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Italiadomani  
PIANO NAZIONALE  
DI RIPRESA E RESILIENZA



# ***RAMSES GPU***

*Presented by:  
Raffaele Pascale*

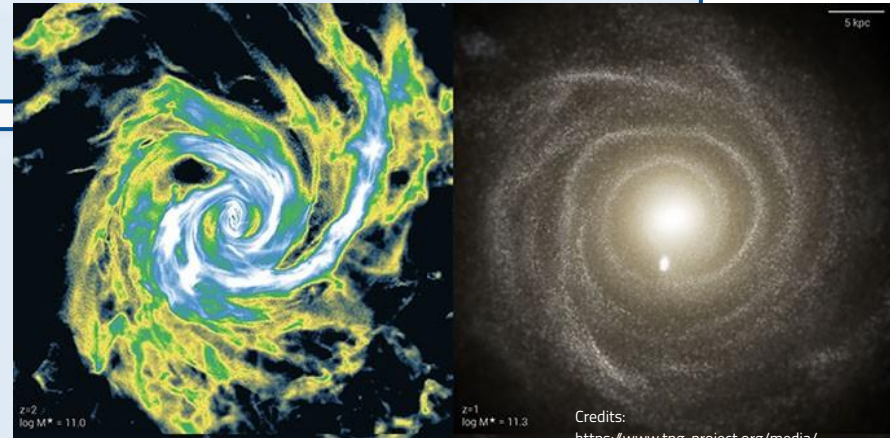
*Collaborators:  
Francesco Calura, Claudio Gheller, Emanuele De Rubeis,  
Donatella Romano, Valentina Cesare*

**Spoke 3 II Technical Workshop, Bologna Dec 17 -19, 2024**

## Context

Hydrodynamical  $N$ -body simulations are **essential in astrophysics** since they provide tests for theories of galaxy formation and evolution.

**High spatial resolutions** are needed to get a deeper understanding of galaxy physics.



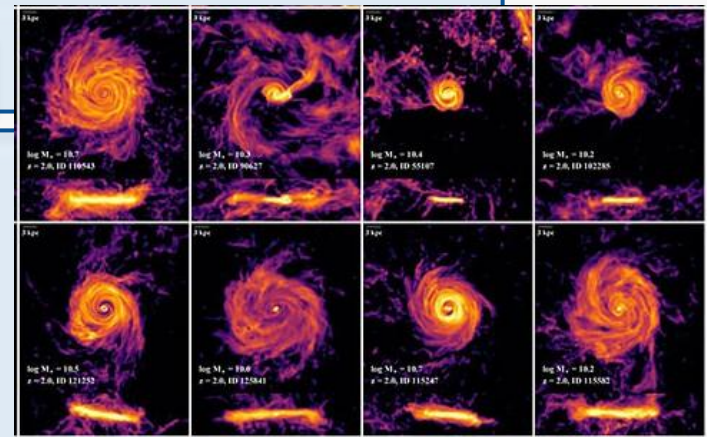
## Challenges

Increase in spatial resolution -> Increase in **computational costs**

Innovative solutions to optimize and accelerate computations.

An effective strategy involves porting hydrodynamical codes onto **GPU architecture (RAMSES)**

22.5 kpc



## Application to RAMSES and MINIRAMSES

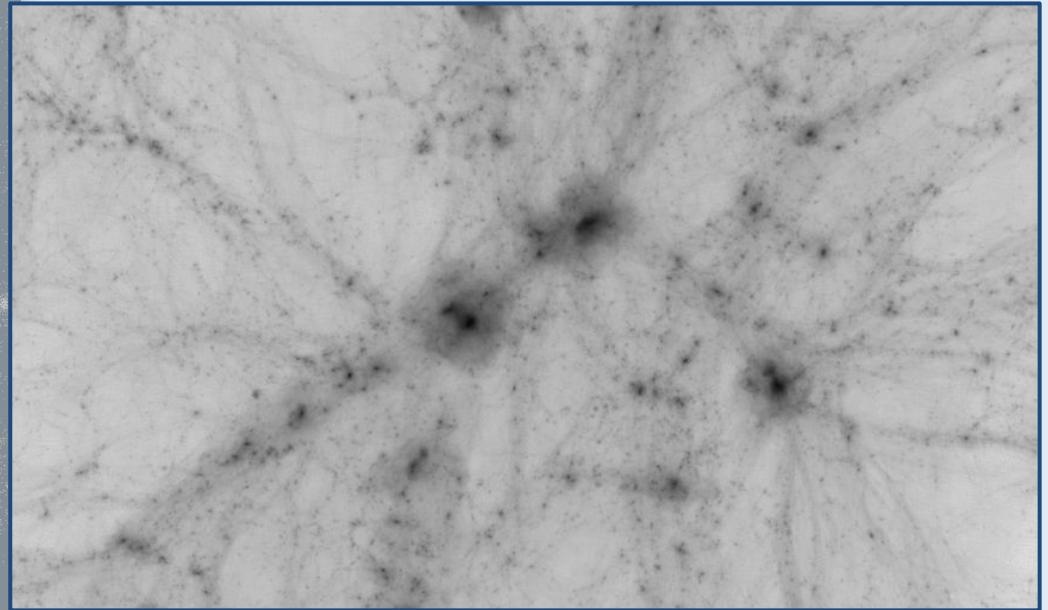
**Ramses** and **Miniramses** are written in Fortran programming language.

**Eulerian** approach for solving compressible hydrodynamics equations

Partially compatible with graphics processing units (GPUs)

Implements adaptive mesh refinement (**AMR**) for resolving structures on different scales

**MINIRAMSES** is an optimized version of Ramses featuring an enhanced grid memory management system, which facilitates memory access and substantially (?) increases the potential for efficient GPU integration of the code.



22.5 kpc

# AMR

(Adaptive Mesh Refinement)

## Identification of Oct Cell:

- It identifies an individual cell within the oct in the computational domain.

## Refinement Evaluation:

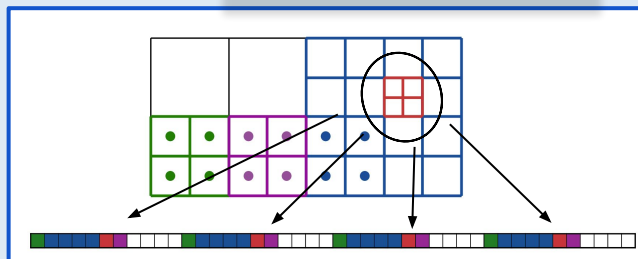
- It assesses if the oct cell meets the criteria for refinement.
- Criteria may include gas density, density gradient, or other physical properties.

## Cell Refinement:

- If the oct cell meets refinement criteria, it is divided into smaller cells.
- The process increases grid resolution in the region of interest.

22.5 kpc

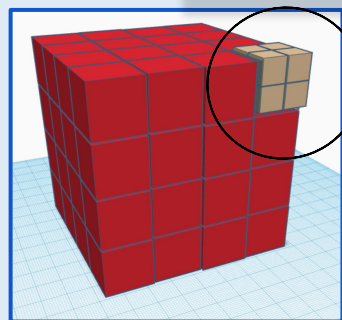
# RAMSES



Example of classical AMR working

During cells refinement, new born cells belonging to the same oct are saved in non-contiguous parts of the memory.

# MINIRAMSES



Introduces the new macrostructure: of super-oct in cell refinement.

ocs in super-octs are saved in contiguous memory locations. Cell adjacent in space close in memory

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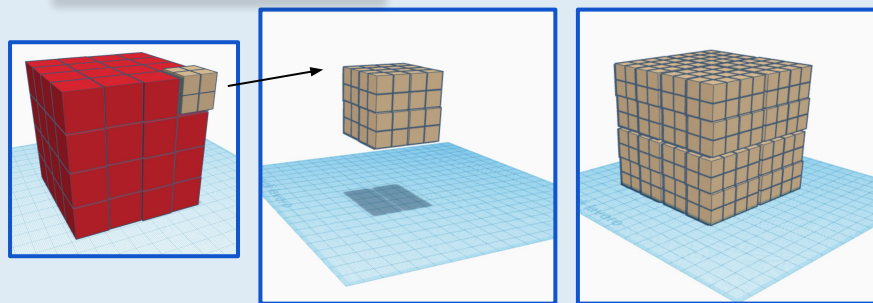
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22.5 kpc

# Super-oct



The **superoct** is a **large cube** composed of smaller sub-cubes, known as octs. Its **hierarchical structure** functions similarly to grid refinement, with each successive level increasing the number of octs along each edge by a factor of 2. As a result, the edge length of the superoct at a given level contains double the number of octs compared to the previous level.

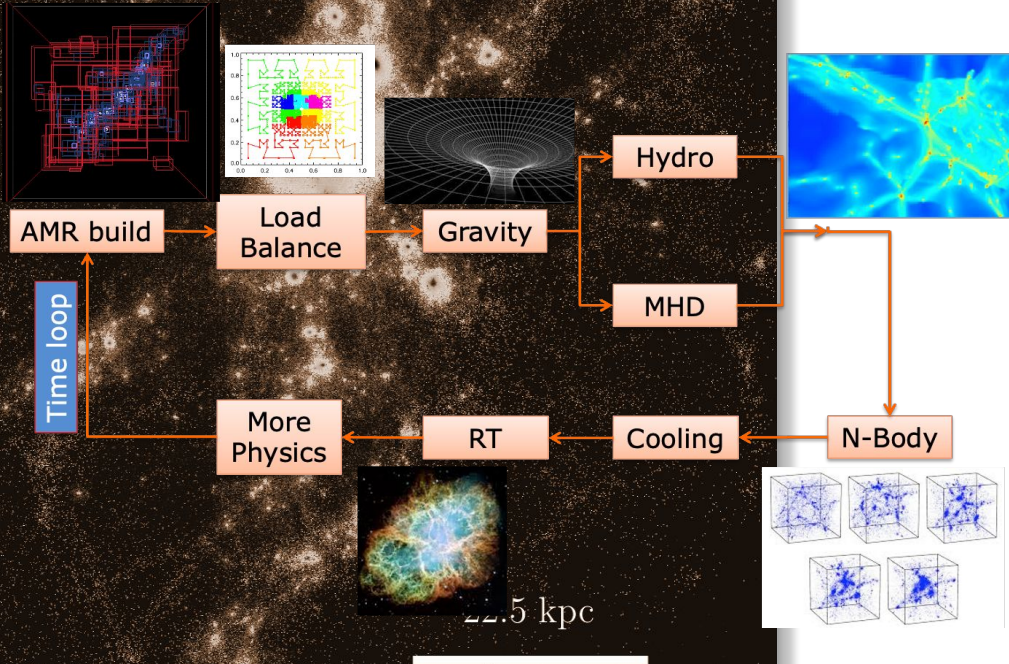
Superoct level (**n**) from 0 to 5. In 3d, number of octs per superoct is  $8^n$

**n = 4** ---> octs per superoct = 4096

**n = 5** ---> octs per superoct = 32768

The larger n, the better the changes for an optimal porting

# Basic functioning of (MINI)RAMSES



## Adaptive Mesh Refinement (AMR):

the grid resolution is dynamically adapted to match the simulation's needs. Regions of interest are refined for higher resolution

## Load Balancing:

RAMSES optimizes computational resources by distributing the workload evenly across processing units.

## Gravity:

Gravity field is computed based on the matter distribution.

## Hydro:

The hydrodynamic equations describing the fluid motion are solved

## N-body:

the trajectories of collisionless particles (e.g., dark matter) are evolved using the leapfrog algorithm.

## Cooling:

Cooling processes to account for energy loss

## More physics:

Additional physics as winds, star formation etc.

## Main goal

Enhancing Efficiency and Decreasing Computational Time.

Adapting components of MINIRAMSES for GPU architecture, resulting in a significant acceleration factor.

## What and how

Identification of two main parts of the code suitable for GPU porting: **N-body + Hydro**

**OpenACC** directives to parallelize time-consuming loops and critical code regions;

Optimization techniques for memory management, and data movement

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# Timescale and milestones

## M6 - Preliminary analysis:

Investigation of MINIRAMSES to identify sections suitable for GPU parallelization

## M8 - GPU porting of Hydro modules:

Identification of modules to port on GPU, evaluation of time performances. Gradual GPU porting of individual modules used in hydrodynamics.

## M10 - Memory management of hydro modules:

Identification of strategy for memory management. Optimization of the code on GPU to maximize performance

## M7 - Getting GPU resources:

Submission o proposal @Cineca

## M9 - Tests

Tests and performance evaluations before and after. Evaluation of initial performance and identification of any issues or bugs.

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# Accomplished work: porting of the hydro solver

## Hydrodynamic solver

The **Godunov** solver is a numerical technique for solving hyperbolic PDEs describing fluid flow.

**Domain Discretization:** The spatial domain undergoes discretization into cells, constituting a 3D grid.

**Flux Calculation Across Cell Boundaries:** For each cell, the Godunov method computes fluxes across its borders, considering fluid properties and boundary conditions.

**State Variable Update:** State variables of the fluid get updated based on computed fluxes, adhering to flow conservation equations.

**Temporal Iteration:** The entire process iterates over each time step until reaching a defined stopping criterion.

22.5 kpc

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## Hydrodynamic solver

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**State Variable Update:** State variables are updated based on computed fluxes, addressing conservation equations.

**Temporal Iteration:** The entire process iterates over each time step until reaching a defined stopping criterion.

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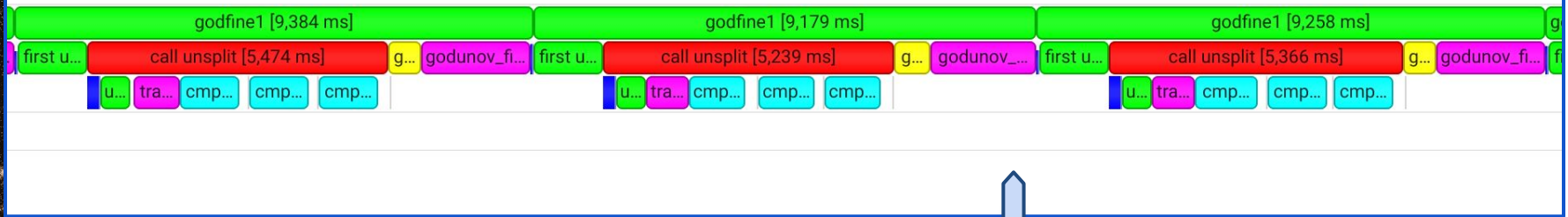
run over 1 CPU

libc_start_main		99,99	/usr/lib64/power9/libc-2.28.so
generic_start_main		99,99	/usr/lib64/power9/libc-2.28.so
main		99,99	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
MAIN_		99,99	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
mdl_init_		99,99	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
mdl_init_master		99,97	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
adaptive_loop_		99,97	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
amr_step_m_amr_step_		85,91	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
godunov_fine_module_godunov_fine_		62,93	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
godunov_fine_module_godfine1_		62,93	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
unsplit_		41,55	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
cmpflxm_	0,00	23,13	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
riemann_lif_	19,81	19,81	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
cmpflxm_	3,32	3,32	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
unsplit_	2,57	18,43	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
trace3d_	8,52	8,52	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
uslope_	5,01	5,01	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
ctoprim_	2,32	2,32	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
godunov_fine_module_godfine1_	19,27	19,30	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
nbors_utils_get_grid_		1,60	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
newdt_fine_module_m_newdt_fine_		11,49	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
synchro_hydro_fine_module_m_sync...		7,34	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
amr_step_m_amr_step_		1,64	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
godunov_fine_module_set_unew_		1,28	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
godunov_fine_module_set_uold_		1,20	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
m_init_refine_adaptive_		9,05	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d
init_refine_basegrid_module_m_init_ref...		4,94	/m100_scratch/userexternal/dromano0/mini-ramses/bin/ramses3d

63% of the time is spent by the hydrodynamical solver (godfine1)

# Accomplished work: porting of the hydro solver

Superoct  
level n=4



## Full CPU run (1CPU)

Sedov3d test: Explosion of a supernovae in a constant medium.  
Only hydro, no gravity.

Major of the computational time is spent during the **call unsplit()**

22.5 kpc

Each call to **godfine1**  
solves hydrodynamics for  
one super-oct

# About time

Time	Total Time	Instances	Avg	Med	Min	Max	StdDev	Style	Range
39.0%	113,570 s	12288	9,242 ms	9,224 ms	9,023 ms	17,758 ms	111,959 µs	PushPop	godfine1
22.0%	65,303 s	12288	5,314 ms	5,298 ms	5,185 ms	12,241 ms	95,784 µs	PushPop	call unsplit
13.0%	39,032 s	36864	1,059 ms	1,059 ms	1,025 ms	1,681 ms	25,469 µs	PushPop	cmpflxm
8.0%	24,286 s	12288	1,976 ms	1,975 ms	1,887 ms	2,103 ms	29,519 µs	PushPop	godunov_fine loops over inner octs
5.0%	15,306 s	12288	1,246 ms	1,242 ms	1,201 ms	2,656 ms	22,636 µs	PushPop	first unparallelized part
3.0%	9,491 s	12288	772,379 µs	753,860 µs	730,857 µs	3,908 ms	43,983 µs	PushPop	traceNd
2.0%	7,556 s	12288	614,924 µs	610,690 µs	603,922 µs	809,955 µs	11,548 µs	PushPop	godunov_fine loops
2.0%	6,399 s	12288	520,759 µs	517,628 µs	504,616 µs	1,788 ms	16,425 µs	PushPop	uslope
1.0%	2,839 s	12288	231,016 µs	229,047 µs	216,086 µs	854,890 µs	10,962 µs	PushPop	ctoprim

full CPU

Time	Total Time	Instances	Avg	Med	Min	Max	StdDev	Style	Range
41.0%	81,610 s	12288	6,641 ms	6,019 ms	4,330 ms	56,130 ms	3,064 ms	PushPop	godfine1
17.0%	34,130 s	12288	2,777 ms	1,873 ms	1,640 ms	50,349 ms	2,231 ms	PushPop	call unsplit
12.0%	23,957 s	12288	1,950 ms	1,870 ms	1,422 ms	38,178 ms	1,056 ms	PushPop	first unparallelized part
11.0%	23,118 s	12288	1,881 ms	1,010 ms	891,428 µs	49,242 ms	1,693 ms	PushPop	ctoprim
7.0%	14,299 s	12288	1,164 ms	1,005 ms	626,919 µs	38,482 ms	964,970 µs	PushPop	godunov_fine loops over inner
3.0%	6,851 s	12288	557,559 µs	549,591 µs	388,902 µs	26,238 ms	421,711 µs	PushPop	uslope
3.0%	6,847 s	12288	557,194 µs	259,935 µs	170,164 µs	37,794 ms	940,941 µs	PushPop	godunov_fine loops
0.0%	1,279 s	36864	34,704 µs	24,491 µs	22,274 µs	36,054 ms	521,073 µs	PushPop	cmpflxm
0.0%	1,239 s	12288	100,790 µs	73,305 µs	62,615 µs	36,000 ms	702,611 µs	PushPop	godunov_fine unlock all octs

intermediate

superoct level 4

Time	Total Time	Instances	Avg	Med	Min	Max	StdDev	Style	Range
48.0%	80,413 s	12288	6,544 ms	6,052 ms	4,877 ms	53,906 ms	2,871 ms	PushPop	godfine1
21.0%	35,495 s	12288	2,889 ms	2,754 ms	2,241 ms	46,178 ms	1,471 ms	PushPop	first unparallelized part
8.0%	14,446 s	12288	1,176 ms	1,123 ms	919,285 µs	37,484 ms	1,140 ms	PushPop	call unsplit
8.0%	13,940 s	12288	1,134 ms	930,689 µs	610,382 µs	37,596 ms	1,315 ms	PushPop	godunov_fine loops over inner octs
6.0%	10,559 s	12288	859,311 µs	845,610 µs	657,483 µs	37,162 ms	629,059 µs	PushPop	ctoprim
3.0%	6,071 s	12288	494,035 µs	173,551 µs	153,833 µs	35,851 ms	1,067 ms	PushPop	godunov_fine loops
0.0%	1,396 s	12288	113,644 µs	72,332 µs	60,166 µs	34,240 ms	816,981 µs	PushPop	godunov_fine unlock all octs
0.0%	1,074 s	36864	29,131 µs	24,435 µs	21,840 µs	36,200 ms	295,540 µs	PushPop	cmpflxm
0.0%	603,318 ms	12288	49,098 µs	37,341 µs	34,819 µs	33,996 ms	563,886 µs	PushPop	save flux Y

full GPU

22.9 kpc

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## Improvements?

Each call to the godfine1 subroutine results in a speedup of approximately **1.5 times (low)**.

The primary reason for the limited gain is the **overhead associated with memory management and communication** between the CPU and GPU.

These tasks consume a significant portion of the processing time, offsetting the potential performance improvements.

22.9 kpc

Time	Total Time	Instances	Avg	Med	Min	Max	StdDev	Style	Range
39.0%	114,974 s	1536	74,853 ms	74,966 ms	73,579 ms	124,786 ms	1,358 ms	PushPop	godfine1
22.0%	65,535 s	1536	42,666 ms	42,772 ms	41,985 ms	86,882 ms	1,164 ms	PushPop	call unsplit
13.0%	38,321 s	4608	8,316 ms	8,359 ms	8,084 ms	12,626 ms	120,361 µs	PushPop	cmpflxm
10.0%	29,599 s	1536	19,270 ms	19,294 ms	18,795 ms	19,835 ms	170,357 µs	PushPop	godunov_fine loops over inner octs
3.0%	11,502 s	1536	7,488 ms	7,489 ms	7,344 ms	11,030 ms	101,876 µs	PushPop	first unparallelized part
3.0%	9,245 s	1536	6,019 ms	6,006 ms	5,937 ms	24,404 ms	470,563 µs	PushPop	traceNd
2.0%	7,595 s	1536	4,945 ms	4,959 ms	4,798 ms	5,092 ms	62,453 µs	PushPop	godunov_fine loops
2.0%	6,194 s	1536	4,033 ms	4,029 ms	3,926 ms	12,636 ms	224,601 µs	PushPop	uslope
1.0%	2,952 s	1536	1,922 ms	1,912 ms	1,889 ms	5,157 ms	84,360 µs	PushPop	save flux X
1.0%	2,939 s	1536	1,913 ms	1,904 ms	1,881 ms	4,884 ms	77,745 µs	PushPop	save flux Y
1.0%	2,893 s	1536	1,883 ms	1,875 ms	1,853 ms	4,849 ms	77,456 µs	PushPop	save flux Z
0.0%	2,784 s	1536	1,812 ms	1,810 ms	1,799 ms	5,202 ms	88,561 µs	PushPop	ctoprim
0.0%	231,607 ms	1536	150,786 µs	150,028 µs	139,678 µs	198,368 µs	6,764 µs	PushPop	godunov_fine unlock all octs

factor 10 speed-up

CPU

full CPU

superoct level 5

Time	Total Time	Instances	Avg	Med	Min	Max	StdDev	Style	Range
49.0%	47,483 s	1536	30,914 ms	29,738 ms	25,495 ms	98,395 ms	7,173 ms	PushPop	godfine1
26.0%	25,935 s	1536	16,885 ms	16,385 ms	11,785 ms	71,956 ms	4,329 ms	PushPop	first unparallelized part
8.0%	7,759 s	1536	5,051 ms	4,743 ms	3,672 ms	36,269 ms	2,467 ms	PushPop	godunov_fine loops over inner octs
6.0%	6,615 s	1536	4,307 ms	4,226 ms	3,681 ms	38,111 ms	1,162 ms	PushPop	call unsplit
5.0%	5,609 s	1536	3,652 ms	3,612 ms	3,075 ms	15,200 ms	600,606 µs	PushPop	ctoprim
2.0%	2,112 s	1536	1,375 ms	1,554 ms	528,941 µs	31,943 ms	1,465 ms	PushPop	godunov_fine loops
0.0%	397,297 ms	1536	258,657 µs	196,445 µs	188,089 µs	33,599 ms	1,174 ms	PushPop	godunov_fine unlock all octs
0.0%	311,673 ms	4608	67,637 µs	62,396 µs	58,275 µs	10,126 ms	157,362 µs	PushPop	cmpflxm
0.0%	214,278 ms	1536	139,504 µs	137,149 µs	133,125 µs	3,299 ms	80,693 µs	PushPop	traceNd
0.0%	131,411 ms	1536	85,554 µs	61,875 µs	59,161 µs	34,311 ms	874,105 µs	PushPop	save flux Y
0.0%	110,519 ms	1536	71,952 µs	63,206 µs	60,237 µs	10,159 ms	261,684 µs	PushPop	uslope
0.0%	101,006 ms	1536	65,759 µs	62,842 µs	60,340 µs	2,166 ms	57,353 µs	PushPop	save flux Z
0.0%	98,094 ms	1536	63,863 µs	62,495 µs	59,268 µs	1,096 ms	26,479 µs	PushPop	save flux X

GPU

full GPU

# Porting of the hydro solver: problems

Superoct level 4: no significant speed-up

Superoct level 5: significant speed-up in the 1CPU vs 1GPU scenario. Sub-optimal in more realistic scenarios.

After evaluation and close collaboration with the support @ Cineca and @NVIDIA, we concluded that **offloading the Nbody component and part of the hydro modules to the GPU is currently not feasible.**

The Nbody and part the hydro modules rely on a `c_f_pointer` function, a Fortran intrinsic procedure used for interoperability with C/C++ code. This function facilitates the exchange of data between Fortran and other languages by providing a Fortran pointer from a C pointer or vice versa. However, this functionality is not available for GPU offloading

22.5 kpc

## Hydro:

The hydrodynamic equations describing the fluid motion are solved

## N-body:

~~the trajectories of collisionless particles (e.g., dark matter) are evolved using the leapfrog algorithm.~~

Completing the GPU porting of these components would require a complete rewrite of the memory management routines in MiniRAMSES, making the code significantly different from the public version and essentially turning it into a separate codebase from the original project.

# Next steps:

Change of code and topic:  
To develop and implement new routines in **RAMSES-RT** for handling **radiative feedback** from individual massive stars, while enhancing computational efficiency through **GPU porting** of critical components.

**RAMSES-RT**: A radiation-hydrodynamics extension of the **RAMSES** code.

It solves the coupled system of **gas dynamics, gravity, and radiative transfer** on an adaptive mesh refinement (AMR) grid.

Radiative transfer is implemented using the moment method with **M1 closure**.

Used to model processes like **reionization, star formation, and stellar feedback** in astrophysical systems.

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## New Radiative Feedback Routine

- **Individual star tracking**: Implement feedback from single massive stars instead of bulk populations.
- **Accurate photoionization**: Direct coupling between stellar radiation and surrounding gas.
- **Time-dependent flux**: Account for star luminosity evolution in time.

## Porting to GPU

- Offloading key routines from CPU to **GPU** to achieve higher parallelization.
- Reducing computational bottlenecks in **radiative transfer and flux updates**.
- Achieving significant speedup for **large-scale simulations**.



# Conclusions and Next steps



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**Impossible to complete the porting of Nbody component and Hydrodynamic solver as long as the NVIDIA compiler is updated.**

**We were able to port on GPU the majority of the subroutines associated with hydrodynamical component.**

The code has a significant speed up in case of superoct level 5, but not superoct level 4

**Initial attempts to employ OpenACC for GPU memory management have not yielded the desired results.**

Improving memory movement could result in significant speed-ups, particularly in scenarios where superoct level 4.

Enhance and optimize **RAMSES-RT** by developing advanced routines to accurately model radiative feedback from individual massive stars. This includes implementing a more precise feedback mechanism and porting key computational components to a **GPU architecture** for significantly improved performance and scalability.

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