What is the surface of a (dynamical) Black Hole?

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Outline

1 Introduction

- 2 Closed trapped surfaces
- **3** Marginally trapped tubes and dynamical Black Holes
- 4 Closed trapped surfaces are clairvoyant !
- **5** The boundary of the region with closed trapped surfaces
- 6 Black Hole Cores



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- But..., what do we mean by A?

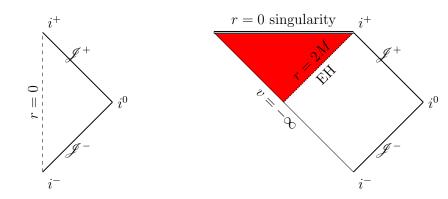


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• Classically, the characteristic feature of a BH is its event horizon EH: the boundary of the region from where one can send signals to infinity —one assumes infinity is well-defined.



The Event Horizon (EH)





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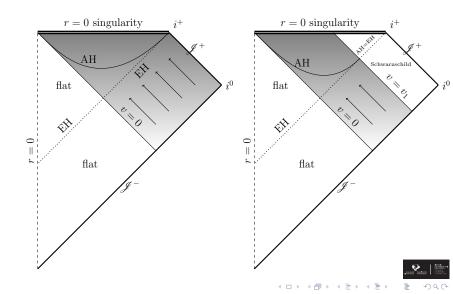


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- However, this leads to unsurmountable practical problems for dynamical BHs.
- EH depends on the *whole* future evolution of the spacetime. In fact, EHs can even start developing in flat regions of spacetime! EHs are *teleological*.



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Teleology of the EH (observe central line!)



How to tell if something is a BH or not?

- How can one recognize, locally, the presence of a BH? For instance, in numerical GR. Or in Astrophysics: what do we mean by the sentence "there is a BH in the center of the Galaxy"?
- As a drastic example of the problems arising Hajicek (Phys. Rev. D 36 (1987) 1065) argued that the structure of the EH can be radically changed, and even fully destroyed, by changing the geometry of the spacetime in a Planck size neighbourhood.



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It is only natural to turn to closed trapped surfaces, the hallmark of gravitational collapse.



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Trapped surfaces



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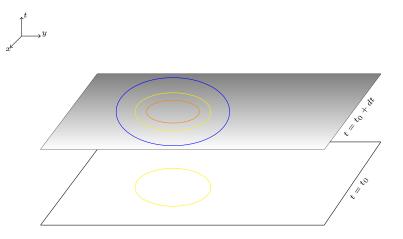
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- The traditional <u>stationary</u> Black Hole solutions have closed trapped surfaces in the region <u>inside the Event Horizon</u>, and only there. And the EH is foliated by marginally trapped surfaces.



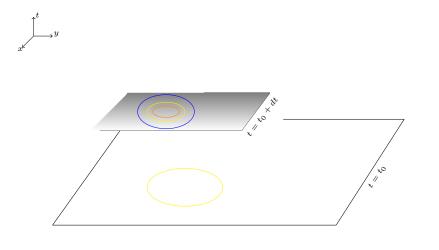
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"Normal situation"





Possible trapping in contracting worlds





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Marginally trapped tubes



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- Actually, MTTs satisfy laws of thermodynamics similar to those of EH. In particular, their area (→ entropy) grows during the collapse, and decreases with Hawking radiation.



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• $ds^2 = g_{ab}(x^c)dx^a dx^b + r^2(x^c)d\Omega^2$ $(a, b, \dots = 0, 1)$ Here $d\Omega^2$ is the round metric on the 2-sphere and det $g_{ab} < 0$.



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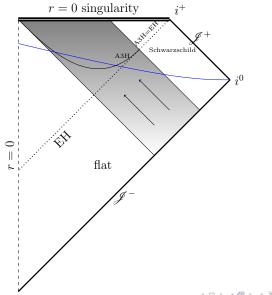
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- In Schwarzschild, $EH \equiv A3H \equiv A3H^{iso}$



Example: The spherically symmetric MTT (A3H)

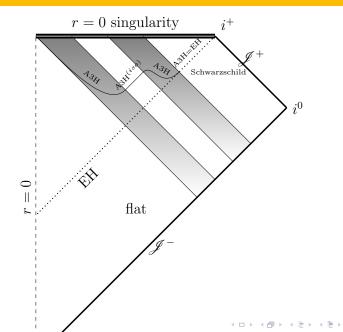




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Case with a portion of Isolated Horizon A3H^(iso)





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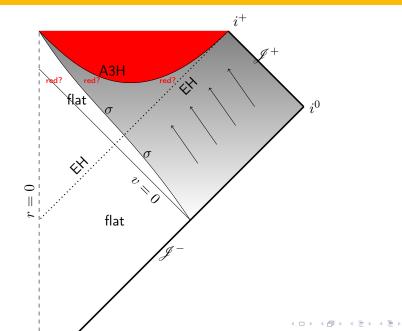
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 - 2 Any closed trapped surface cannot be fully contained in a region with r > 2m.
 - 3 Thus, all possible closed trapped surfaces must intersect the region with r < 2m.
- But, can closed trapped surfaces —other than round spheres—penetrate outside A3H? How far can they go?



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A dynamical situation





A3H does not bound general trapped surfaces

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- How far can these closed trapped surfaces go away from A3H?



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- Can closed trapped surfaces actually penetrate into flat regions?
- Where can there be closed trapped surfaces?



Trapped surfaces behave wildly



Trapped surfaces even penetrate flat portions!

Example: imploding Vaidya spacetime

Vaidya $ds^2 = -\left(1 - \frac{2m(v)}{r}\right)dv^2 + 2dvdr + r^2d\Omega^2$



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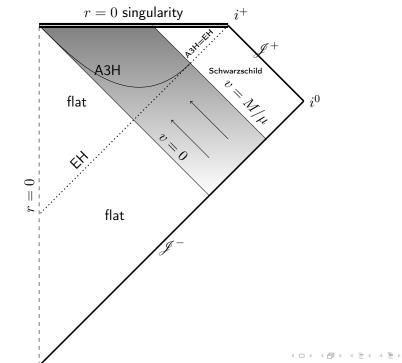
Consider the following simple mass function

$$m(v) = \begin{cases} 0 & v < 0\\ \mu v & 0 \le v \le M/\mu\\ M & v > \mu \end{cases}$$

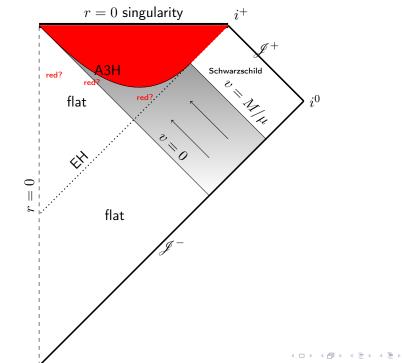
Thus, this is flat for v < 0, it ends in a Schwarzschild region with mass M ($v > M/\mu$), and it is self-similar in the intermediate Vaidya region for $0 < v < M/\mu$.



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A closed trapped surface penetrating outside A3H and into the flat region!

We constructed, analytically and explicitly, examples of closed future-trapped surfaces going far away from $r \leq 2m$ and entering well inside the flat region in the (self-similar) Vaidya spacetime.



The closed future-trapped surface is composed of:



• Flat region: a topological disk on an equatorial plane



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- Vaidya region: a topological cylinder on that equatorial plane



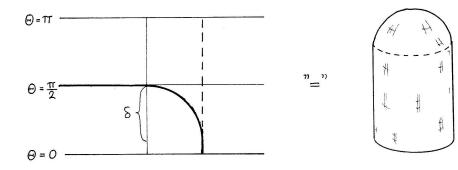
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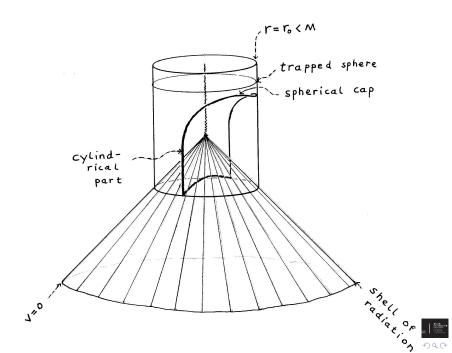
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 - $\bullet\,$ a final "capping" disk defined on $r=\gamma M$
- Here $\gamma < 0.68514$ is a constant, and $\mu > \frac{1}{4\gamma}$ is required.



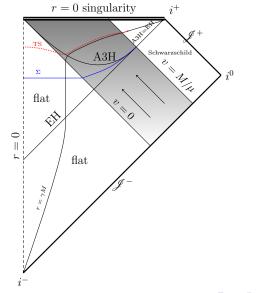




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Bengtsson & Senovilla, Phys. Rev. D 79 (2009) 024027





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Closed trapped surfaces may intersect the flat region

They do enter into the flat region (if the mass function rises fast enough).



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Closed trapped surfaces are highly non-local

They can have portions in a flat region of spacetime whose whole past is also flat in clairvoyance of energy that crosses them elsewhere to make their compactness feasible.



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The boundary *B* of the region containing closed trapped surfaces?



\mathscr{B} is not an MTT!

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- In general, one does not know where is *B*, not even for spherical symmetry !!



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Black Hole Cores



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- Surely enough, any flat region is certainly not essential for the existence of the black hole.
- What is?



Definition of Core

Definition

A region \mathscr{Z} is called the core of the region with closed future-trapped surfaces if it is a minimal closed connected set that needs to be removed from the spacetime in order to get rid of all such closed future-trapped surfaces, [and such that any point on the boundary $\partial \mathscr{Z}$ is connected to \mathscr{B} in the closure of the remainder].



Definition of Core

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A region \mathscr{Z} is called the core of the region with closed future-trapped surfaces if it is a minimal closed connected set that needs to be removed from the spacetime in order to get rid of all such closed future-trapped surfaces, [and such that any point on the boundary $\partial \mathscr{Z}$ is connected to \mathscr{B} in the closure of the remainder].

• Here, "minimal" means that there is no other set \mathscr{Z}' with the same properties and properly contained in \mathscr{Z} .



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- Here, "minimal" means that there is no other set \mathscr{Z}' with the same properties and properly contained in \mathscr{Z} .
- The final technical condition is needed because one could identify a particular removable region to eliminate the future-trapped surfaces, excise it, but then put back a tiny but central isolated portion to make it smaller. However, this is not what one wants to cover with the definition.



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Theorem (Bengtsson and JMMS, PRD 83 (2011) 044012)

In spherically symmetric spacetimes, there are closed future-trapped surfaces (topological spheres) penetrating both sides of the apparent 3-horizon A3H\A3H^{iso} with arbitrarily small portions inside the region $\{r < 2m\}$.



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From this surprising theorem one derives:

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In spherically symmetric spacetimes, $\mathscr{Z} = \{r \leq 2m\}$ are the only spherically symmetric cores of \mathscr{T} . Therefore, $\partial \mathscr{Z} = A3H$ are the only spherically symmetric boundaries of a core.



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However, A3H is quasilocal and can be defined and identified by observing just around it.

It is thus surprising, and perhaps with a deep meaning, that $A3H = \partial \mathscr{Z}$ can happen



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- This would happen if any MTT H other than A3H is such that its causal future $J^+(H)$ is not a core —the core being a proper subset of $J^+(H)$.



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- And this could serve as a general definition, for non-spherically symmetric situations.
- However, it may also happen that all boundaries of cores are MTTs...



Grazie!

Thank you very much!



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