







# **DAO4MATTO**: the Real-Time Control solution for a Multi-Conjugate Adaptive Optics test bench

Alessandro Ballone

on behalf of the whole

OAPd Instrumentation & Adaptive Optics Group

USCVIII General Assembly - 16/10/2024



### 16/10/24

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1









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USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench









Very happy to be here!

Until 2 yrs ago, I was doing theoretical astrophysics with hydrodynamical and N-body simulations.



### USCVIII- DAO4MATTO: the Real-Time Contro solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1









MATTO (Multi-conjugate Adaptive Techniques Test Optics) is a wide field adaptive optics bench, to be built starting from 2025.

Its ambitious goal is to serve as an international facility to test current and future MCAO techniques, mostly with off-the-shelf components.

It is probably the only multi-purpose bench that <u>can mimic very large and</u> <u>extremely large telescopes</u>!











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Funded by the Programma Nazionale di Resistenza e Resilienza (PNRR), through the **STILES** Program.

STILES: Strengthening the Italian leadership in ELT and SKA.

About 70M € for many different work packages.

Coordinated by INAF, in collaboration with 7 Italian Universities and international research institutes.

STILES is funding many projects in different INAF institutes!

https://pnrr.inaf.it/progetto-stiles/













How does AO work?

1) **measure the distortion** introduced in the incoming wavefront by the atmospheric turbulence (through a Wavefront Sensor)

2) the measured distortion is **converted in correction commands** of a corrector device (usually a Deformable Mirror)

This has to be done very fast (by a **Real-Time Control System**) at the typical time variation frequency of the atmospheric turbulence.











What is MCAO? And most importantly: why MCAO?

Anisoplanatism...

We are probing only the effect of turbulence close to our reference star (actually, within a turbulence coherence "isoplanatic" angle)



USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

![](_page_8_Picture_0.jpeg)

![](_page_8_Picture_2.jpeg)

![](_page_8_Picture_3.jpeg)

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![](_page_8_Figure_8.jpeg)

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

![](_page_9_Picture_0.jpeg)

![](_page_9_Picture_2.jpeg)

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What is MCAO? And most importantly: why MCAO?

Anisoplanatism...

We are probing only the effect of turbulence close to our reference star (actually, within a turbulence coherence "isoplanatic" angle)

We want to uniformly correct **larger fields of view** and for the **effect of different atmospheric layers**!

# **Multi-Conjugate Adaptive Optics**

And to cover the whole field of view and increase the sky coverage, Laser Guide Stars (LGS) are certainly needed!

![](_page_9_Figure_11.jpeg)

![](_page_10_Picture_0.jpeg)

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![](_page_11_Picture_11.jpeg)

Credit: Schmidt et al. (2017), Inouye Solar Telescope

![](_page_12_Picture_0.jpeg)

![](_page_12_Picture_2.jpeg)

![](_page_12_Picture_3.jpeg)

![](_page_12_Picture_4.jpeg)

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Credit: Neichel & Rigaut (2012), Gemini Observatory

![](_page_13_Picture_0.jpeg)

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# **Multi-Conjugate Adaptive Optics**

And to cover the whole field of view and increase the sky coverage, Laser Guide Stars (LGS) are certainly needed!

### All developed at OAPd!

![](_page_13_Figure_12.jpeg)

![](_page_13_Picture_13.jpeg)

![](_page_13_Picture_14.jpeg)

![](_page_14_Picture_0.jpeg)

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![](_page_14_Picture_3.jpeg)

![](_page_14_Picture_4.jpeg)

MATTO needs to adapt to:

- source types, numbers, positions
- (new!) wavefront sensing techniques
  - telescope sizes (the whole system has to be "rescalable")
- new technologies or future upgrades
- different atmospheric characteristics

The magic word is... MODULARITY!

![](_page_14_Picture_12.jpeg)

![](_page_15_Picture_0.jpeg)

![](_page_15_Picture_2.jpeg)

![](_page_15_Picture_3.jpeg)

![](_page_15_Picture_4.jpeg)

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![](_page_15_Figure_12.jpeg)

![](_page_16_Picture_0.jpeg)

Ministero dell'Università e della Ricerca

![](_page_16_Picture_3.jpeg)

![](_page_16_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

![](_page_16_Picture_7.jpeg)

### USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1

![](_page_17_Picture_0.jpeg)

![](_page_17_Picture_2.jpeg)

![](_page_17_Picture_3.jpeg)

![](_page_17_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- <u>3 normal LEDs</u> for the NGSs
- <u>3 OLED screens</u> for the LGSs (elongated!)

![](_page_17_Picture_9.jpeg)

![](_page_17_Picture_10.jpeg)

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1

![](_page_18_Picture_0.jpeg)

![](_page_18_Picture_2.jpeg)

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The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system

![](_page_18_Figure_8.jpeg)

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1

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The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system

E.g., <u>linear stages</u> to adjust the conjugation of the correction Deformable Mirrors

![](_page_19_Figure_9.jpeg)

Missione 4 • Componente 2 Investimento 3.1

![](_page_20_Picture_0.jpeg)

![](_page_20_Picture_2.jpeg)

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![](_page_20_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence

![](_page_21_Picture_0.jpeg)

![](_page_21_Picture_2.jpeg)

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![](_page_21_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence

If done in a controlled way, this means simulating a <u>turbulent phase</u> <u>distortion history</u> and inputting it on some physical wavefront aberrators.

Needs to be very fast. Typical turbulence coherence time frequency ~ **1 kHz**!!!

![](_page_22_Picture_0.jpeg)

![](_page_22_Picture_2.jpeg)

![](_page_22_Picture_3.jpeg)

![](_page_22_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence

### Aberrators:

- <u>3 Deformable Mirrors (97 actuators)</u> for the NGSs
- <u>3 Tip-Tilt Mirrors</u> + <u>3 fast Spatial Light</u> <u>Modulators</u> for the LGSs

![](_page_22_Picture_12.jpeg)

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1

![](_page_23_Picture_0.jpeg)

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![](_page_23_Picture_3.jpeg)

![](_page_23_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence

### Aberrators:

 <u>4</u> photo-lithographically etched phase screens, mounted on <u>fast rotating</u> <u>stages</u>

![](_page_23_Picture_11.jpeg)

![](_page_24_Picture_0.jpeg)

![](_page_24_Picture_2.jpeg)

![](_page_24_Picture_3.jpeg)

![](_page_24_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence
- measure the wavefront distortion

![](_page_24_Figure_10.jpeg)

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1

![](_page_25_Picture_0.jpeg)

![](_page_25_Picture_2.jpeg)

![](_page_25_Picture_3.jpeg)

![](_page_25_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence
- measure the wavefront distortion
- <u>6 stable Spatial Light Modulators</u> (phase masks)
   +
  - <u>6 GigE Vision technical cameras</u>

to mock any type of Wavefront Sensing Technique

![](_page_25_Picture_13.jpeg)

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1

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![](_page_26_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence
  - measure the wavefront distortion
  - correct the wavefront distortion

a) build an Interaction Matrix (corrector commands  $\rightarrow$  wavefront shape)

b) pseudo-invert the Interaction Matrix to get a **Reconstruction Matrix** (wavefront shape  $\rightarrow$  <u>corrector commands</u>)

At AO loop rates (≥ 1 kHz!!!) perform **Matrix-Vector-Multiplications** (MVMs) to move from measured wavefront aberrations to compensating commands.

In MCAO this has to be done "tomographically", i.e. for every layer of atmosphere

![](_page_27_Picture_0.jpeg)

![](_page_27_Picture_2.jpeg)

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![](_page_27_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence
  - measure the wavefront distortion
  - correct the wavefront distortion
- <u>3 Deformable Mirrors (~200, 450, 800 actuators)</u> for the wavefront correction (and possibly to introduce the simulated turbulent distortion).

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![](_page_28_Picture_4.jpeg)

The control system **operationally** needs to:

- simulate the sources

- move optical elements on motorized stages, to rescale the system
  - introduce simulated turbulence
  - measure the wavefront distortion
  - correct the wavefront distortion
- check the AO system performance

![](_page_28_Picture_12.jpeg)

![](_page_29_Picture_0.jpeg)

![](_page_29_Picture_2.jpeg)

![](_page_29_Picture_3.jpeg)

![](_page_29_Picture_4.jpeg)

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  - introduce simulated turbulence
  - measure the wavefront distortion
  - correct the wavefront distortion
- check the AO system performance

![](_page_29_Picture_12.jpeg)

<u>**1 GigE Vision "Scientific" Camera**,</u> with high resolution

USCVIII- DAO4MATTO: the Real-Time Control solution for a MCAO test bench

Missione 4 • Componente 2 Investimento 3.1

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mask

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WFS SLM

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#### **DAO4MATTO: Real-Time Control** OAPd CED 2 x Optical Fiber MMF Duplex LC OM4 23 x Direct attach copper cab WFS WFS WFS WFS WFS WES patch camera camera camera camera Many devices, some to be camera camera controlled typical coherence time frequency ~ 1 kHz!!! NGS turb DM NGS turb DM turb DM 3 x servers (OS: Linux) with 6 1 to 3 x DisplayPor 9 x RJ45 Cat6 Ethe UHSP UHSP LGS TTM turb turb SLM cutting-edge AMD EPYC 9648X Switched Switched SL M PDU PDU 3 x PCIe dedicated cabl **CPUs** 5 x RJ45 Cat6 Ethern 6 x USB WFS Switched Switched WFS WFS WFS Switched mask SLM mask PDU PDU PDU mask mask SLM SLM SLM 1 x storage server Switched Switched 4x turbulence PDU rotating PDU hase screens 1 x DisplayPort onito 2 x AMD/Intel workstations (OS: 5 x RJ45 Cat6 Ethernet WFS SLM WFS SLM WFS SLM WFS SLM Windows) for additional interface DM1 + DM2 + DM3 chille LGSWFS linear stages Switched PDU 8 x USB 12x LGS source 1 x 25Gb/s and 1 x 1Gb/s network LGS sources scientifi d sensing XY stages conjugation inear stage switches

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Finanziato dall'Unione europea NextGenerationEU

![](_page_31_Picture_2.jpeg)

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![](_page_31_Picture_4.jpeg)

#### **DAO4MATTO: Real-Time Control** 2 x Optical Fiber MMF Duplex LC OM4 WFS WFS WFS WFS WFS patch camera camera camera camera Many devices, some to be camera camera controlled typical coherence time frequency ~ 1 kHz!!! NGS turb DM NGS turb turb DM 3 x servers (OS: Linux) with 6 9 x RJ45 Cat6 Eth LGS TTM cutting-edge AMD EPYC 9648X Switched Switched PDU PDU **CPUs** 5 x RJ45 Cat6 Ethern WFS Switched Switched Switched PDU PDU PDU mask SLM 1 x storage server Switched Switched 4x turbulence PDU rotating PDU hase screens onite 2 x AMD/Intel workstations (OS: 5 x RJ45 Cat6 Ethernet WFS SLM WFS SLM Windows) for additional interface DM1 + DM2 + DM3 LGSWFS linear stage Switched PDU 8 x USB 12x LGS source LGS sources 1 x 25Gb/s and 1 x 1Gb/s network d sensing XY stages conjugation inear stage switches

![](_page_31_Picture_6.jpeg)

![](_page_32_Picture_0.jpeg)

Finanziato dall'Unione europea NextGenerationEU

![](_page_32_Picture_2.jpeg)

![](_page_32_Picture_3.jpeg)

![](_page_32_Picture_4.jpeg)

# **DAO4MATTO: Real-Time Control**

MATTO is multi-purpose  $\rightarrow$  needs to <u>adapt</u> to different experiments

MATTO is a facility  $\rightarrow$  long lived, can/will be <u>upgraded</u> with new devices

Again, the magic word is... MODULARITY!

We will develop our own RTC SW, based on the **DAO** (Durham Adaptive Optics) RTC package (in collaboration with CfAI)

![](_page_32_Figure_10.jpeg)

![](_page_33_Picture_0.jpeg)

Finanziato dall'Unione europea NextGenerationEU

![](_page_33_Picture_2.jpeg)

![](_page_33_Picture_3.jpeg)

![](_page_33_Picture_4.jpeg)

# **DAO4MATTO: Real-Time Control**

**DAO** (Durham Adaptive Optics) RTC package:

- Inspired by CACAO (Guyon+18), using NUMA-based shared memory data exchange between processes → Very modular!
- **Open source** (soon to be publicly released)
- C/C++ and Python based (low latency and jitter)
- Already compatible with a large number of devices
- Already provided with a large collection of H/SRTC functionalities
- Currently used and developed for other AO projects, including HARMONI's HRTC [3]

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Finanziato dall'Unione europea NextGenerationEU

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# DAO4MATTO: Real-Time Control

A very preliminary prototype of DAO4MATTO, to test DAO's functionalities, has been already implemented!

Single-conjugate AO system

- 1 ALPAO DM292 (292 actuators) Deformable Mirror
- 1 Shack-Hartmann Wavefront Sensor
- 2 FLI C-Blue One 1.7 technical and performance cameras

![](_page_34_Picture_11.jpeg)

![](_page_35_Picture_0.jpeg)

Finanziato dall'Unione europea NextGenerationEU

![](_page_35_Picture_2.jpeg)

![](_page_35_Picture_3.jpeg)

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![](_page_36_Picture_4.jpeg)

# DAO4MATTO: Real-Time Control

A very preliminary prototype of DAO4MATTO, to test DAO's functionalities, has been already implemented!

**OPEN LOOP** 

Wavefront

(SH centroids)

pupil plane

Single-conjugate AO system

- 1 ALPAO DM292 (292 actuators) Deformable Mirror
- 1 Shack-Hartmann Wavefront Sensor
- 2 FLI C-Blue One 1.7 technical and performance cameras

**CLOSED LOOP** 

![](_page_36_Picture_12.jpeg)

28/06/24

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# Summary:

- MATTO is a new facility for testing Multi-Conjugated Adaptive Optics at Very and Extremely Large Telescopes.
- At OAPd, but for the whole INAF and for any international institute wishing to use it!
- Very ambitious and multi-purpose → Maybe less demanding, but possibly as complex as a on-sky telescope instrument...
- DAO4MATTO is its Real-Time Control System. Equivalently complex!
- Work in progress, but a first complete version ready by the end of 2026.

# **STAY TUNED!**

![](_page_38_Picture_0.jpeg)

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![](_page_38_Picture_3.jpeg)

![](_page_38_Picture_4.jpeg)

# **Questions?** Suggestions?

Ballone et al. (2024), Proceedings of the SPIE, Volume 13101

Viotto et al. (2023), Proceedings of the Adaptive Optics for Extremely Large Telescopes (AO4ELT7), 7th Edition

The research activities described in this paper were carried out with the contribution of the Next Generation EU funds within the National Recovery and Resilience Plan (PNRR), Mission 4 - Education and Research, Component 2 - From Research to Business (M4C2), Investment Line 3.1 - Strengthening and creation of Research Infrastructures, Project IR0000034 – "STILES - Strengthening the Italian Leadership in ELT and SKA".

16/10/24

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