



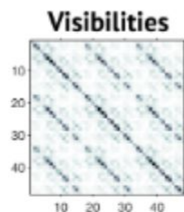
Separating Point Source Contaminants at the Visibility Level

Shreyam Parth Krishna

SKA Cosmology SWG Meeting 2024; 4/11/24; Nice, France

Bluebild Algorithm

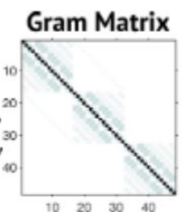
- Solves for $I(r)$ in $\int_{\mathbb{S}^k} I(r) e^{-j\langle r, p_i - p_j \rangle} dr = V_{ij}$ by framing a generalised eigenvalue problem and decomposing visibilities into different eigenvectors, via fPCA. Eigenvector + sampling operator gives eigenfunctions. These give eigenimages - independent and sorted by energy. Can be filtered.



α_i

$=$

λ_i



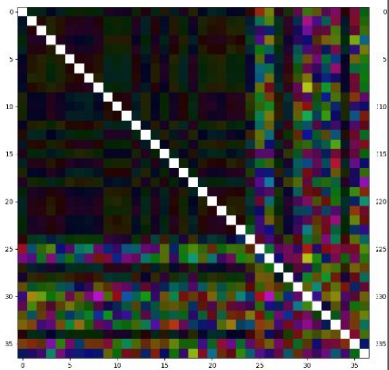
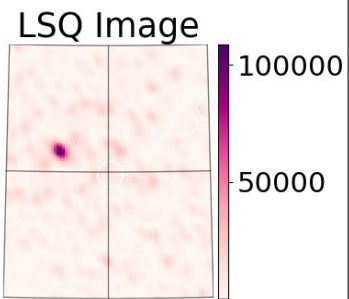
α_i

Normalised
Eigenfunctions

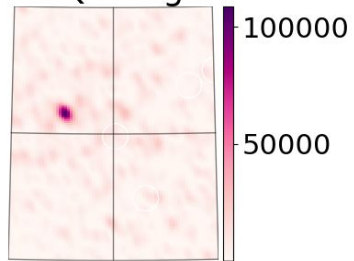
$$\epsilon_m = \Psi \alpha_m$$

$$\hat{I}_{lsq}(r) = \sum_m \lambda_m |\epsilon_m(r)|^2 = \sum_m \lambda_m |\Psi \alpha_m|^2$$

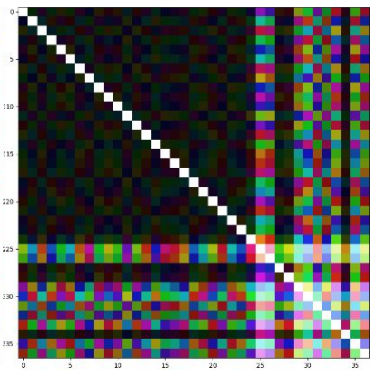
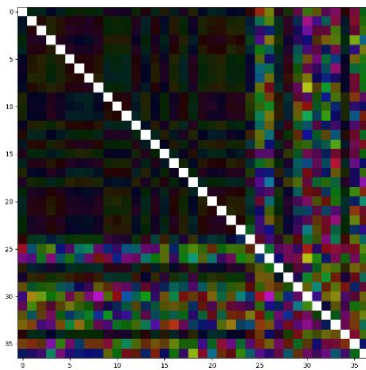
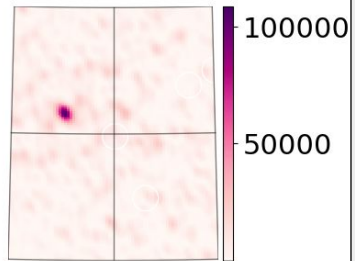
- Flexible continuous spherical imager for interferometric applications; 3D nuFFT Type-3 - no w approximation/stacking



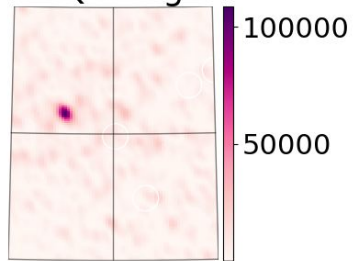
LSQ Image



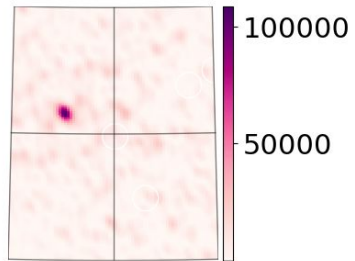
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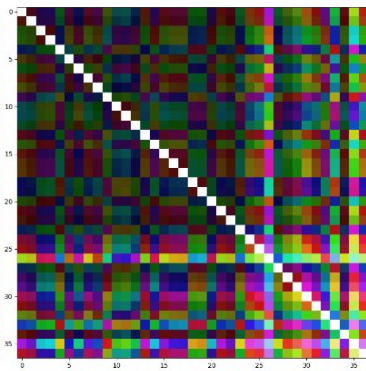
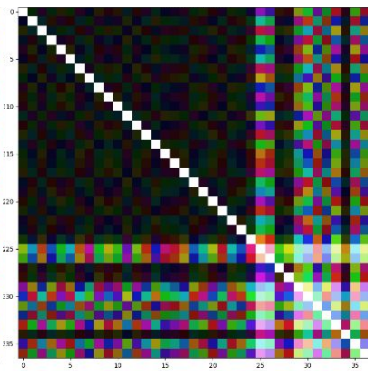
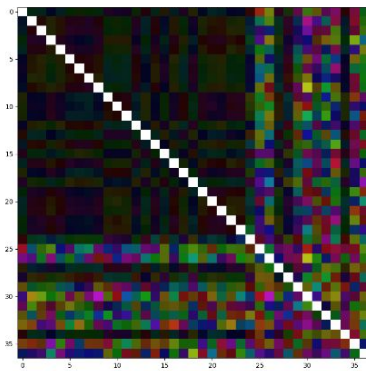
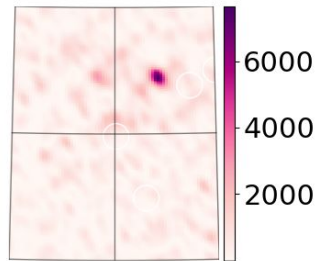
LSQ Image



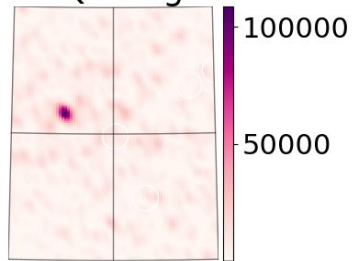
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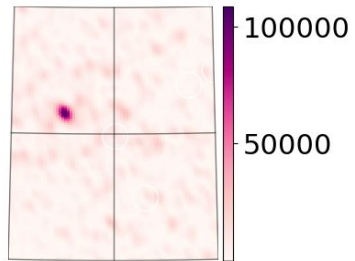
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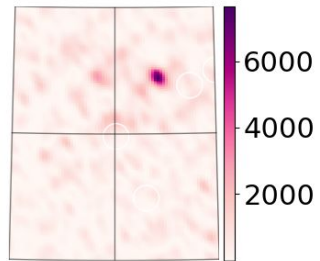
LSQ Image



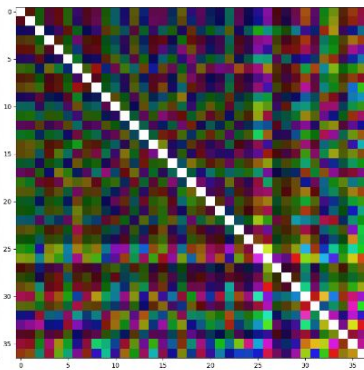
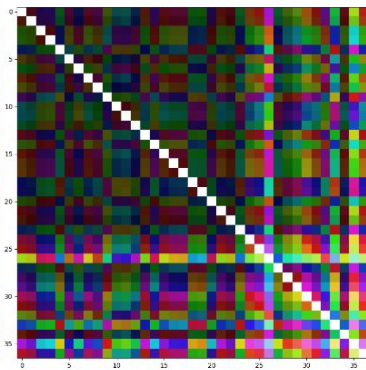
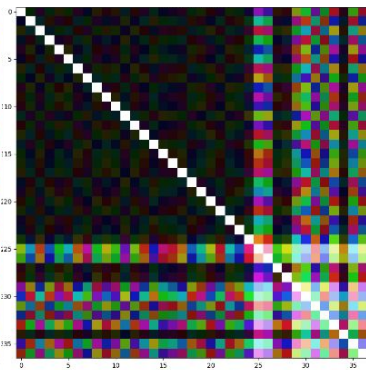
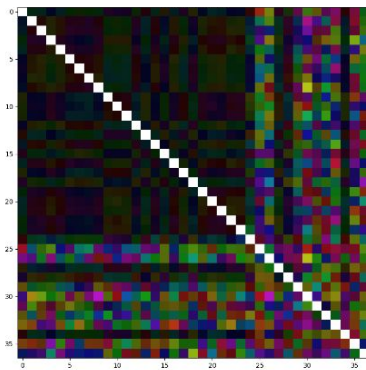
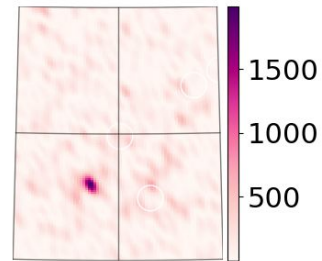
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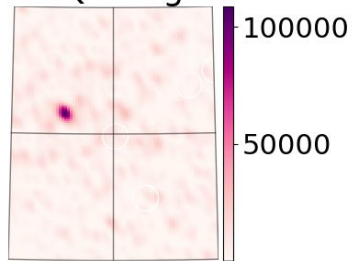
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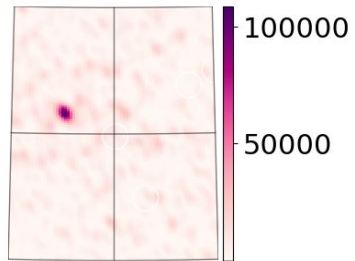
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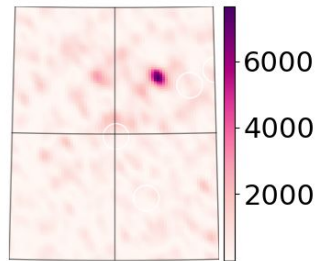
LSQ Image



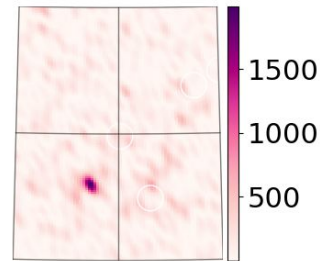
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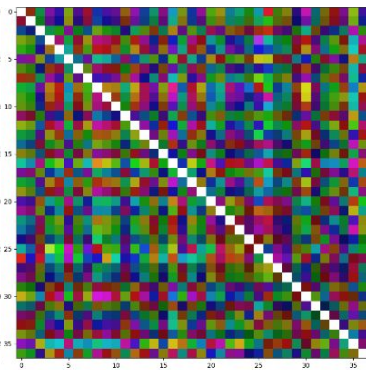
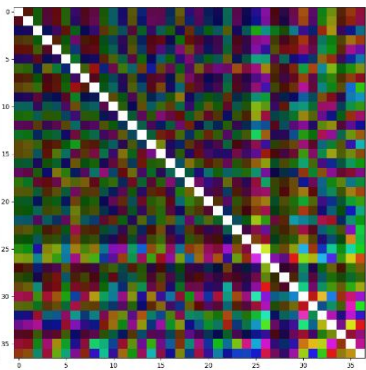
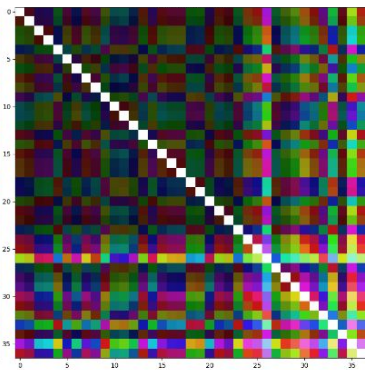
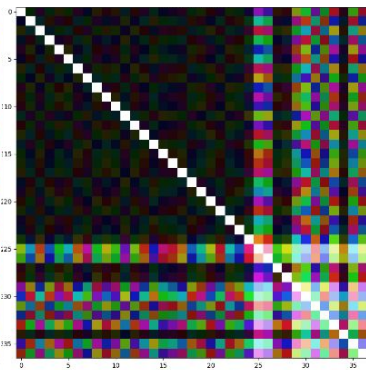
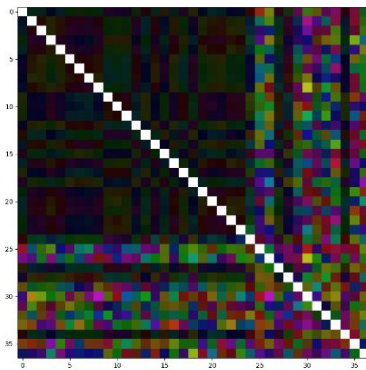
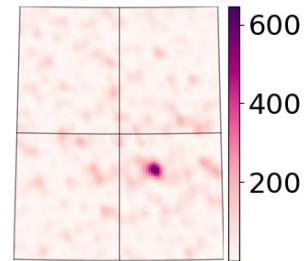
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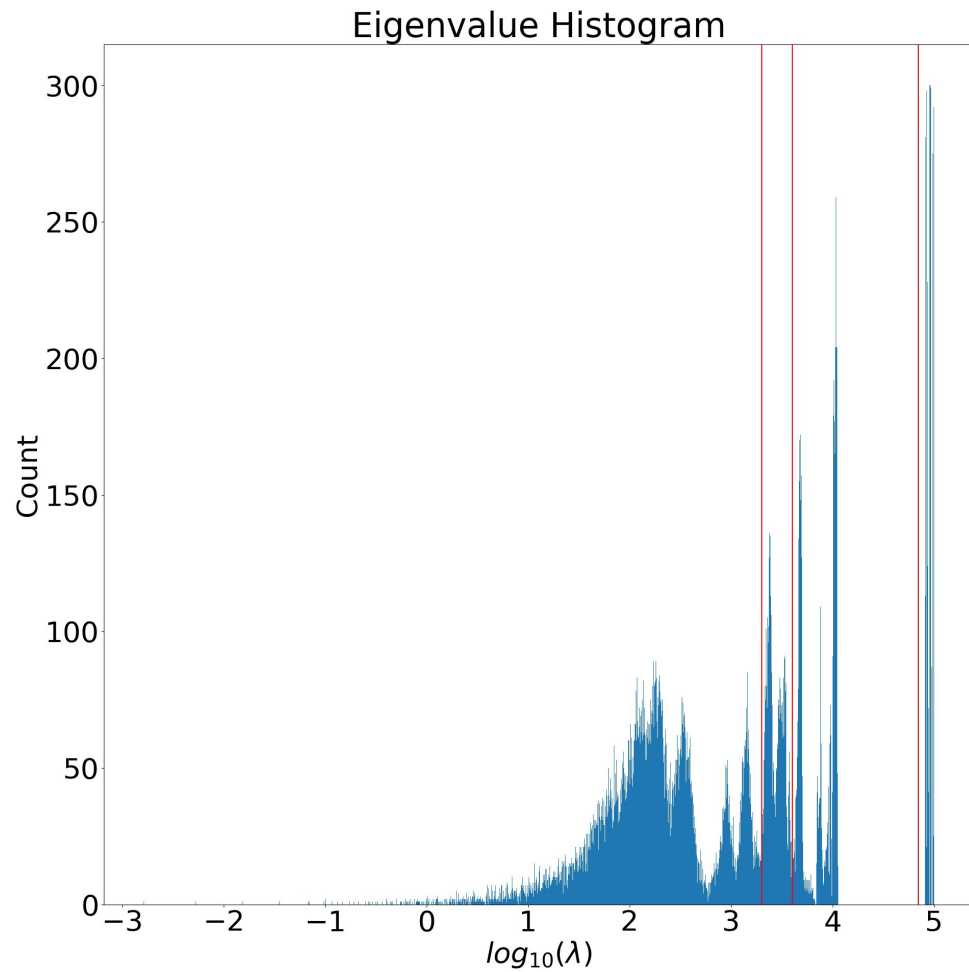


Level = 2



Level = 3





Bluebild Imaging Plus Plus (BIPP)

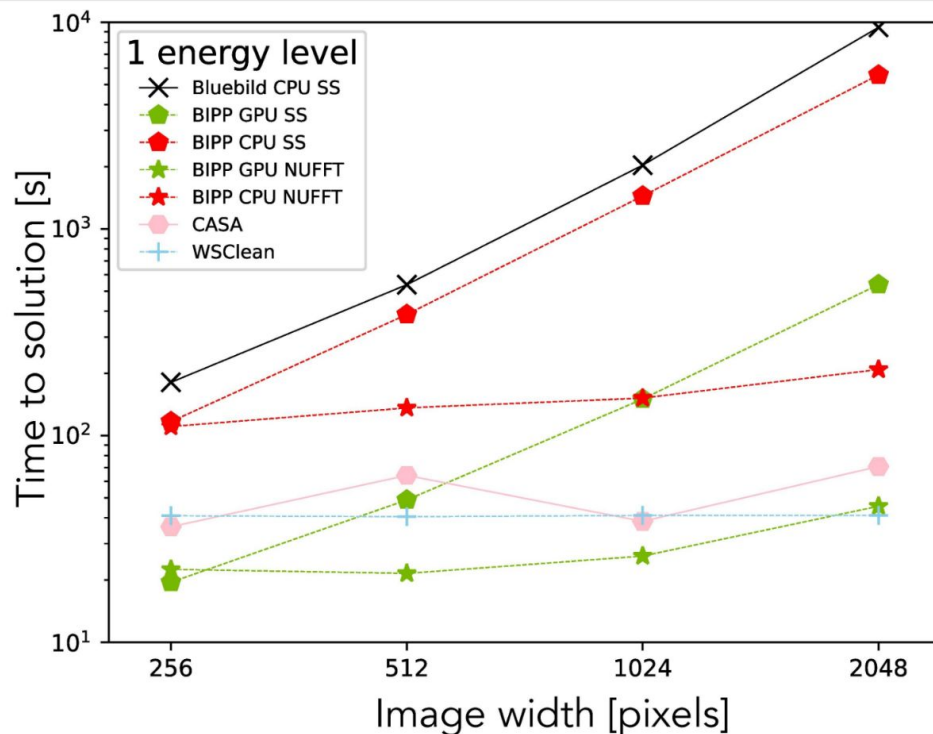
- **C++ ported** version with **python wrapper** for wider community release
- **HPC implementation** with support for CUDA (NVIDIA) and HIP (AMD)
- **MPI Parallelism** and **Domain partitioning** inbuilt
- No deconvolution - only dirty images
- **Github:** <https://github.com/epfl-radio-astro/bipp>
- **Arxiv:** <https://arxiv.org/pdf/2310.09200>

Bluebild Imaging Plus

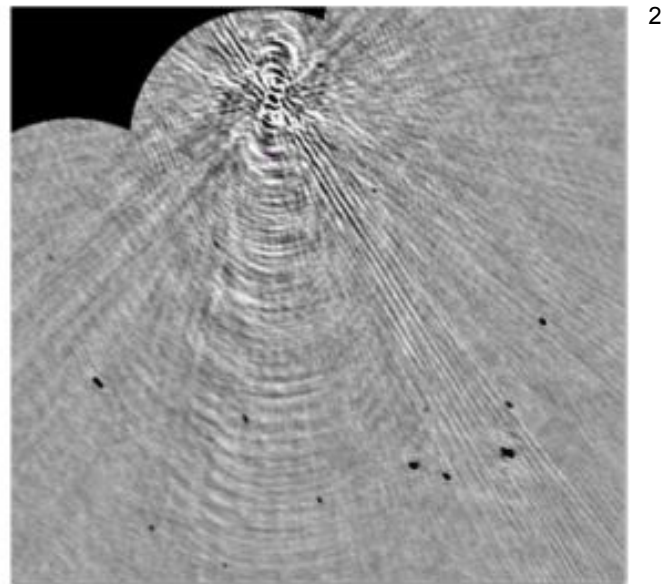
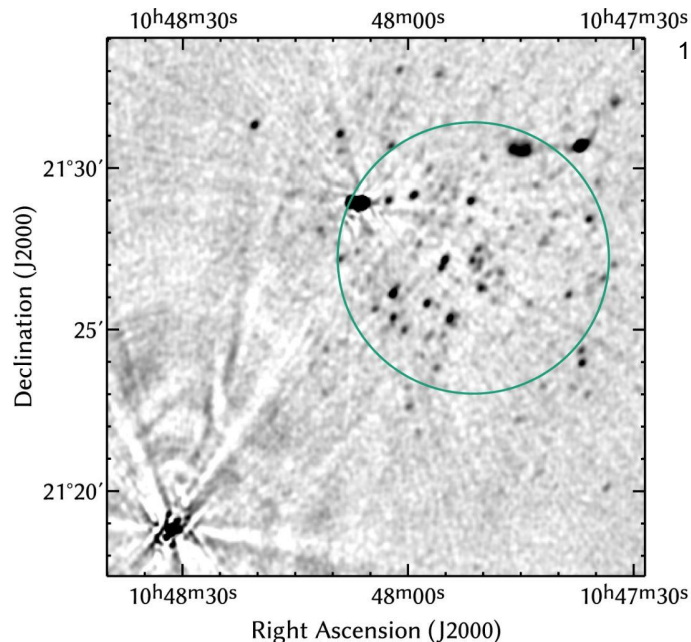
- **C++ ported** version with **pythor**
- **HPC implementation** with **supp**
- **MPI Parallelism** and **Domain p**
- No deconvolution - only dirty ima
- **Github:** <https://github.com/epfl-r>
- **Arxiv:** <https://arxiv.org/pdf/2310>

Ongoing Work:

- **Deconvolution** incorporation: Radler (Radio Astronomical Deconvolution Library), ML deconvolution

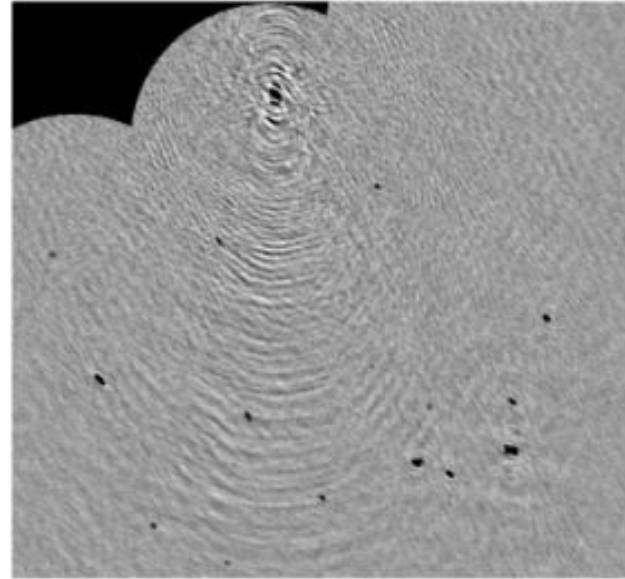
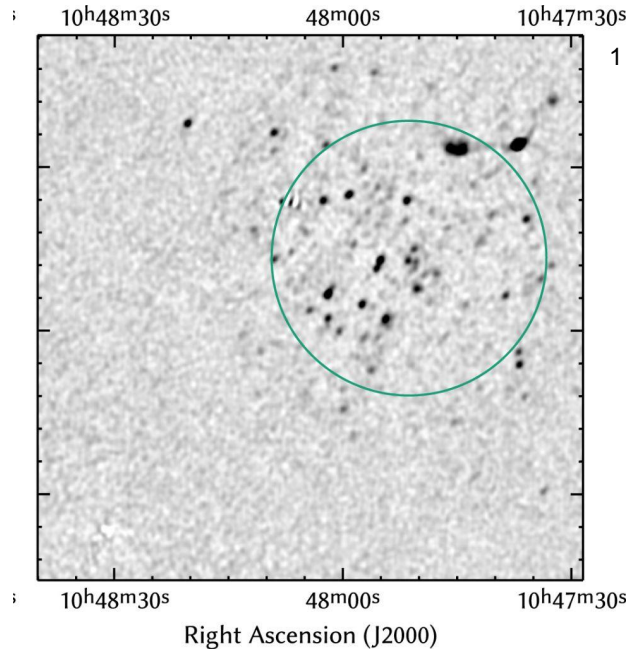


Bright Point Source Contaminants are Ubiquitous in Radio Astronomy



Typically solved by peeling or modelling and subtracting source in visibility space
Eg: Obit⁴, Ionpeel⁵ etc.

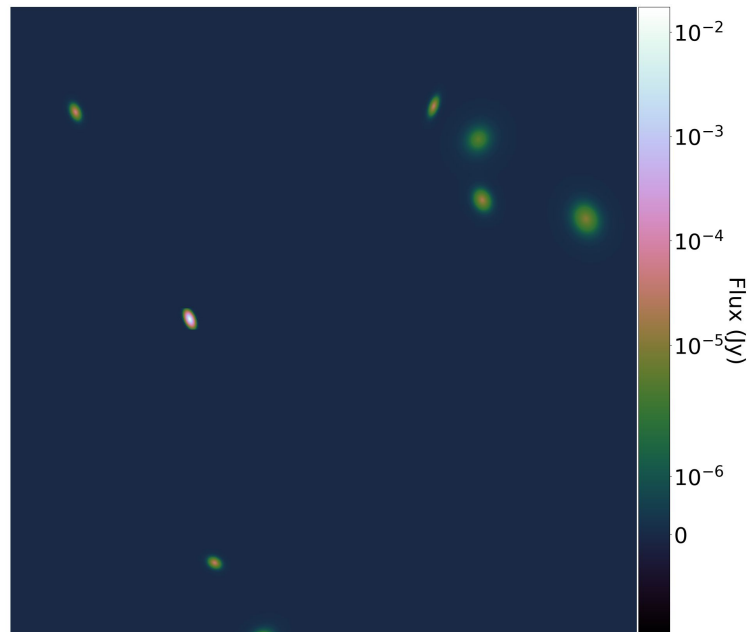
Bright Point Source Contaminants are Ubiquitous in Radio Astronomy



But perfect peeling is not always possible.

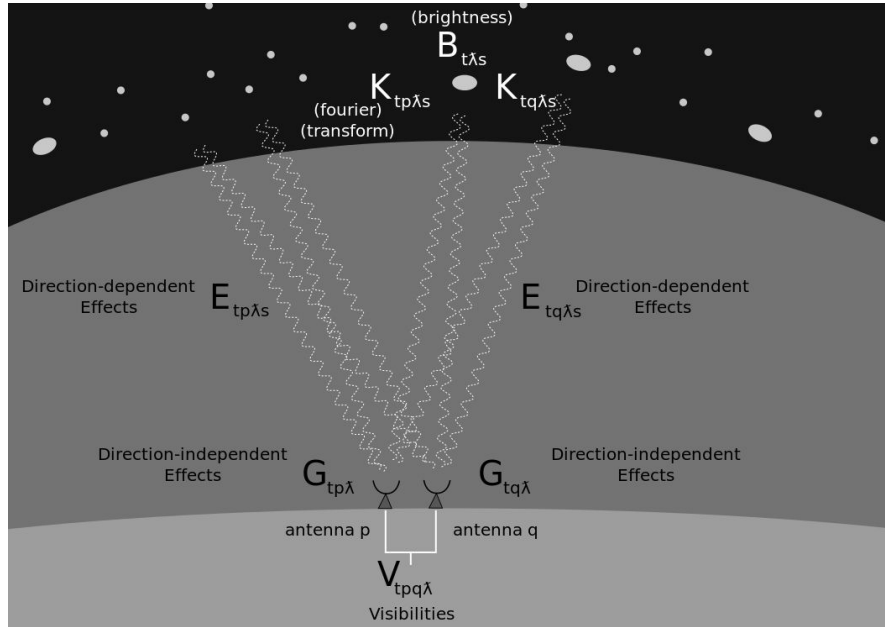
Separating Contaminating Point Sources at the Visibility Level

- Model: **T-RECS**¹ x 1000
100x range in SNR for gaussian sources in small FOV (0.025 deg) image; 1 frequency channel
- Visibilities Generated using **SKA Low Configuration on OSKAR** utilising Karabo Pipeline²
 - 200 MHz
 - 1.5 GHz (SKA Mid Frequencies)
- Realistic Simulation - **Observational Effects**
- Since BIPP works on visibilities - **separation of interferometric artifacts?**



(Simplified) Radio Interferometric Measurement Equation

$$V_{tpq} = G_{tp} E_{tps} B_{pq} E_{tqs} G_{tq} + N_t^1$$



G_{tp} - Direction Independent (DI) gains,
antenna p

E_{tps} - Direction Dependent (DD) gains,
antenna p, direction s

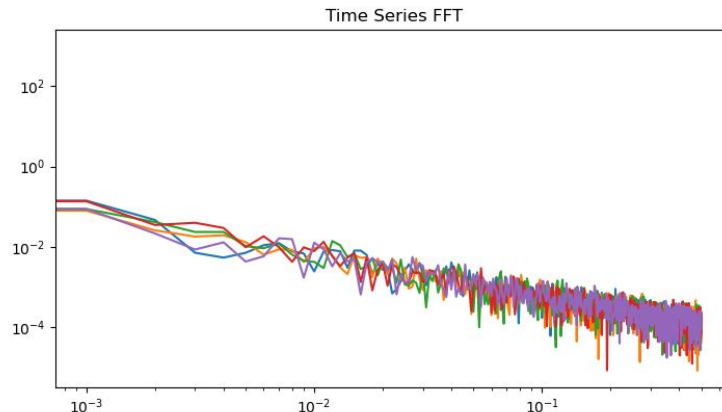
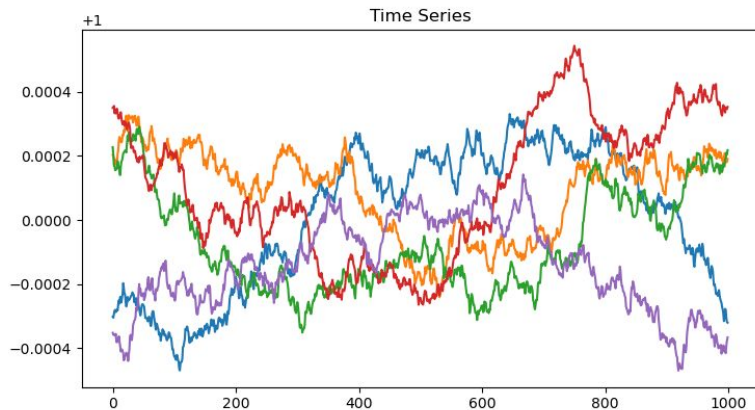
B_{pq} - Sky brightness, baseline pq

N_t - Receiver Noise

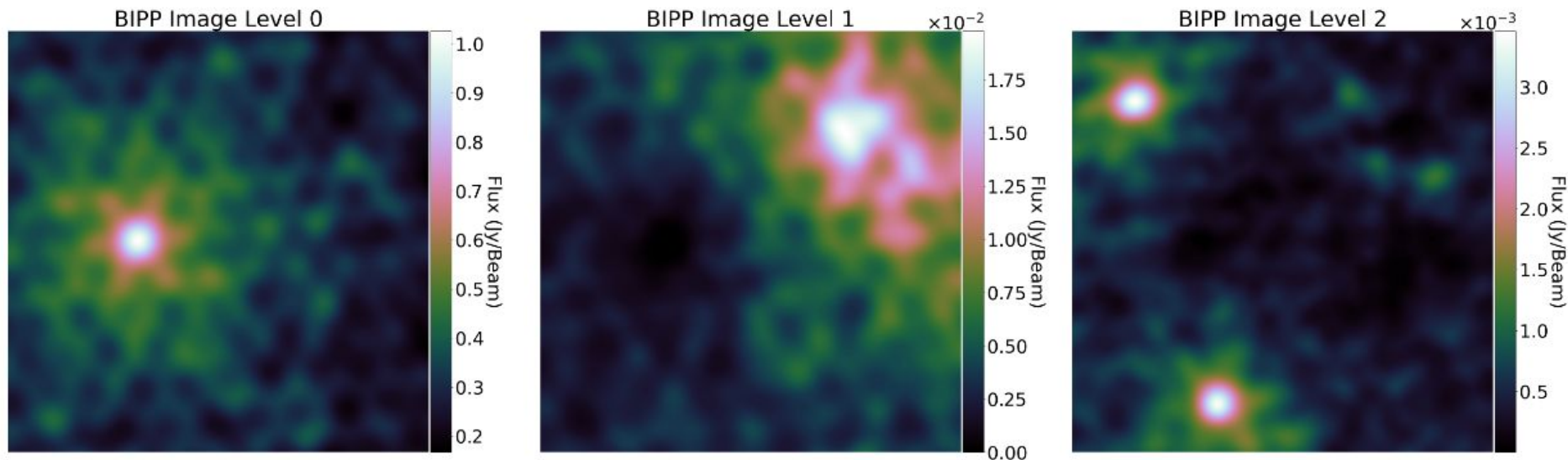
Additive (Noise) and Multiplicative (Calibration) Errors

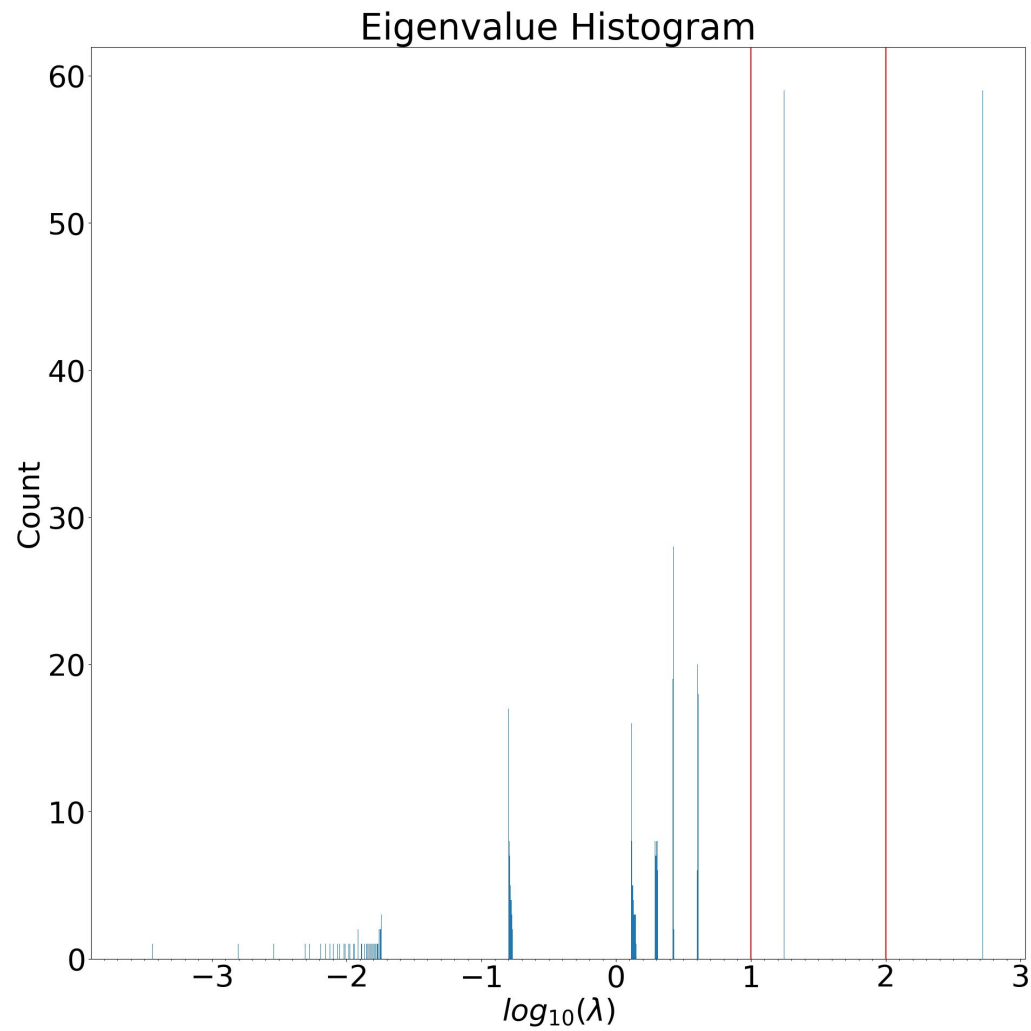
$$\Delta\sigma_N = \frac{2kT_{sys}}{A_e \sqrt{2N_{baselines} N_{pol} \Delta v \Delta t}}$$

$$G_{tp} = A_{tp} e^{i\theta_{tp}}$$

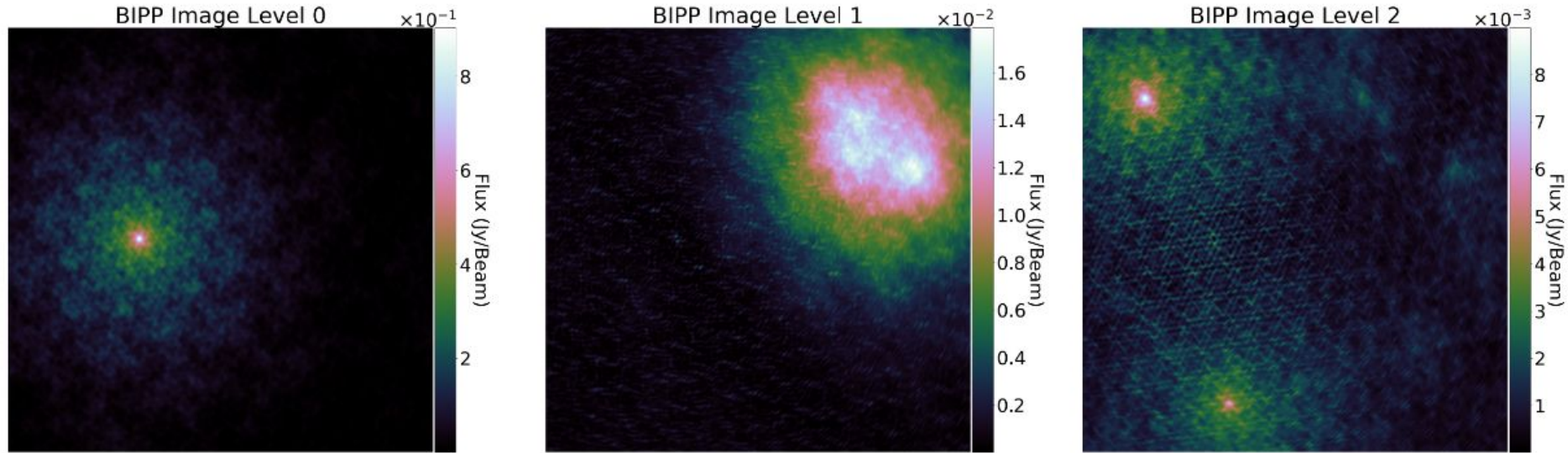


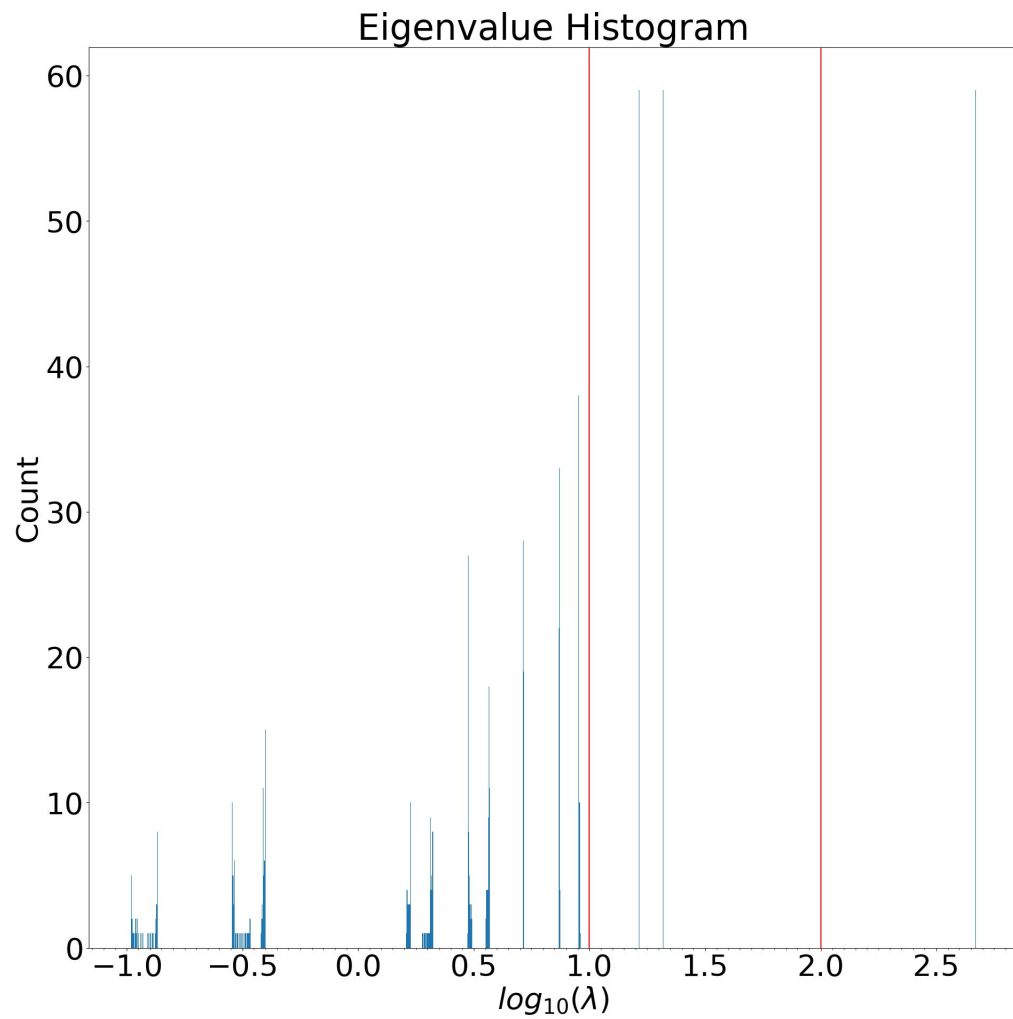
200 MHz; 10 min observation; No noise; No cal. Errors





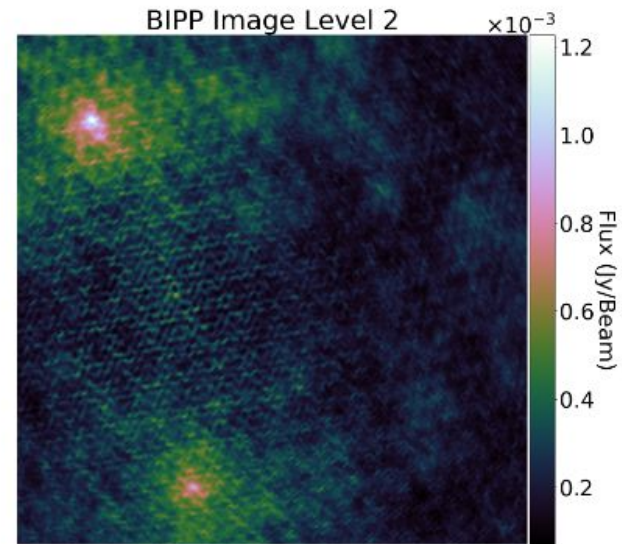
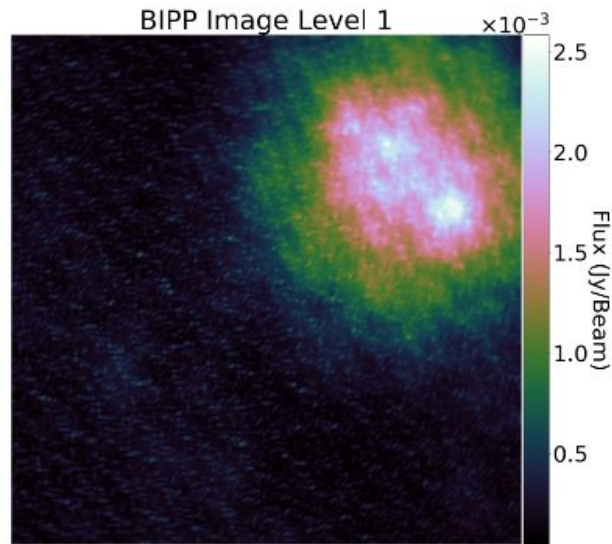
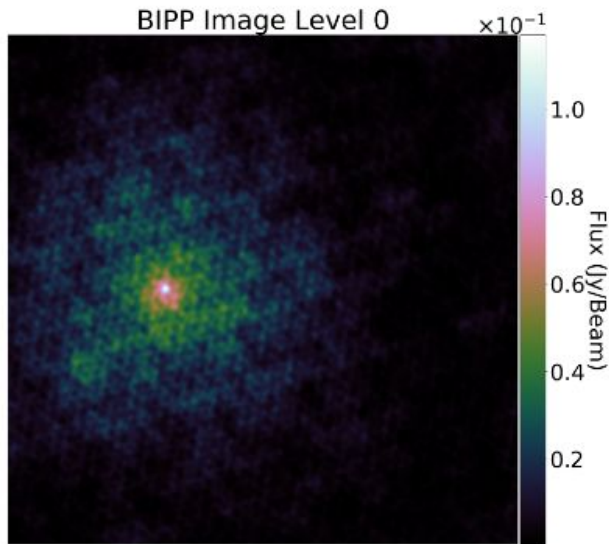
1500 MHz; 10 min observation; No noise; No cal. errors



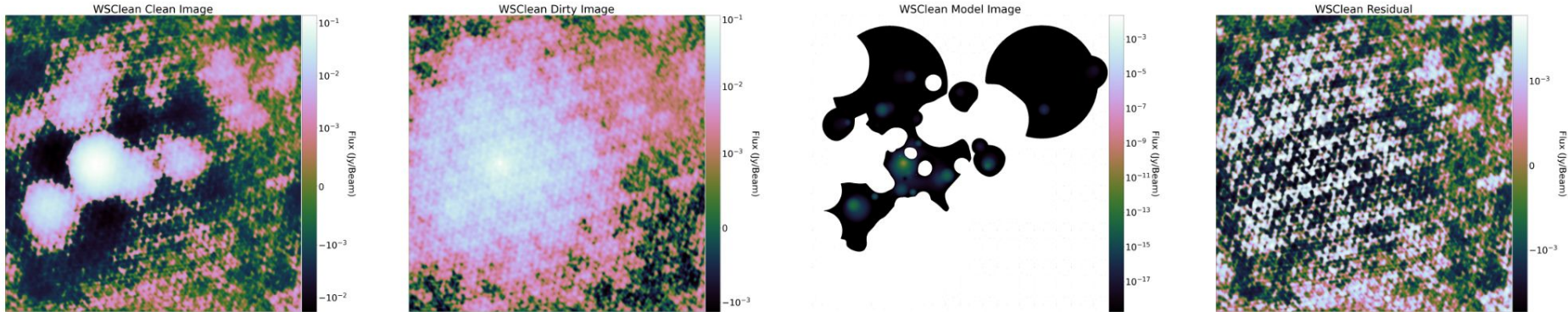


1500MHz; 10 min obs.; No noise; Low calibration errors

$$g_p = A_p e^{i\theta_p} \quad \mu_A = 1, \sigma_A = 0.07, \mu_\theta = 0, \sigma_\theta = 0.1667$$

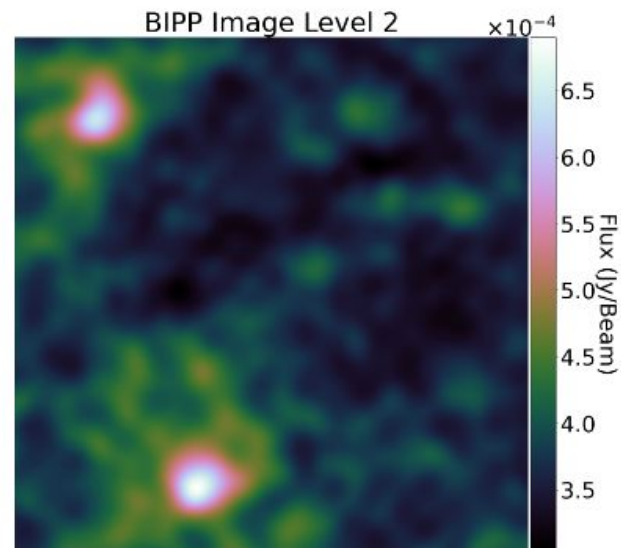
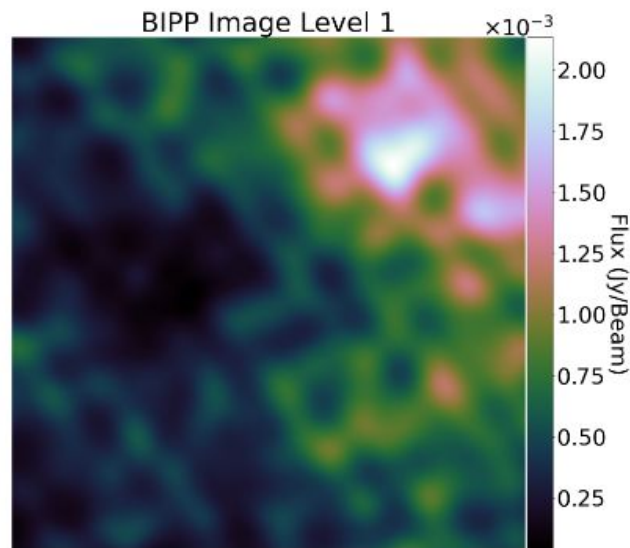
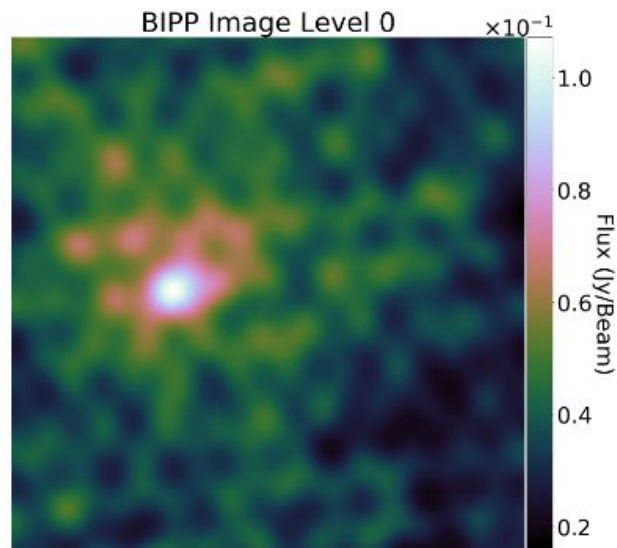


1500MHz; 10 min obs.; No noise; Low calibration errors

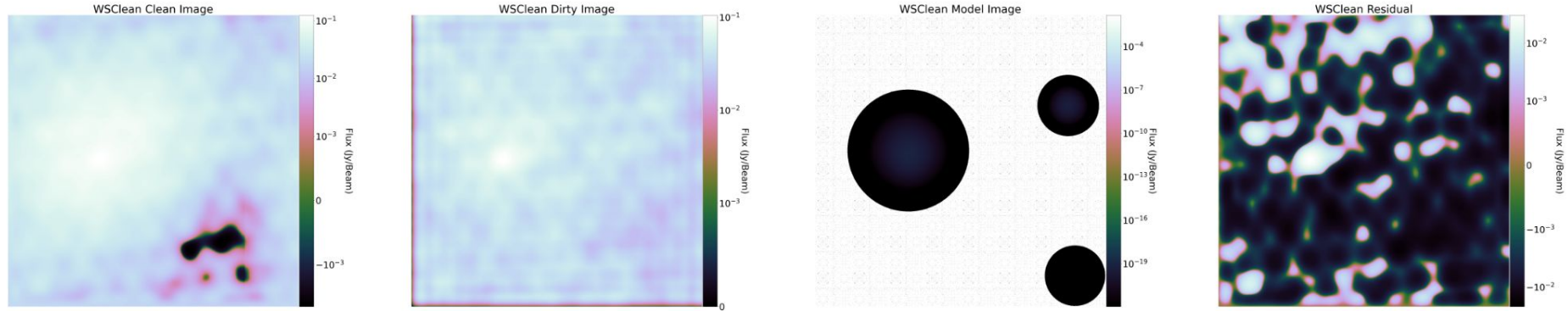


200MHz; 10 min obs.; 8 h noise; Low calibration errors

$$g_p = A_p e^{i\theta_p} \quad \mu_A = 1, \sigma_A = 0.07, \mu_\theta = 0, \sigma_\theta = 0.1667$$

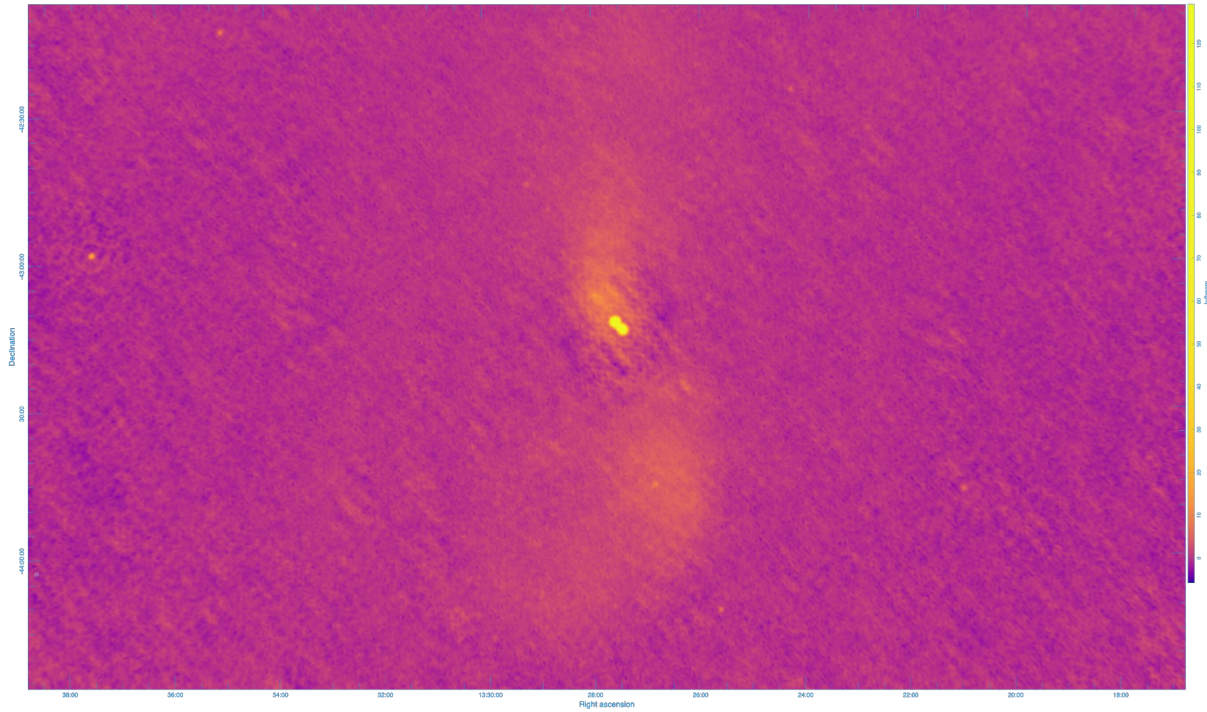


200MHz; 10 min obs.; 8h noise; Low calibration errors

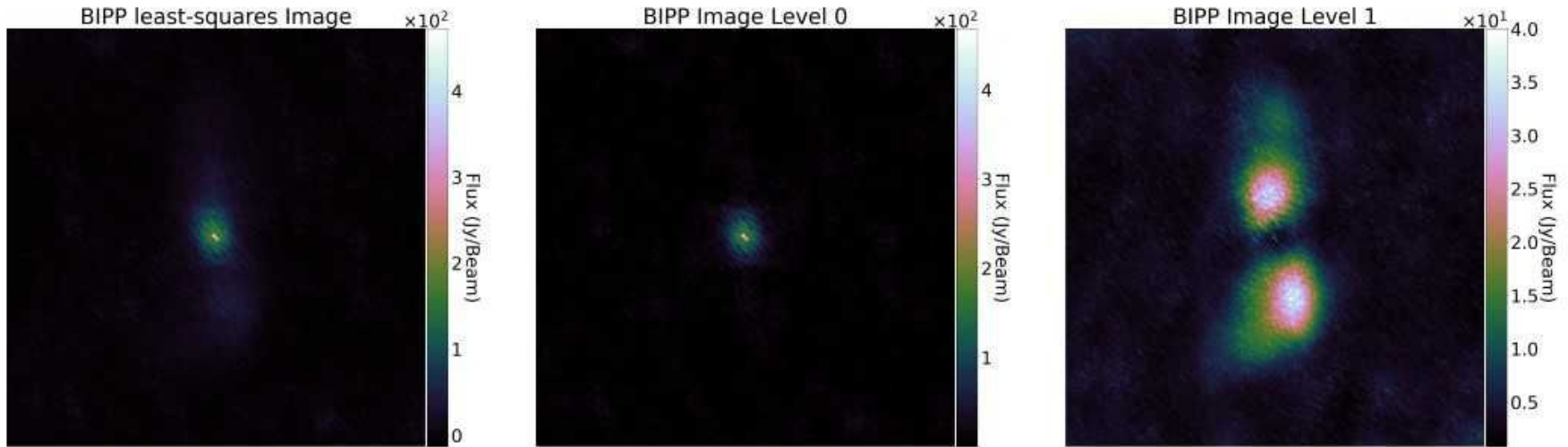


Real(istic) Data

- MWA Phase I Observation of Centaurus A
- 11.37 deg FoV
- 175.35 MHz Observation
- MWA Phase I - sensitivity to extended structure



Real(istic) Data BIPP Output



Summary:

- Separation of contaminating bright point sources possible with BIPP.
- But if contaminating source is **extended** in size, separation is **incomplete**.
- BIPP point source separation is **resilient to realistic observational errors**.
- BIPP bright source separation works on **real MWA Data**.

Future Work:

- **Deconvolved Images comparison**

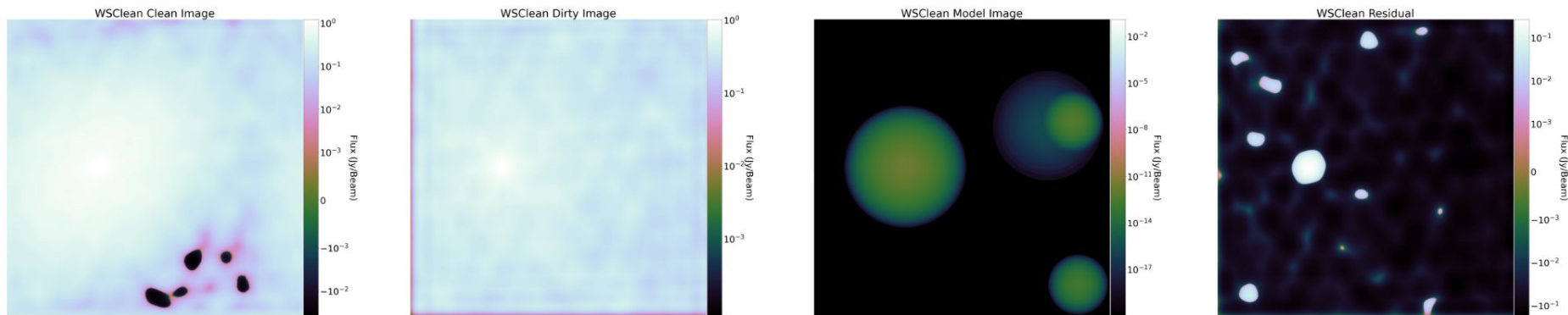
Contact me at shreyam.krishna@epfl.ch for any questions!

Next-Generation Radio Interferometry Team

- PASC proposal to optimize, validate, and integrate Bluebild in precursor pipelines
- Team:
 - **Emma Tolley**: Team leader
 - **Etienne Orliac**: HPC, benchmarking, optimization, C & CUDA kernels
 - **Simon Frasch**: GPU nuFFT library, parallelism
 - **Remi Poitevineau**: Baseline reweighting, deconvolution
 - **Shreyam Krishna**: scientific use cases
 - **Paul Hurley, Sepand Kashani**: Algorithm development/expertise
 - Ex Members: Michele Bianco, Arpan Das, Matthieu Simeoni, M. Roshan

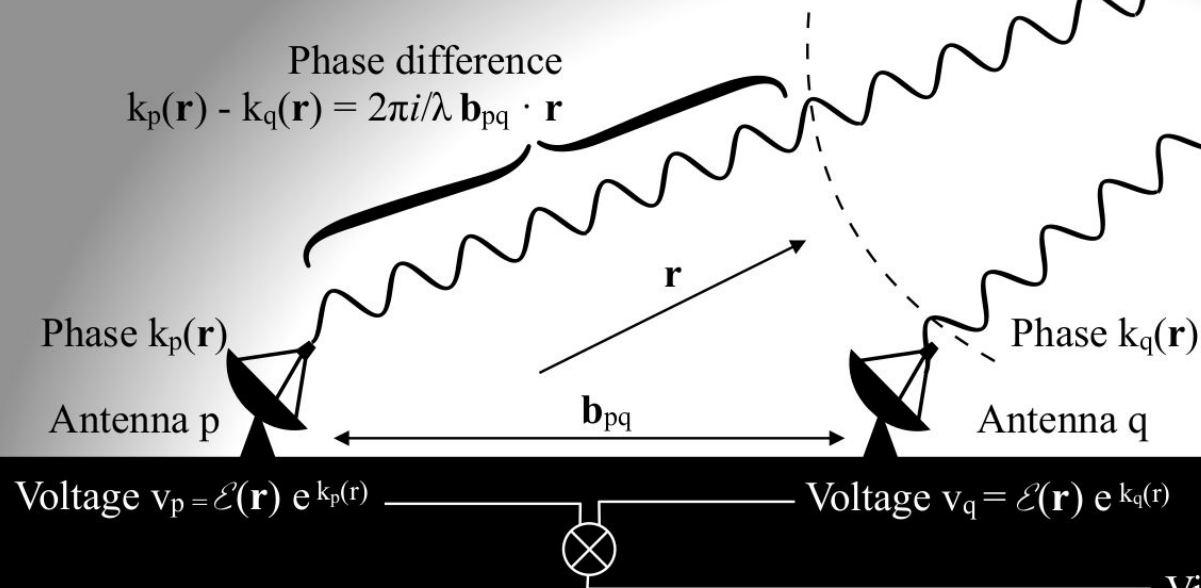
Contact me at shreyam.krishna@epfl.ch for any questions!

200 MHz; 10 min observation; No noise; No cal. Errors



Radio Interferometric Imaging

Electric field $\mathcal{E}(\mathbf{r})$
with brightness
 $I(\mathbf{r}) \equiv \langle \mathcal{E}(\mathbf{r}) \mathcal{E}(\mathbf{r})^H \rangle$



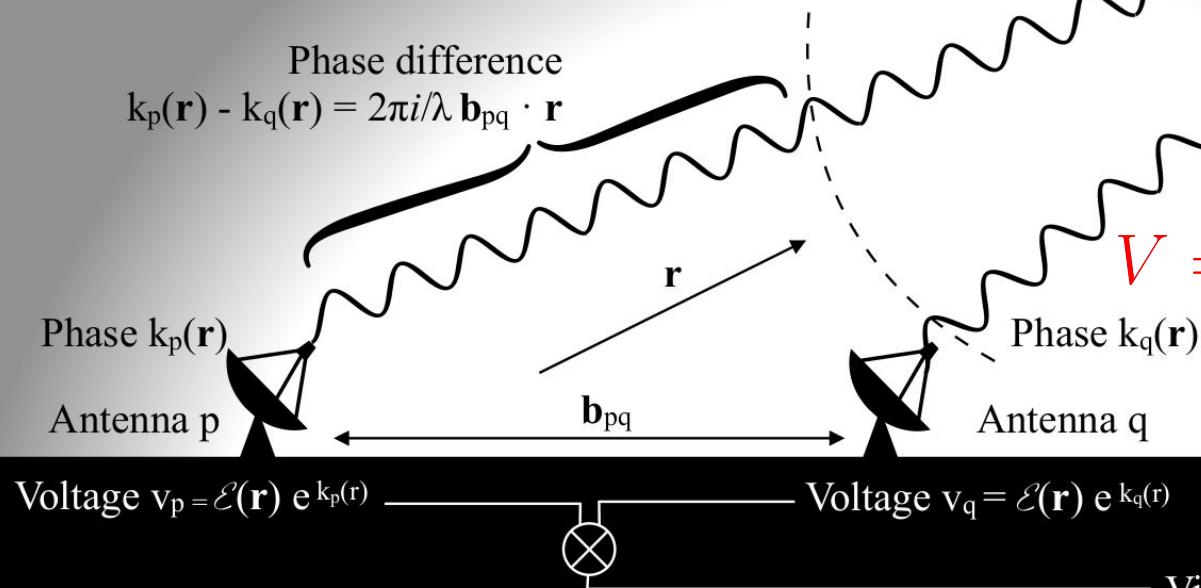
$$V_{pq} = \langle v_p v_q^H \rangle$$

$$= \int I(\mathbf{r}) e^{k_p(\mathbf{r}) - k_q(\mathbf{r})} d\Omega$$

$$= \int I(\mathbf{r}) e^{2\pi i/\lambda \mathbf{b}_{pq} \cdot \mathbf{r}} d\Omega$$

Radio Interferometric Imaging

Electric field $\mathcal{E}(\mathbf{r})$
with brightness
 $I(\mathbf{r}) \equiv \langle \mathcal{E}(\mathbf{r}) \mathcal{E}(\mathbf{r})^H \rangle$



$$v = \Psi^* \epsilon + n$$

$$V = \langle v v^* \rangle = \Psi^* I \Psi + n$$

$$\text{Visibility } V_{pq} = \langle v_p v_q^H \rangle$$

$$= \int I(\mathbf{r}) e^{k_p(\mathbf{r}) - k_q(\mathbf{r})} d\Omega$$

$$= \int I(\mathbf{r}) e^{2\pi i / \lambda \mathbf{b}_{pq} \cdot \mathbf{r}} d\Omega$$

Radio Interferometric Imaging

Backprojection for the sky image: $\tilde{I} = \Psi V \Psi^*$

Bluebird uses the Moore-Penrose Inverse:

$$\Psi^* (\Psi^* \Psi)^{-1} = \Psi^* (G_\Psi)^{-1}$$

$$\tilde{I} = \Psi^* (G_\Psi)^{-1} V (G_\Psi)^{-1} \Psi$$

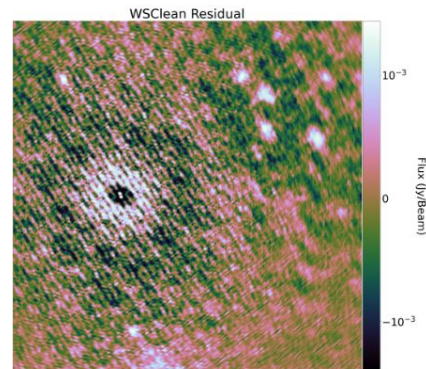
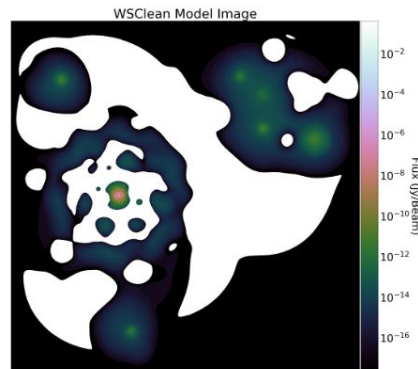
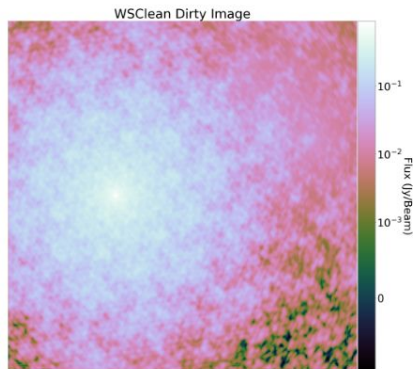
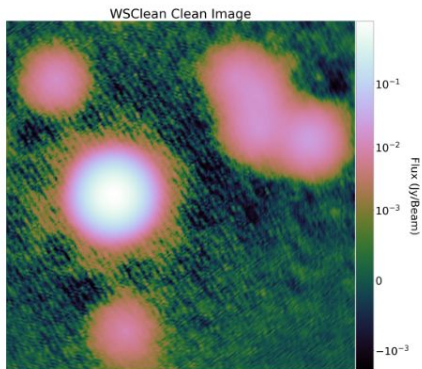
G often ill-conditioned and difficult to invert

$$\tilde{I} = \sum_a \lambda_a |\epsilon_a|^2 = \sum_a \lambda_a |\Psi \alpha_a|^2$$

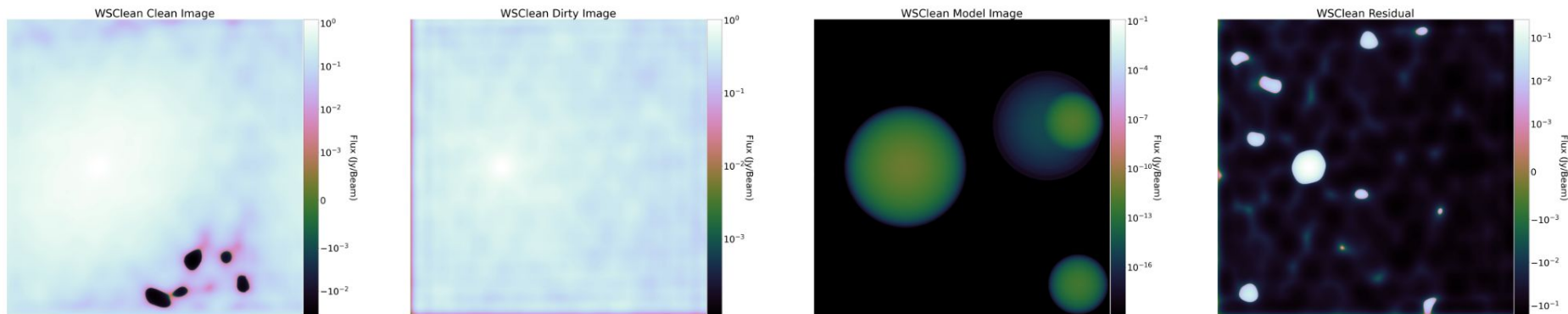
This is achieved by a generalised eigenvalue decomposition:

$$V \alpha_a = \lambda_a G_\Psi \alpha_a$$

1500 MHz; 10 min observation; No noise; No cal. errors



200MHz; 10 min obs.; 8 h additive noise; No cal. errors



Bluebird Algorithm¹

Pseudo-Inverse Least Squares Solution

$$\tilde{\Psi} = \Psi G_{\Psi}^{-1} = \Psi (\Psi^* \Psi)^{-1}$$

$$\hat{I}(r) = \tilde{\Psi} \mathbf{E}[yy^*] \tilde{\Psi}^* = \Psi G_{\Psi}^{-1} \mathbf{E}[yy^*] G_{\Psi}^{-1} \Psi^*$$

$$\hat{I}(r) = \sum_m \lambda_m |\epsilon_m(r)|^2$$

$$\epsilon_m = \Psi \alpha_m \quad \hat{I}(r) \Psi \alpha_m = \lambda_m \Psi \alpha_m$$

$$\mathbf{E}[yy^*] \alpha_m = \lambda_m G_{\Psi} \alpha_m$$