

Introducing LensCharm

Charming Bayesian Generative Strong Lensing

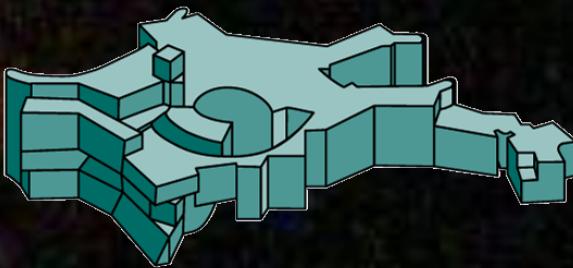
Matteo Guardiani, Julian Rüstig,
Jakob Roth, Philipp Frank, and Torsten Enßlin



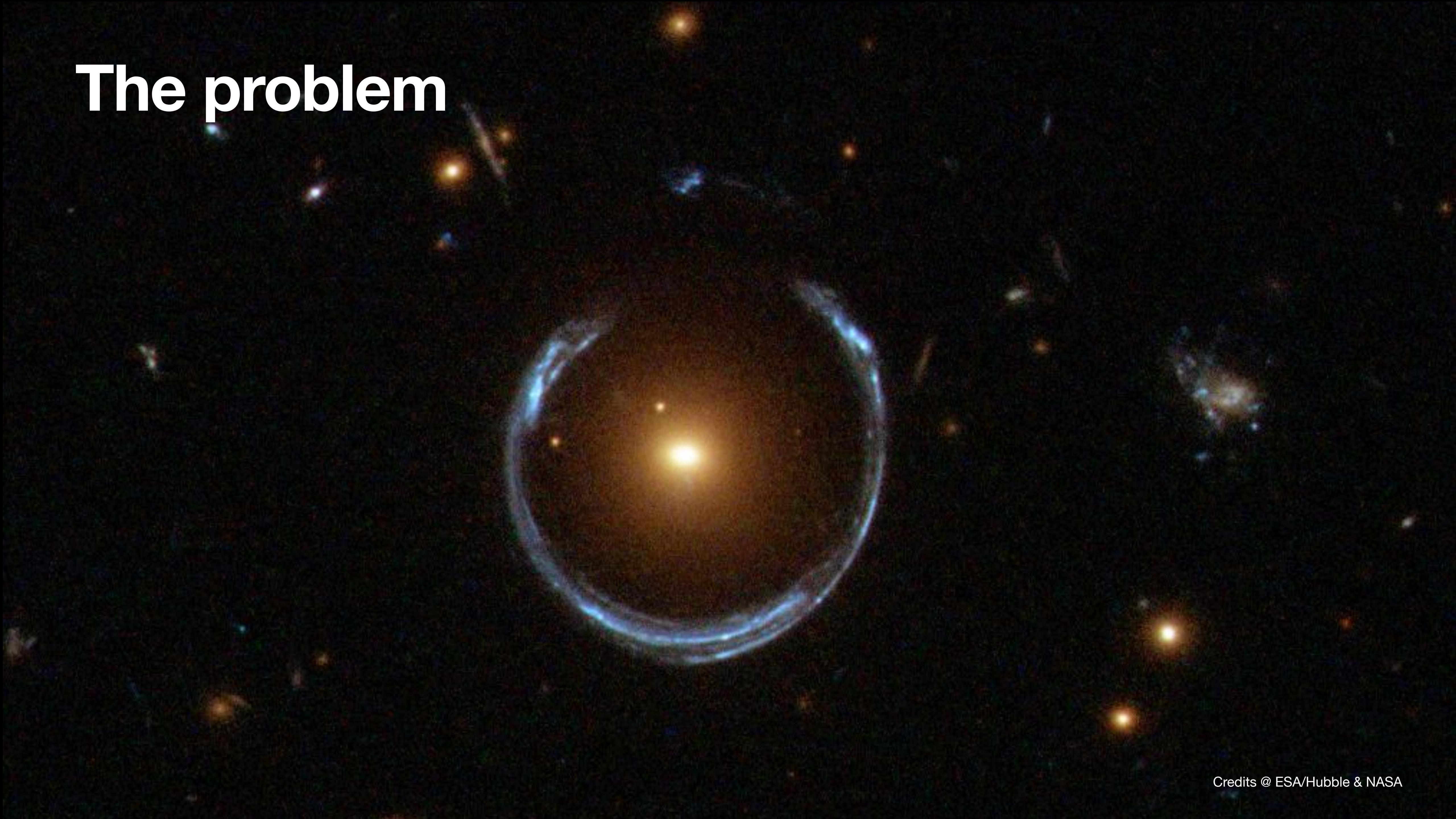
MACHINE LEARNING
FOR ASTROPHYSICS
2ND EDITION
CATANIA, 8-12 JULY, 2024



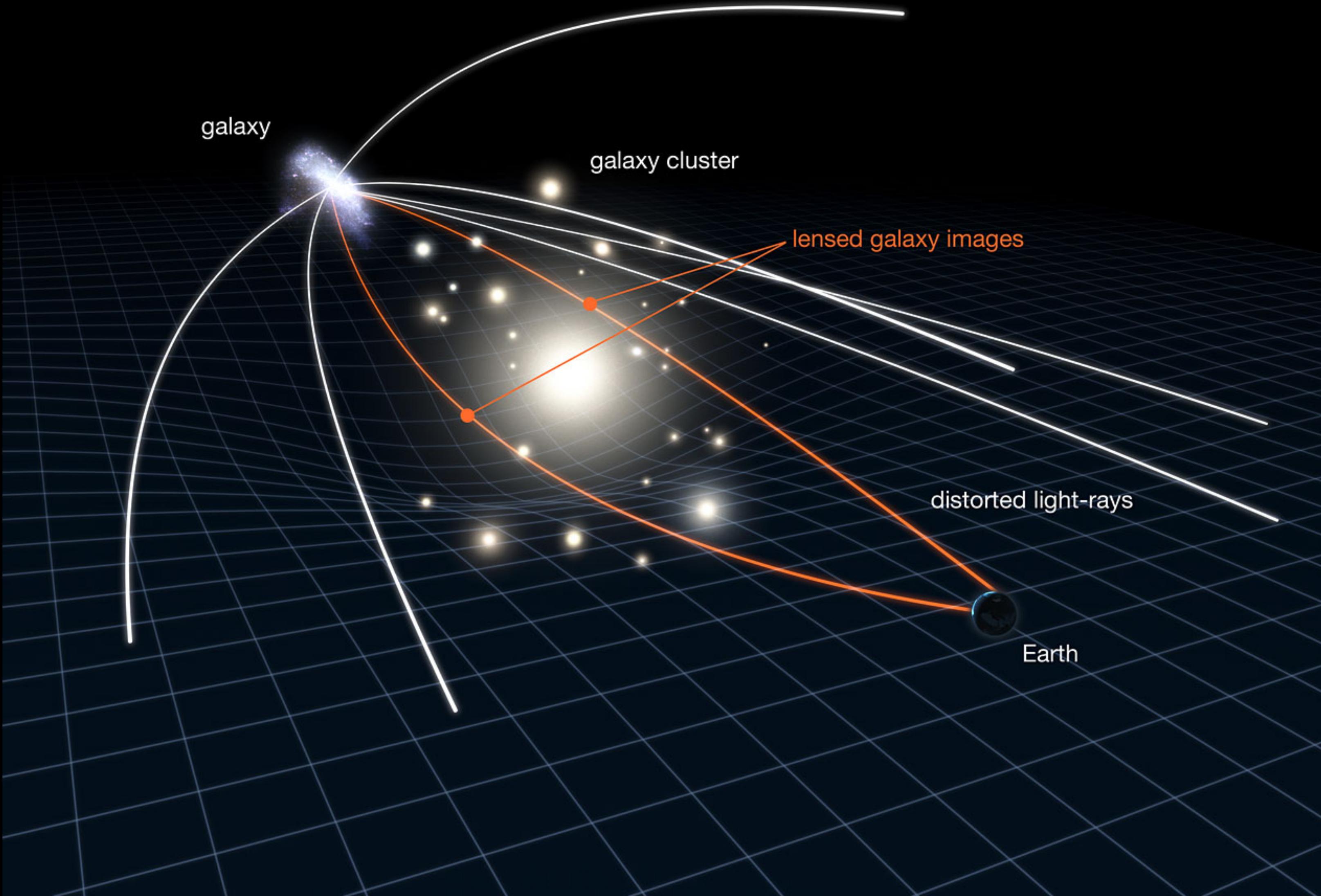
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FOR ASTROPHYSICS



The problem



The problem



Strong lensing with IFT

Information field theory

Bayes' Theorem

$$P(s \mid d) =$$

Information field theory

Bayes' Theorem

$$P(s | d) = \frac{P(d | s)}{\int P(d | s) ds}$$

Information field theory

Bayes' Theorem

$$P(s | d) = \frac{P(d | s) P(s)}{\text{ }}$$

Information field theory

Bayes' Theorem

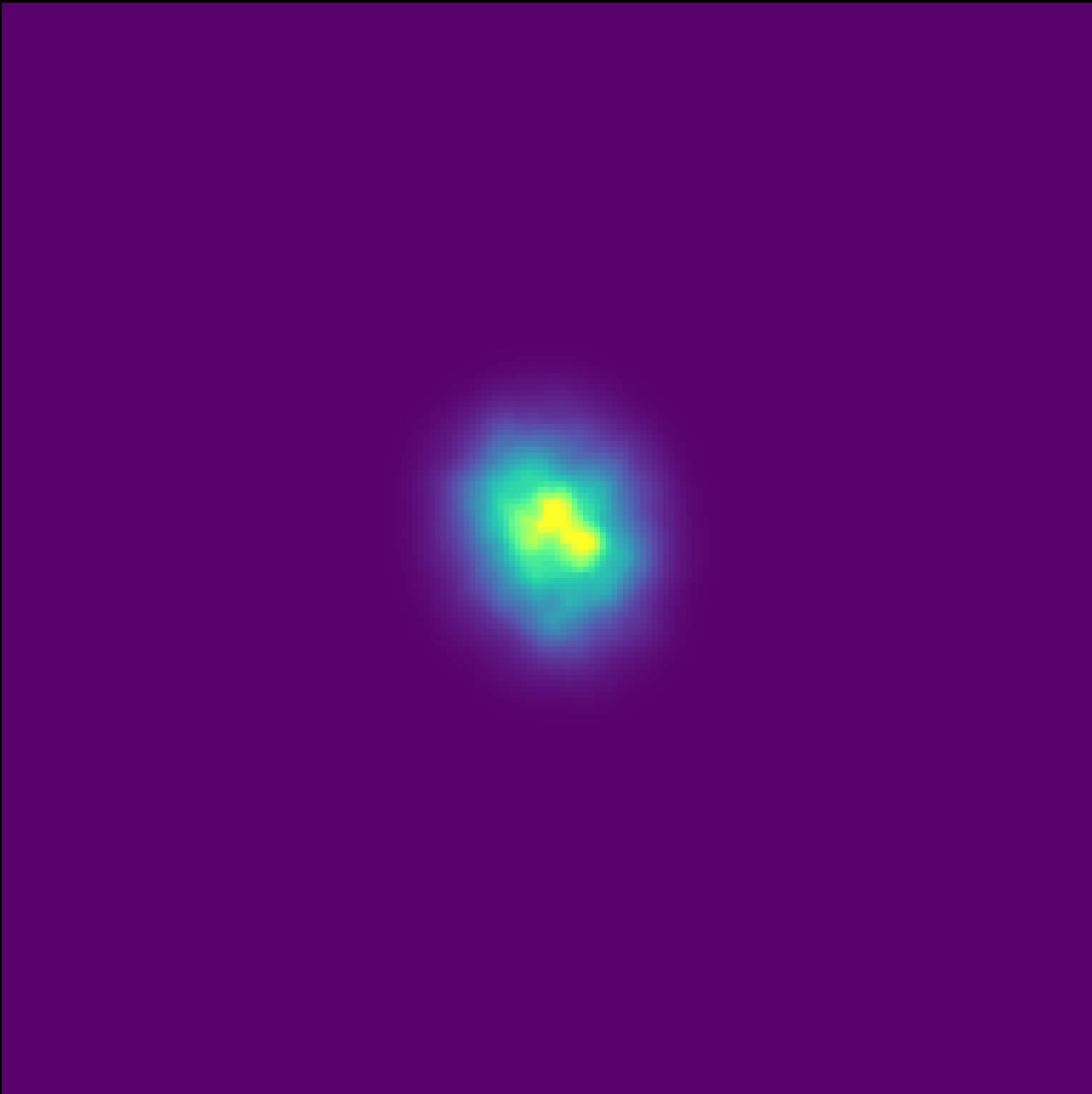
$$P(s | d) = \frac{P(d | s) P(s)}{P(d)}$$

The prior

$$P(s | d) = \frac{P(d | s) P(s)}{P(d)}$$

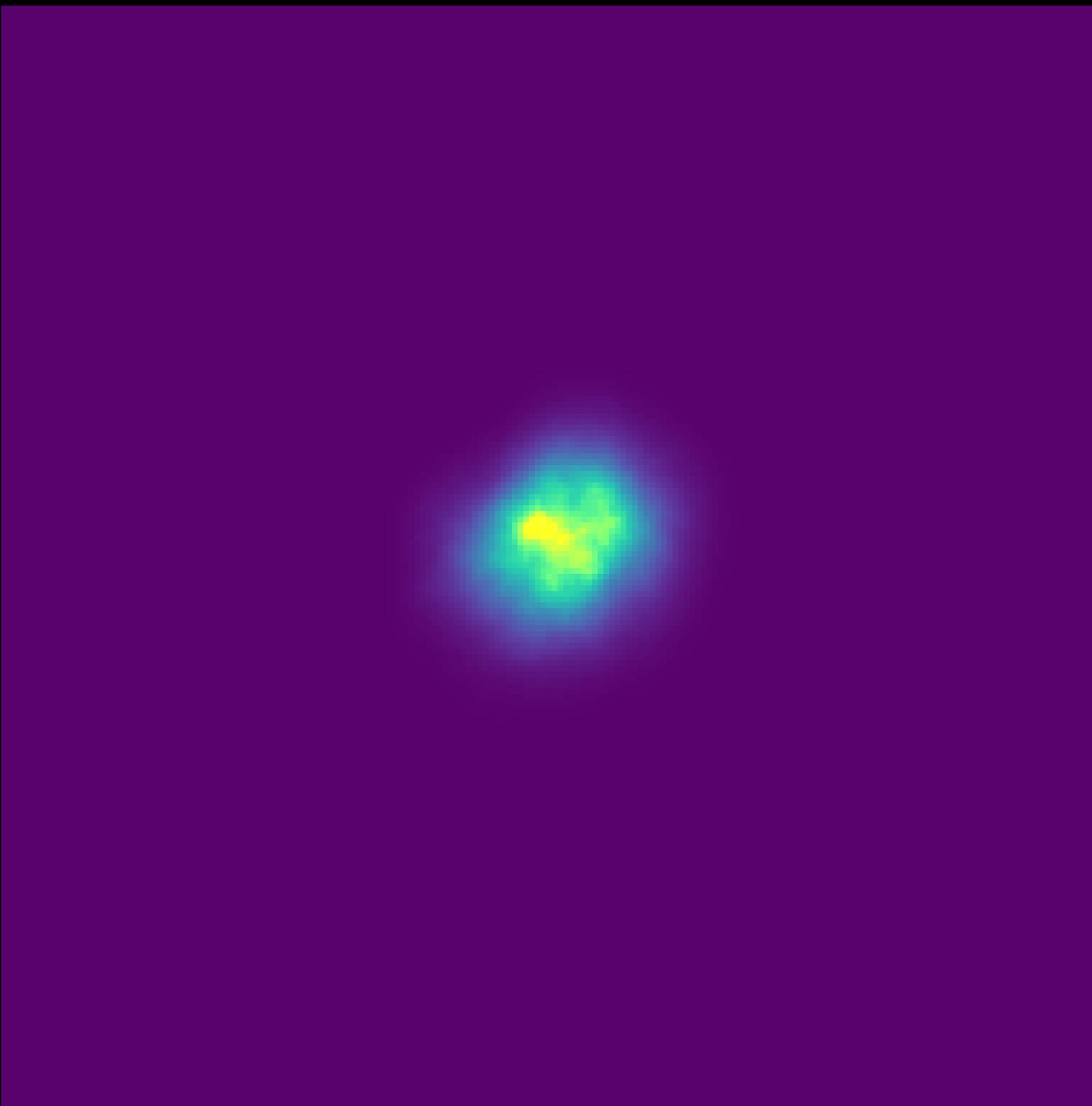
The prior Source galaxy

$$P(s)$$



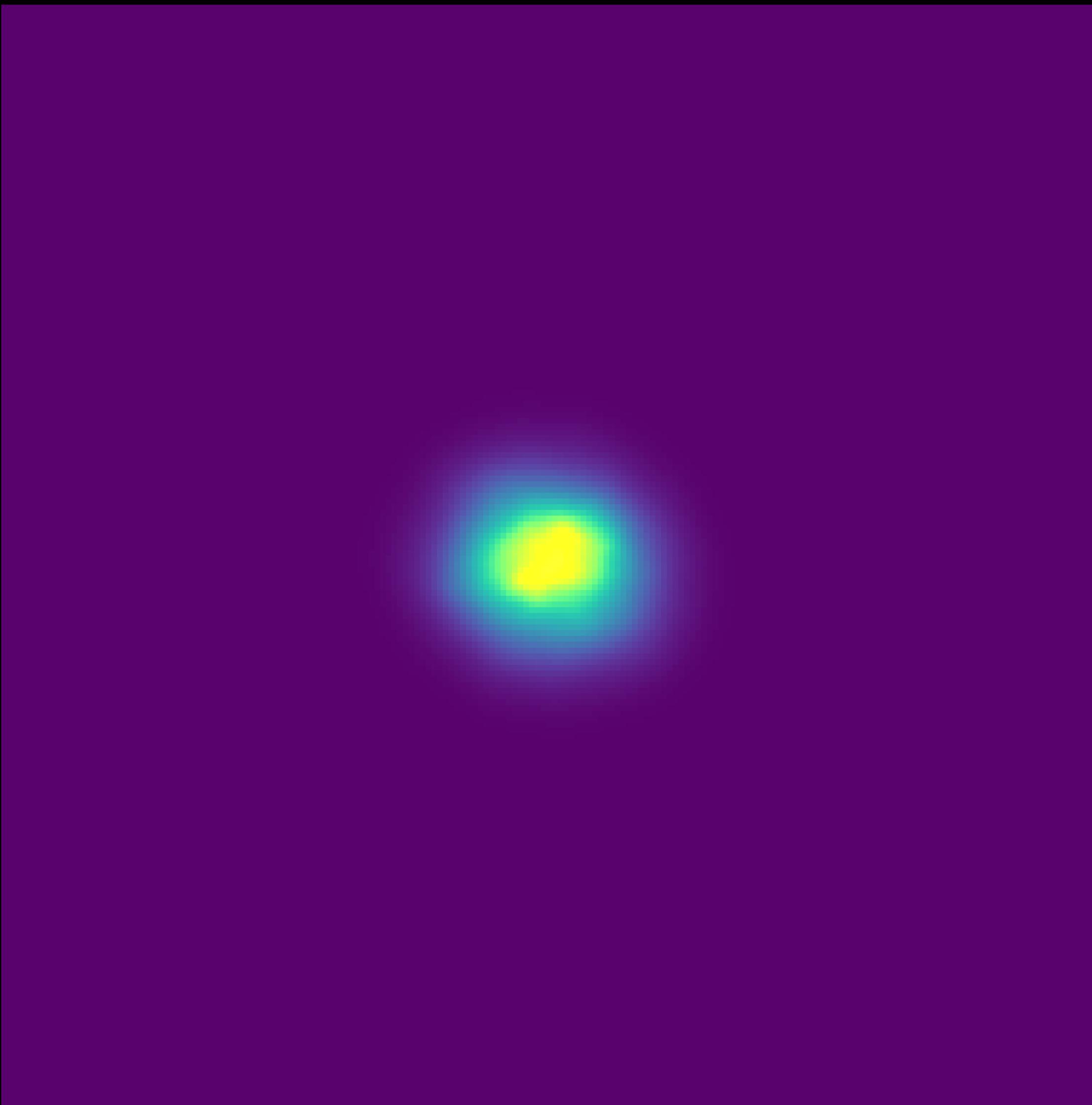
The prior Source galaxy

$$P(s)$$



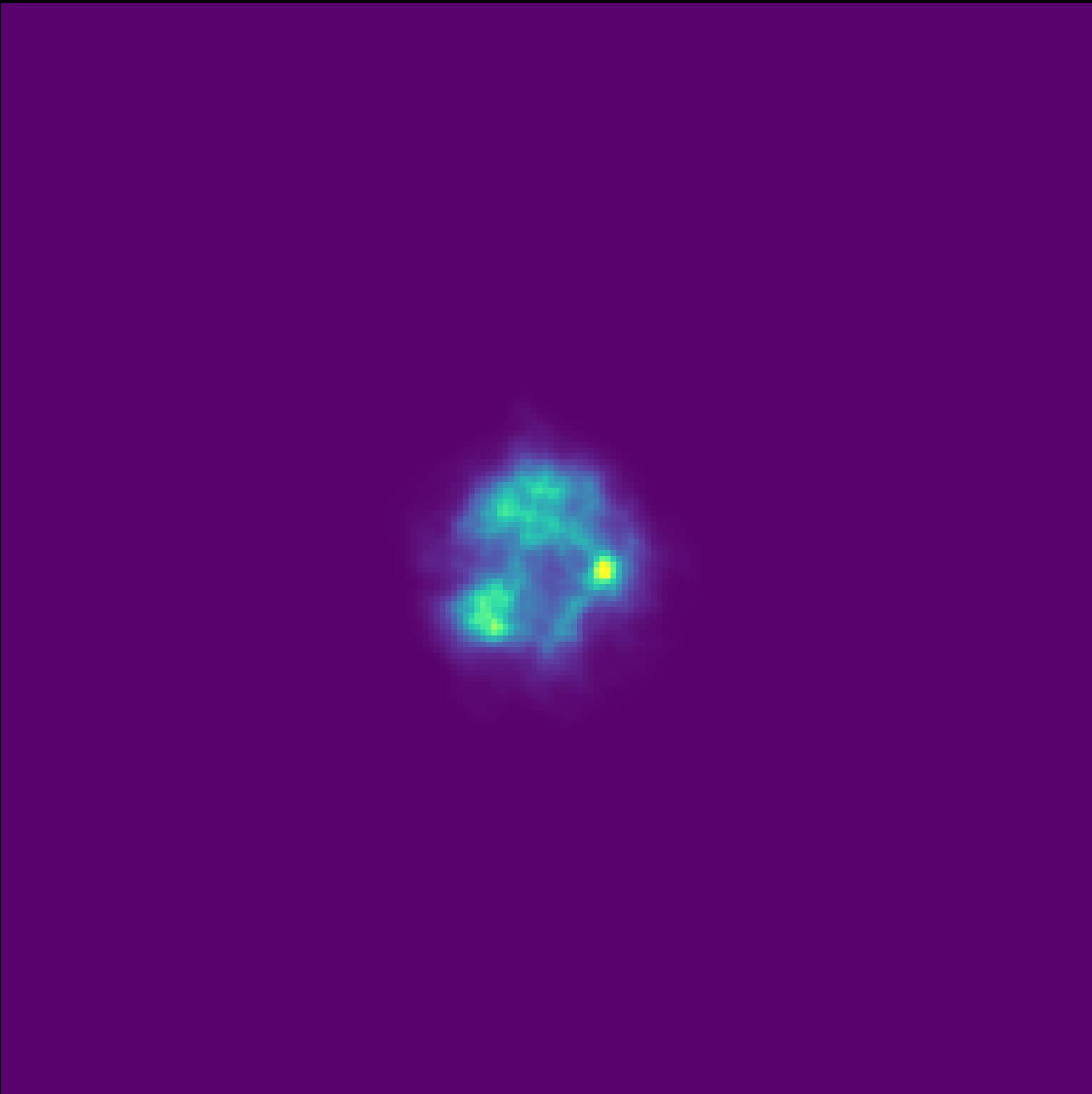
The prior Source galaxy

$$P(s)$$



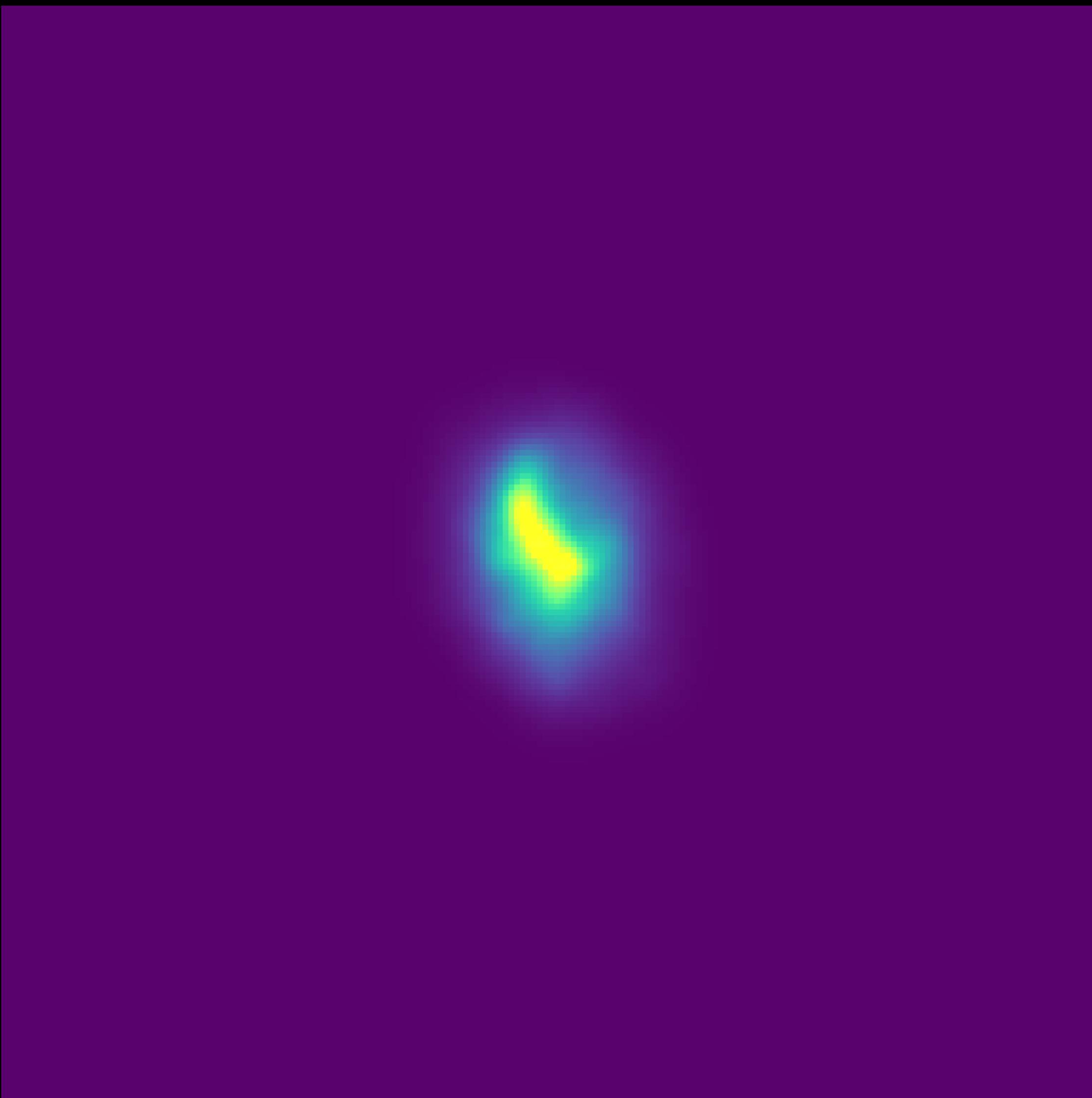
The prior Source galaxy

$$P(s)$$



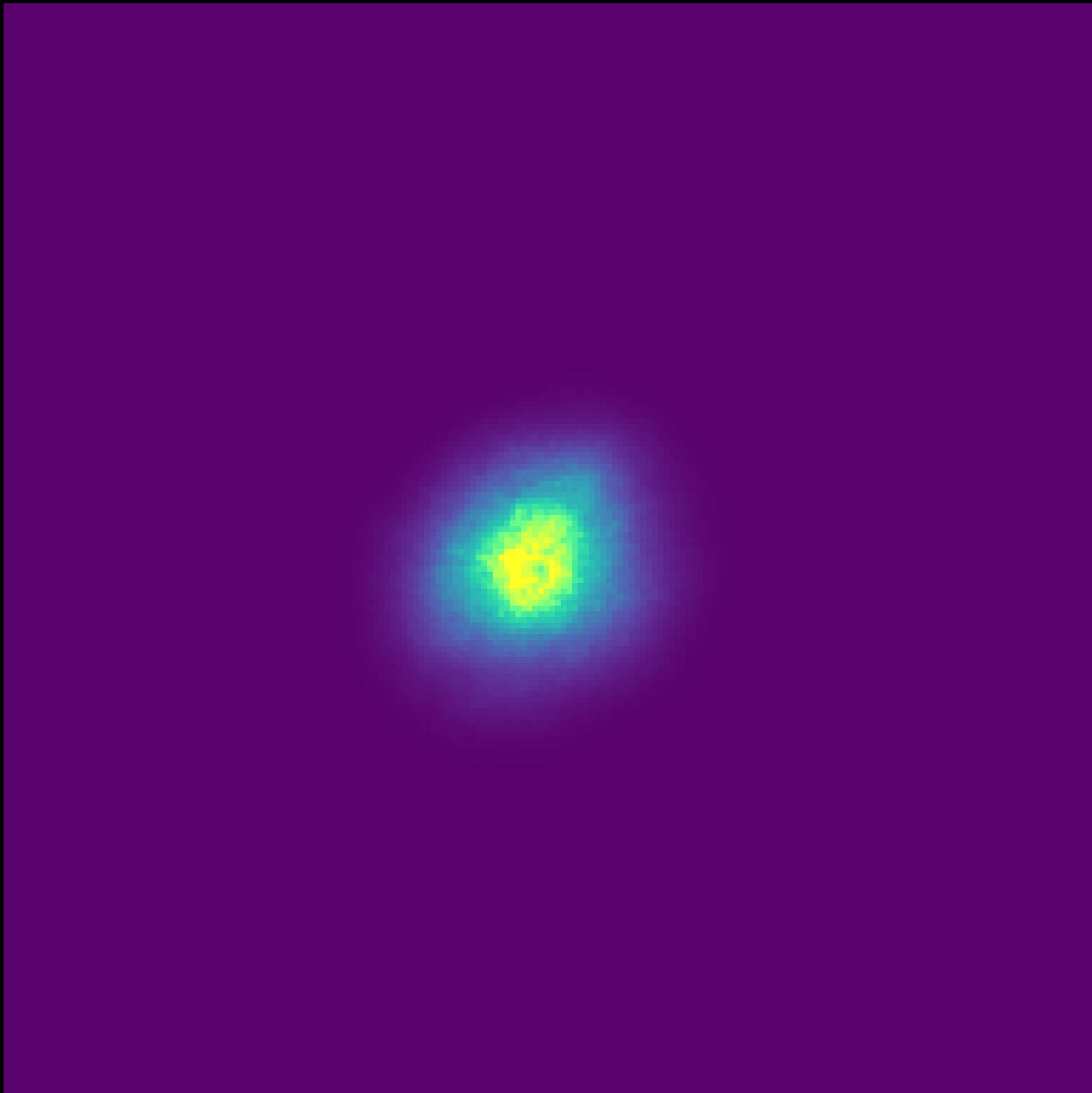
The prior Source galaxy

$$P(s)$$



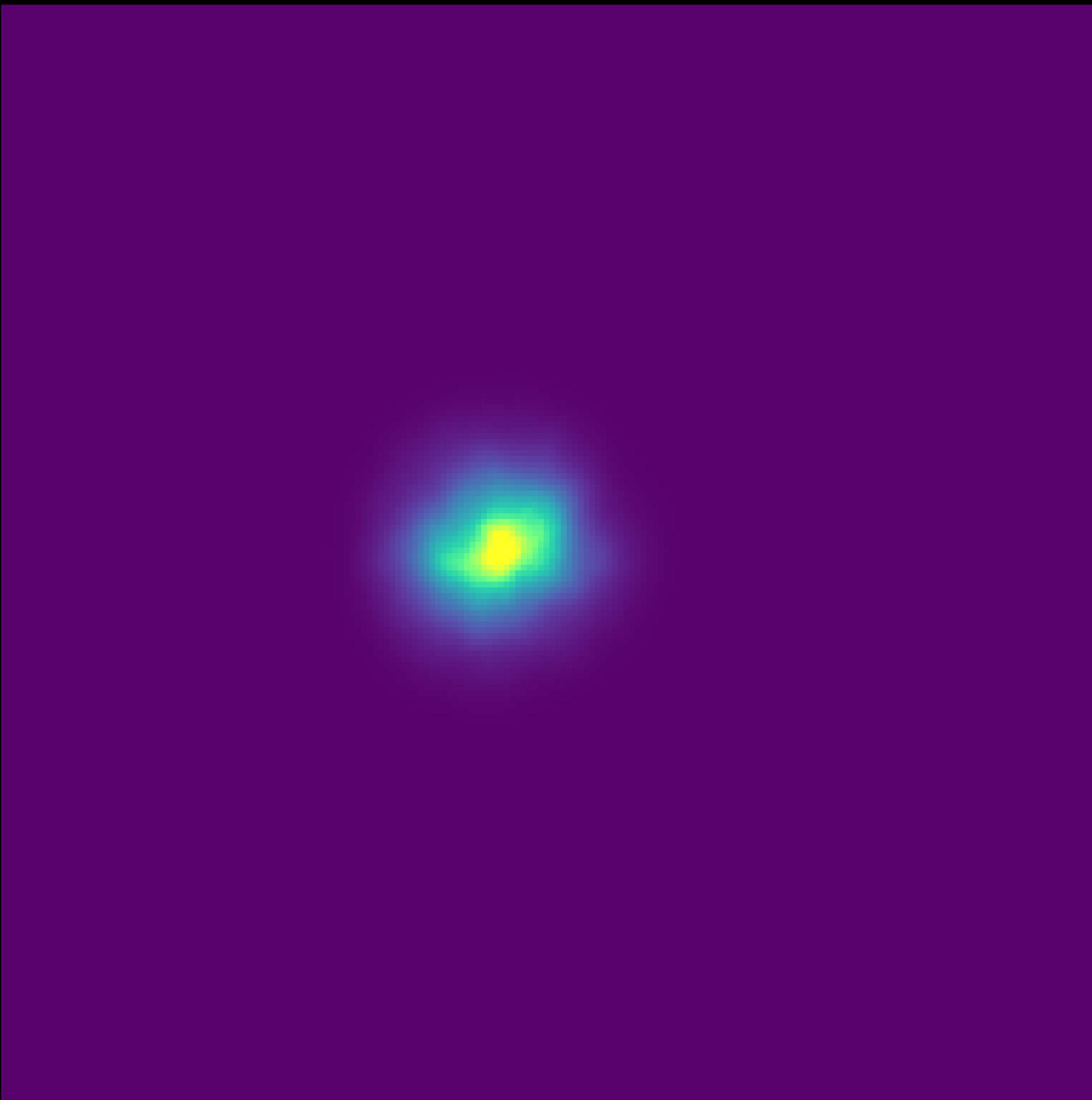
The prior Source galaxy

$$P(s)$$



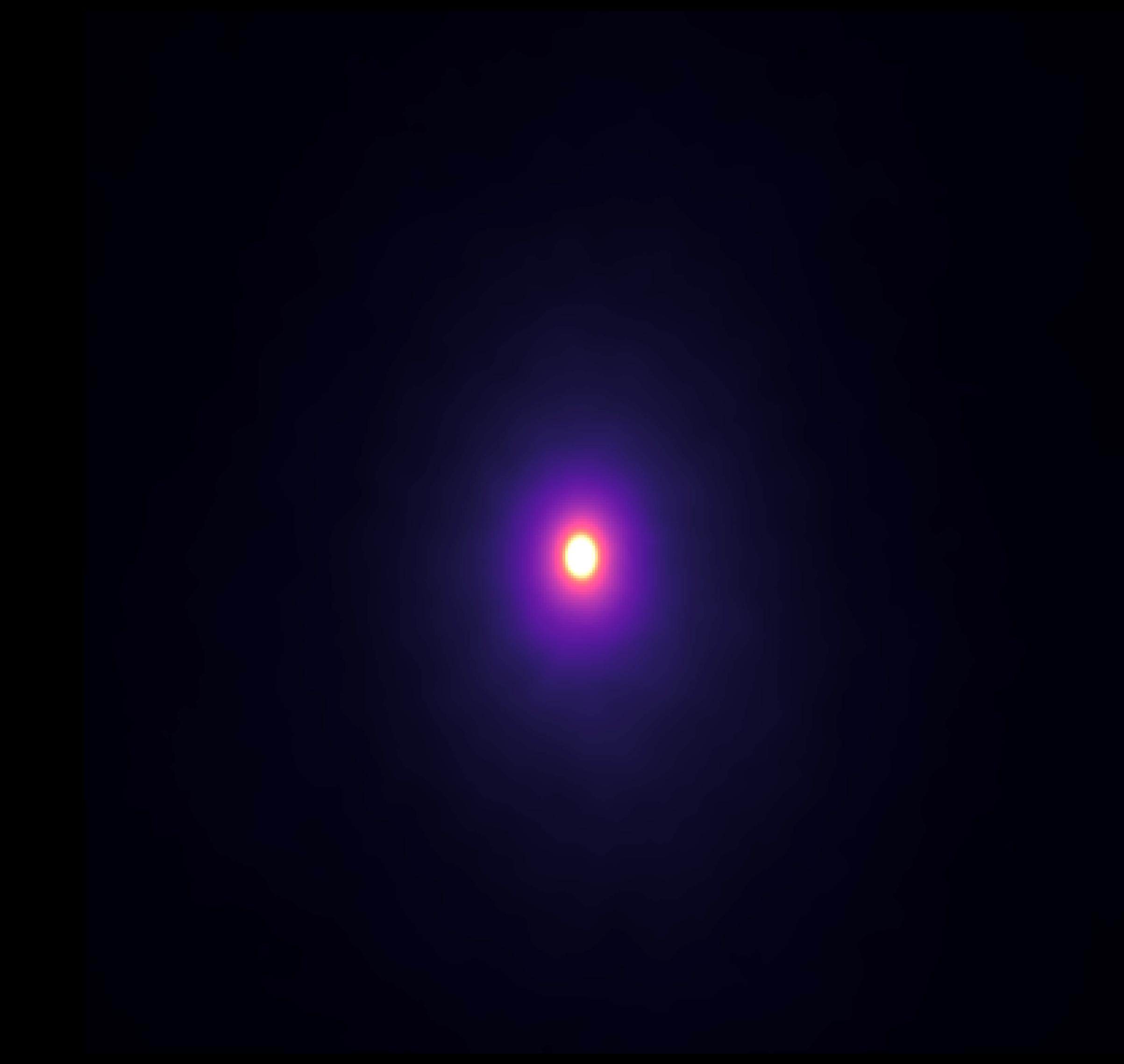
The prior Source galaxy

$$P(s)$$



The prior Convergence

$$P(s)$$



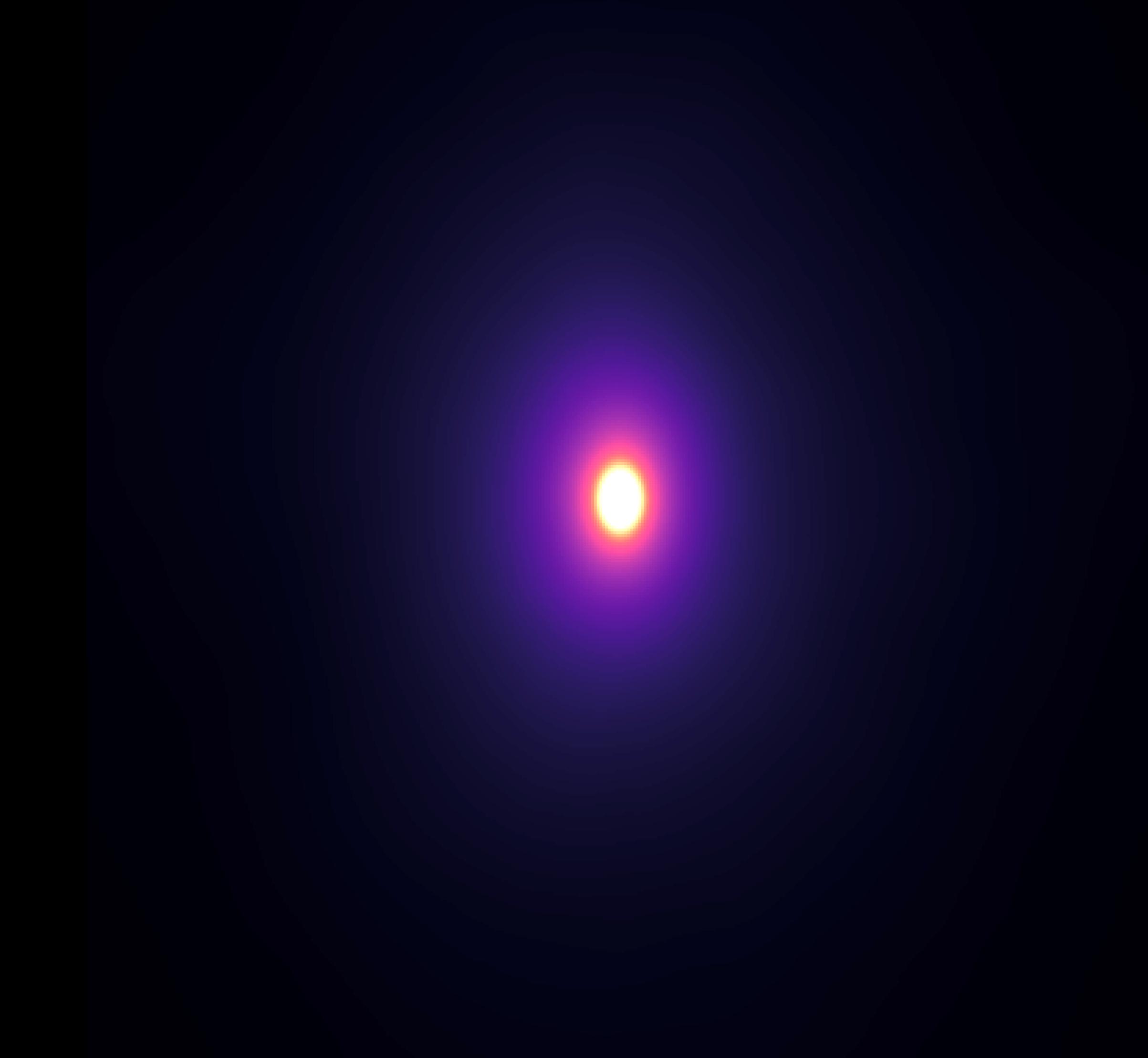
The prior Convergence

$P(s)$



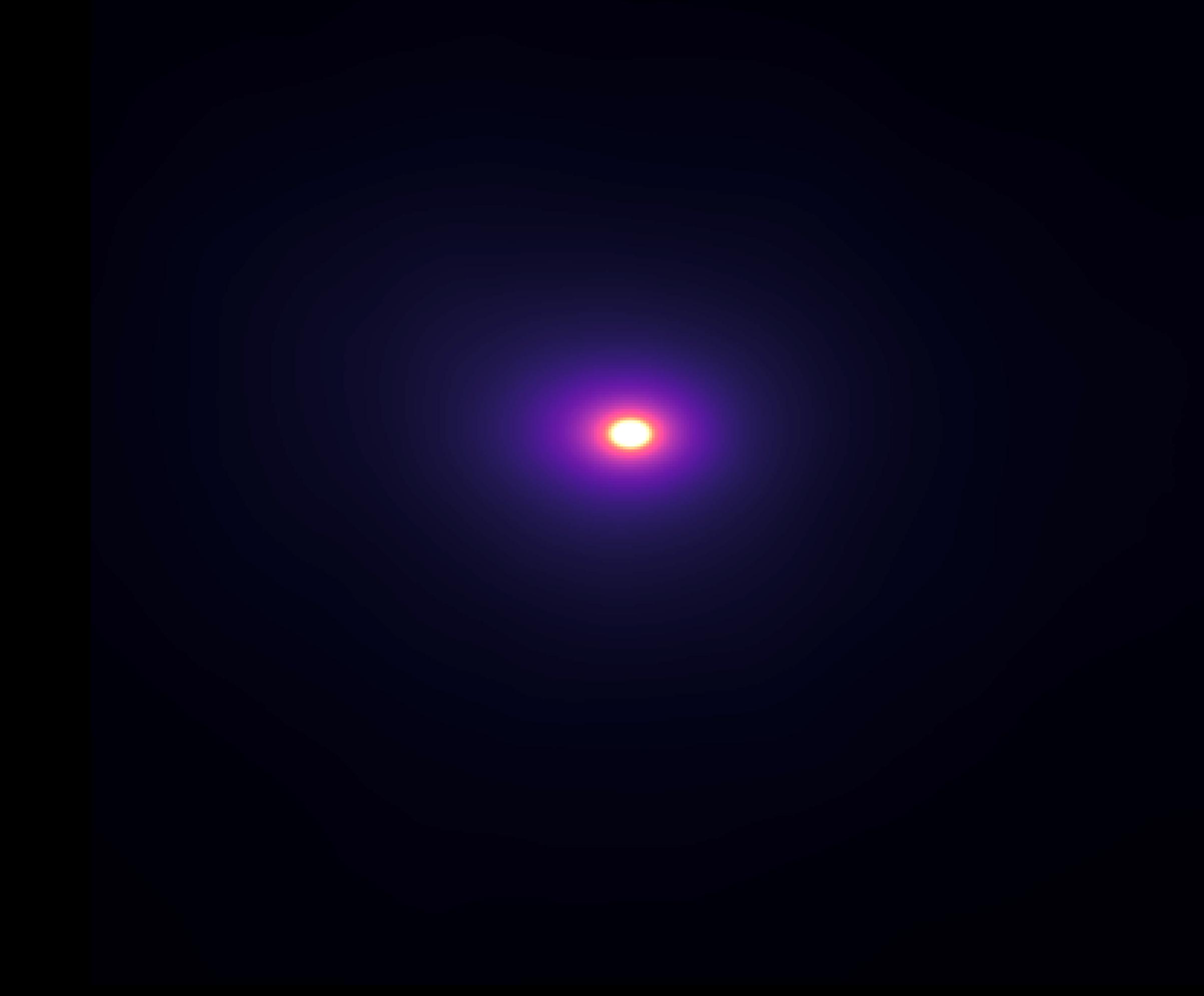
The prior Convergence

$P(s)$



The prior Convergence

$P(s)$



The prior Convergence

$P(s)$



The prior Convergence

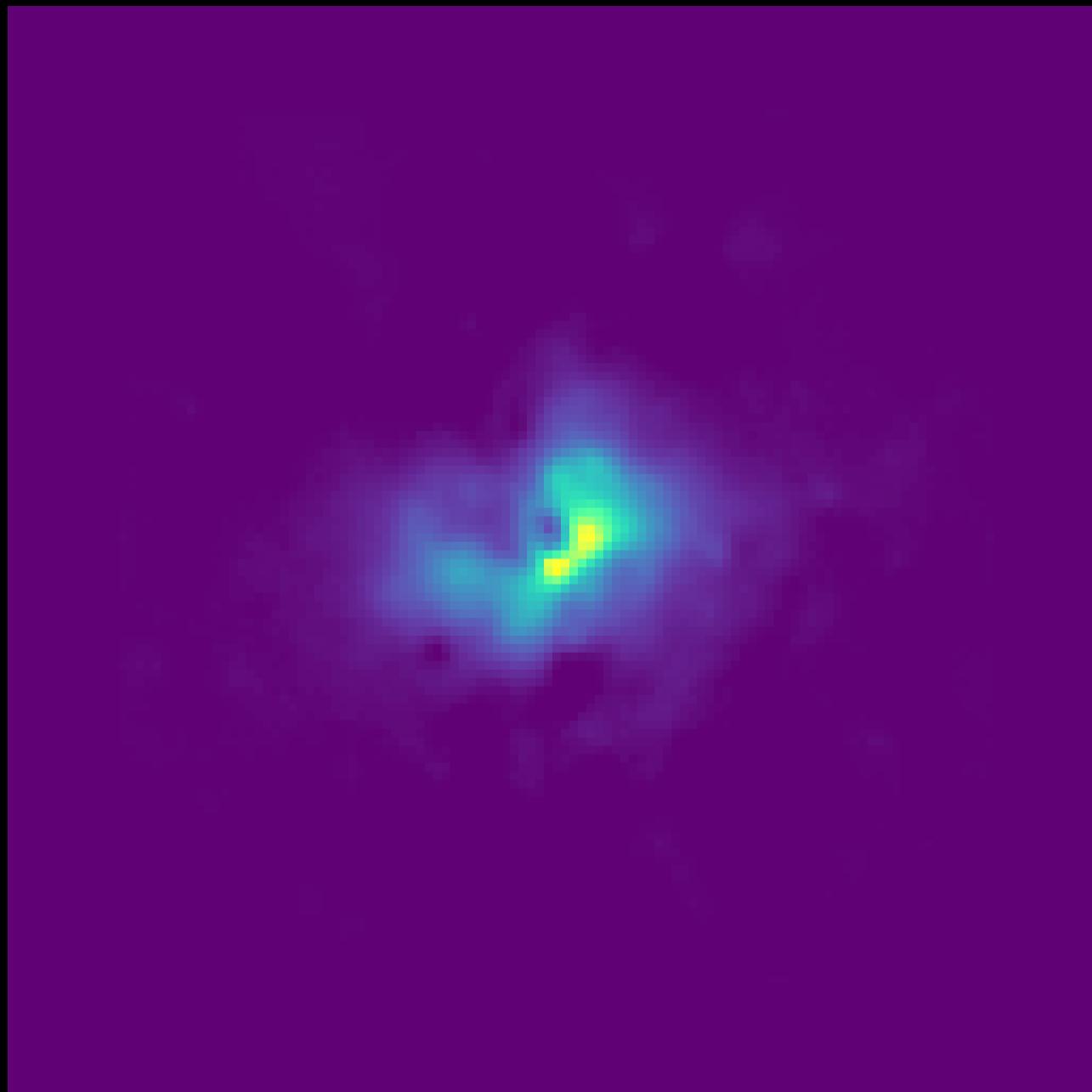
$P(s)$

The Likelihood

$$P(s | d) = \frac{P(d | s) P(s)}{P(d)}$$

The Likelihood

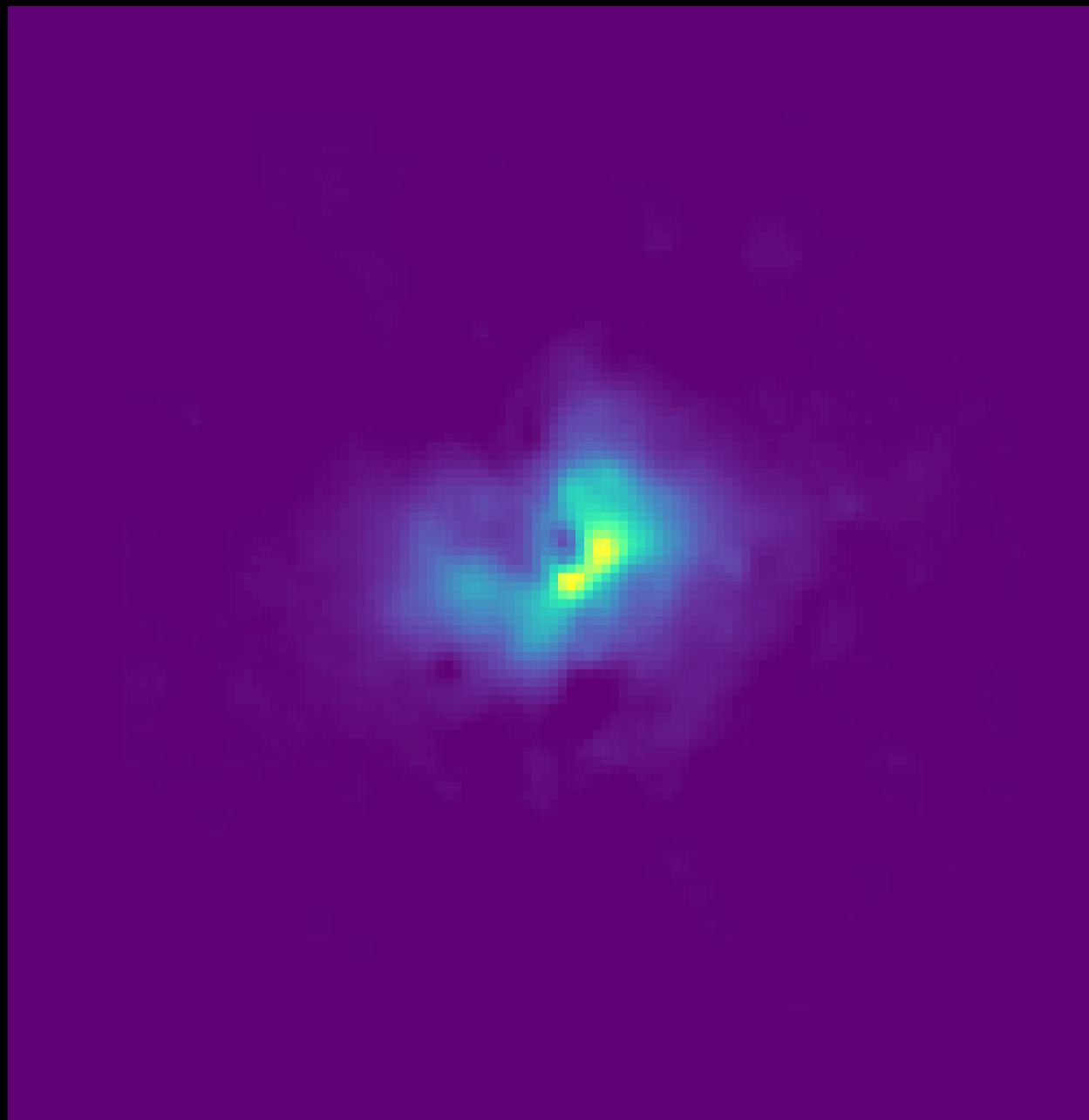
Strong lensing response



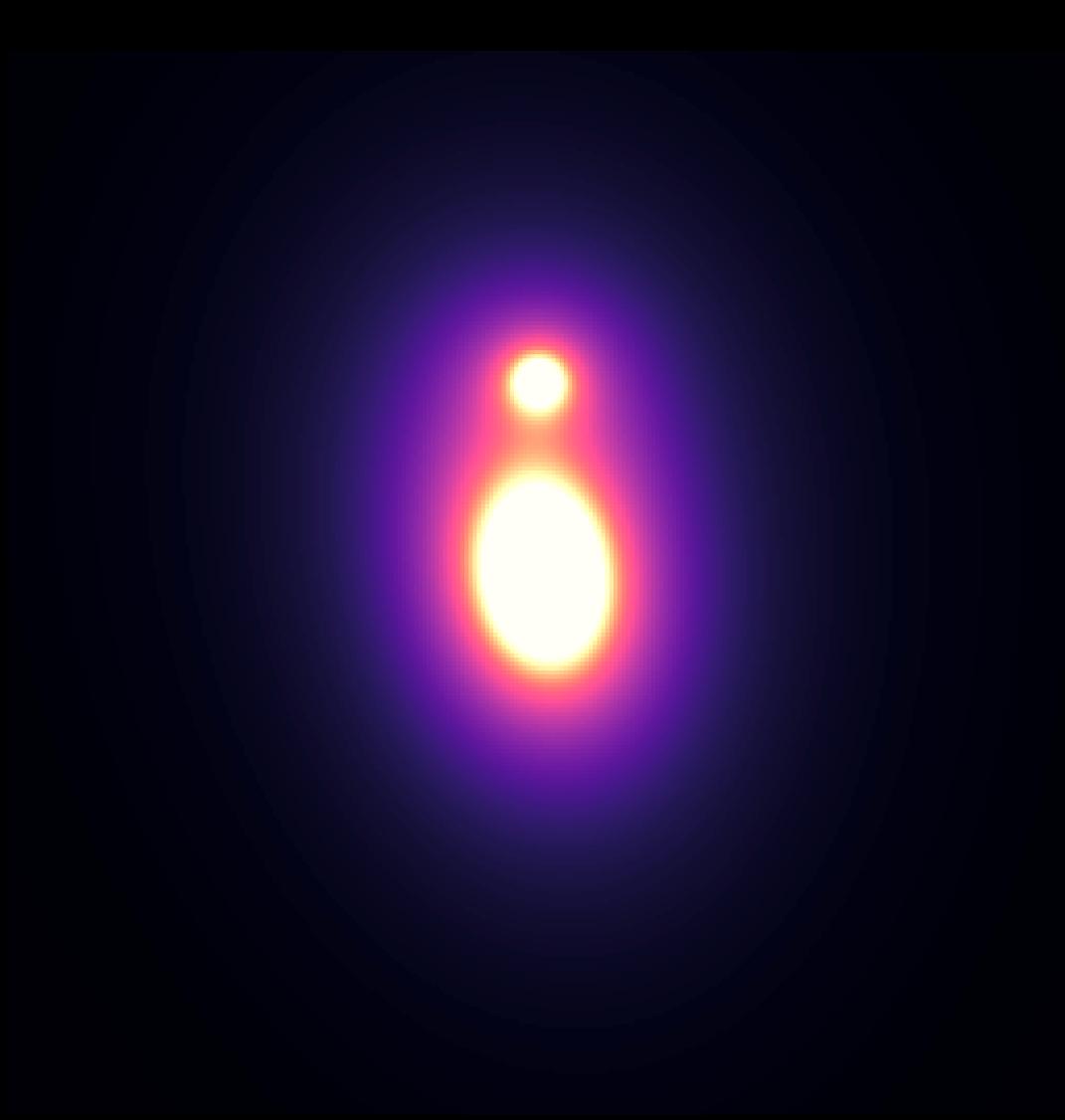
Source galaxy

The Likelihood

Strong lensing response



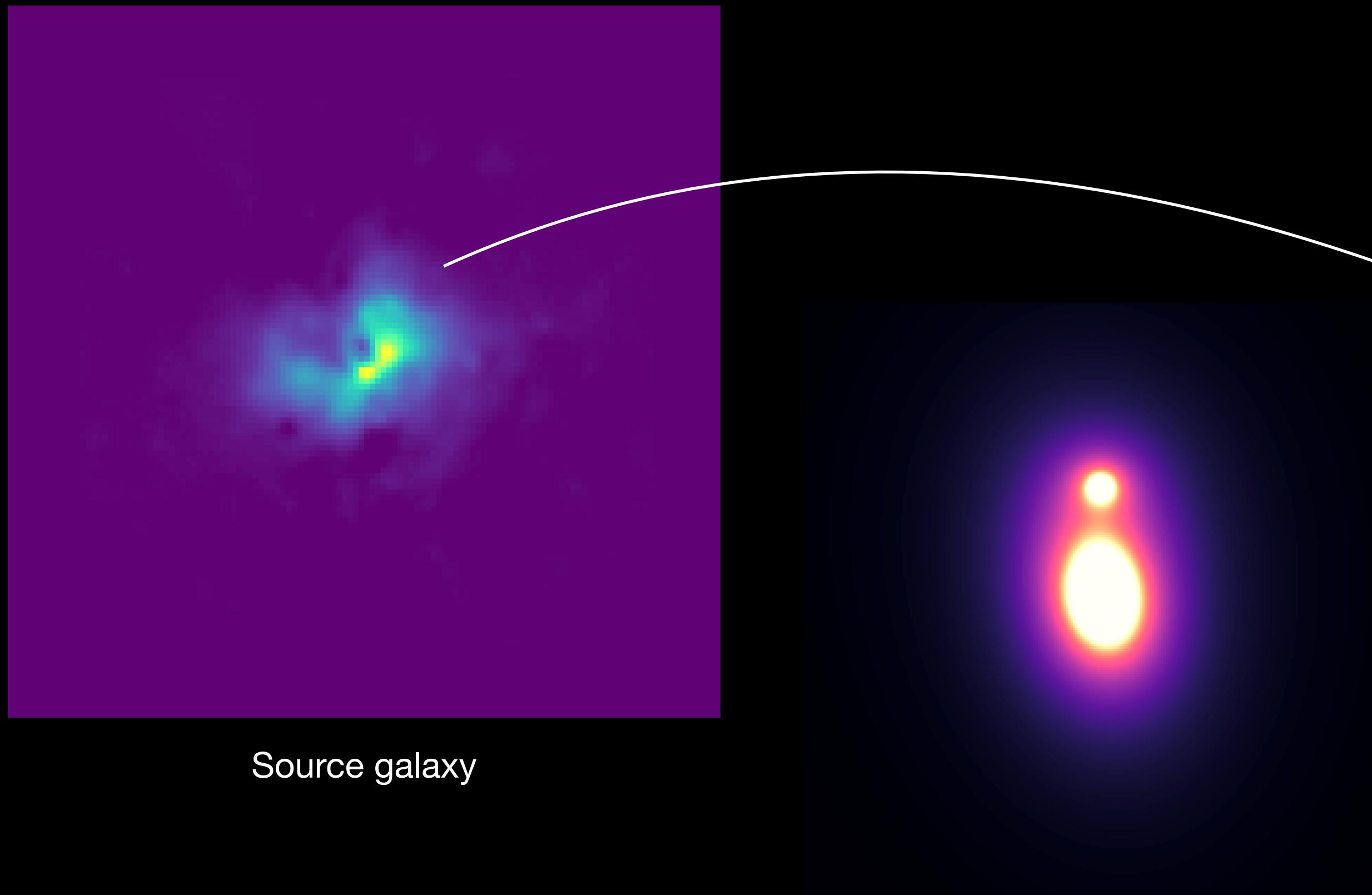
Source galaxy



DM halo mass profile

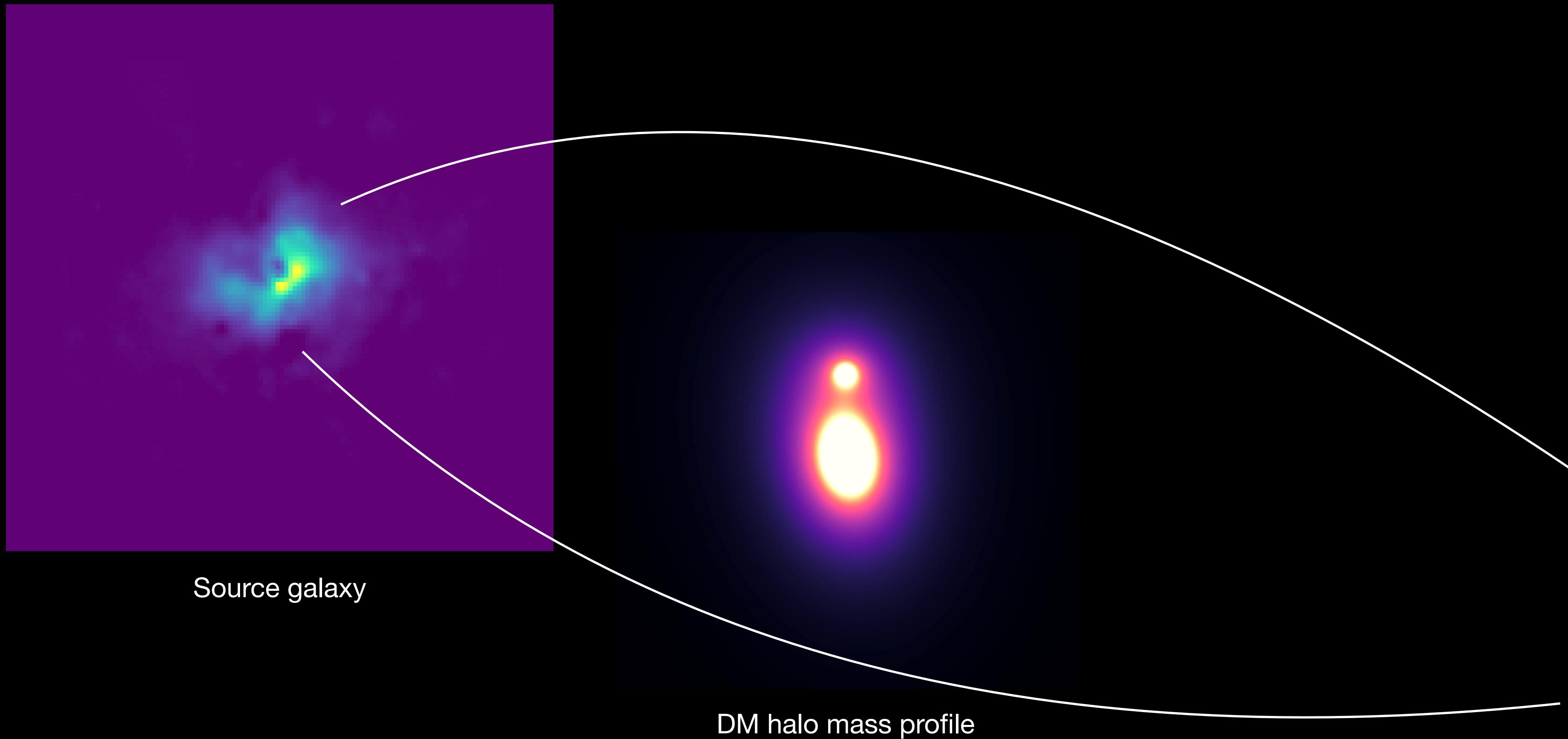
The Likelihood

Strong lensing response



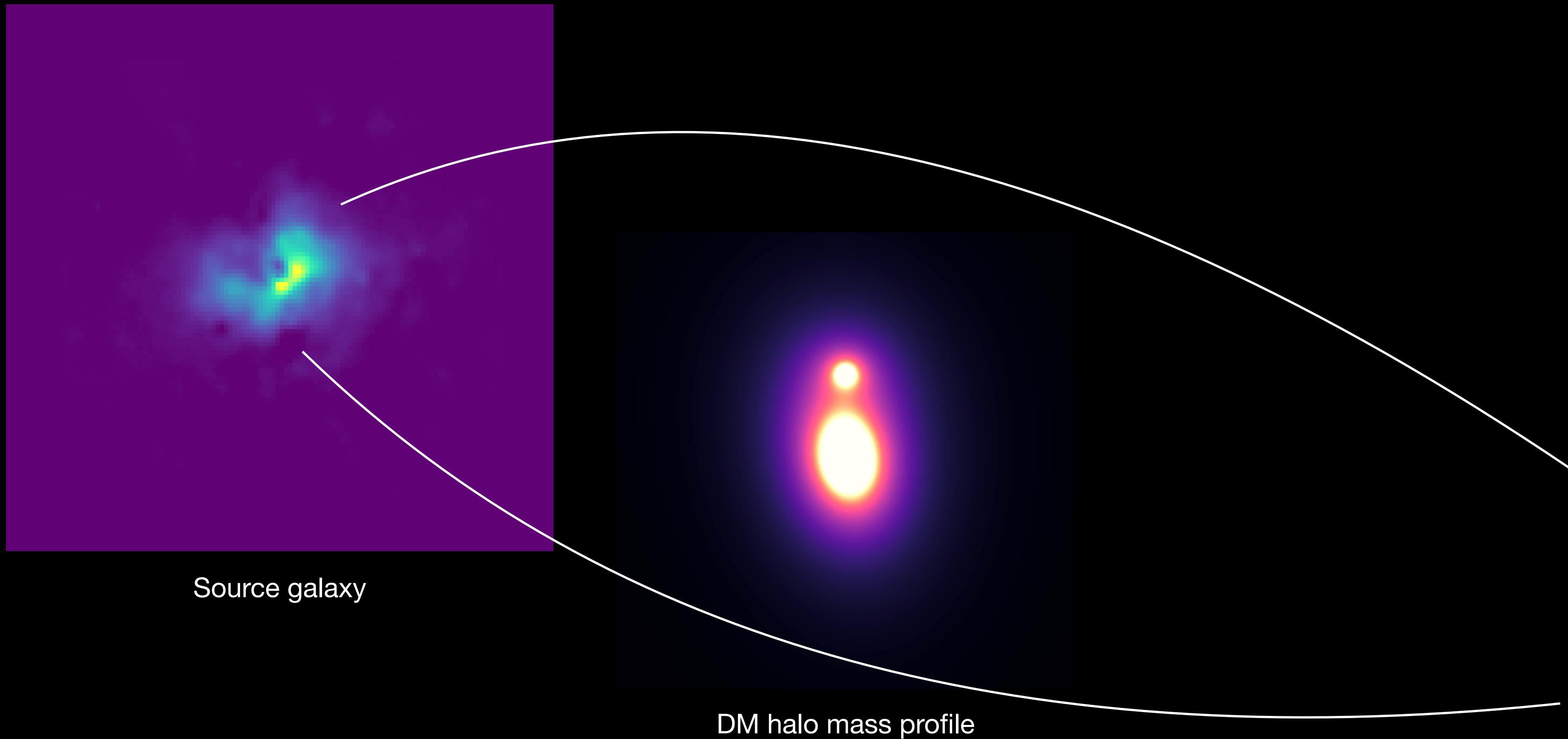
The Likelihood

Strong lensing response



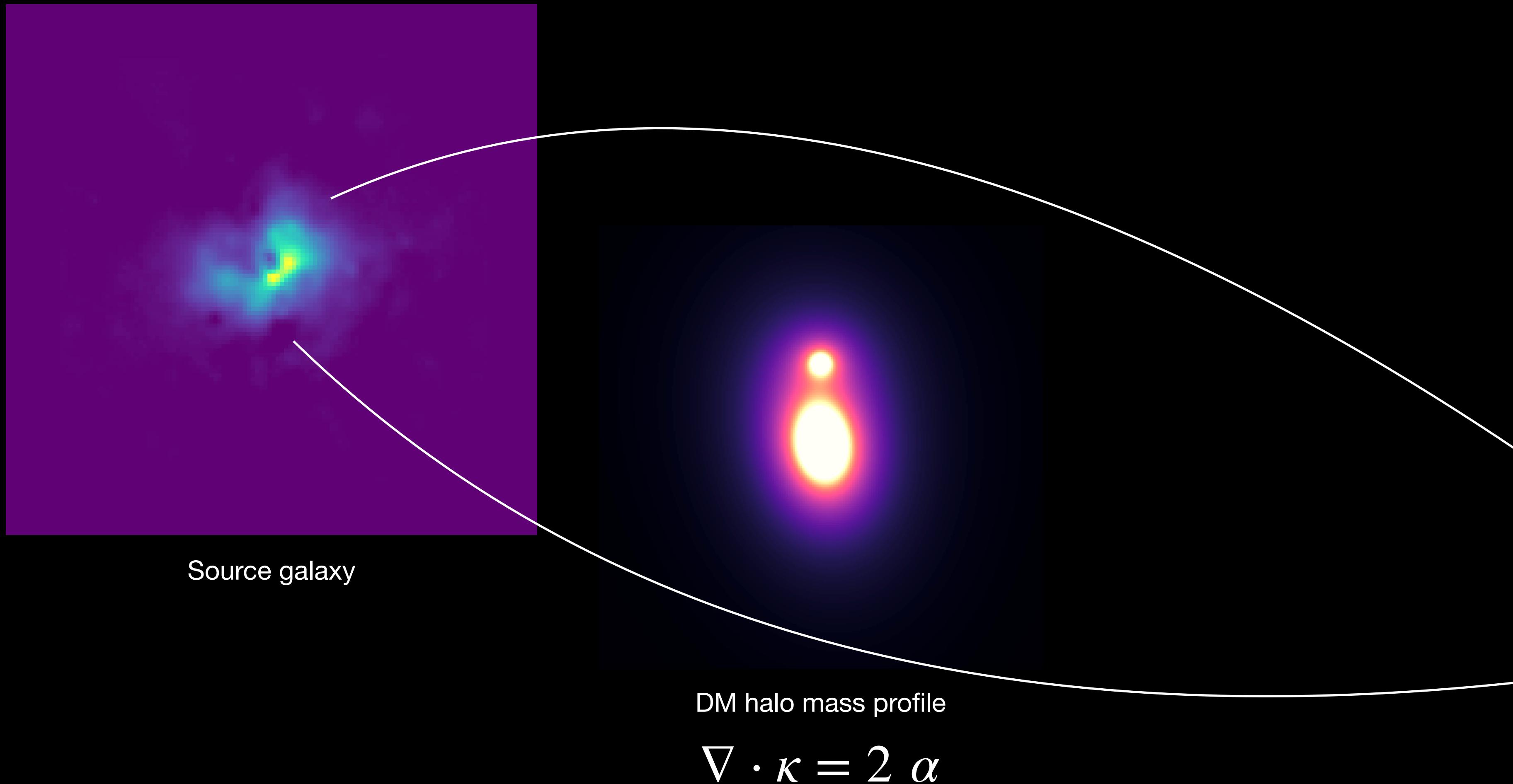
The Likelihood

Strong lensing response



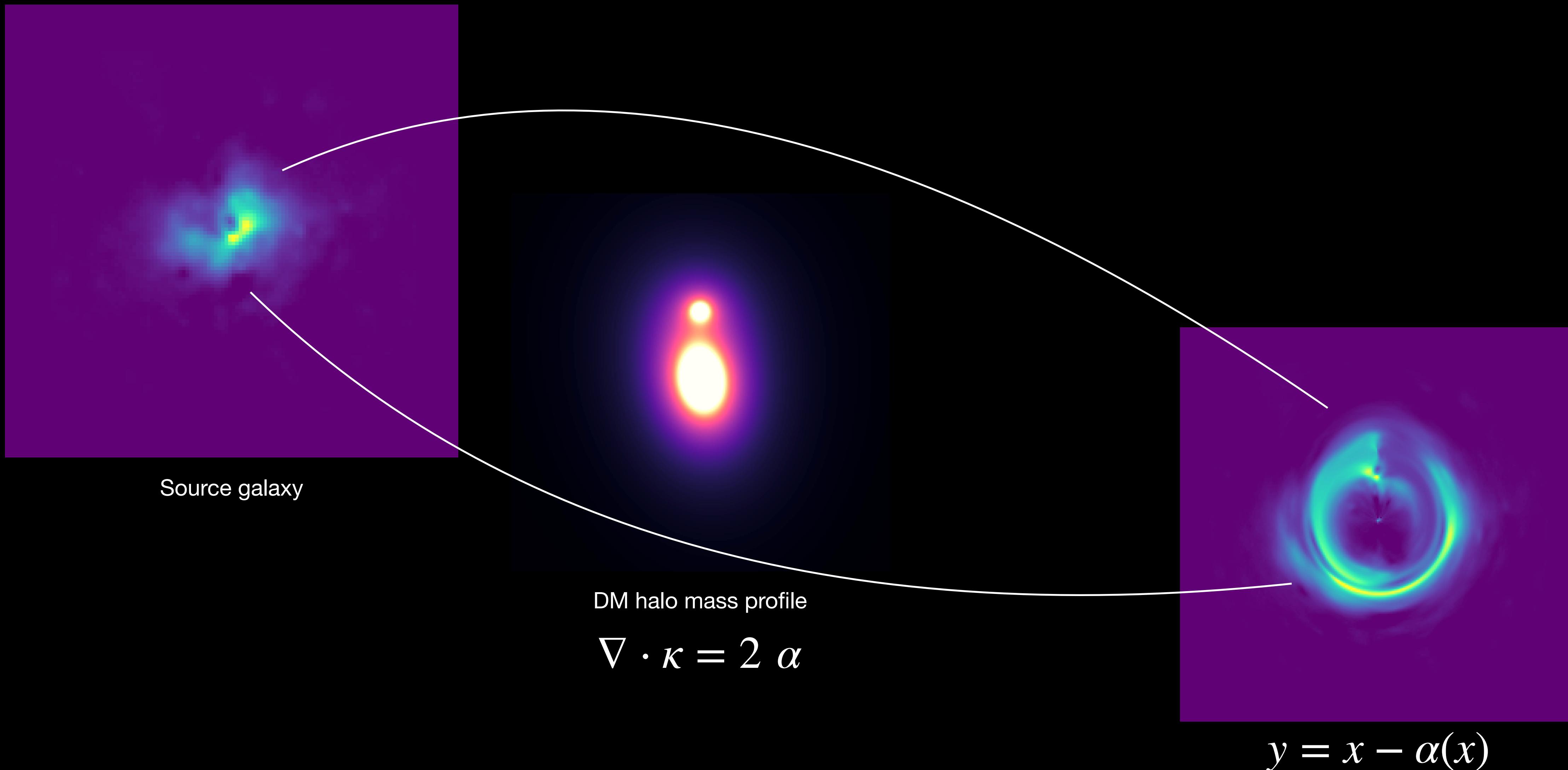
The Likelihood

Strong lensing response

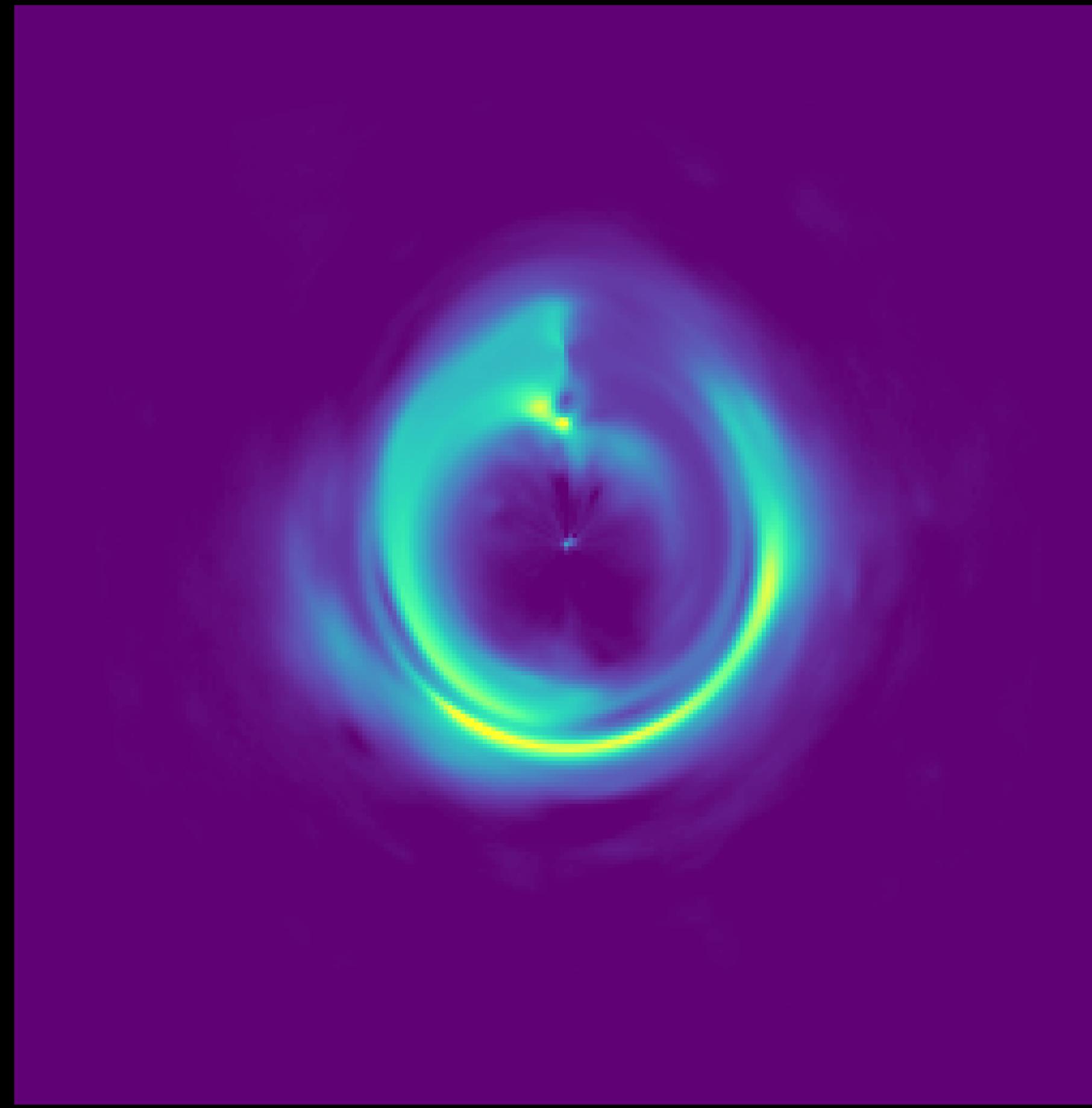


The Likelihood

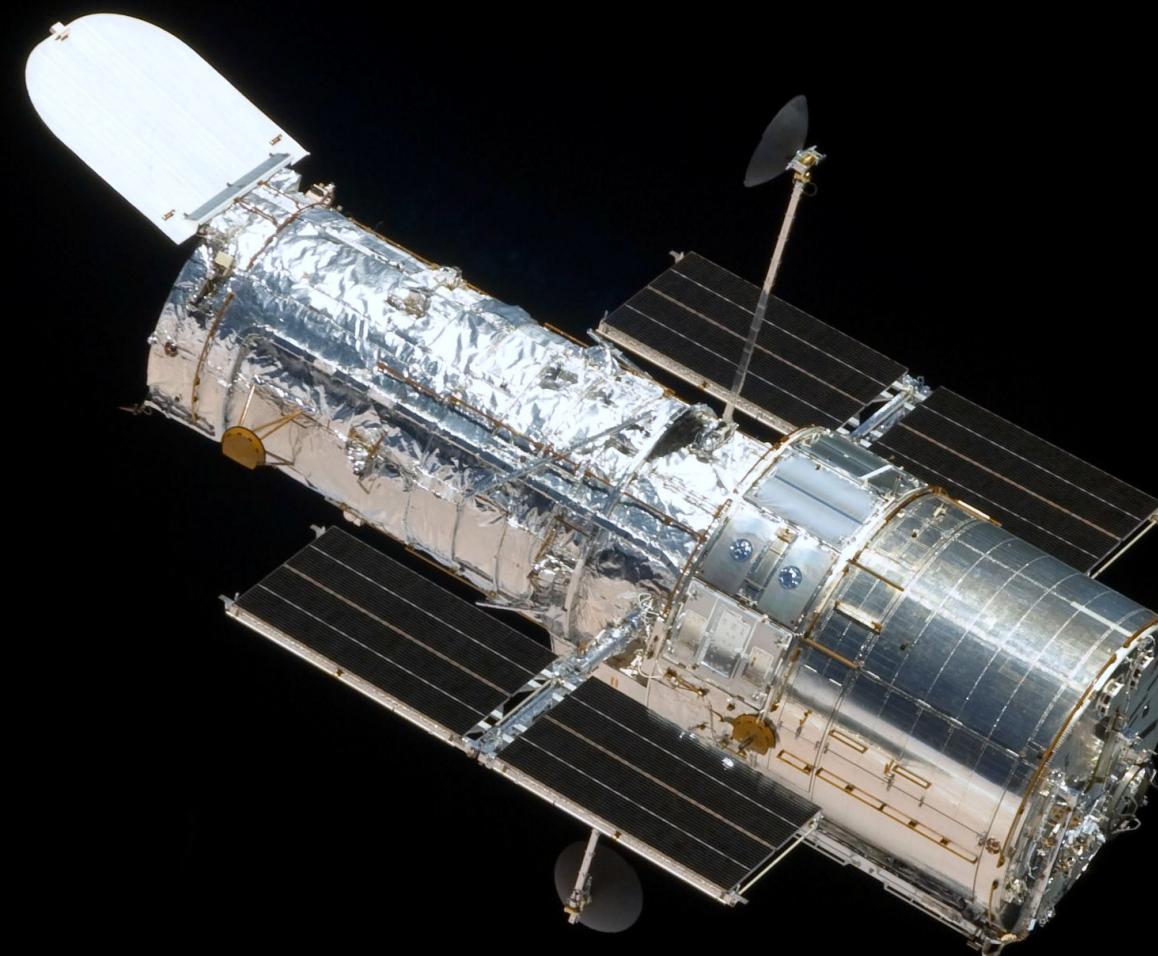
Strong lensing response



The Likelihood Instrument response

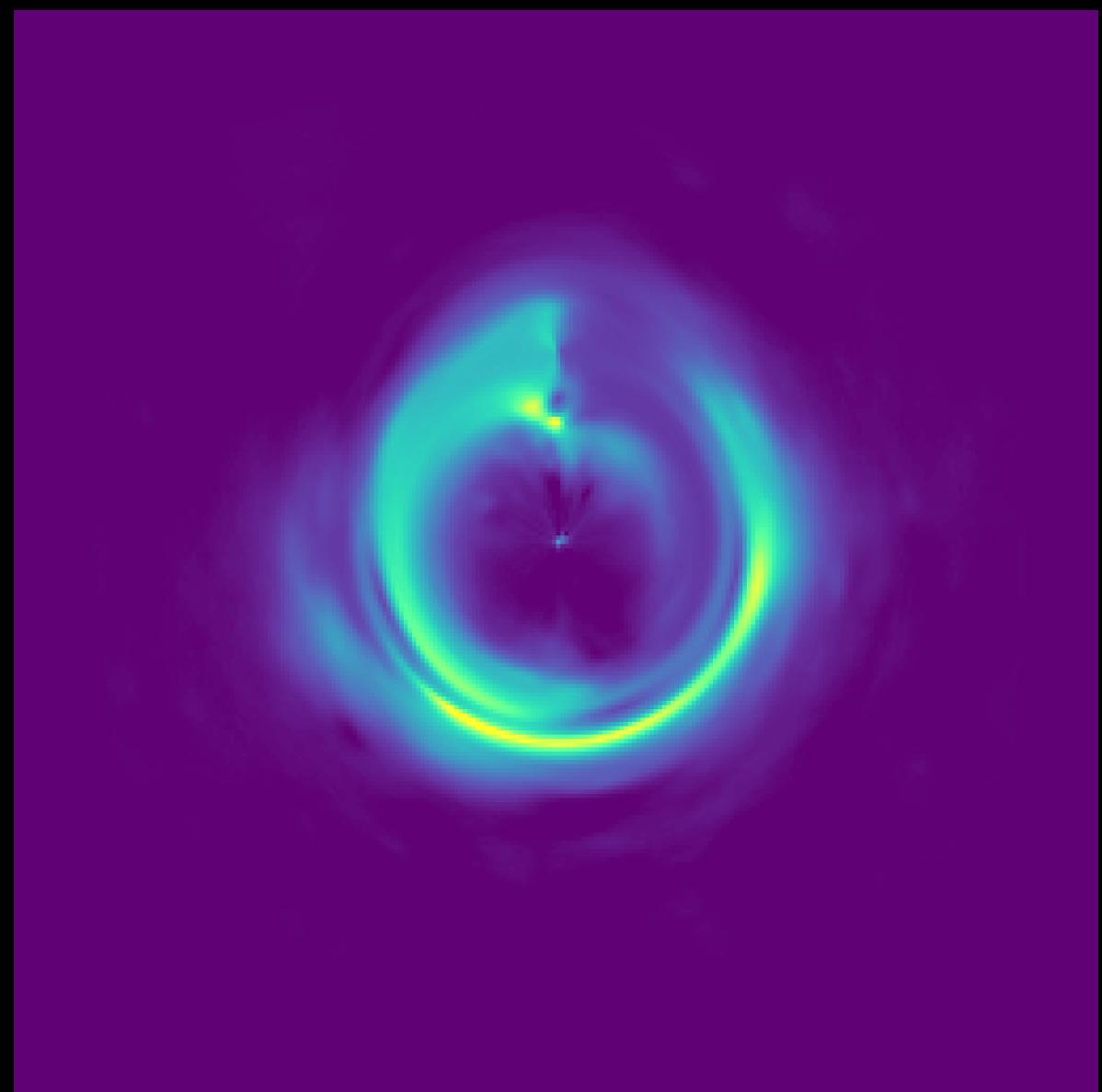


Lensed galaxy signal

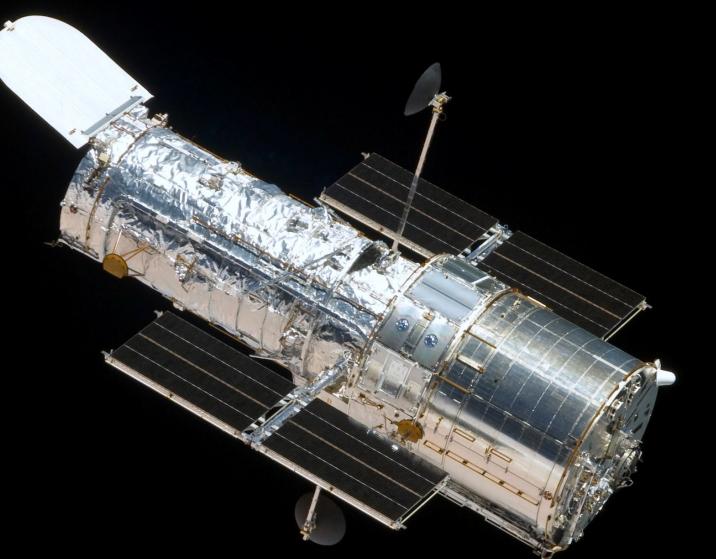


Hubble Space Telescope

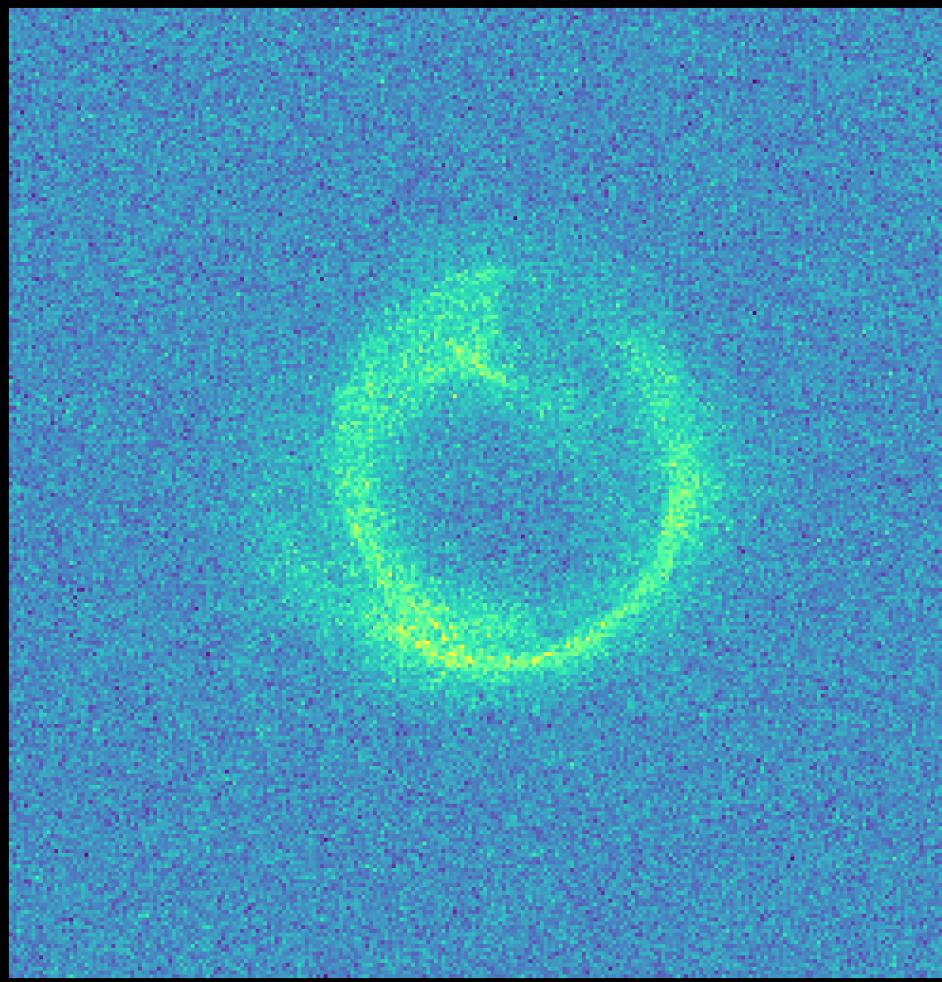
The Likelihood Instrument response



Lensed galaxy signal

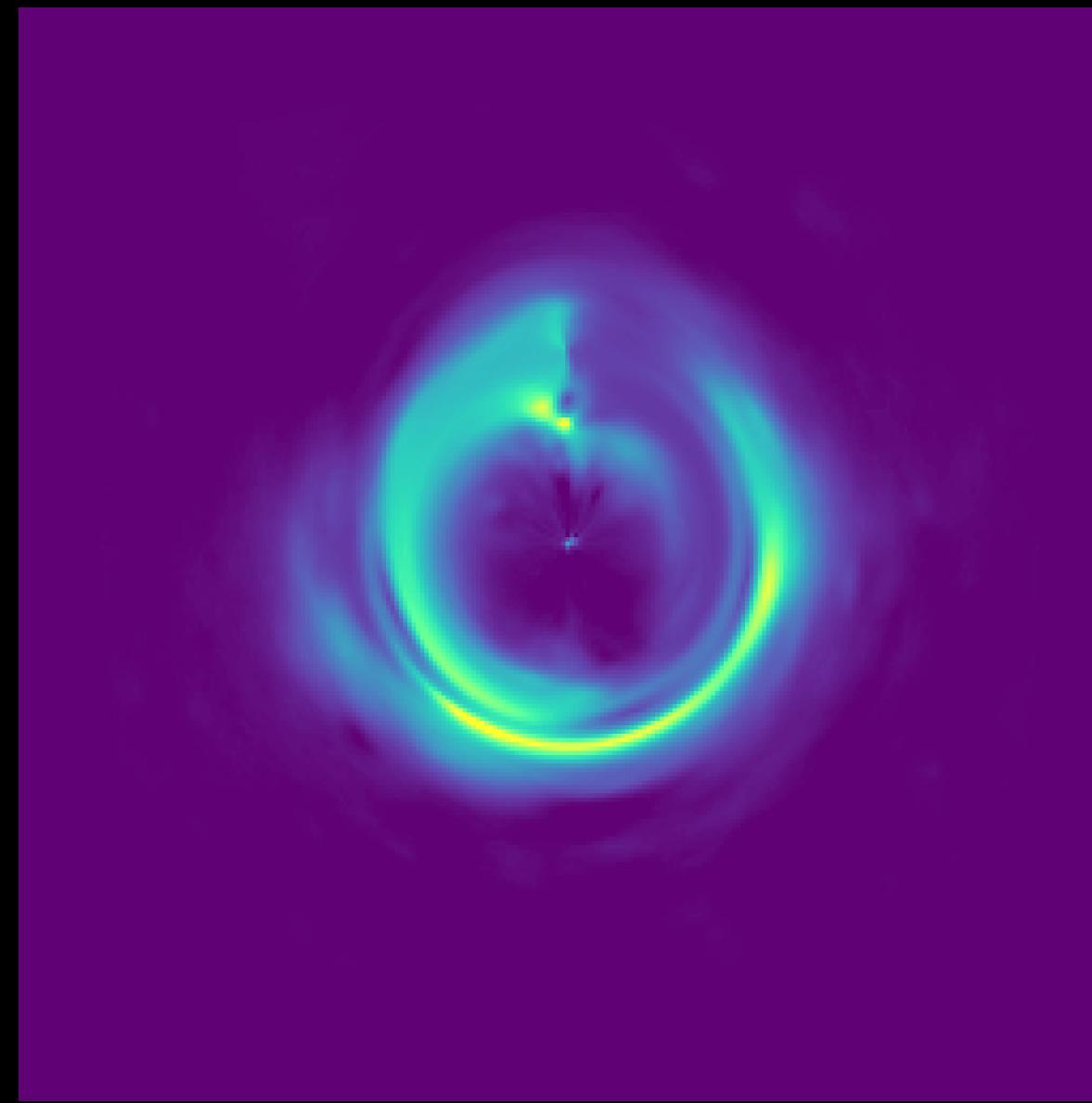


Hubble Space Telescope



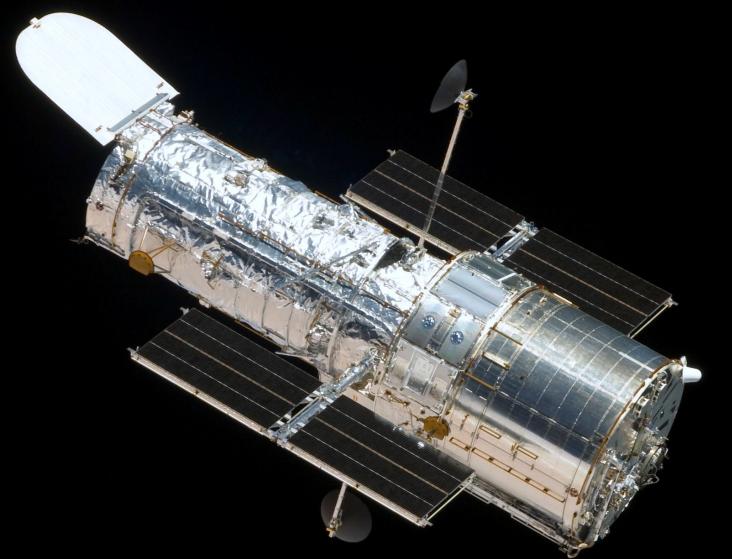
Data on Earth

The Likelihood Instrument response



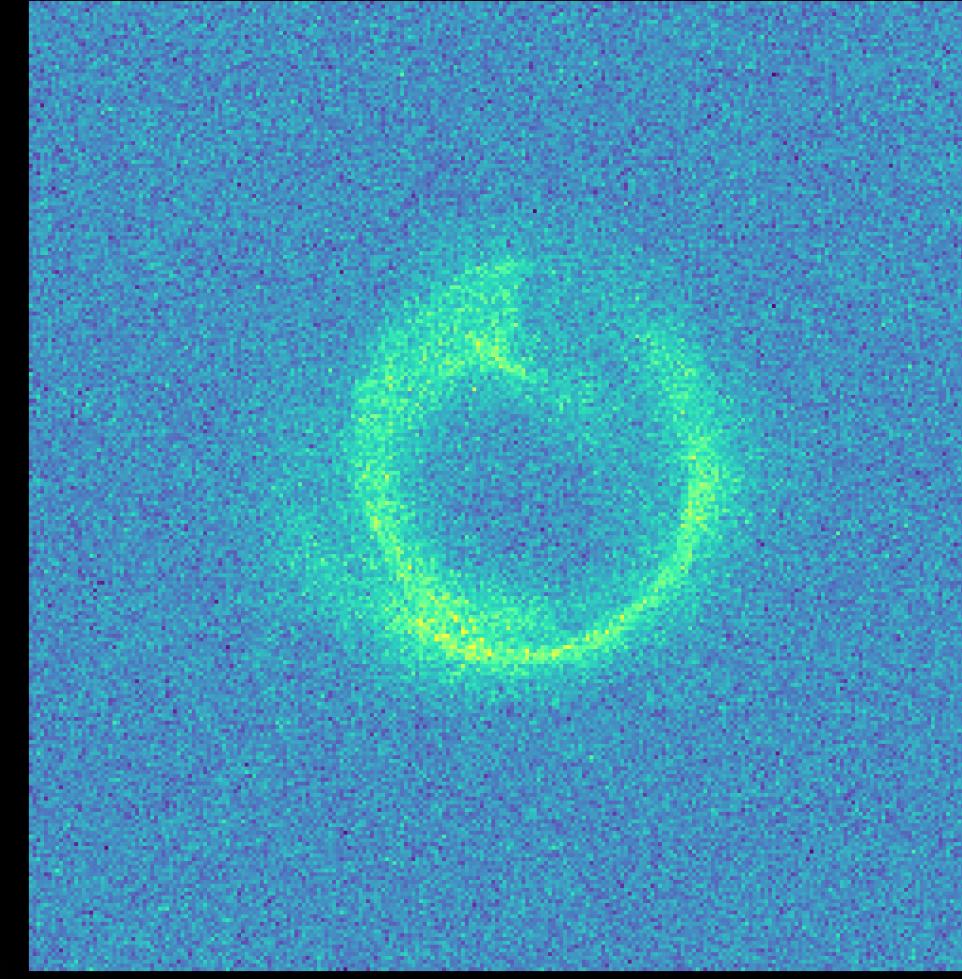
Lensed galaxy signal

$$L(\textcolor{red}{s})$$



Hubble Space Telescope

$$RL(\textcolor{red}{s})$$



Data on Earth

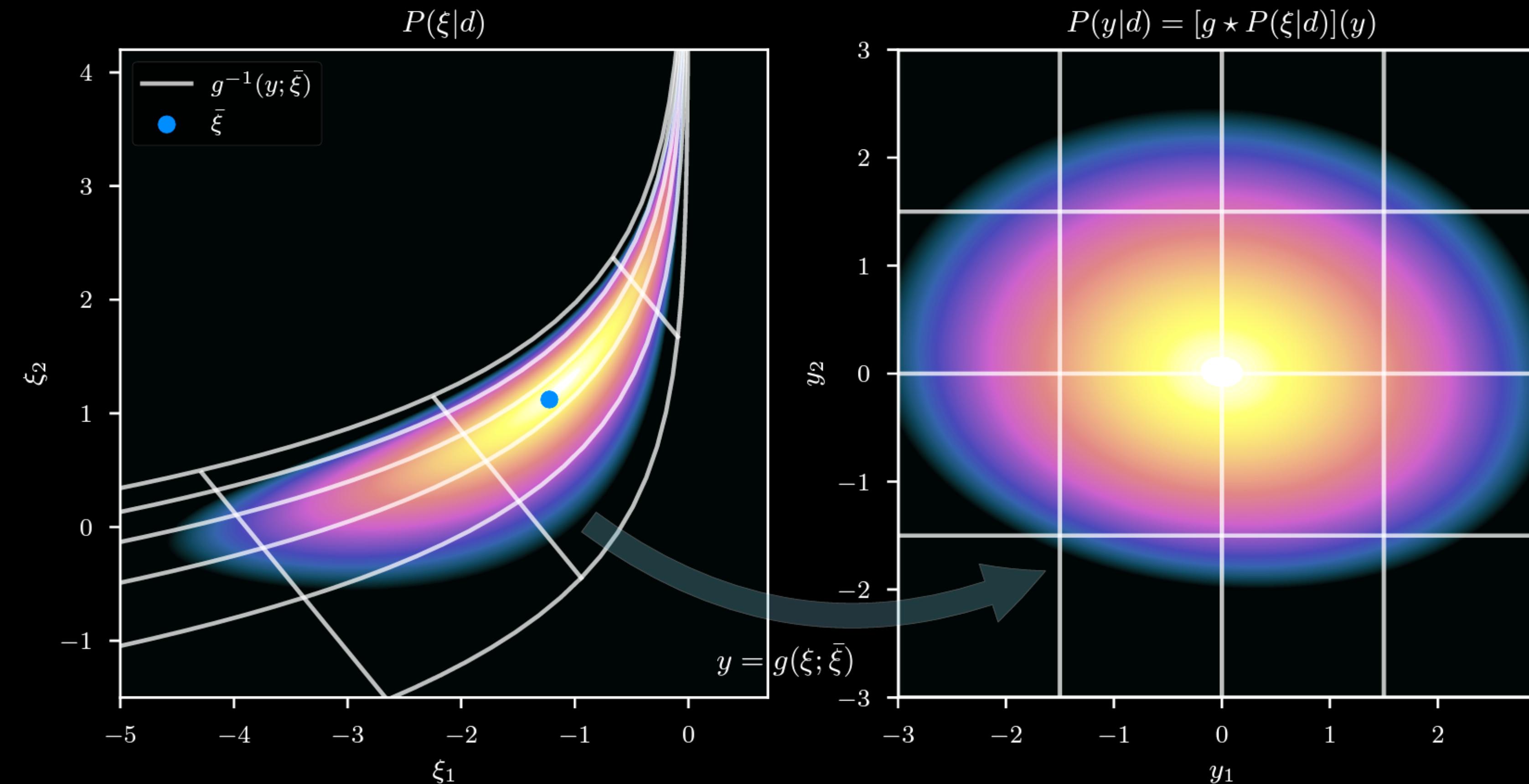
$$P(d | s) = \mathcal{G}(RL(\textcolor{red}{s}) - d, \sigma_h)$$

The Posterior

$$P(s | d) = \frac{P(d | s) P(s)}{P(d)}$$

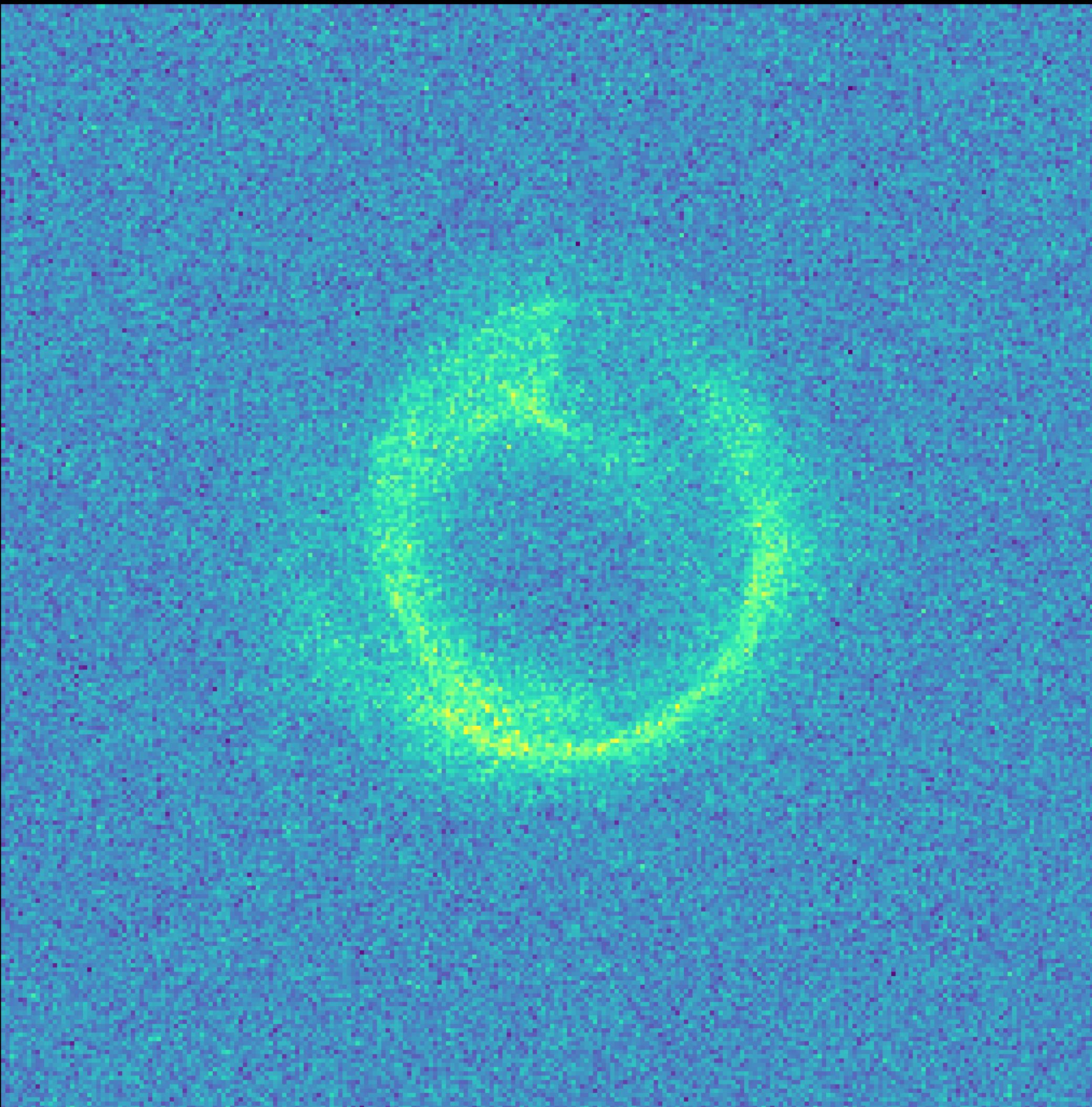
Inference

geometric Variational Inference



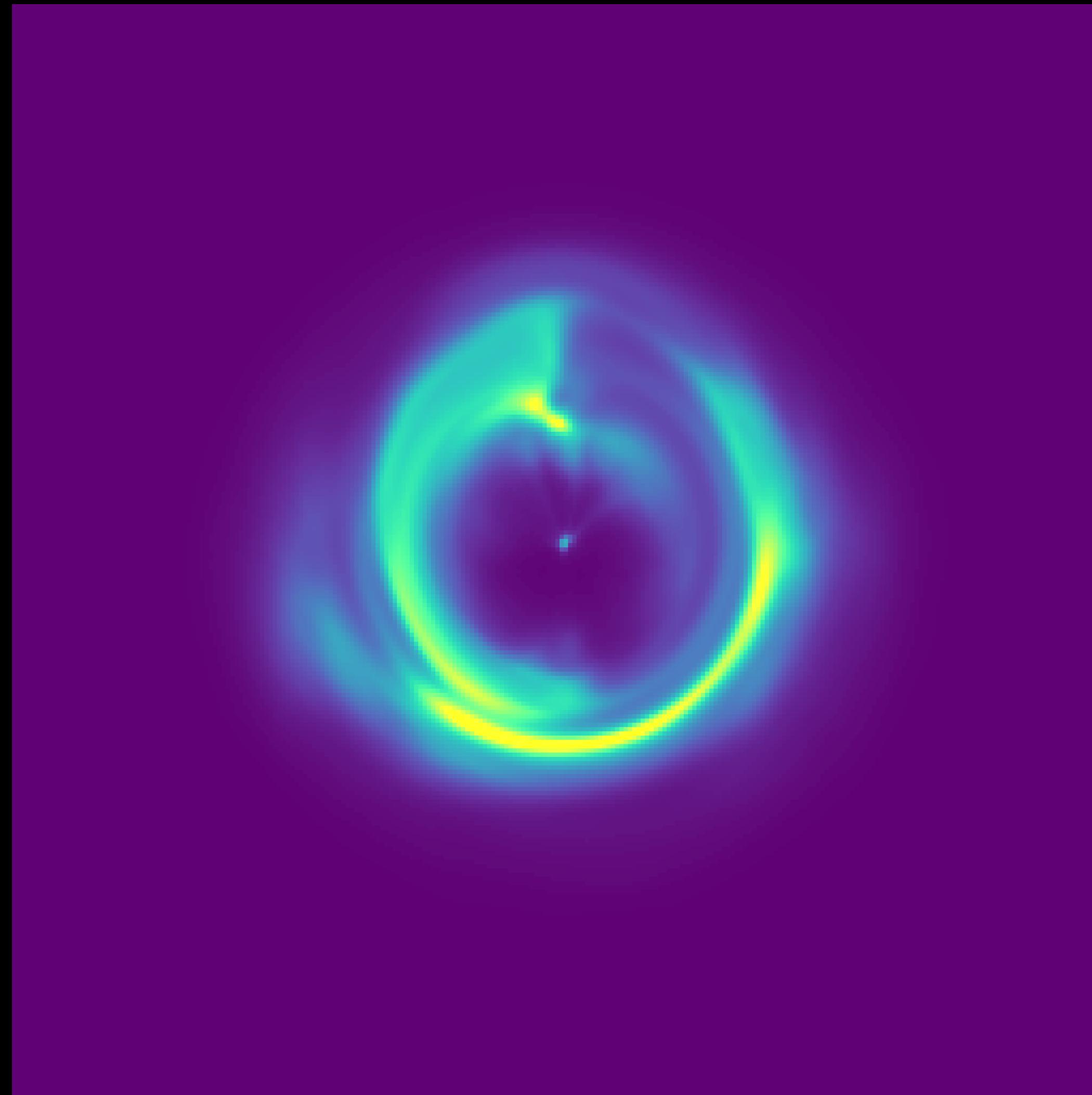
Credits @ Frank, P.; Leike, R.; Enßlin, T.A. Geometric Variational Inference. *Entropy* **2021**, *23*, 853.

The Data



Simulated HST data

The Reconstruction

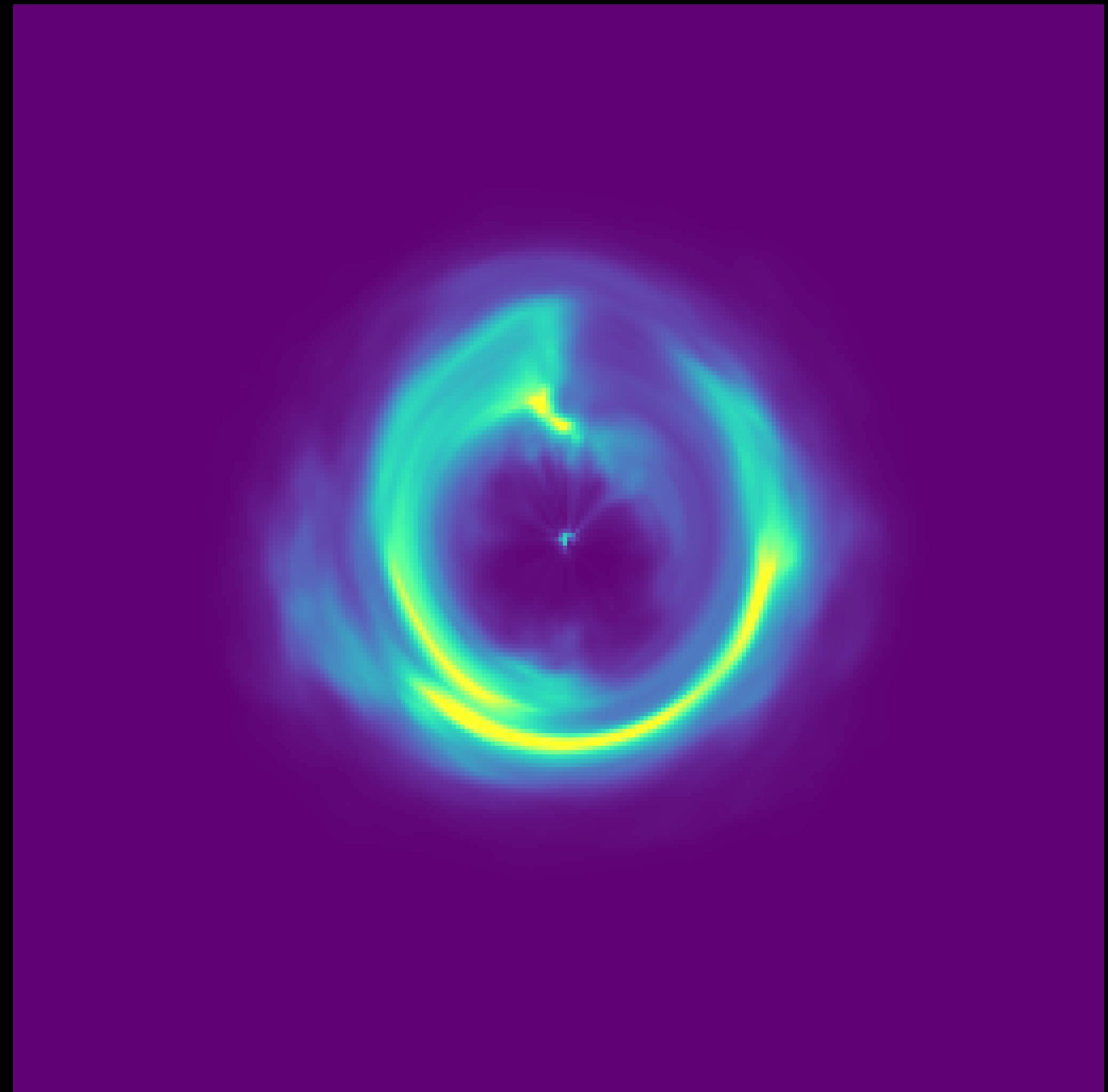


Lensed source light

Inference

Posterior (L_s)

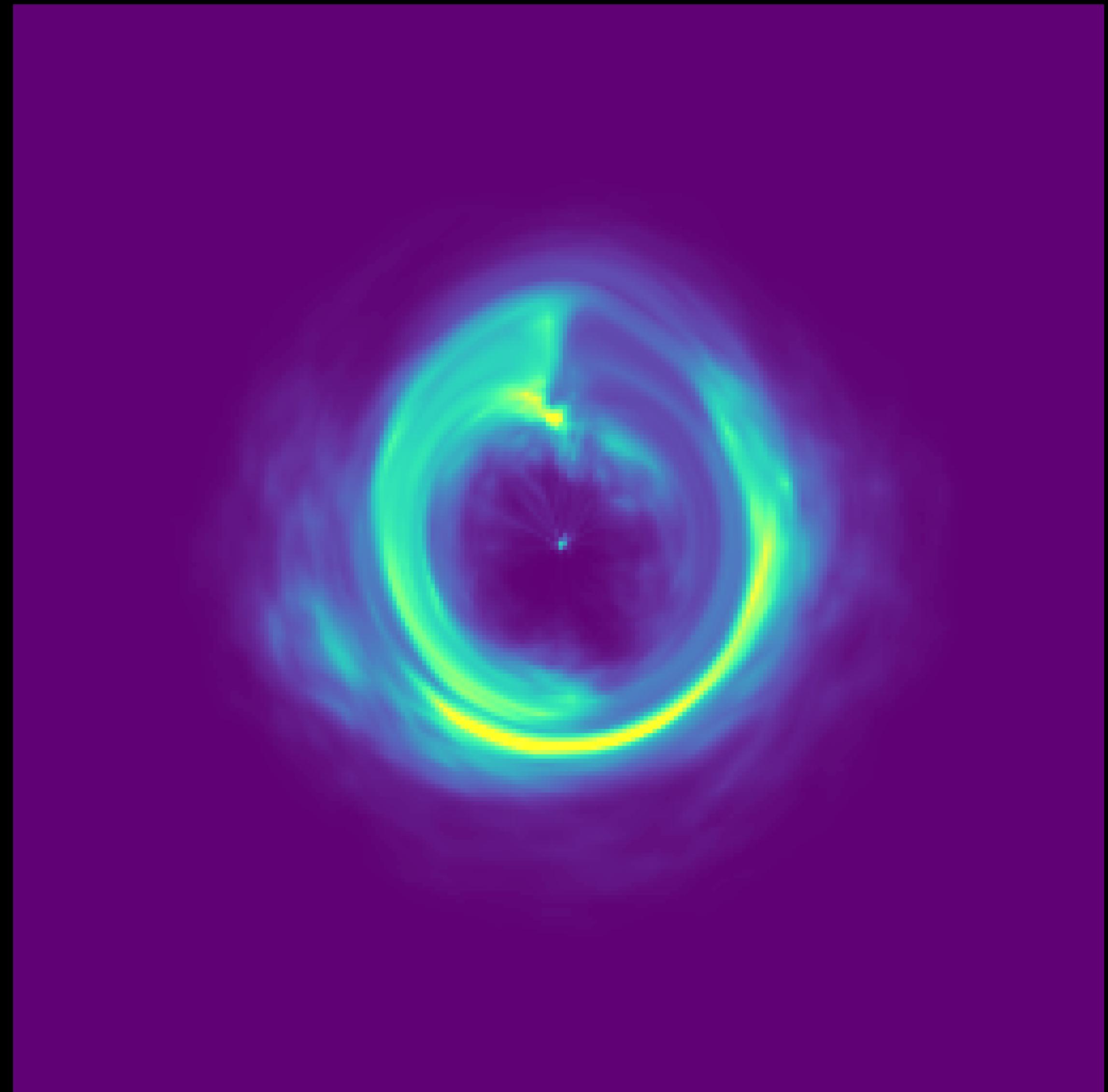
$$P(s \mid d)$$



Inference

Posterior (L_s)

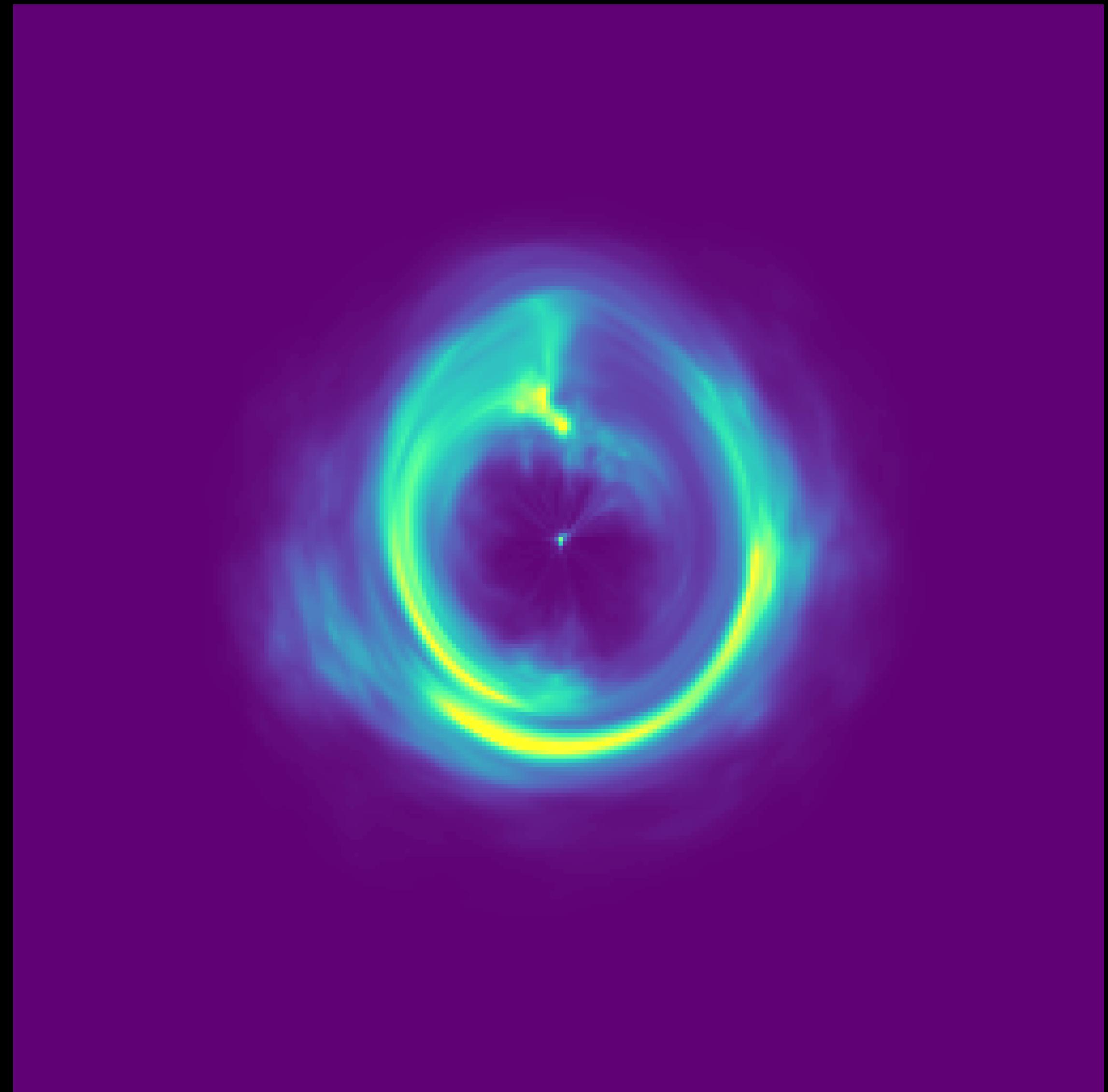
$$P(s \mid d)$$



Inference

Posterior (L_s)

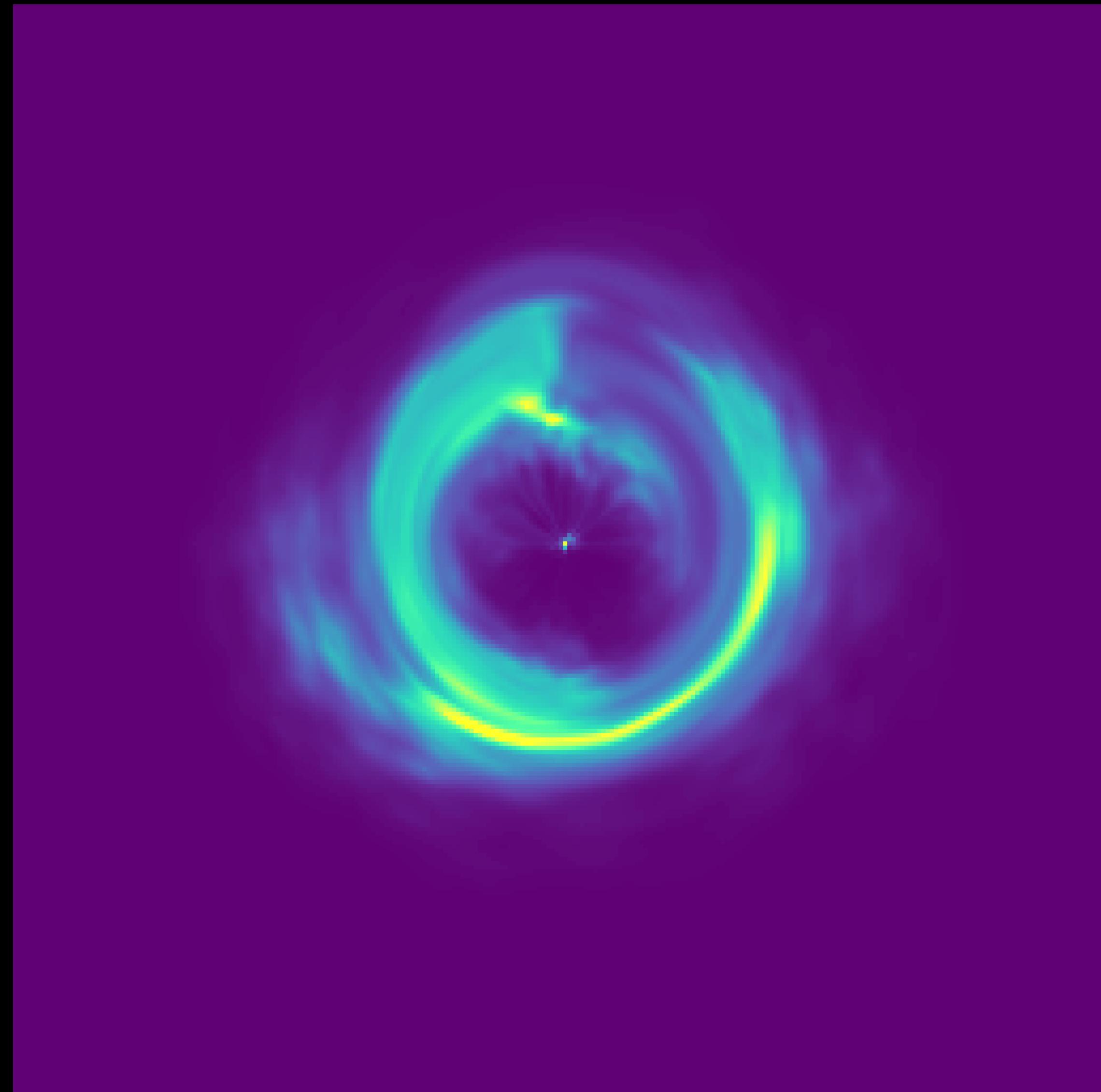
$$P(s \mid d)$$



Inference

Posterior (L_s)

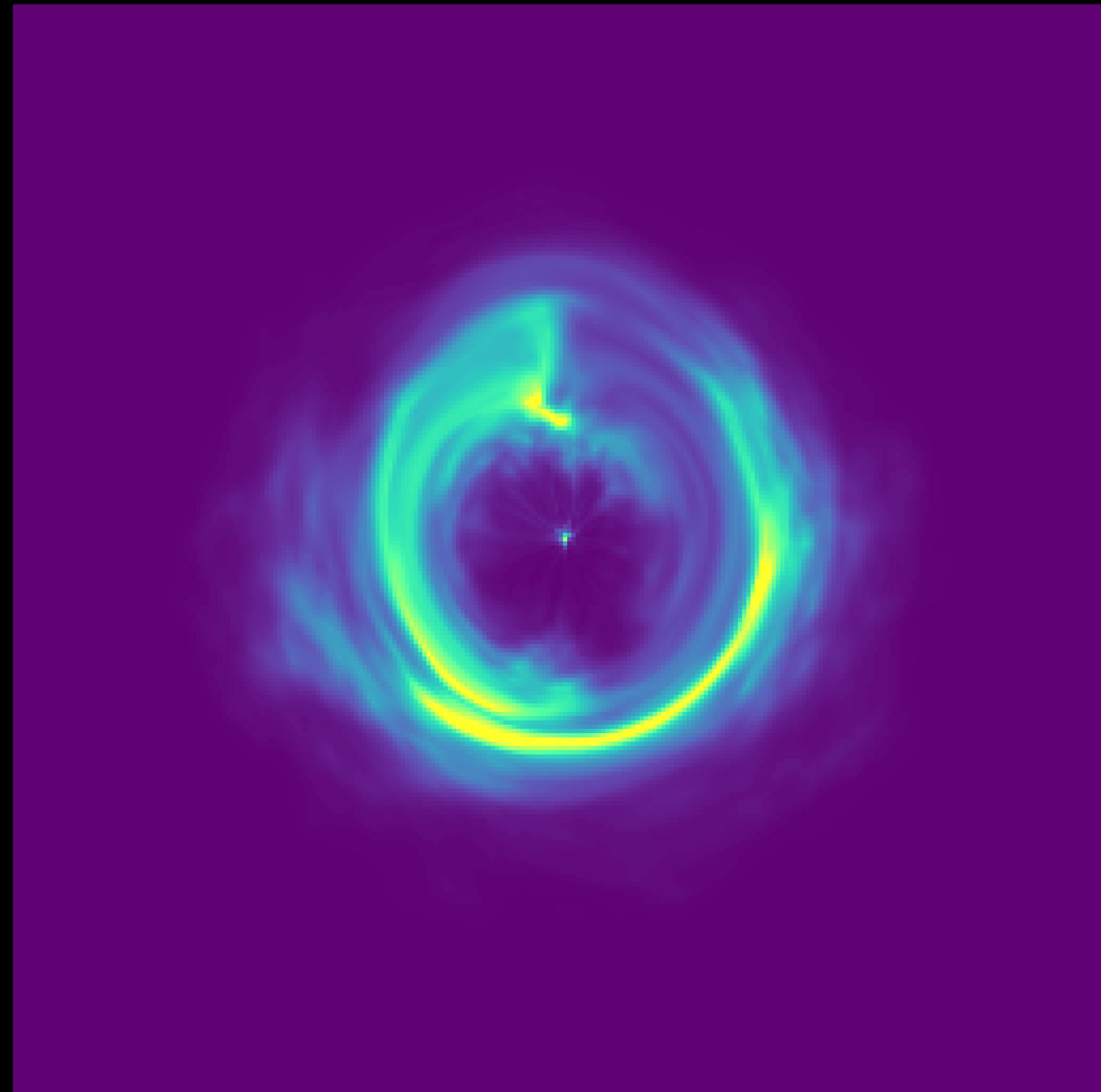
$$P(s \mid d)$$



Inference

Posterior (L_s)

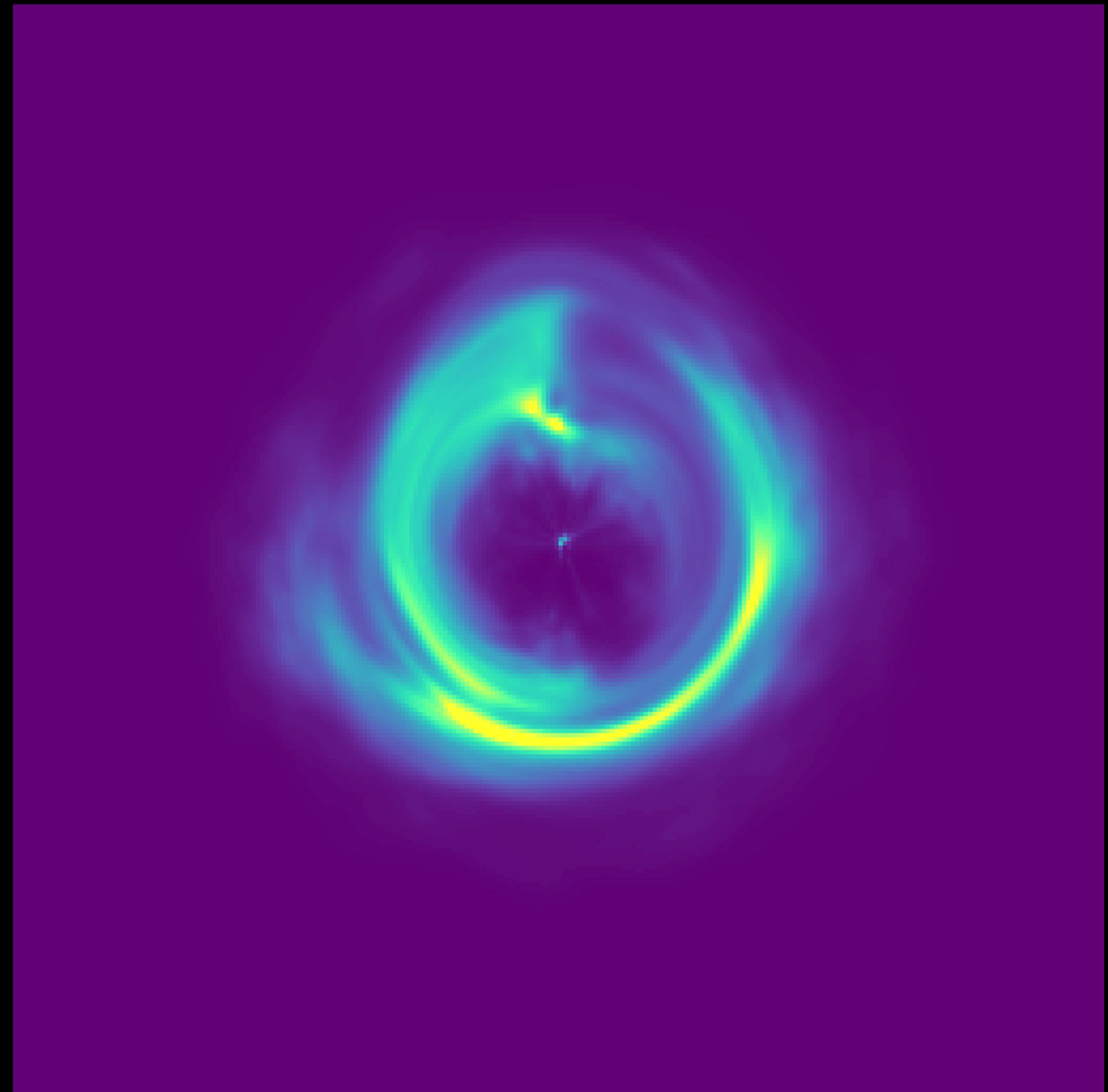
$$P(s \mid d)$$



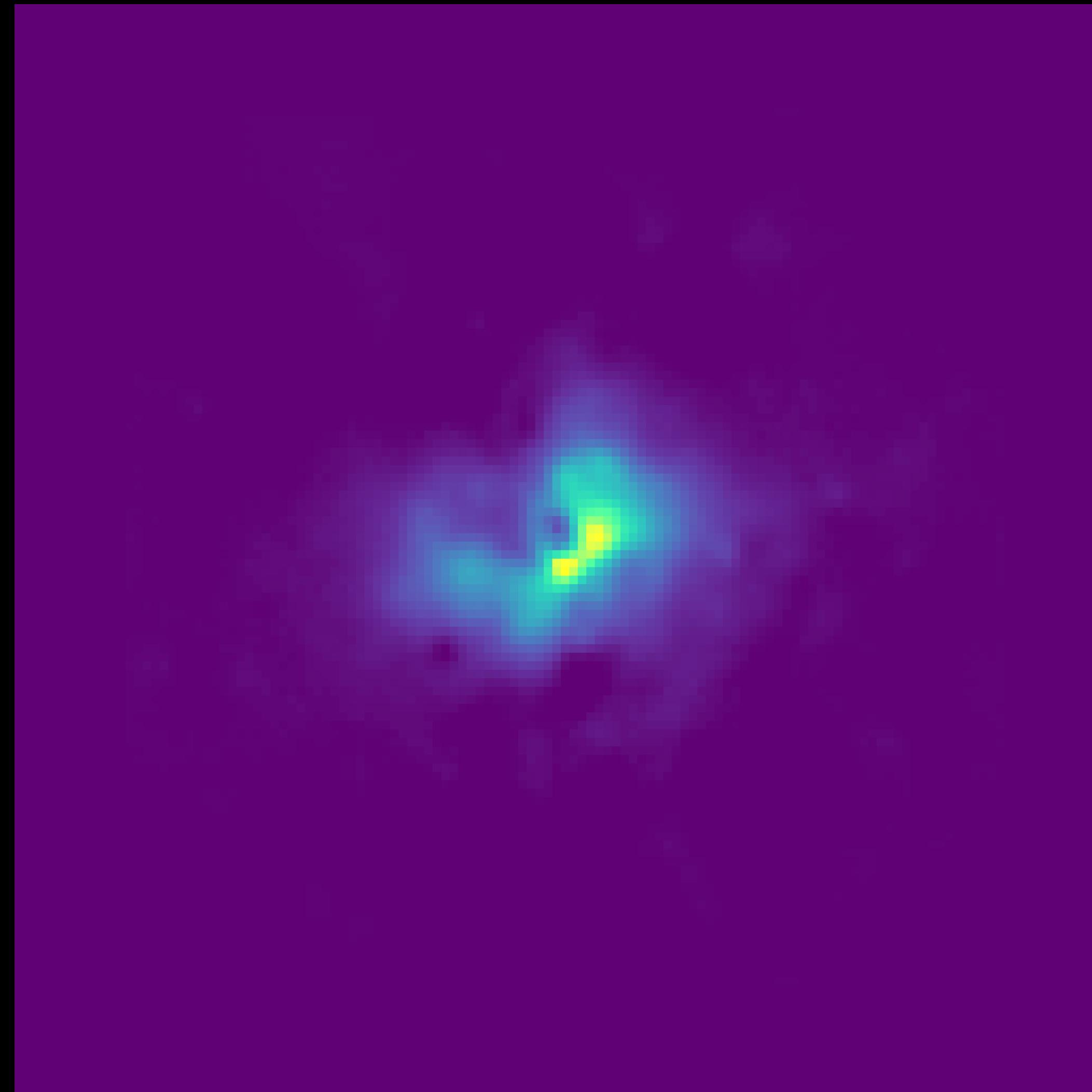
Inference

Posterior (L_s)

$$P(s \mid d)$$

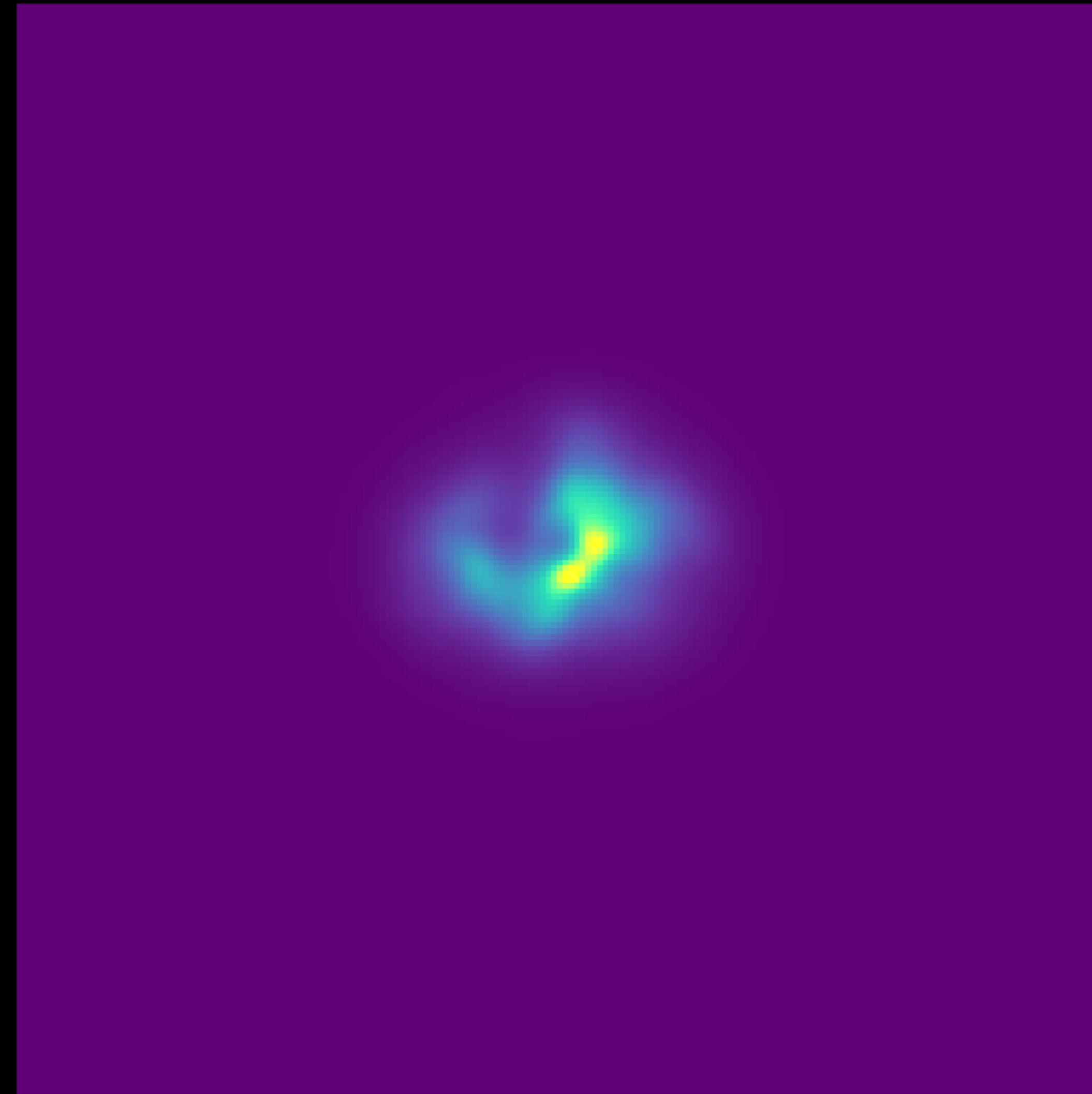


The Source



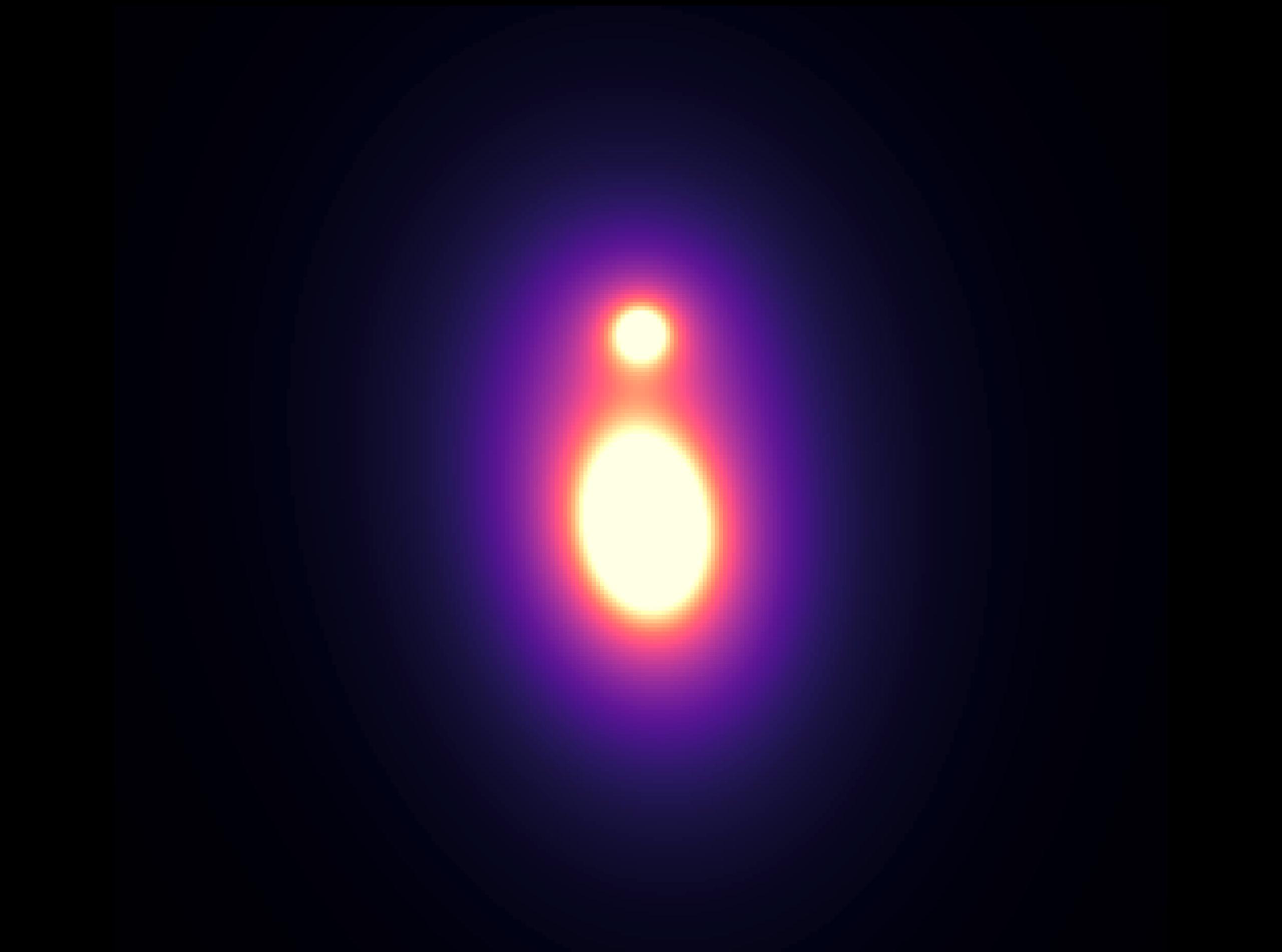
Ground truth

The Source



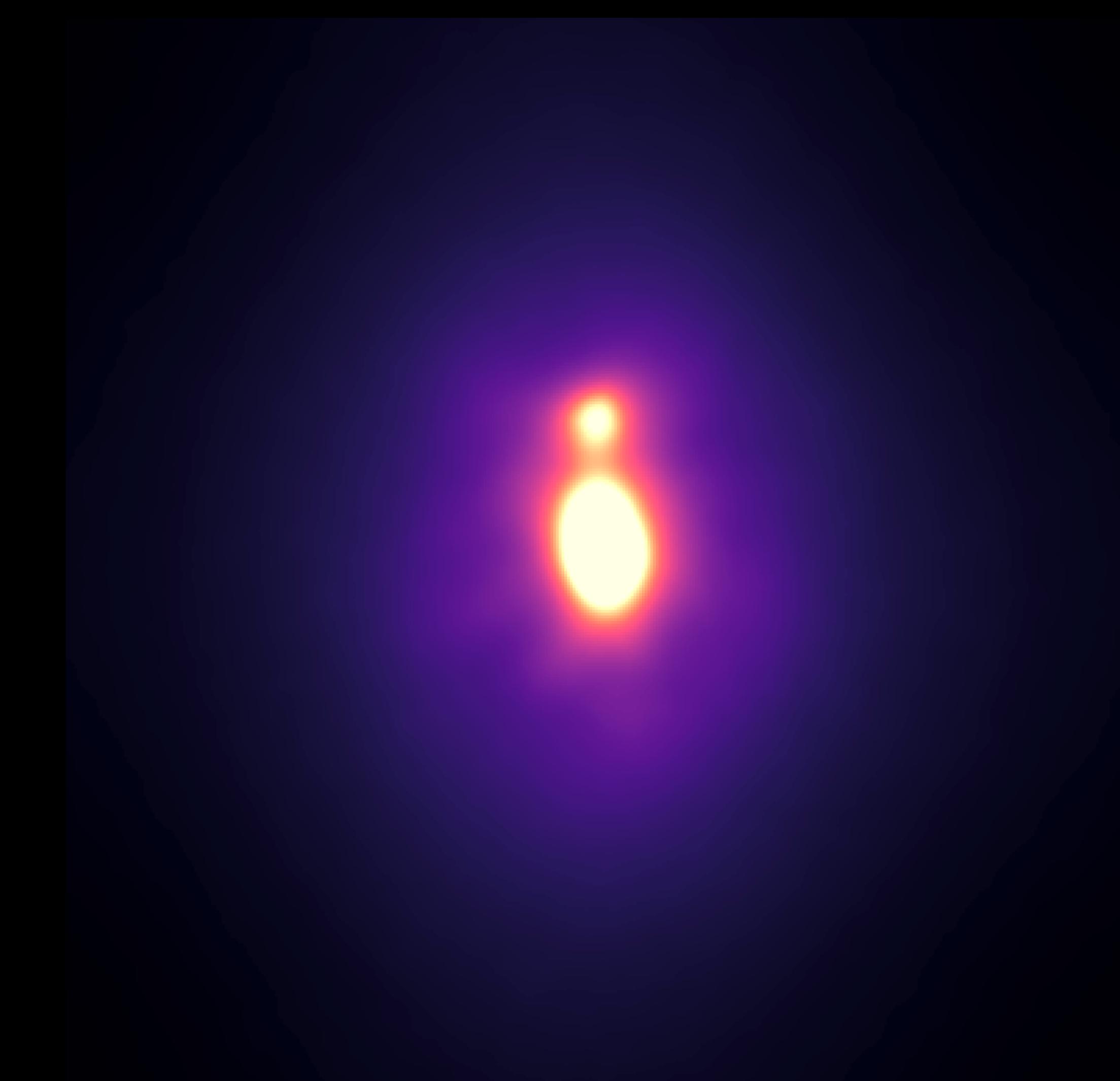
Posterior mean

The Convergence



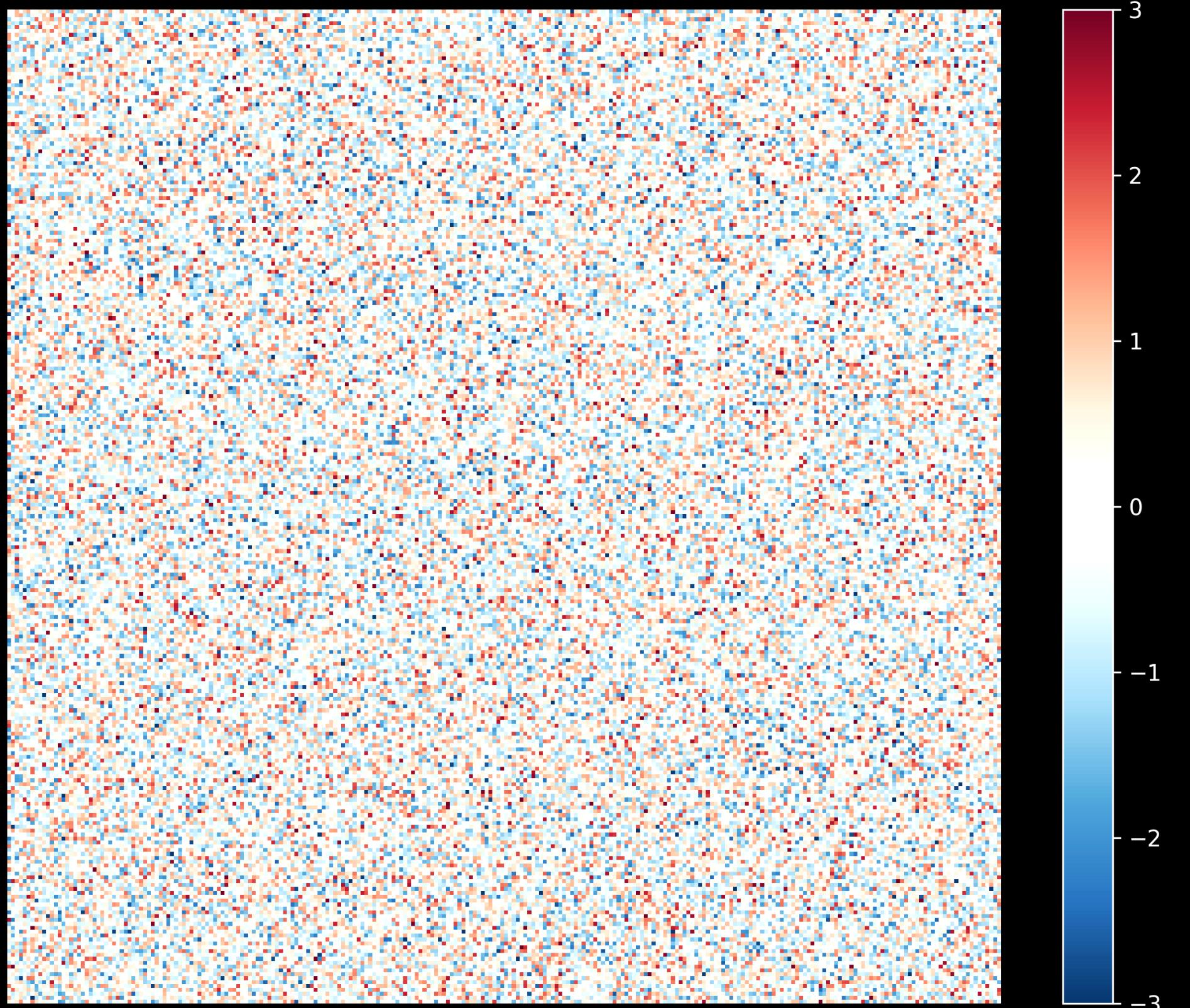
Ground truth mass distribution

The Reconstruction



Reconstructed projected mass distribution

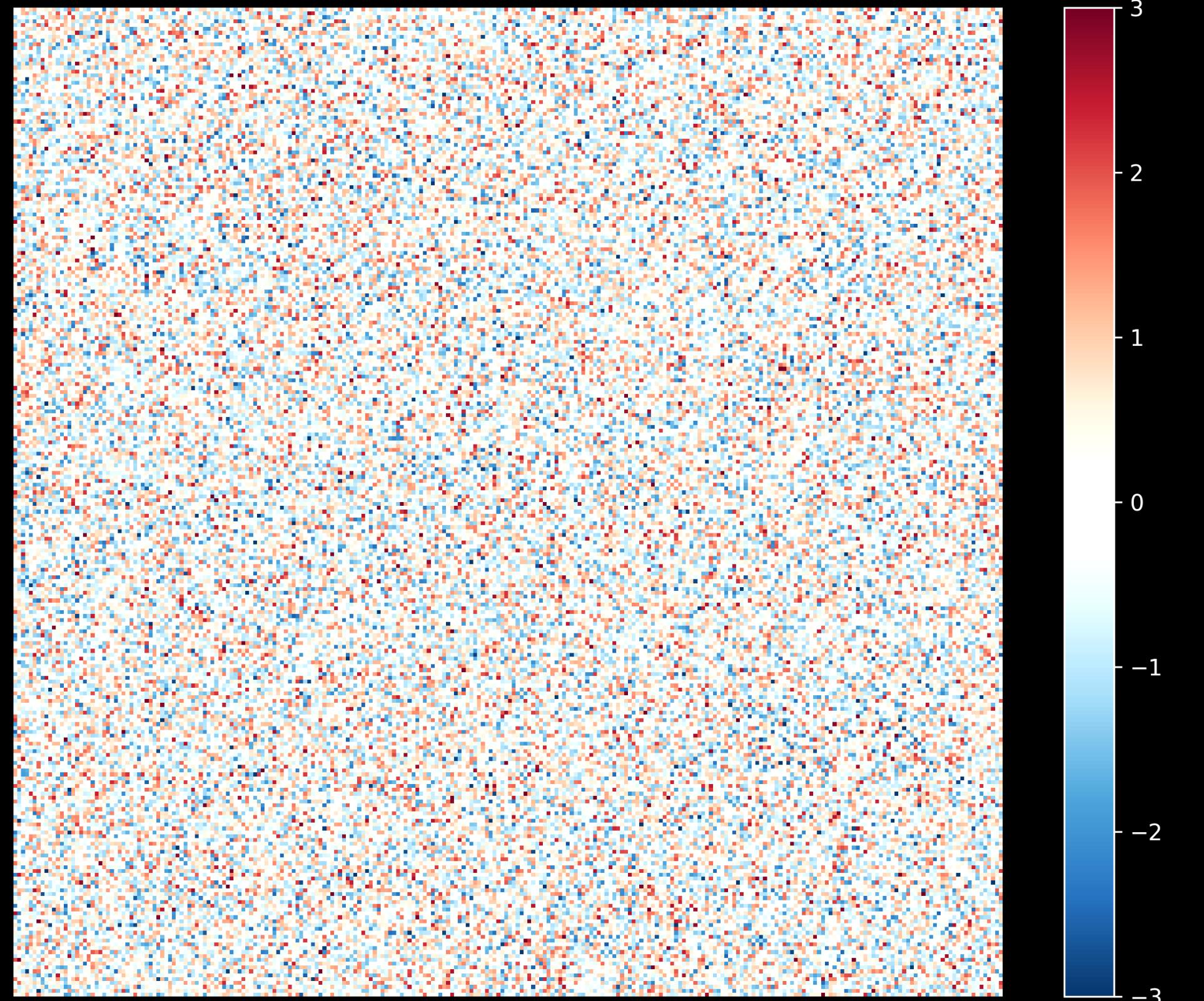
Take home



Lensed light noise-weighted residuals

Take home

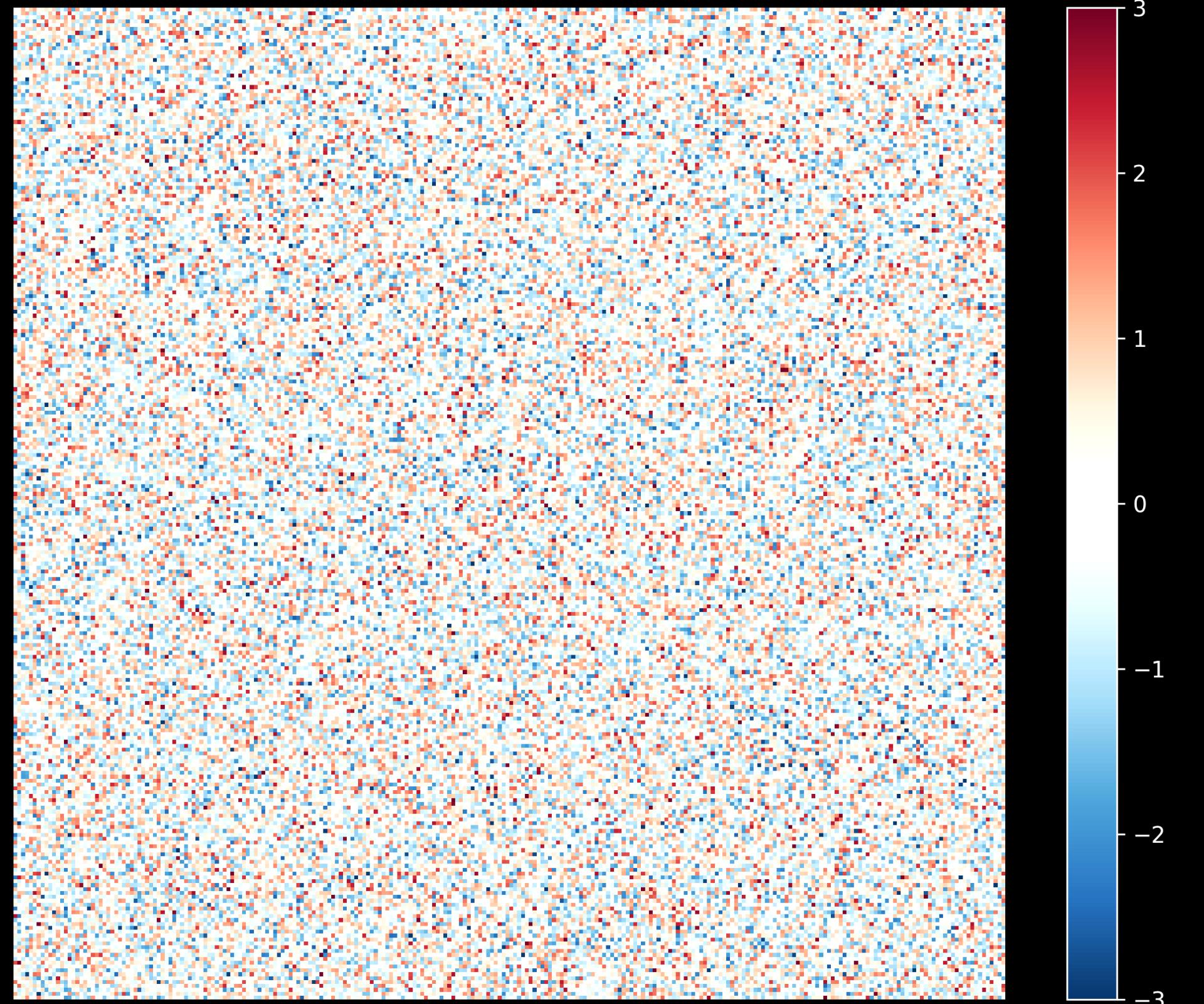
- Flexible source brightness distribution models



Lensed light noise-weighted residuals

Take home

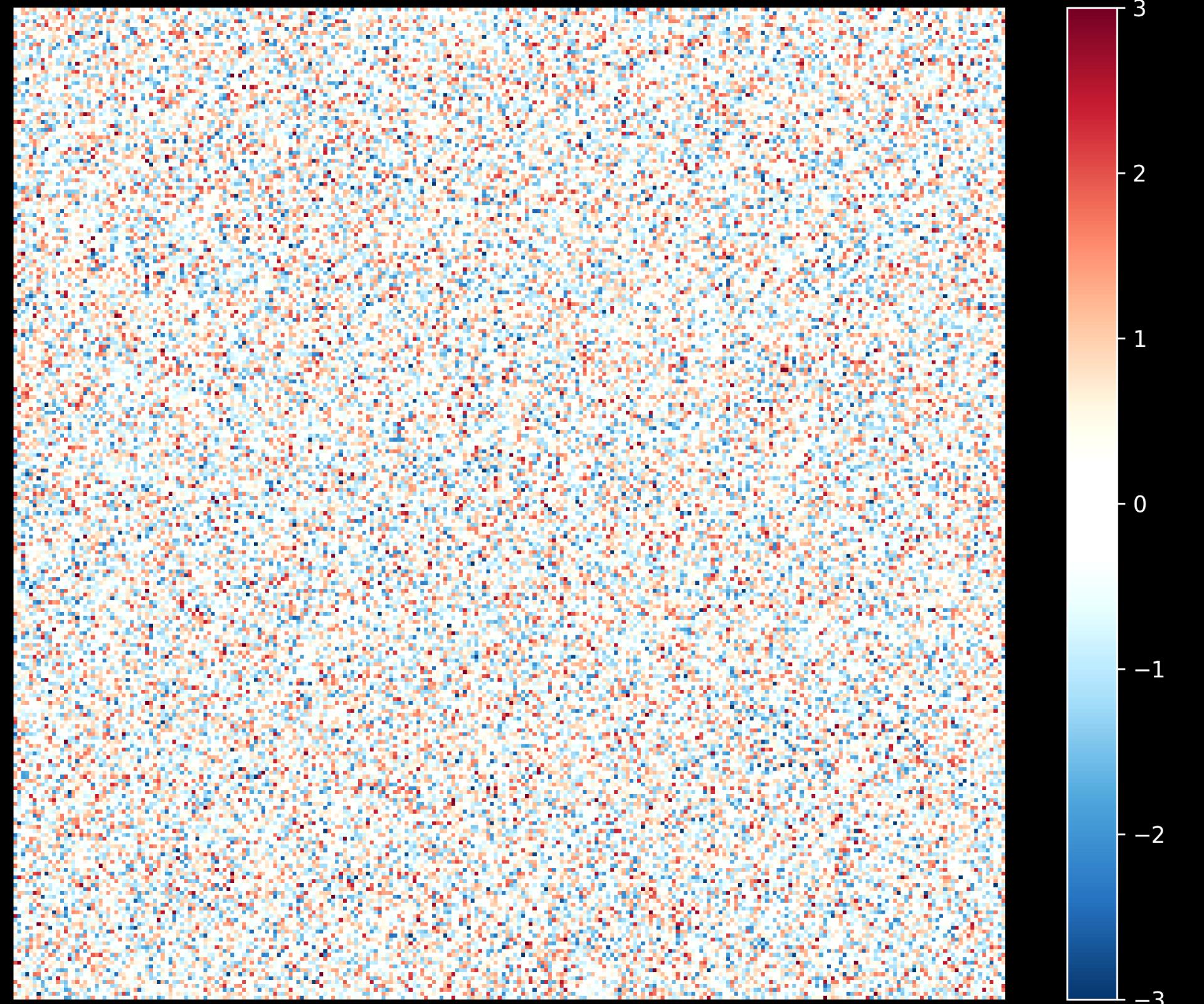
- Flexible source brightness distribution models
- Flexible mass distribution models



Lensed light noise-weighted residuals

Take home

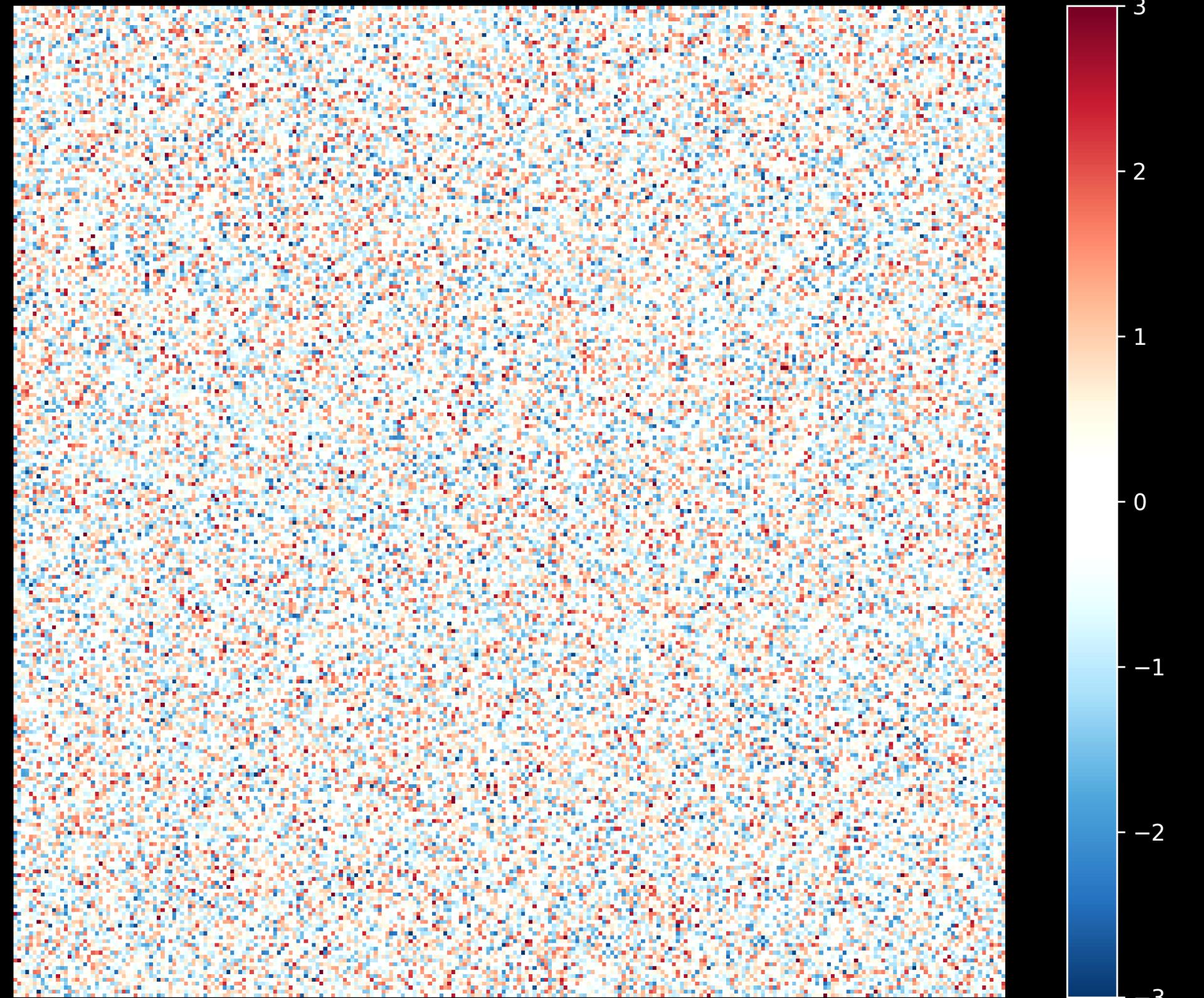
- Flexible source brightness distribution models
- Flexible mass distribution models
- Instrumental effects



Lensed light noise-weighted residuals

Take home

- Flexible source brightness distribution models
- Flexible mass distribution models
- Instrumental effects
- Uncertainty estimates

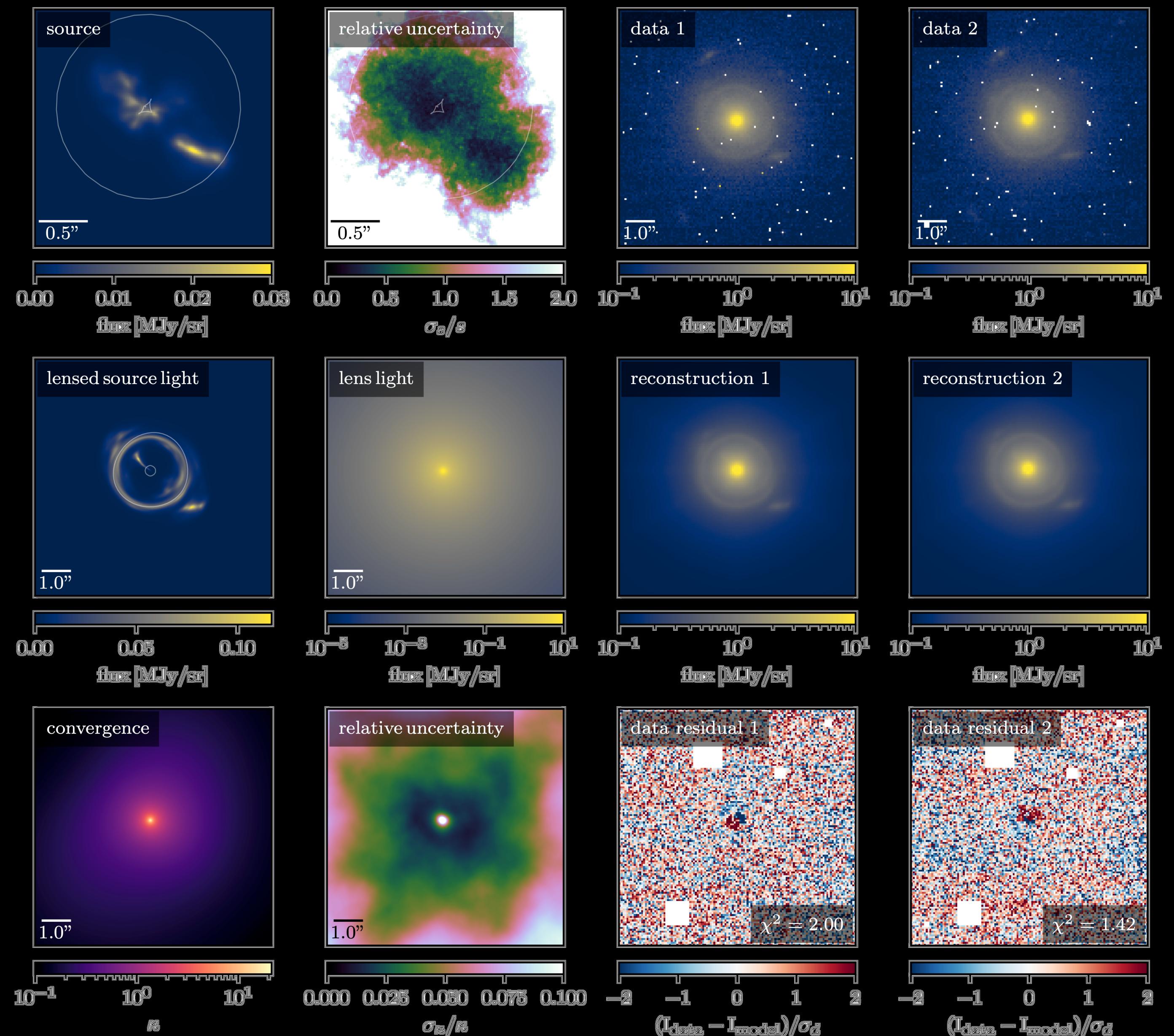


Lensed light noise-weighted residuals

Future Work

Future Work

- Improve mass models and substructure detection
- Incorporate multi-wavelength observations (radio \rightarrow X-ray)
- Enlarge charming models library :)
- And more...



SPT-0418 JWST data application

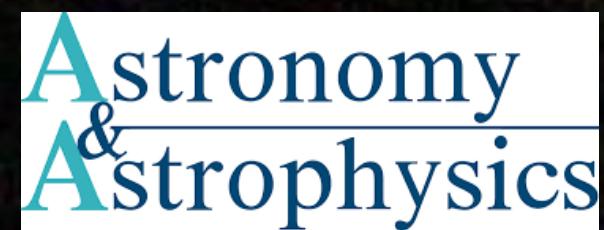


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Thank you!



Rüstig J., Guardiani M. et al., Introducing LensCharm
A charming Bayesian strong lensing reconstruction framework
<https://doi.org/10.1051/0004-6361/202348256>

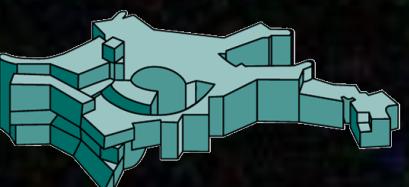


<https://gitlab.mpcdf.mpg.de/ift/lenscharm>

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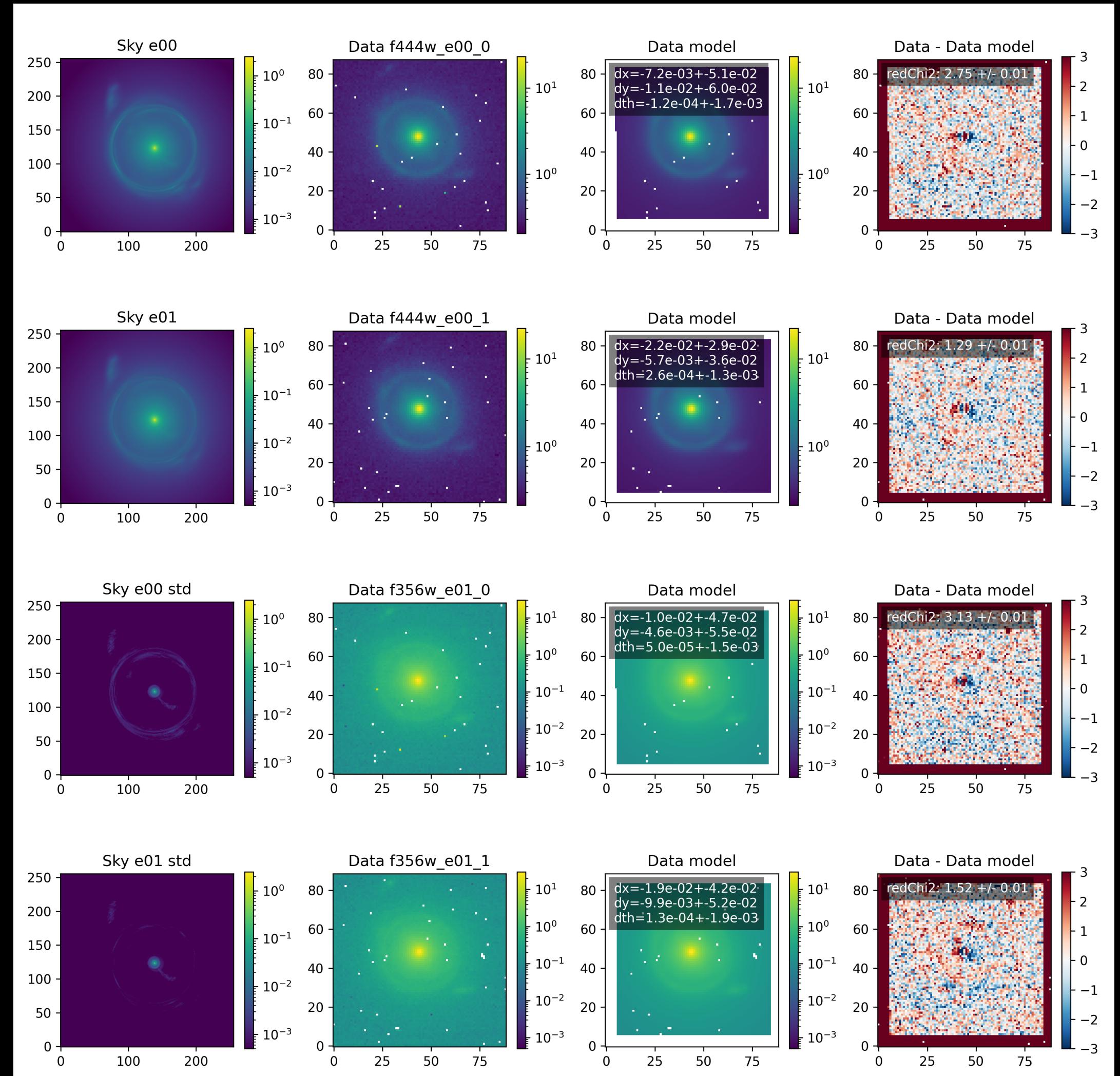


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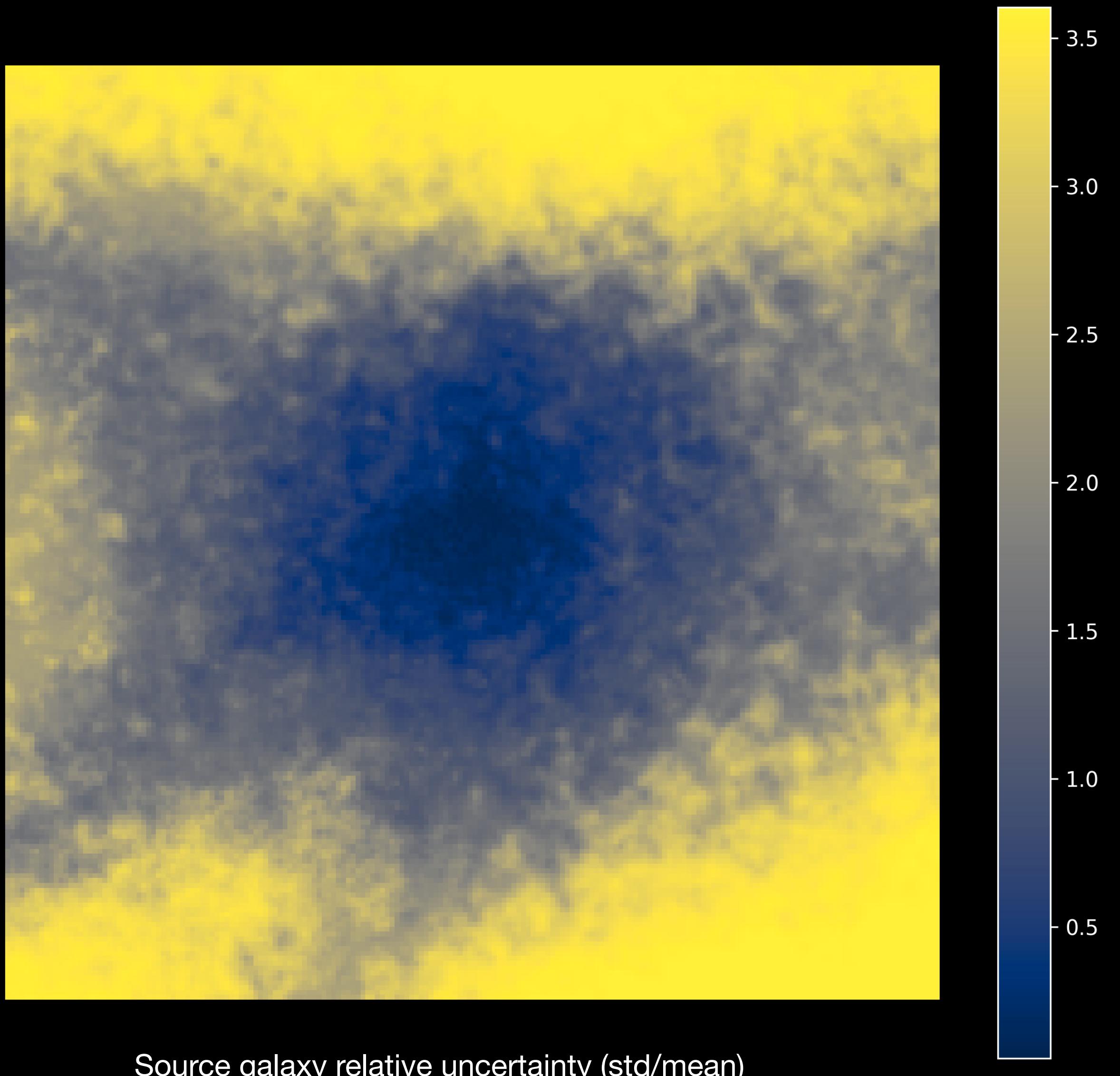
Backup

Multi-frequency SPT0418-47 (preliminary)



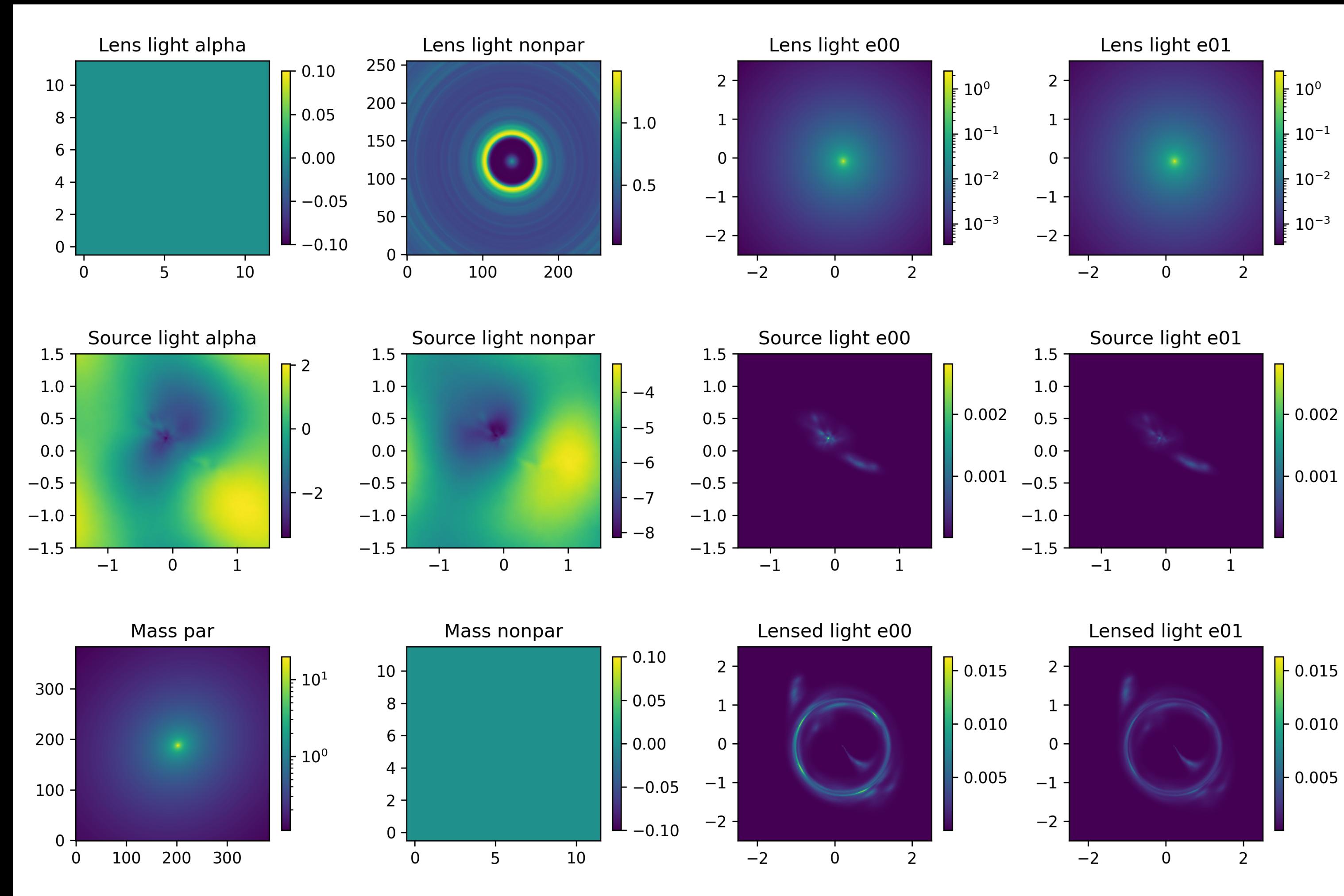
Backup

More uncertainties



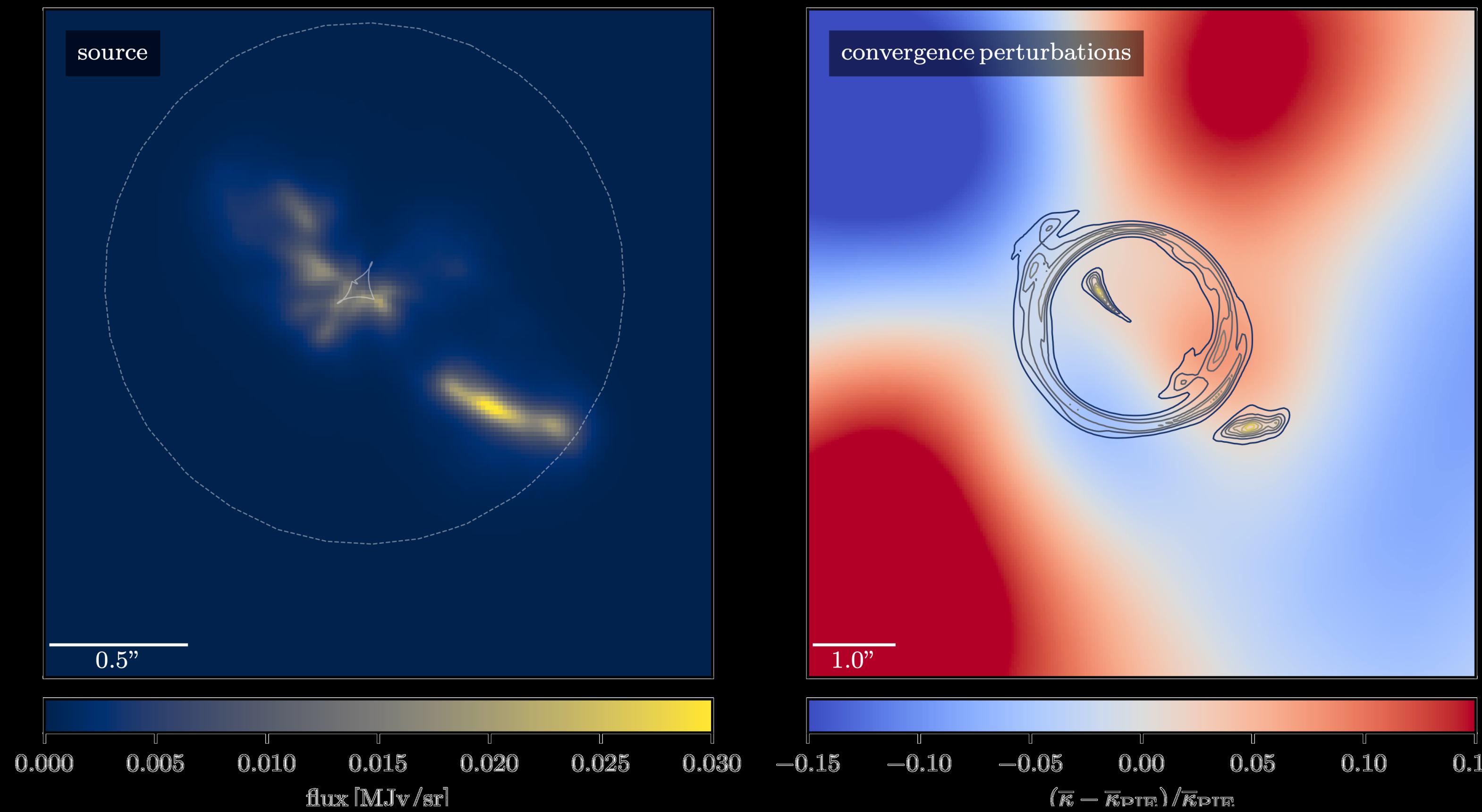
Backup

Multi-frequency SPT0418-47 (preliminary)



Backup

Single-frequency SPT0418-47



Backup

SPT0418-47

