with ASKAP at 947 MHz
 - Flux cut at $S > 0.14$ mJy
 - $n_{gal} \sim 0.3 \text{ gal/arcmin}^2$
 - Two source finder algorithms: `SeLavy` and `PyBDSF`
 - Weight maps to account for varying completeness in the survey

Data sets

- *Euclid Deep Field South* (pgal0.90 and pstar0.05)
- *EMU Main Survey* (Selavy and PyBDSF)

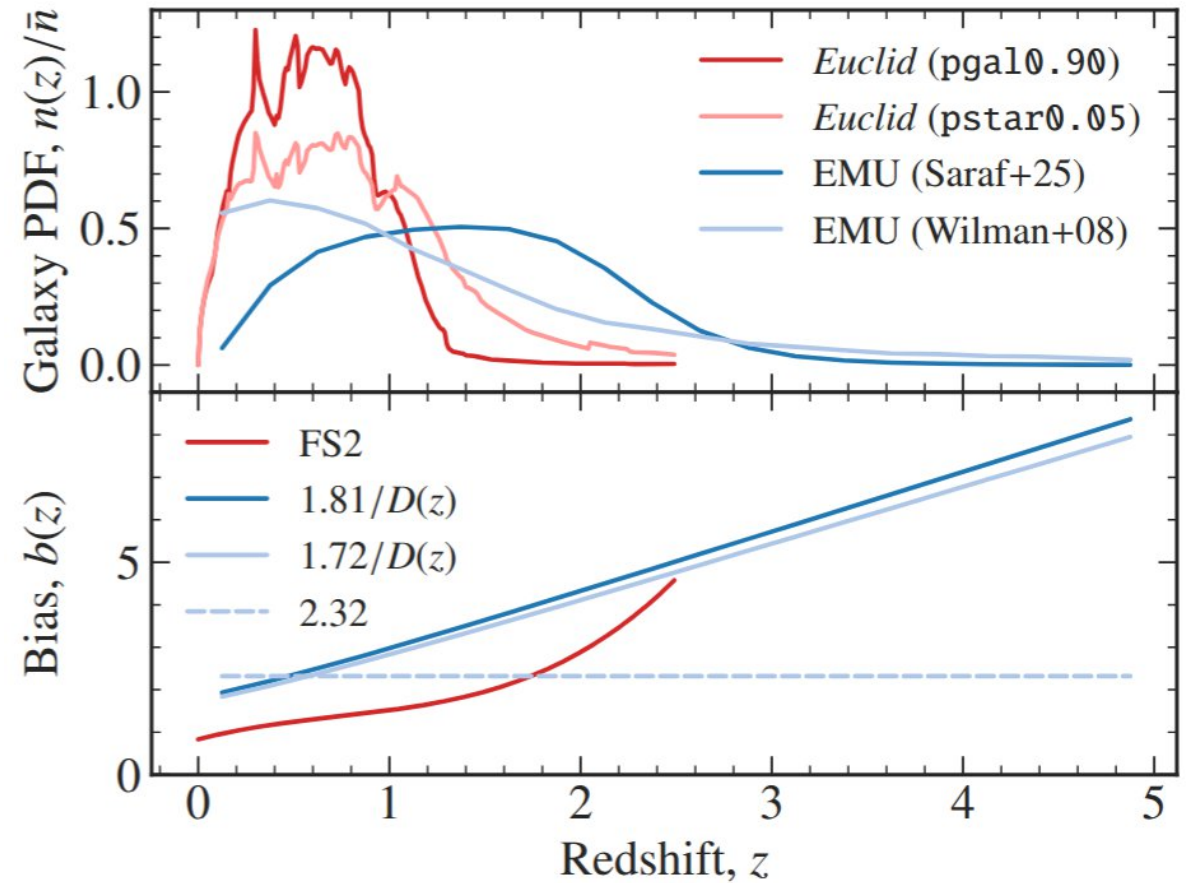
$$\Delta(\hat{n}) = \frac{N(\hat{n})}{w(\hat{n}) \bar{N}} - 1$$



Theoretical modeling

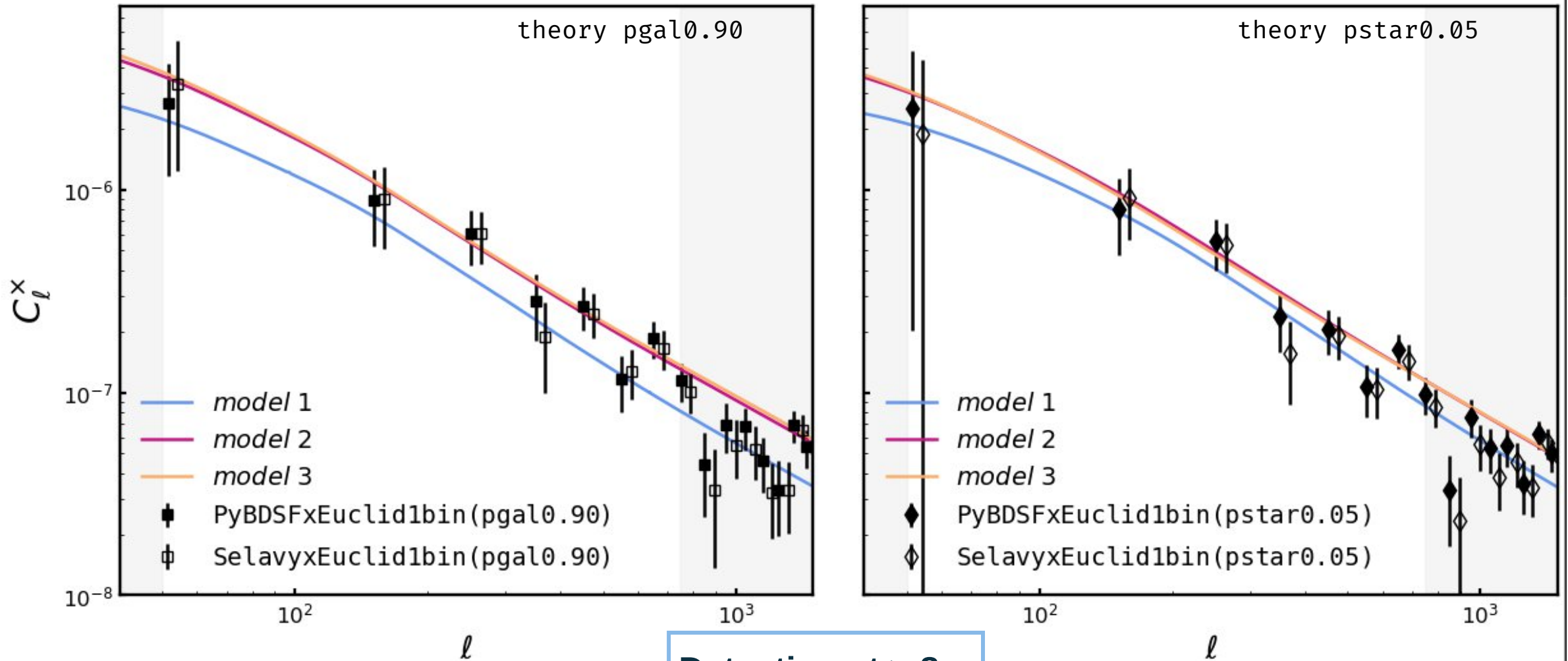
$$C_{\ell}^{AB} \simeq \int \frac{c dz}{H(z)} W_A(z) W_B(z) P\left(k = \frac{\ell + 1/2}{r(z)}, z\right)$$

$$W_A(z) = \frac{H(z) b_A(z) n_A(z)}{c r(z) \bar{n}_A}$$



- **Model 1:** analytical $n_{\text{EMU}}(z)$ and $b_{\text{EMU}}(z) = 1.81/D(z)$ from *Saraf+*, 2025
- **Model 2:** SKADS $n_{\text{EMU}}(z)$ from *Wilman +*, 2008 and $b_{\text{EMU}}(z) = 1.72/D(z)$ from *Tanidis +*, 2024
- **Model 3:** SKADS $n_{\text{EMU}}(z)$ from *Wilman +*, 2008 and $b_{\text{EMU}}(z) = 2.32$ from *Tanidis +*, 2024

Measured angular power spectra



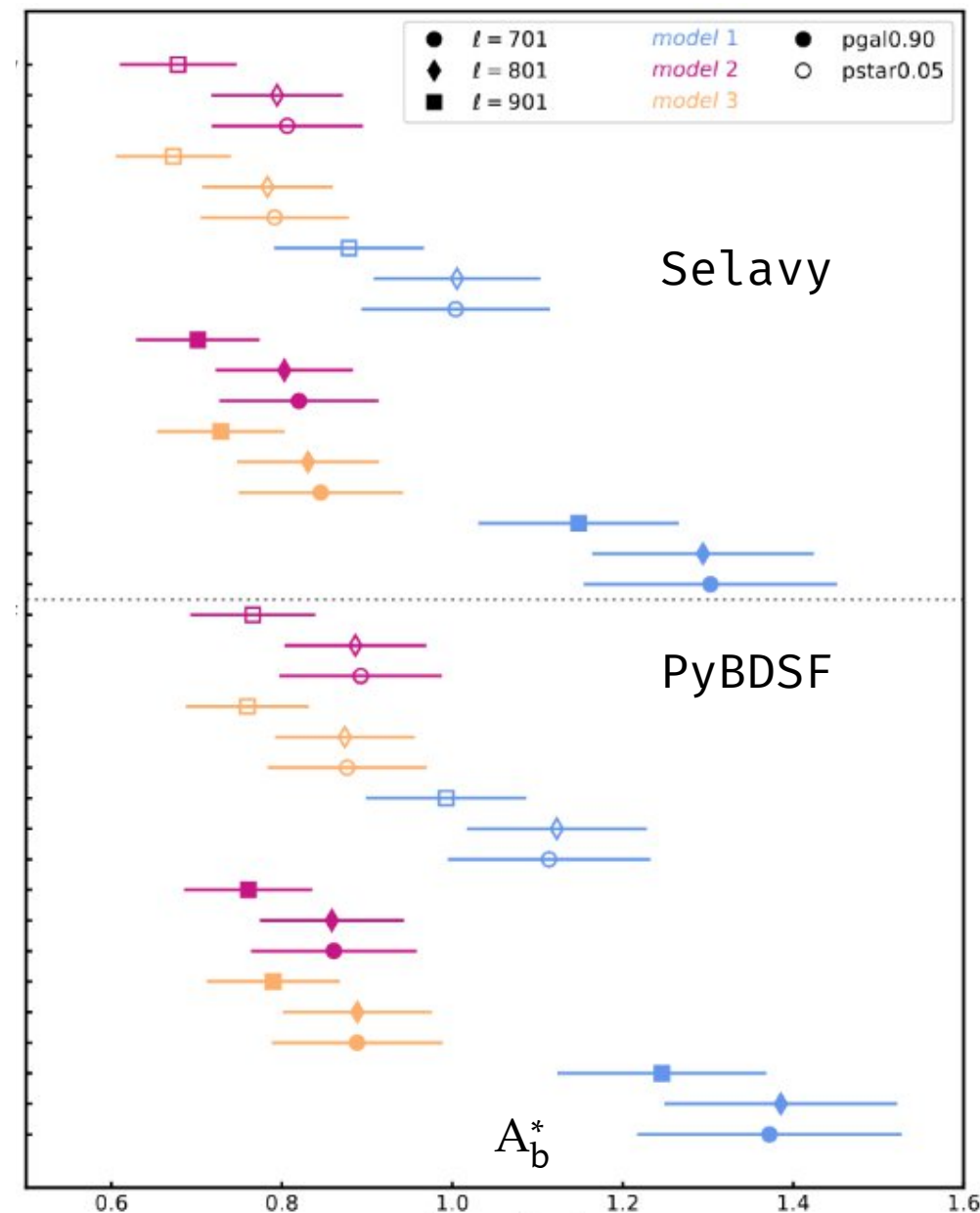
Detection at $> 8 \sigma$

Overall amplitude fitting

$$A_b^* = \frac{\mathbf{t}^t \Sigma^{-1} \mathbf{d}}{\mathbf{t}^t \Sigma^{-1} \mathbf{t}}$$

$$\sigma_{A_b^*} = \frac{1}{\sqrt{\mathbf{t}^t \Sigma^{-1} \mathbf{t}}}$$

- $\mathbf{t}$ theory vector
- $\mathbf{d}$ data vector
- Σ covariance from data



Cross shot noise estimates

Assuming the samples to be Poissonian, the cross-shot noise is (see *Harrison+, 2016; Urban+, 2024*)

$$N_{\ell}^{AB} = \frac{\bar{n}_{A \wedge B}}{\bar{n}_A \bar{n}_B} \longrightarrow \text{angular number density of objects in common between the two catalogues}$$

Being Euclid the densest survey, and since we lack a cross-matched catalogue of EMU sources, we introduce the parameter

$$f_{\Lambda} = \frac{\bar{n}_{EMU \wedge Euclid}}{\bar{n}_{EMU}} \longrightarrow \frac{f_{\Lambda}}{\bar{n}_{Euc}} \leq \frac{1}{\bar{n}_{Euc}} \approx \begin{cases} 8.0 \times 10^{-9} \text{ sr}^{-1} & \text{for pgal0.90} \\ 4.4 \times 10^{-9} \text{ sr}^{-1} & \text{for pstar0.05} \end{cases}$$

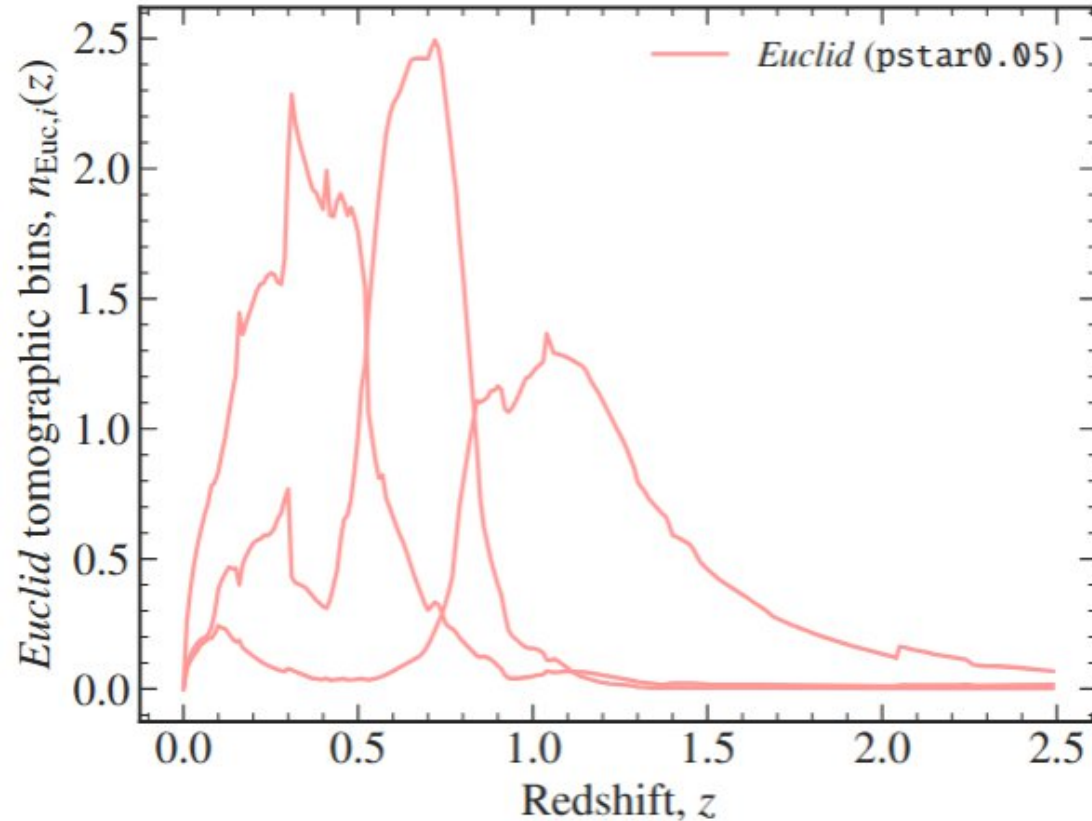
Overall amplitude and shot noise fitting

$$\boxed{m = A_b t + C_{\text{shot}}^{\times}} \xrightarrow{\chi^2 \text{ minimization}} \boxed{\vartheta^* = (\mathbf{T}^\dagger \Sigma^{-1} \mathbf{T})^{-1} \mathbf{T}^\dagger \Sigma^{-1} d}$$

<i>Euclid</i>	EMU	ℓ_{max}	$A_b^* \pm \sigma_{A_b^*}$		3- σ bounds on $C_{\text{shot}}^{\times}$ [sr ⁻¹]		$\chi^2/\text{d.o.f.}$	
			PyBDSF	Selavy	PyBDSF	Selavy	PyBDSF	Selavy
pgal0.90	<i>Model 1</i>	901	1.54±0.27	1.53±0.27	<4.93e-08	<3.92e-08	1.21	1.19
	<i>Model 2</i>	901	1.03±0.18	1.04±0.18	<4.45e-08	<3.32e-08	1.23	1.16
	<i>Model 3</i>	901	1.01±0.18	1.02±0.18	<4.30e-08	<3.14e-08	1.23	1.16
pstar0.05	<i>Model 1</i>	901	1.29±0.21	1.20±0.20	<3.20e-08	<2.58e-08	1.36	1.57
	<i>Model 2</i>	901	1.06±0.17	1.00±0.17	<2.63e-08	<2.00e-08	1.37	1.56
	<i>Model 3</i>	901	1.10±0.18	1.03±0.17	<2.42e-08	<1.79e-08	1.37	1.55

EMU N(z) estimates

Including Euclid tomographic bins (3bin configuration)



- *Baseline model* (Alonso +, 2021, and Saraf +, 2025)

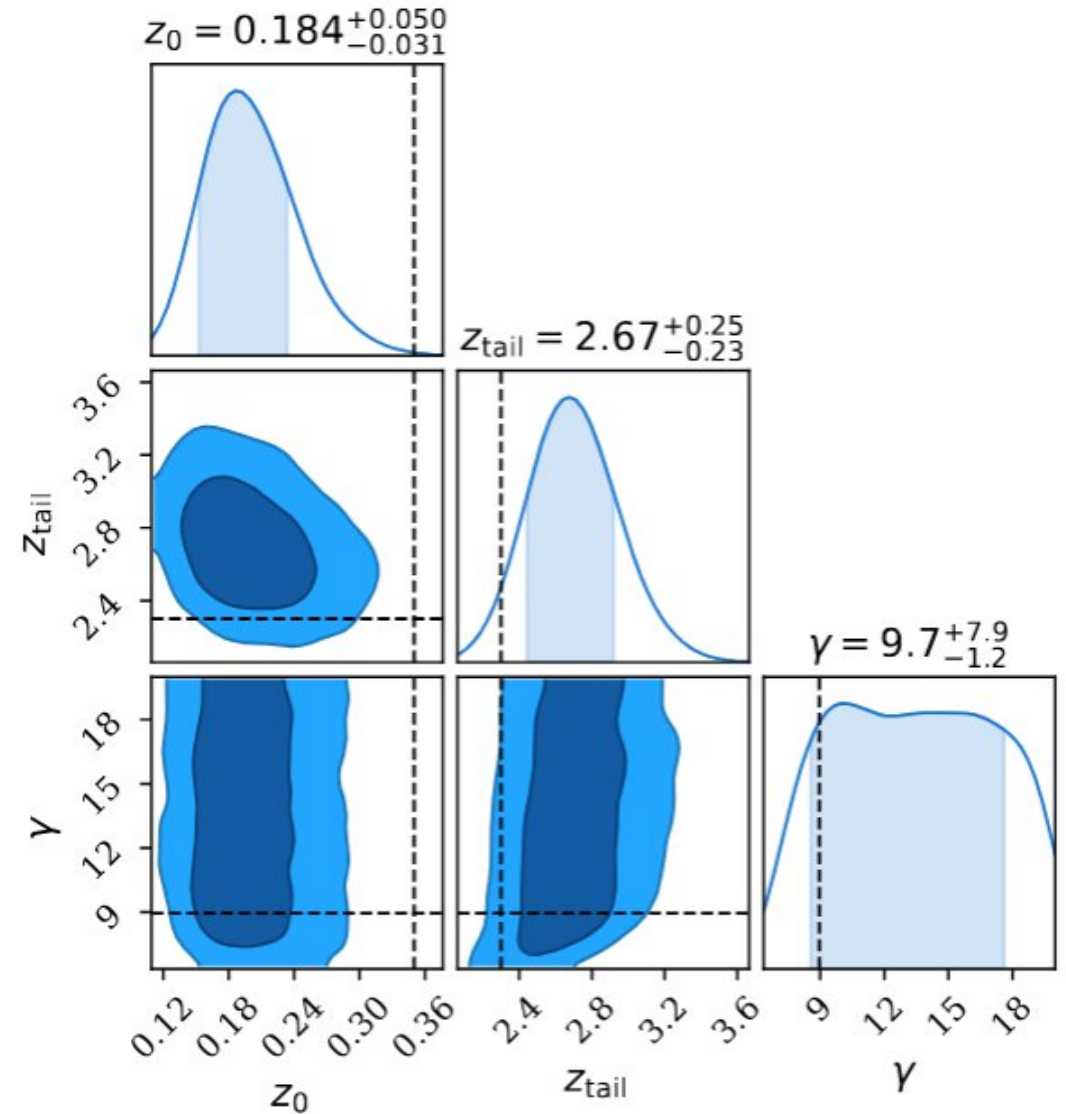
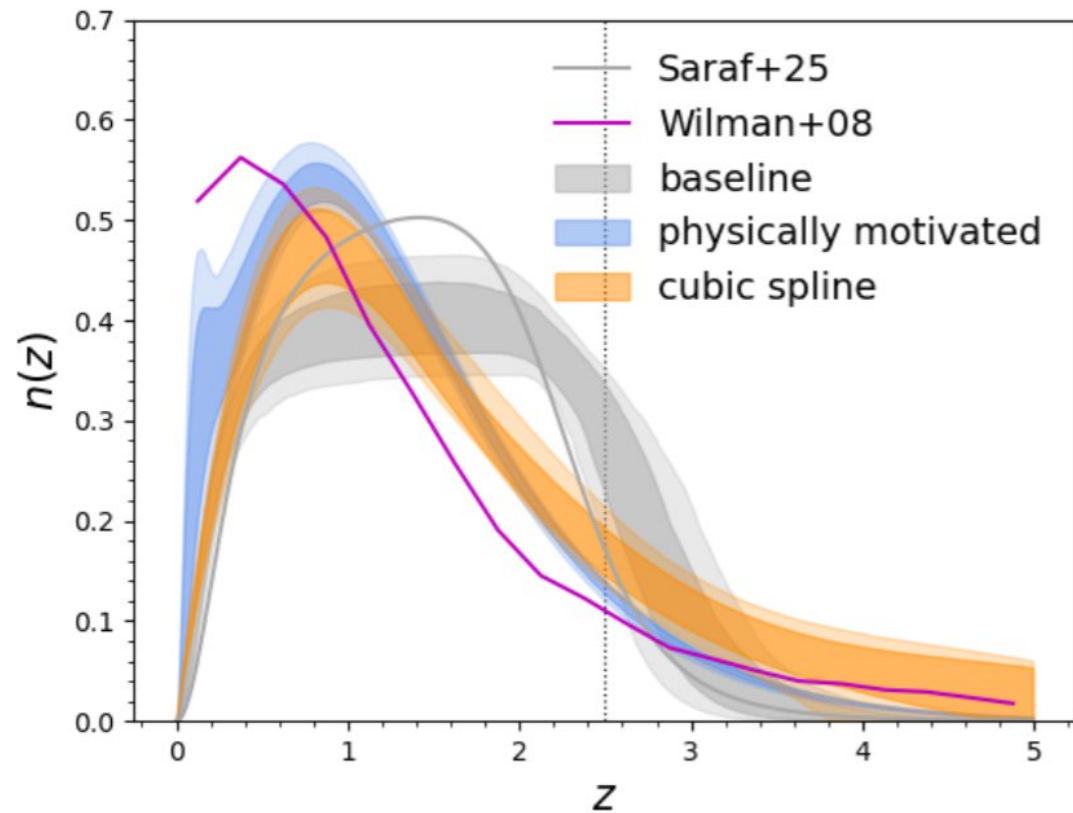
$$n_{\text{EMU}}(z) \propto \frac{(z/z_0)^2}{1 + (z/z_0)^2} \frac{1}{1 + (z/z_{\text{tail}})^\gamma}$$

- *Physically motivated* including two different populations: SFG and AGNs

$$n_{\text{EMU}}(z) \propto \frac{z^2}{1 + z} \left[\exp\left(-\frac{z}{z_0}\right) + \frac{r^2}{(1 + z)^a} \right]$$

- *Cubic spline* with nodes at the center of redshift bins

EMU $N(z)$ estimates



Conclusions

- First measurement of cross-correlation angular power spectrum between Euclid and EMU
- High significance of the detection for all configurations
- Some final tests before wrapping up the paper (e.g. *covariance estimation*)