



# ASTRI PMC Software

S. Germani - Università di Perugia



DIPARTIMENTO DI ECCELLENZA  
MIUR 2023/2027  
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**unipg**  
DIPARTIMENTO  
DI FISICA E GEOLOGIA

CTA SST AIV Software Meeting  
Milano - 20/2/2024



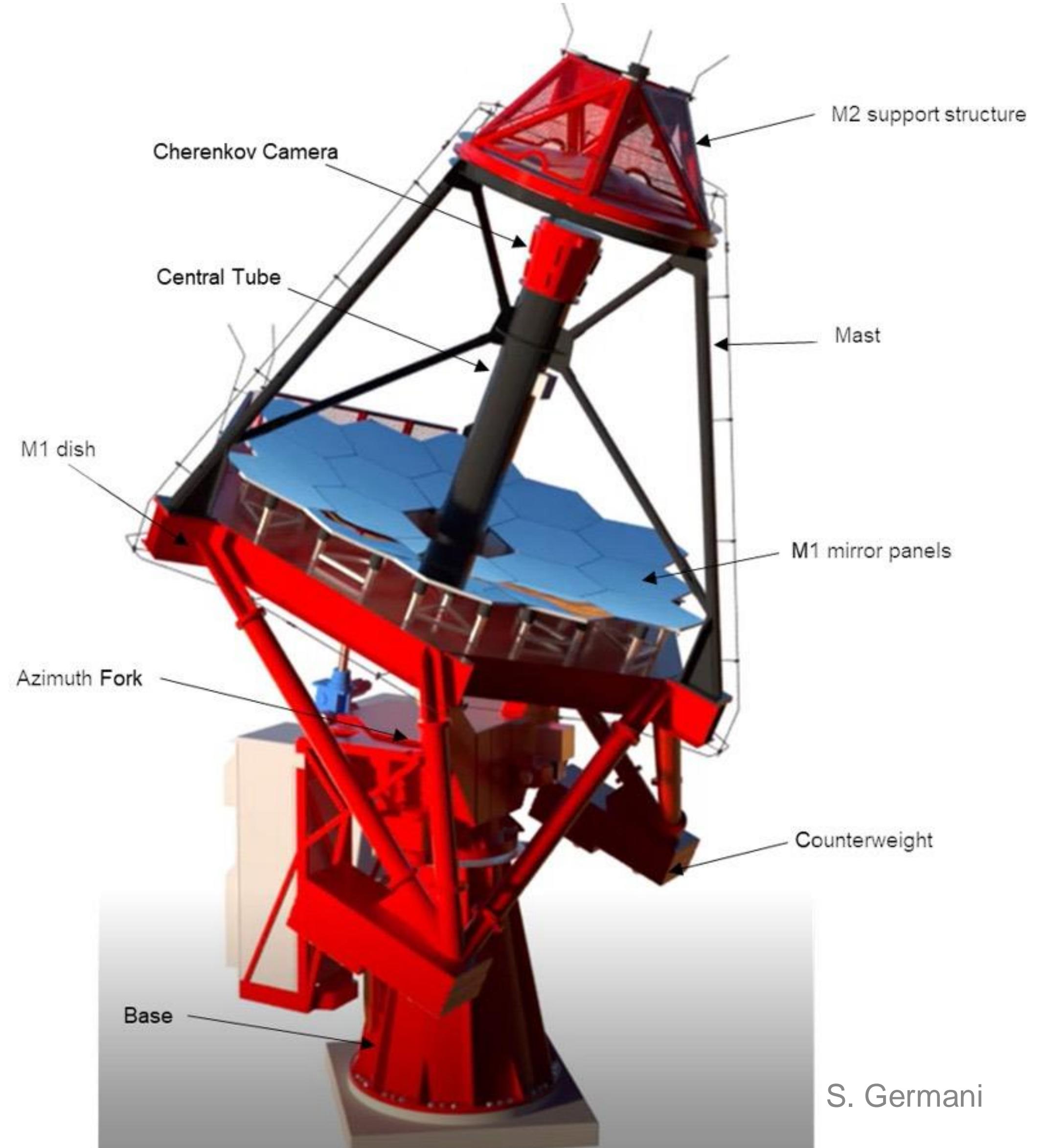
# Summary

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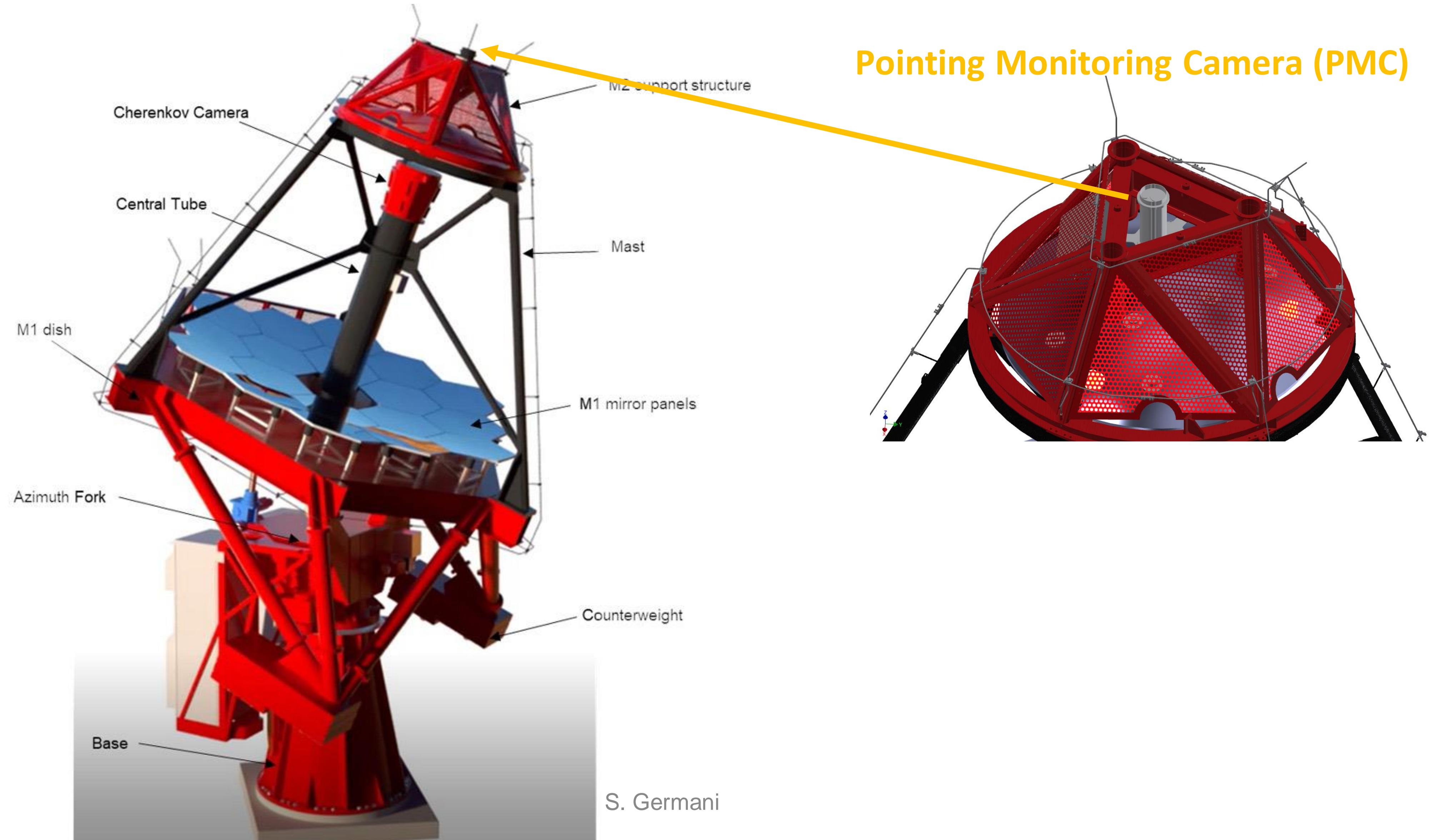


- ASTRI Mini Array PMC System
- PMC Hardware
- PMC Software
- ASTRI1 Tests

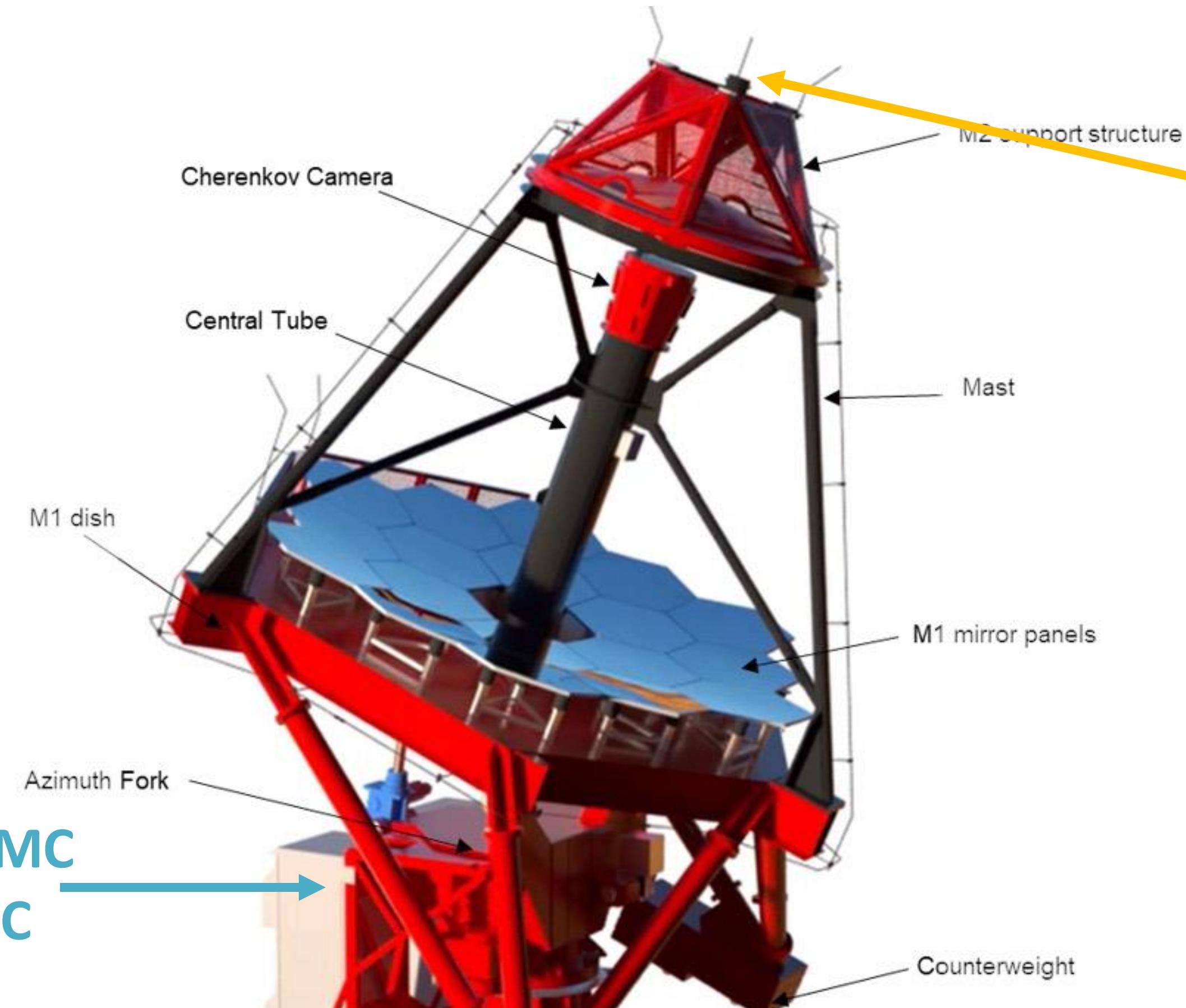
# The Hardware



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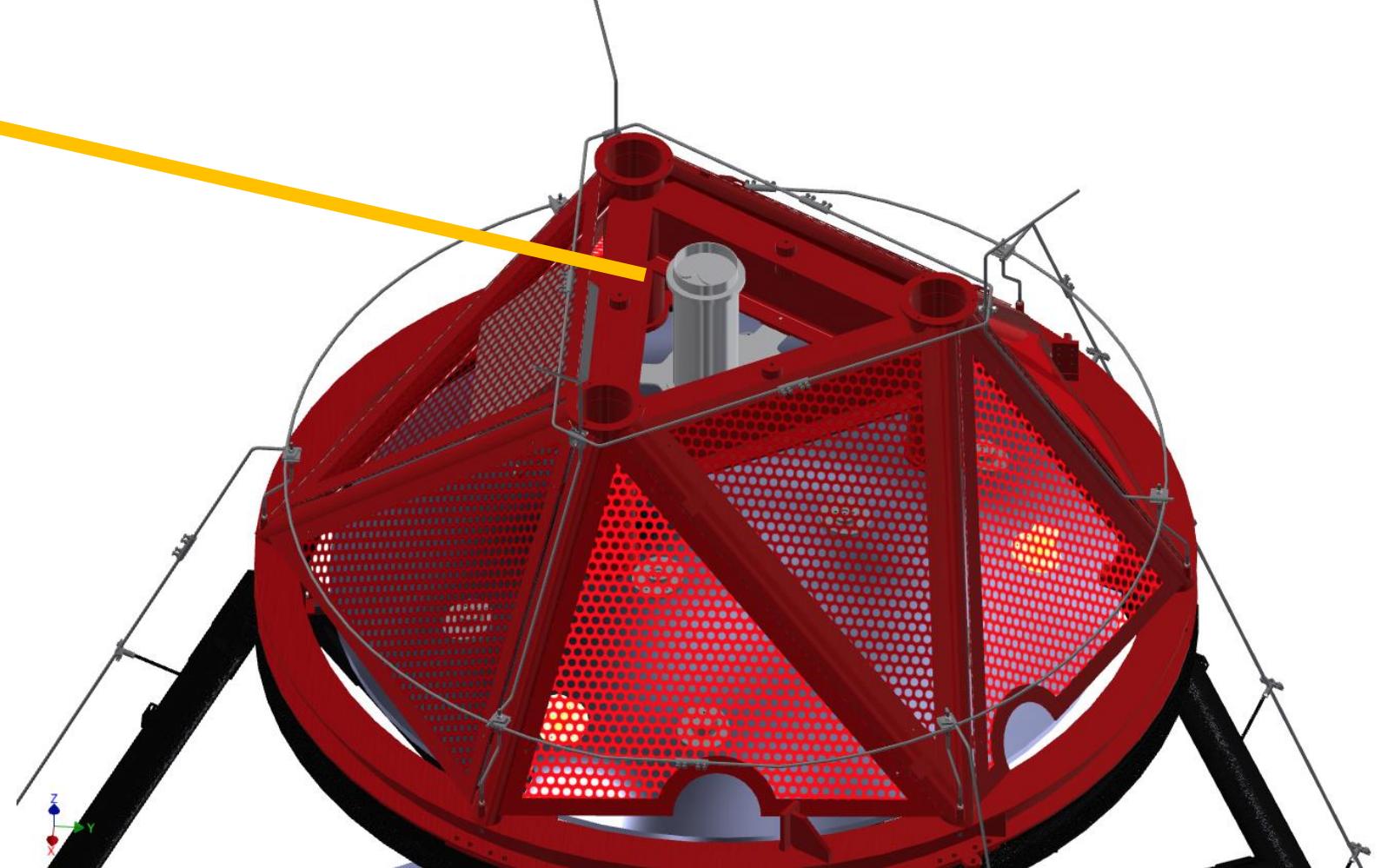
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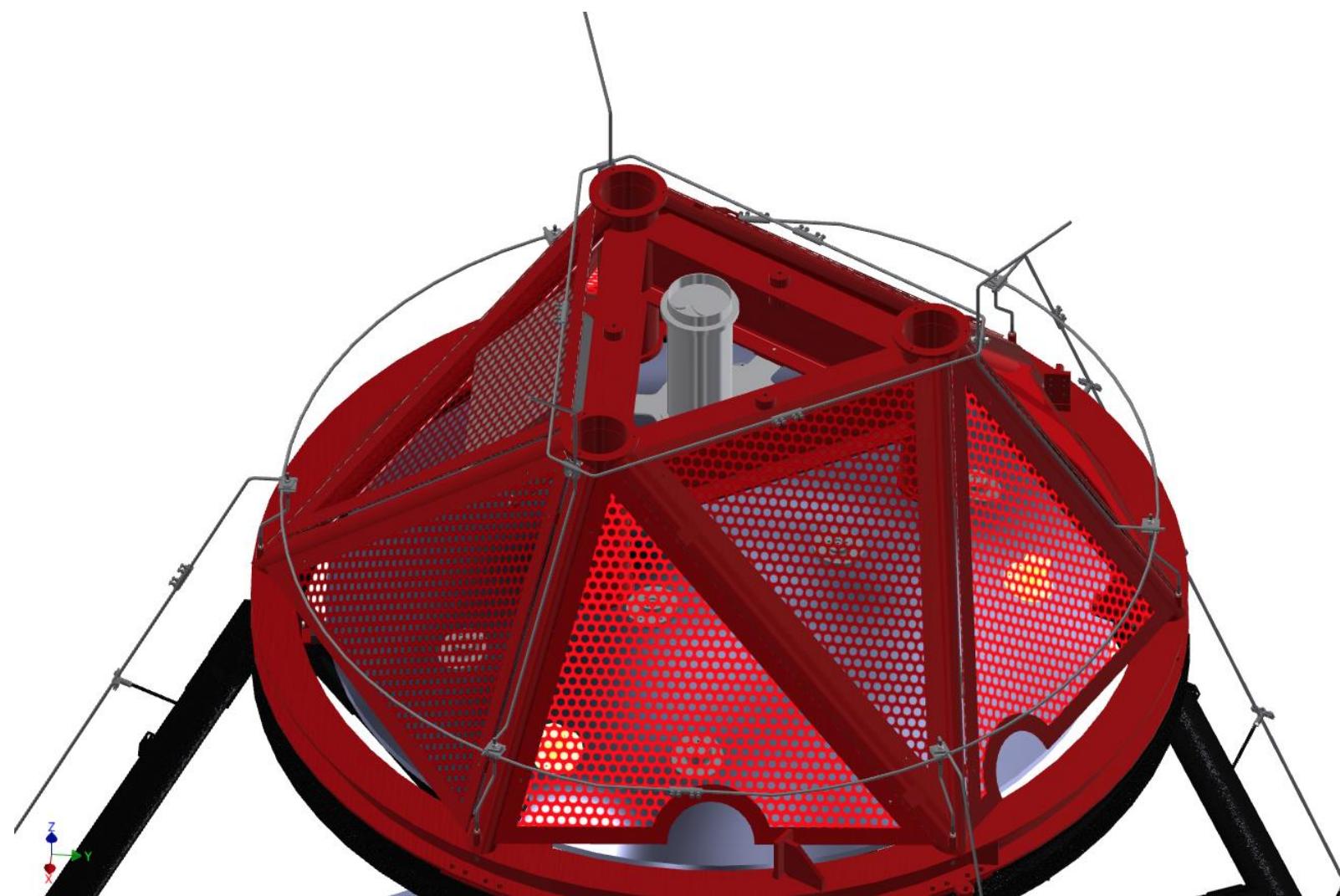
**Cabinet with PMC  
Local Control PC**



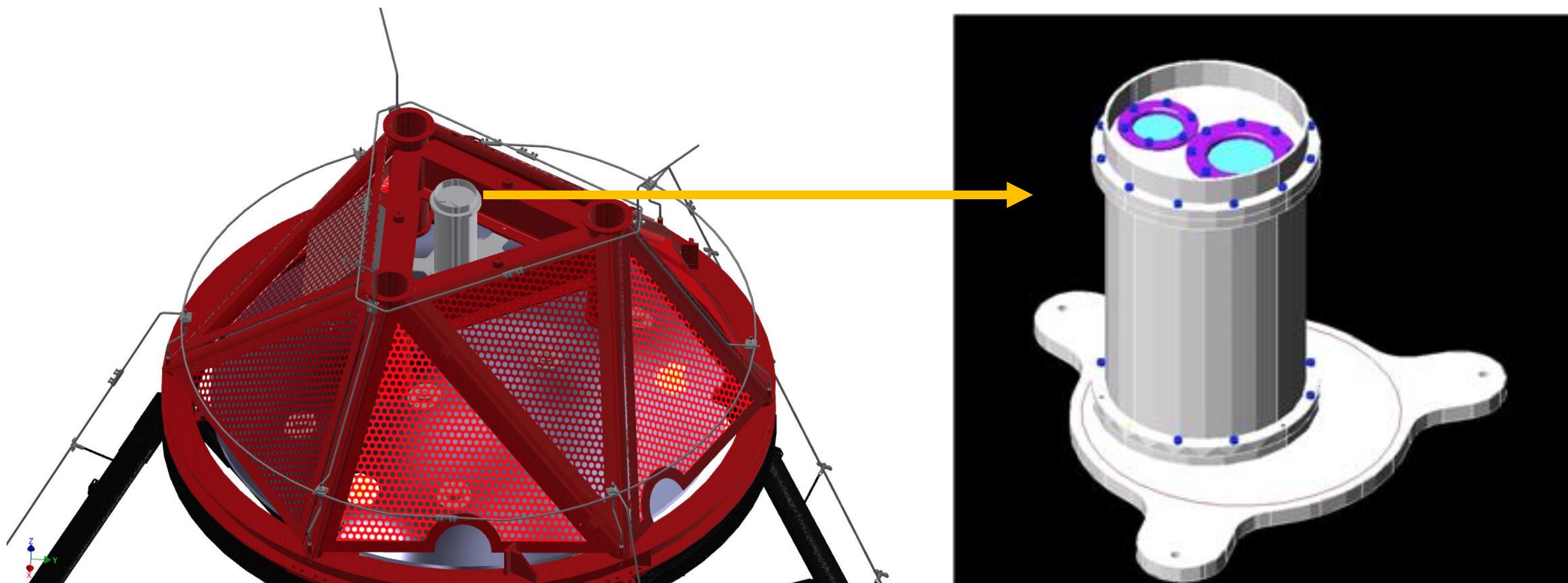
**Pointing Monitoring Camera (PMC)**



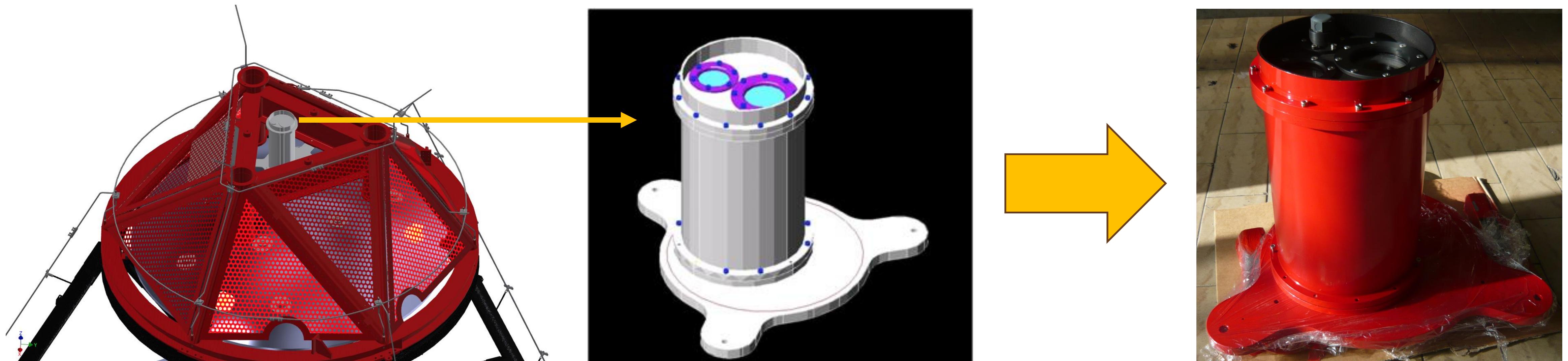
# The PMC Mechanical Structure



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# PMC Sensor and Optics

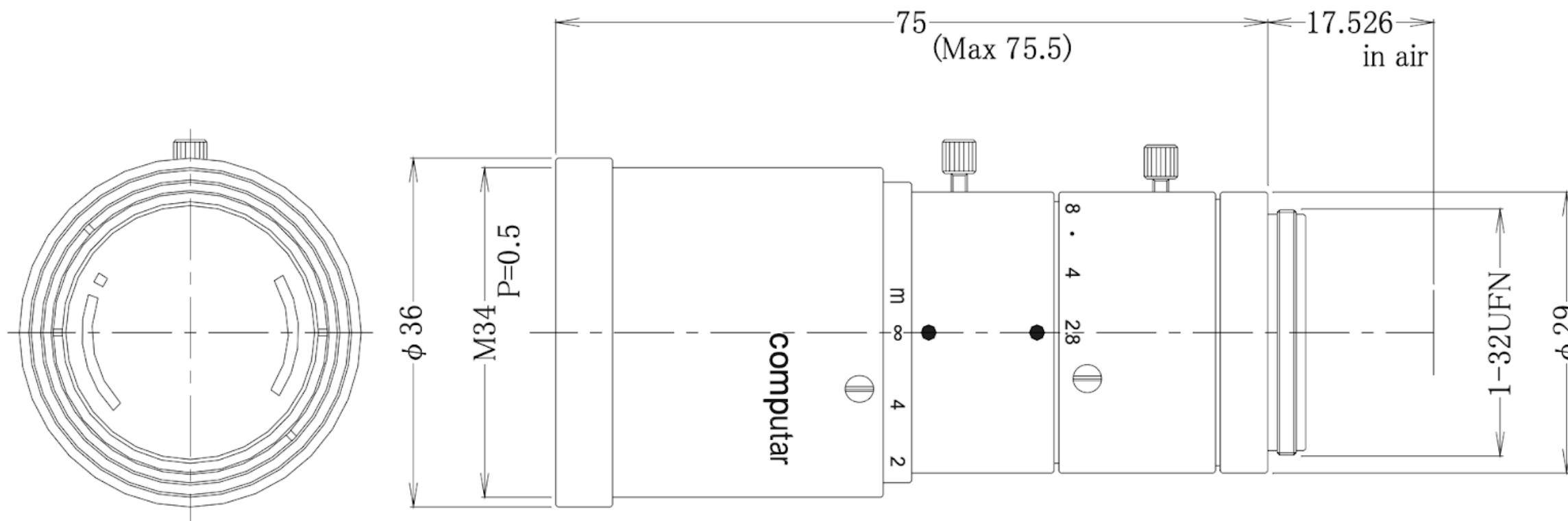


FLIR Blackfly S GigE  
(Model: BFS-PGE-63S4M-C)



# PMC Sensor and Optics

Computar M7528-MPW3 lens

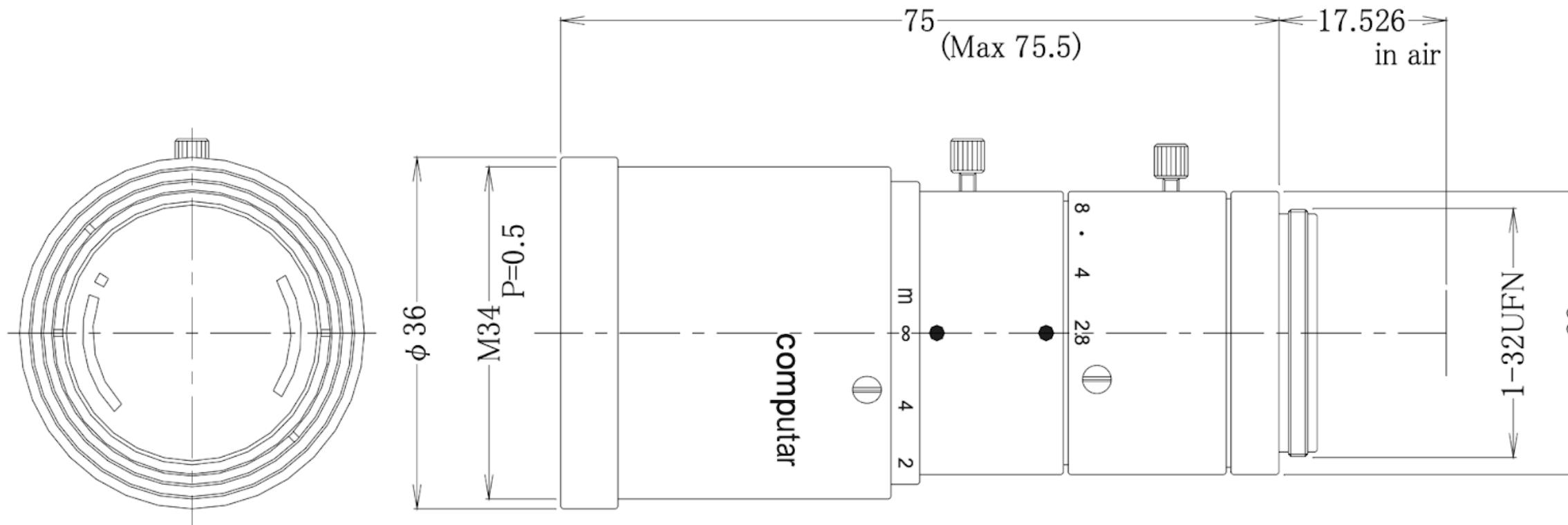


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# PMC Local Control PC

Fanless Industrial PC  
Linux OS (Ubuntu)  
1 Gbit LAN ports



# PMC Local Control PC

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PC configured as DHCP server  
assigning IP to Camera



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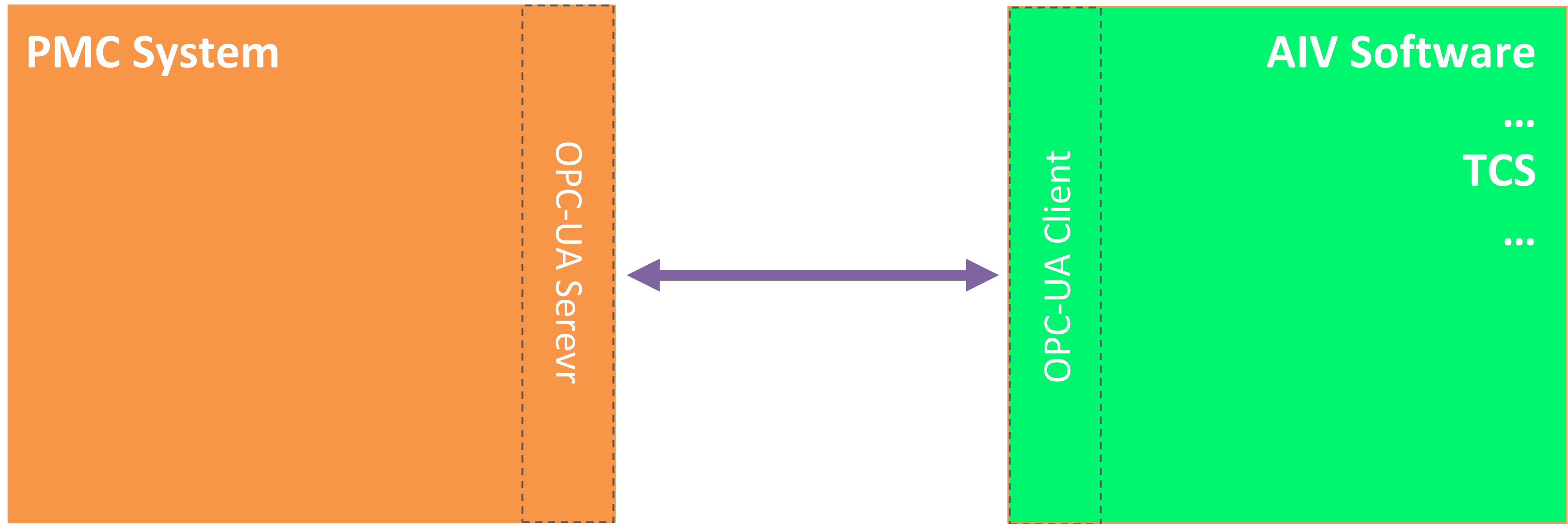
To Telescope  
Switch



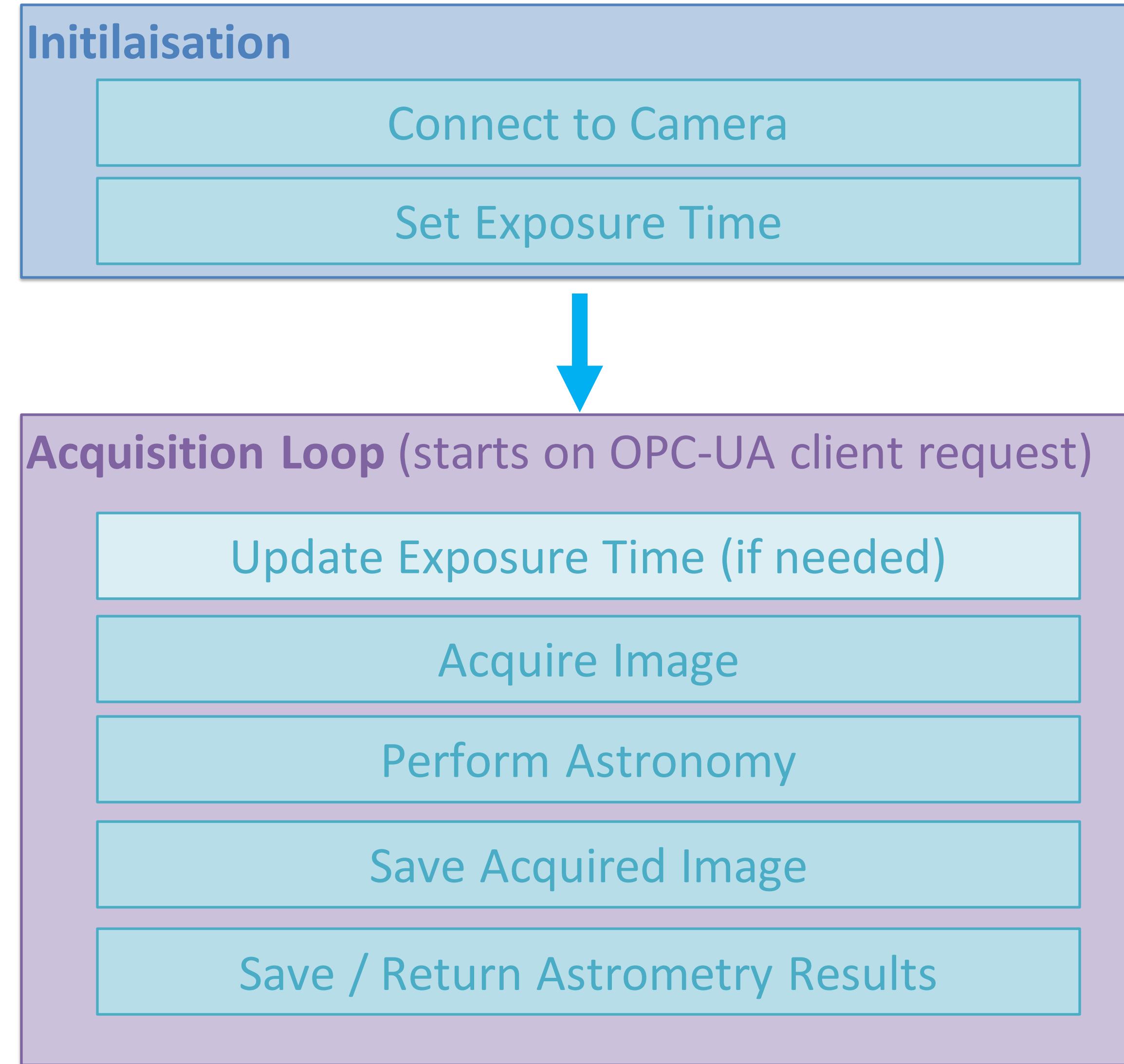
PC configured as DHCP server  
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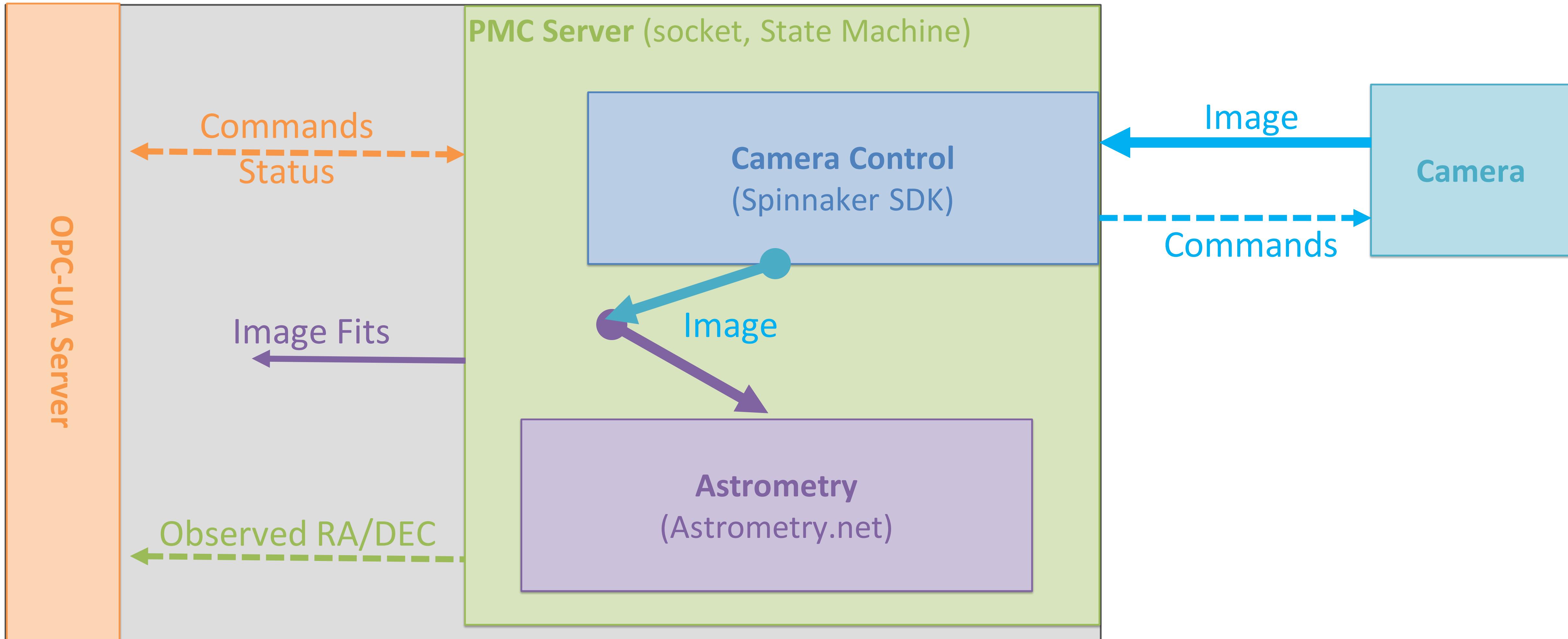
# OPC-UA Interface



# Operational Steps



# Functional Diagram



# Software Libraries



Reliable GigE Architecture, Exceptional Performance.

## Spinnaker SDK

C++ based

Linux → Ubuntu 20.04, Ubuntu 22.04, ...

<https://www.flir.eu/products/spinnaker-sdk/>



C based

Linux → Ubuntu / Debian...

<https://astrometry.net/>

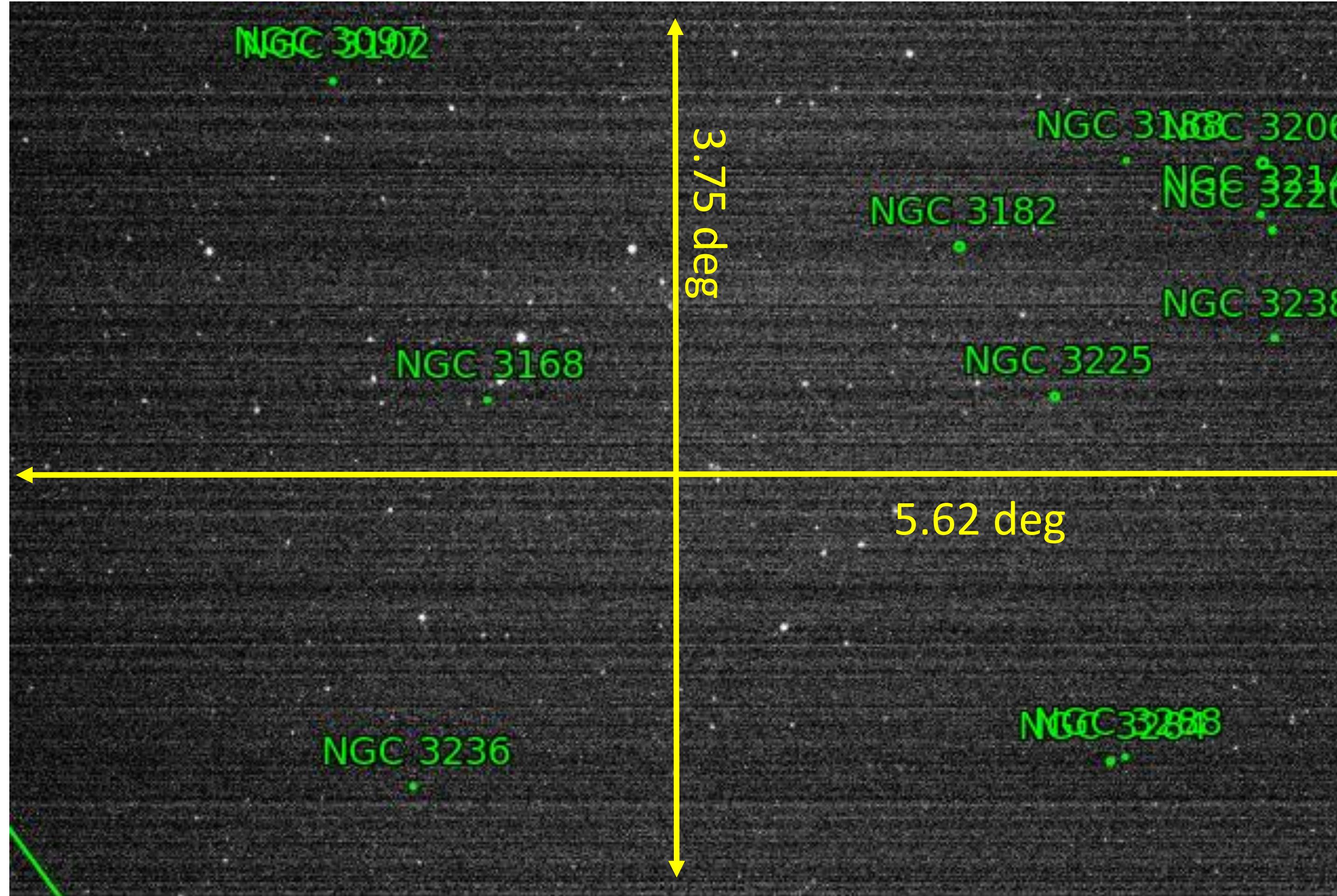


# Measures

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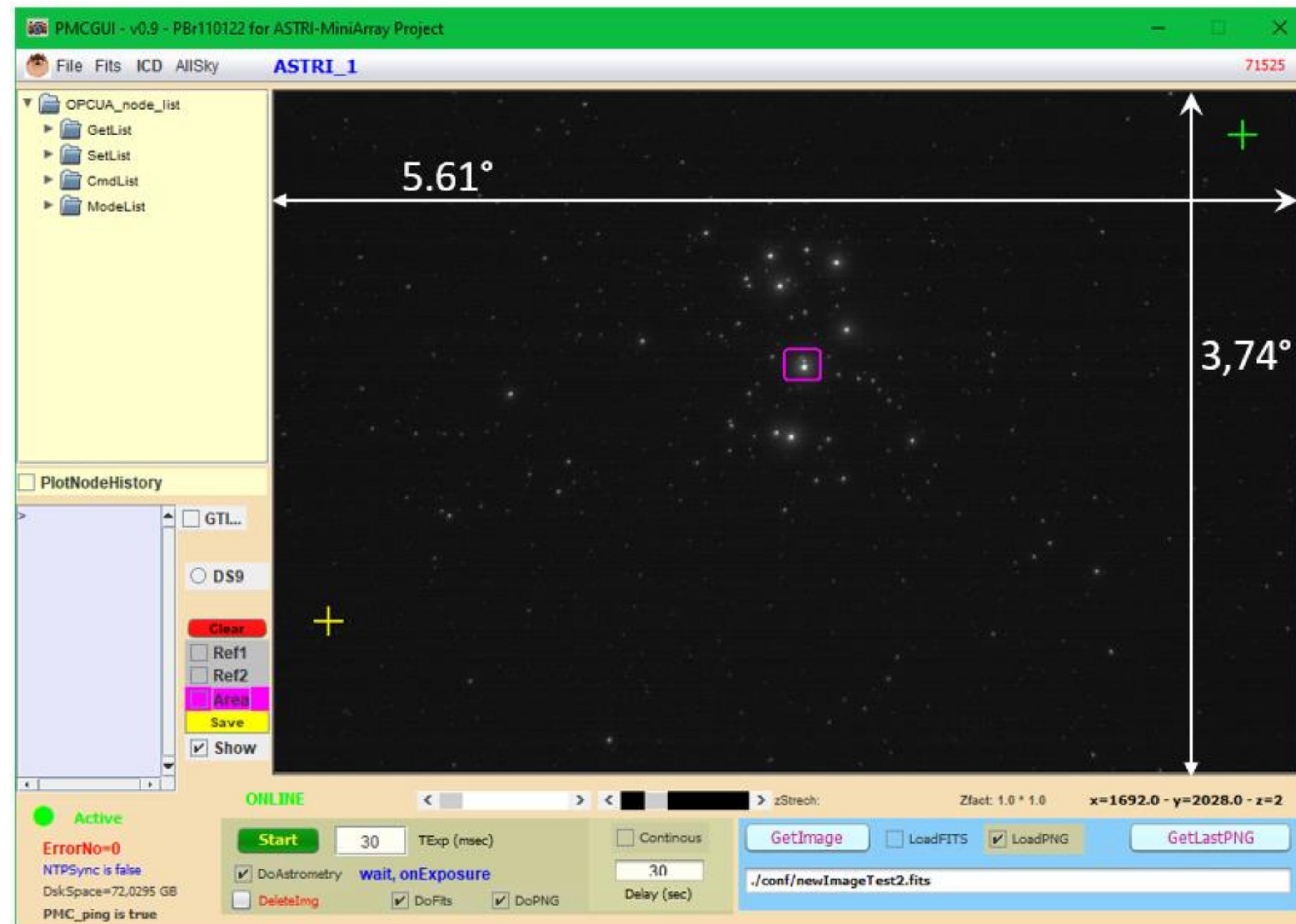


# Astrometry



Successfully tested exposure times  
below 1 ms

Typical exposure time used : 0.5-1 s



# Contributors

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- P. Bruno (INAF OA-Catania)
- OPC-UA Server
- AIV GUI
  
- S. Germani
- LCS PC Setup
- PMC Server (with Camera Control and Astrometry)  
developed starting from ASTRI-Horn software by D. Fugazza (INAF OA-Brera)

# Repeated Measurements

For several telescope positions the PMC image has been acquired twice in order to compare Astrometry results with the same expected Alt-Az

Difference between two measurements at the same Telescope position:

$$d = \theta_2 - \theta_1$$

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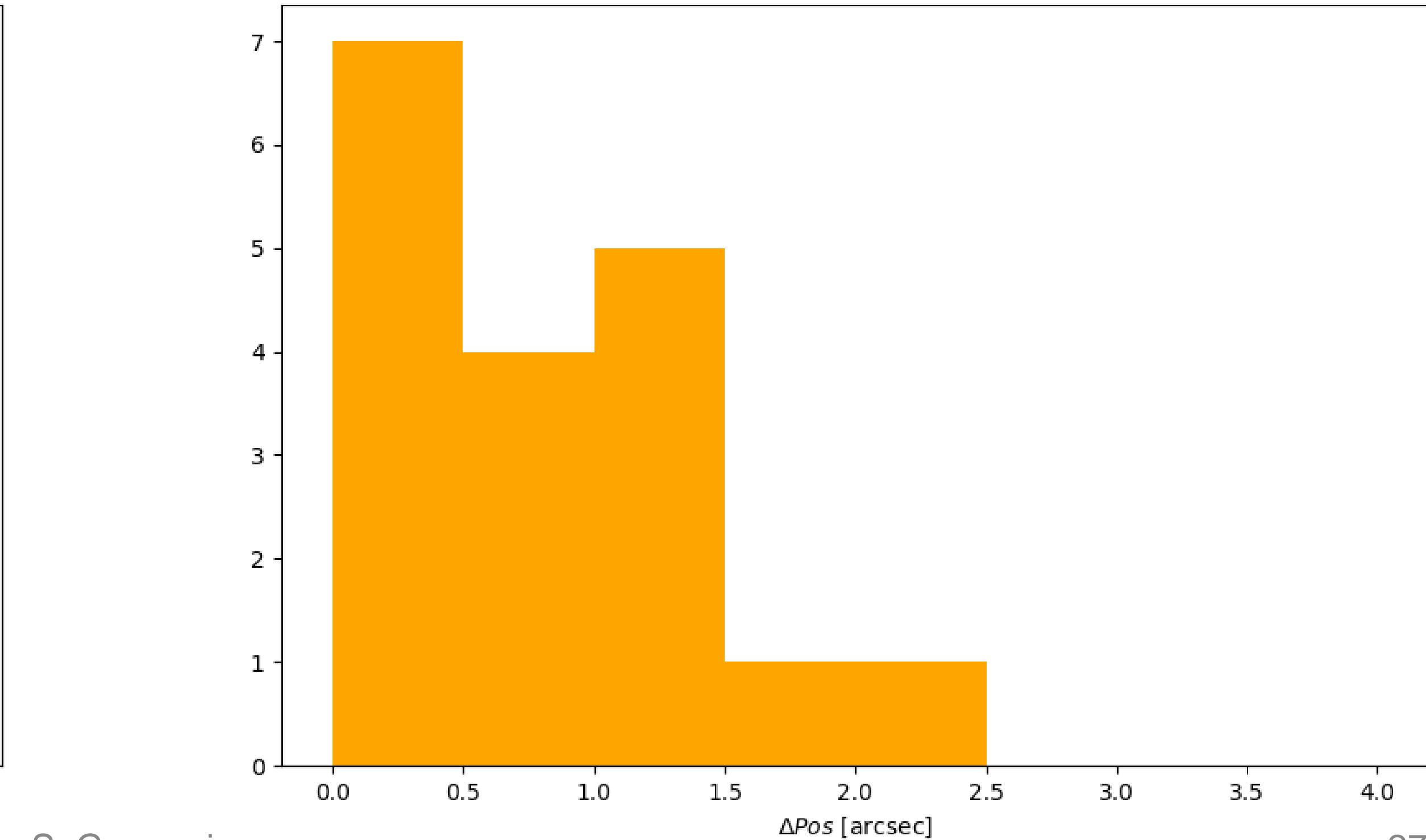
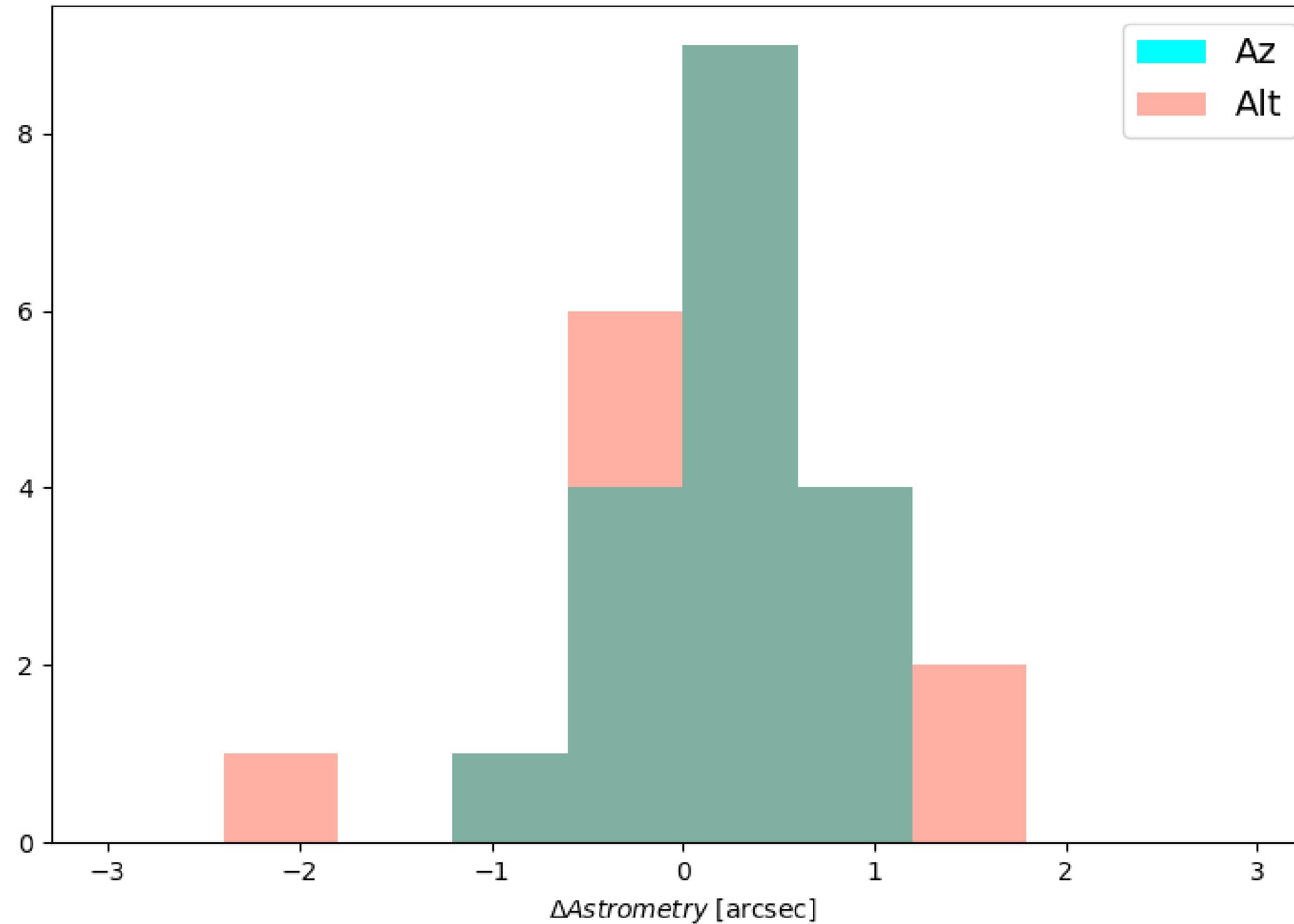
Extract the error on the angle measurement:

$$\sigma_\theta = \frac{\sigma_d}{\sqrt{2}}$$

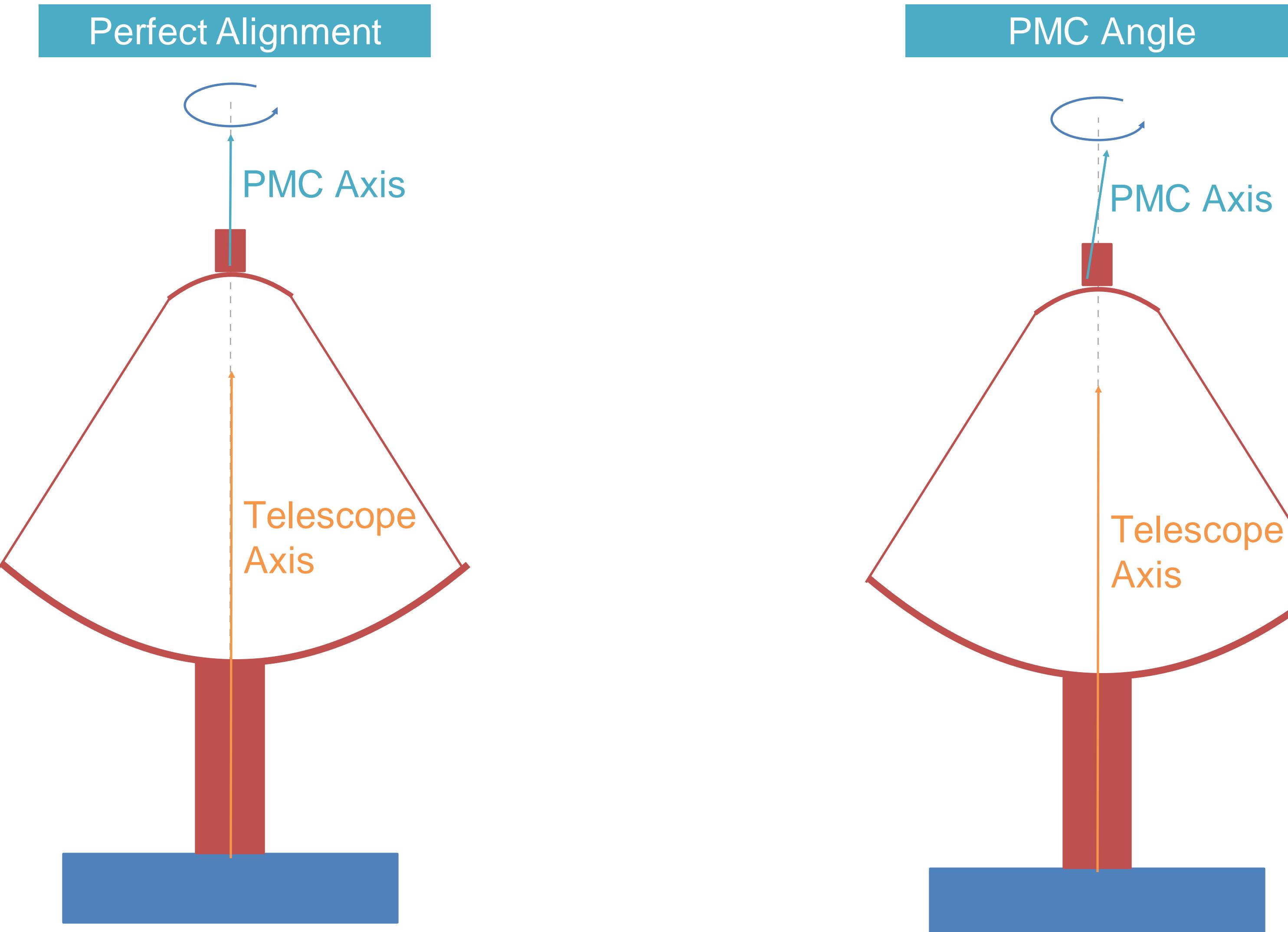
# Repeated Measurements

Az:  $StdDev \rightarrow 0.51$  arcsec  
Alt:  $StdDev \rightarrow 0.71$  arcsec  
Angle:  $68\% Quant \rightarrow 1.1$  arcsec

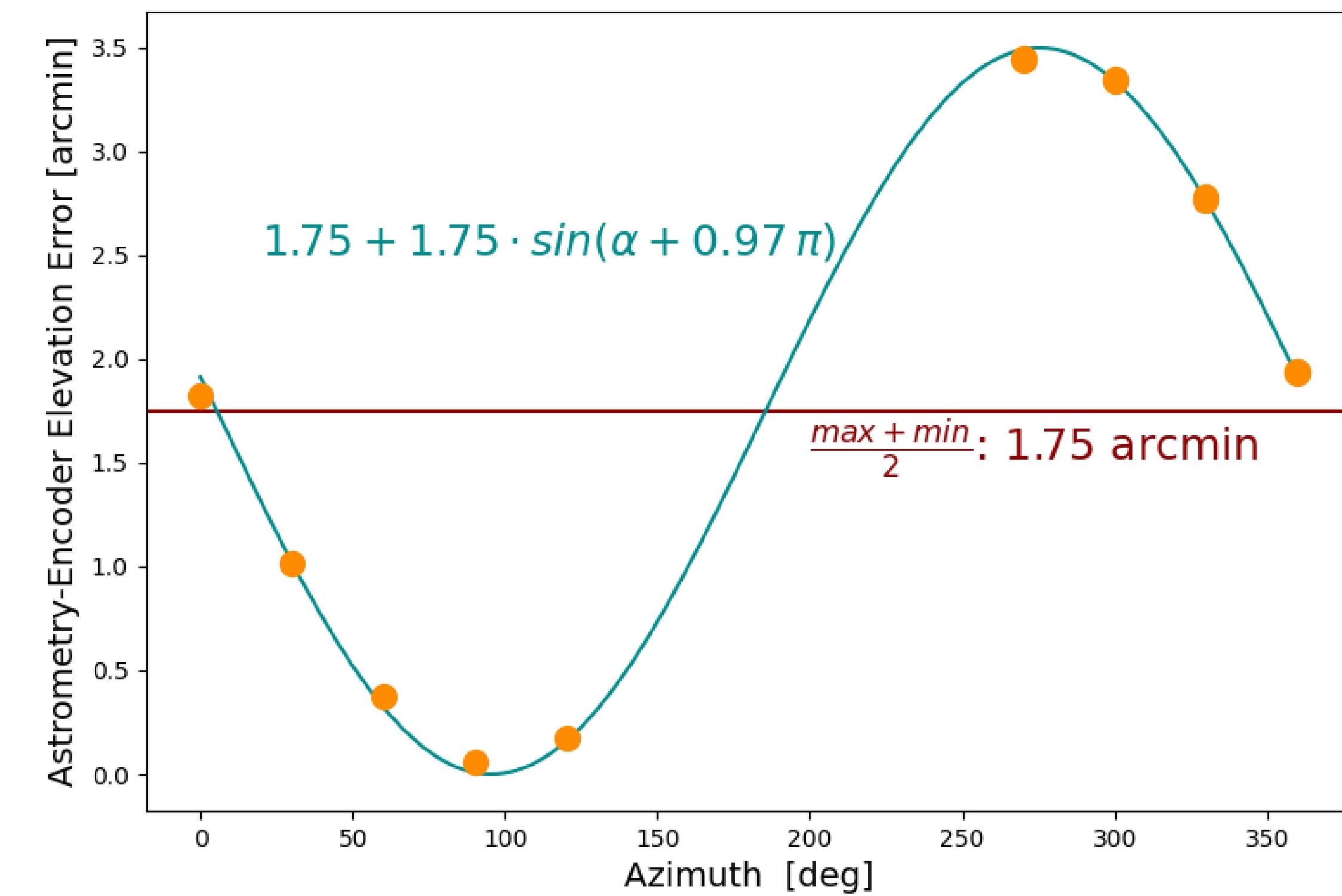
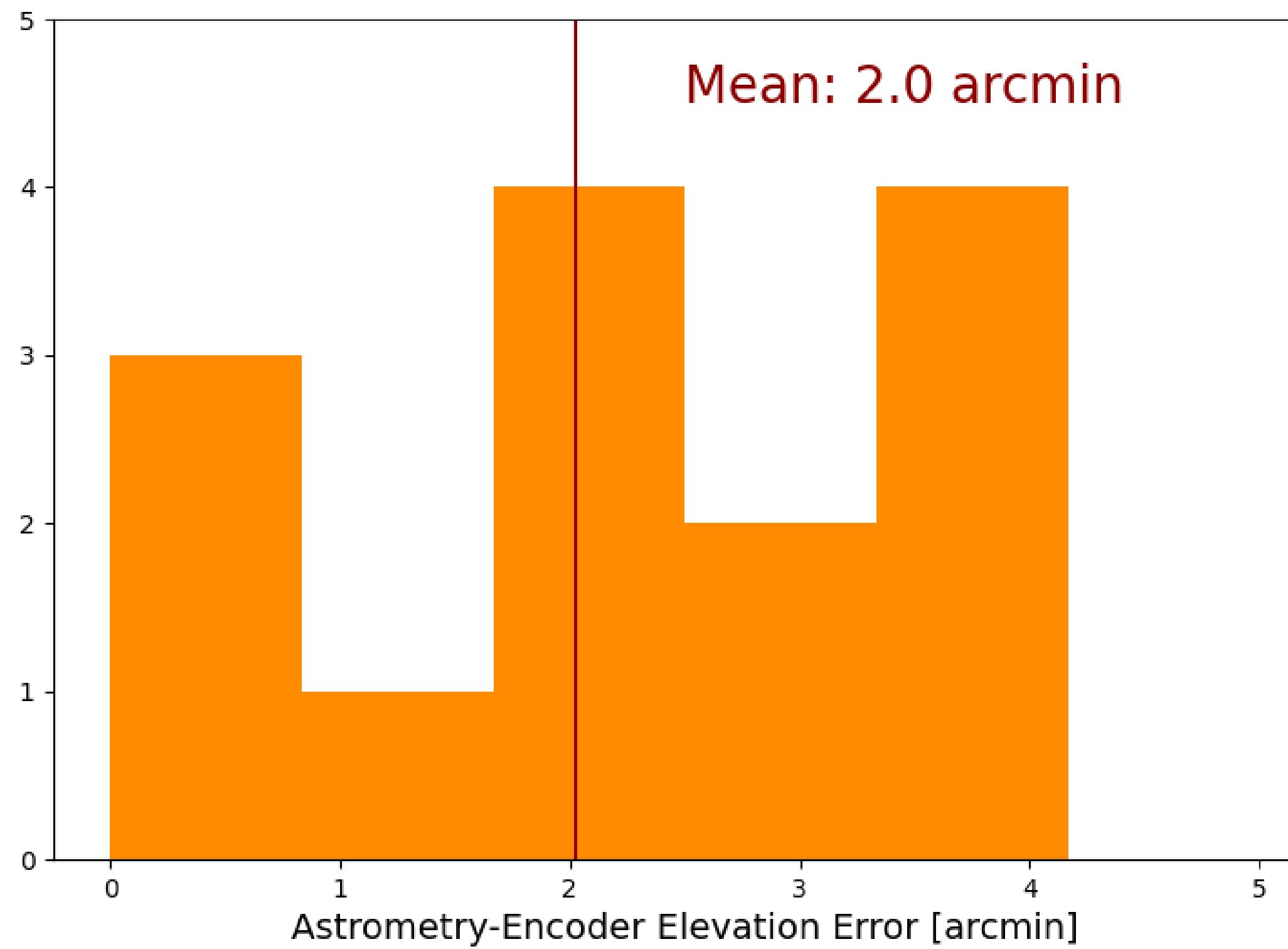
$StdDev/\sqrt{2} \rightarrow 0.4$  arcsec  
 $StdDev/\sqrt{2} \rightarrow 0.5$  arcsec  
 $68\% Quant/\sqrt{2} \rightarrow 0.8$  arcsec



# PMC - Structure Alignment Calibration



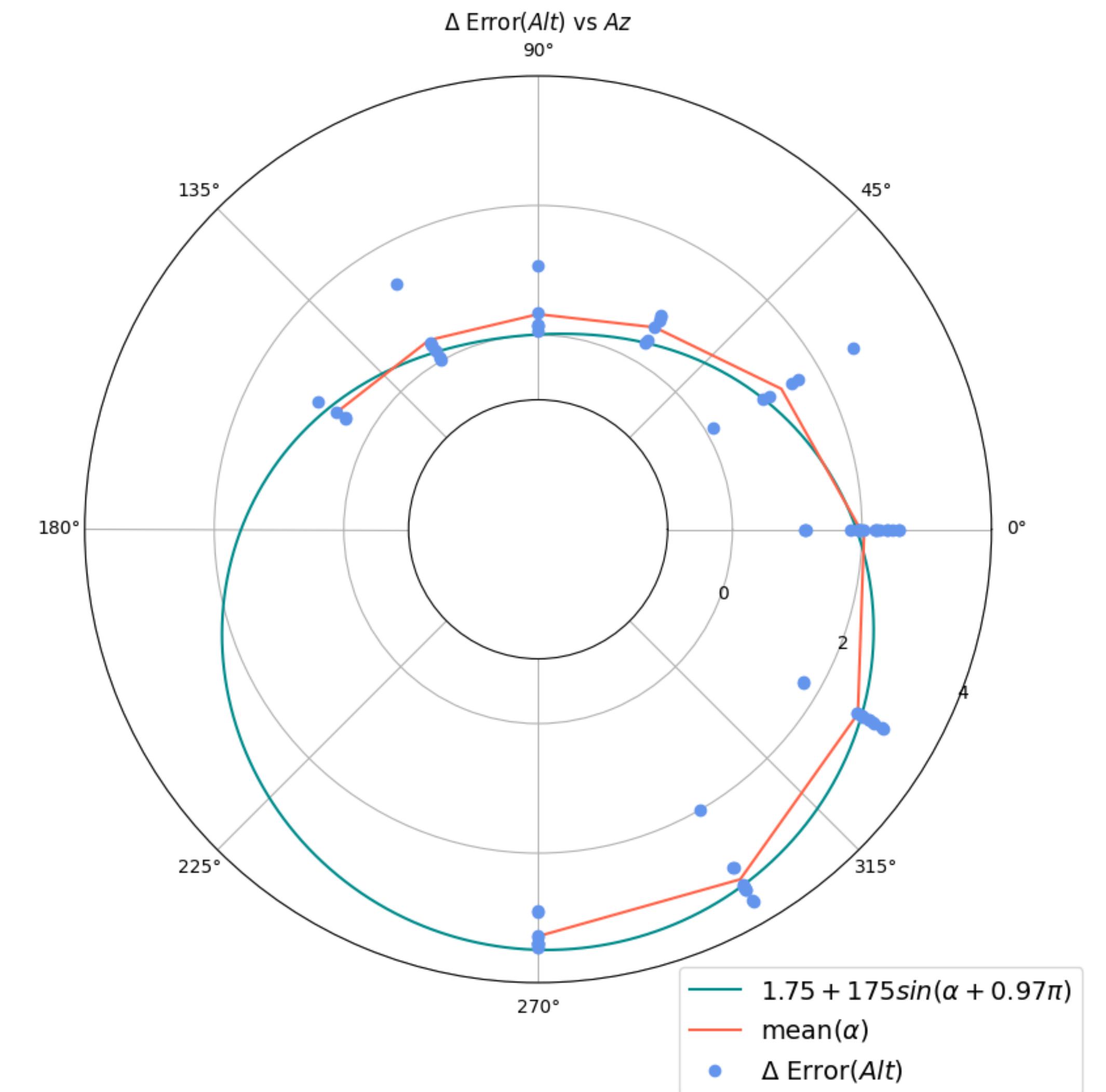
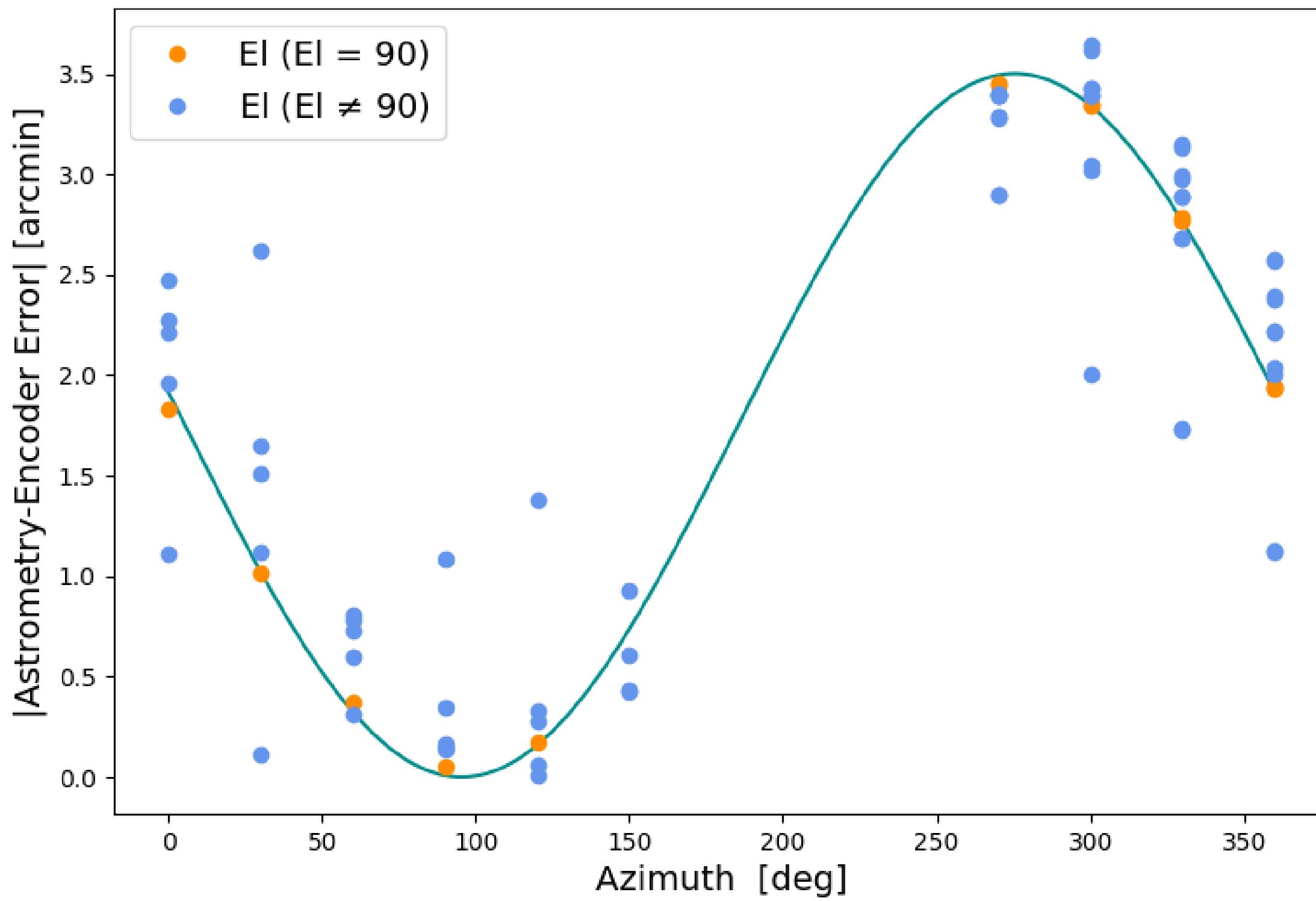
# Astrometry Error – Encoder Error: Alt~90°



# Alt Error Difference vs Az

Telescope Tracking Software Updated in the meanwhile – Measurement to be Repeated

|Astrometry Error – Encoder Error|



# Conclusions

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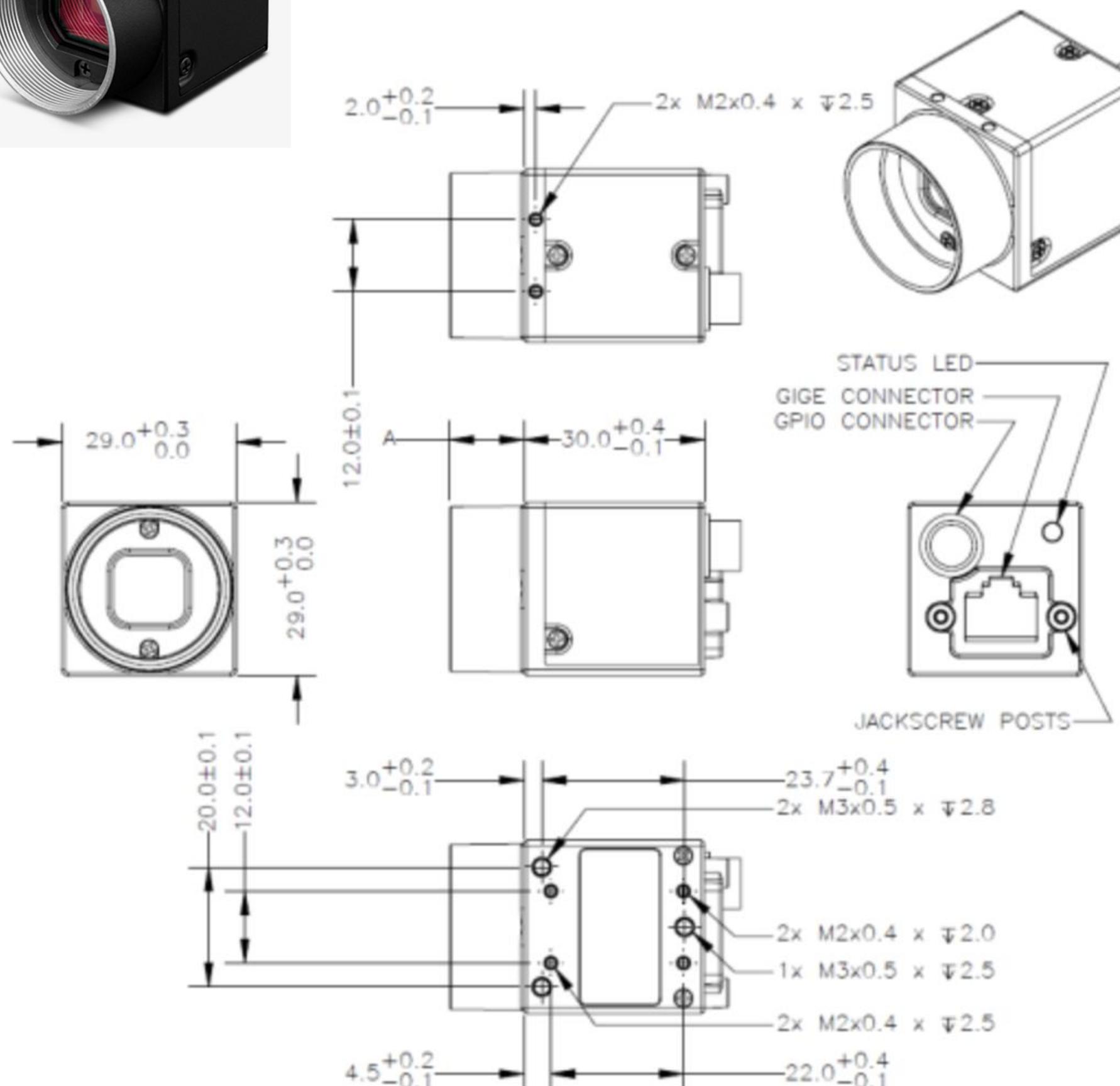
- PMC Software
- Dedicated LC PC Inside Telescope cabinet
- Control and Analysis C/C++ based
- External Interface OPC-UA based
- PMC System tested and used several times for ASTRI1 AIV
- Repeated Astrometry measurements at the same Telescope Pointing Directions (Angular measurement spread < 1 arcsec)

# Backup

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# Camera Details



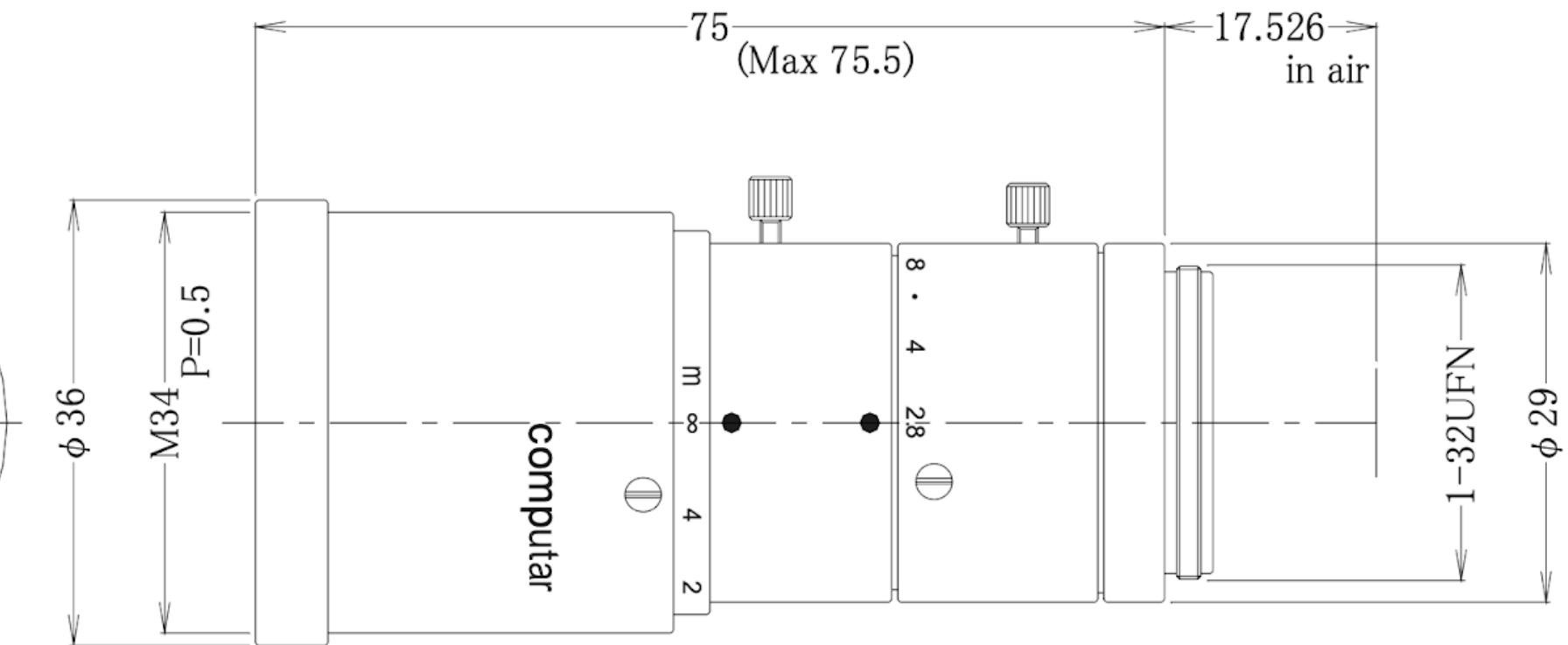
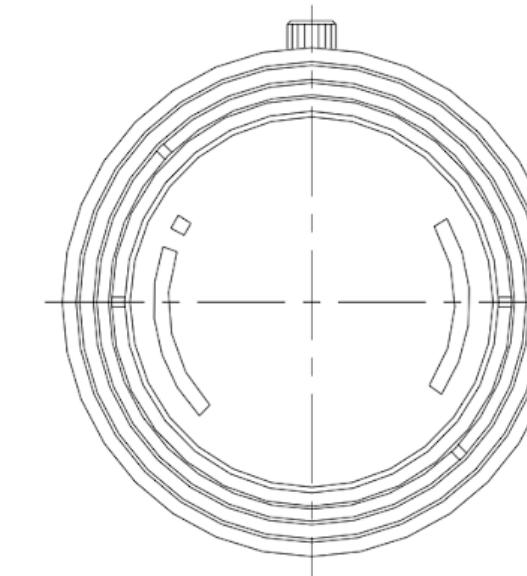
S. Germani

<b>BFS-PGE-63S4M</b>	
<b>Firmware Version</b>	1811.3.3.0
<b>Resolution</b>	3072 x 2048
<b>Frame Rate*</b>	19.0 FPS
<b>Megapixels</b>	6.3 MP
<b>Chroma</b>	Mono
<b>Sensor</b>	Sony IMX178, CMOS, 1/1.8"
<b>Readout Method</b>	Rolling shutter with global reset
<b>Pixel Size</b>	$2.4\text{ }\mu\text{m}$
<b>Lens Mount</b>	C-mount
<b>ADC</b>	10-bit / 12-bit/ 14-bit
<b>Minimum Frame Rate</b>	1 FPS
<b>Gain Range</b>	0 to 47 dB
<b>Exposure Range</b>	25 us to 30 s
<b>Acquisition Modes</b>	Continuous, Single Frame, Multi Frame
<b>Partial Image Modes</b>	Pixel binning, ROI
<b>Image Processing</b>	Gamma, lookup table, and sharpness
<b>Sequencer</b>	Up to 8 sets using 5 features
<b>Image Buffer</b>	240 MB
<b>User Sets</b>	2 user configuration sets for custom camera settings
<b>Flash Memory</b>	6 MB non-volatile memory
<b>Opto-isolated I/O</b>	1 input, 1 output
<b>Non-isolated I/O</b>	1 bi-directional, 1 input
<b>Serial Port</b>	Supported
<b>Auxiliary Output</b>	3.3V, 120 mA maximum
<b>Interface</b>	GigE
<b>Power Requirements</b>	Power over Ethernet (PoE); or 12 V nominal (8 - 24 V)
<b>Power Consumption</b>	2.6 W (POE); 2.1 W (GPIO) maximum
<b>Dimensions/Mass</b>	29 mm x 29 mm x 30 mm / 36 g
<b>Machine Vision Standard</b>	GigE Vision v1.2
<b>Compliance</b>	CE, FCC, KCC, RoHS, REACH. The ECCN for this product is: EAR099.
<b>Temperature</b>	Operating: 0°C to 50°C Storage: -30°C to 60°C
<b>Humidity</b>	Operating: 20% to 80% (no condensation) Storage: 30% to 95% (no condensation)
<b>Warranty</b>	3 years

# Optics Details

$f = 75\text{mm}$   $F 2.8$   
For 2/3 type Cameras  
C-Mount

**M7528-MPW3**



2/3  
type

C

Model No.	M7528-MPW3		Effective Lens Aperture	Front	$\phi 26.1\text{mm}$	
Focal Length	75mm			Rear	$\phi 15.8\text{mm}$	
Max. Aperture Ratio	1:2.8			Distortion	2/3 type( $Y=5.5\text{mm}$ ) <b>0.33%</b>	
Max. Image Format	$8.8\text{mm} \times 6.6\text{mm} (\phi 11\text{mm})$			1/1.8 type( $Y=4.5\text{mm}$ )	<b>0.21%</b>	
Operation Range	Iris	F2.8 - 16.0		1/2.5 type( $Y=3.55\text{mm}$ )	<b>0.12%</b>	
	Focus	0.4m - inf.		Back Focal Length	14.6mm	
Control	Iris	Manual		Flange Back Length	17.526mm	
	Focus	Manual		Mount	C-Mount	
Object Dimension at M.O.D.	2/3 Type	47.0 x 35.2 mm		Filter Size	M34 P=0.5mm	
	1/1.8 Type	38.4 x 28.8 mm		Dimensions	$\phi 36\text{mm} \times 75\text{mm}$	
	1/2.5 Type	30.4 x 22.9 mm		Weight	102g	
Angle of View	D	2/3 type	1/1.8 type	1/2.5 type	$5.4^\circ$	
	H				$4.3^\circ$	
	V				$3.3^\circ$	
Operating Temperature	$-10^\circ\text{C} - +50^\circ\text{C}$					

# Repeated Measurements -Toy MC

