

Convolutional Neural Networks for Detecting Moving Objects in Wide-Field Surveys



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12 July, International Conference on Machine Learning for Astrophysics

Image credit: Caltech



Acknowledgements

- This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No 945363.
- This project has received funding from the Swiss National Foundation grant agreement 40B2-0194729 / 2.
- This project was hosted by the Caltech Infrared Processing and Analysis Center.



EPFL BRIDGE group

- Belén Yu Irureta-Goyena, PhD student
- Elisabeth Rachith, PhD student
- Stephan Hellmich, postdoc
- Jean-Paul Kneib, PI

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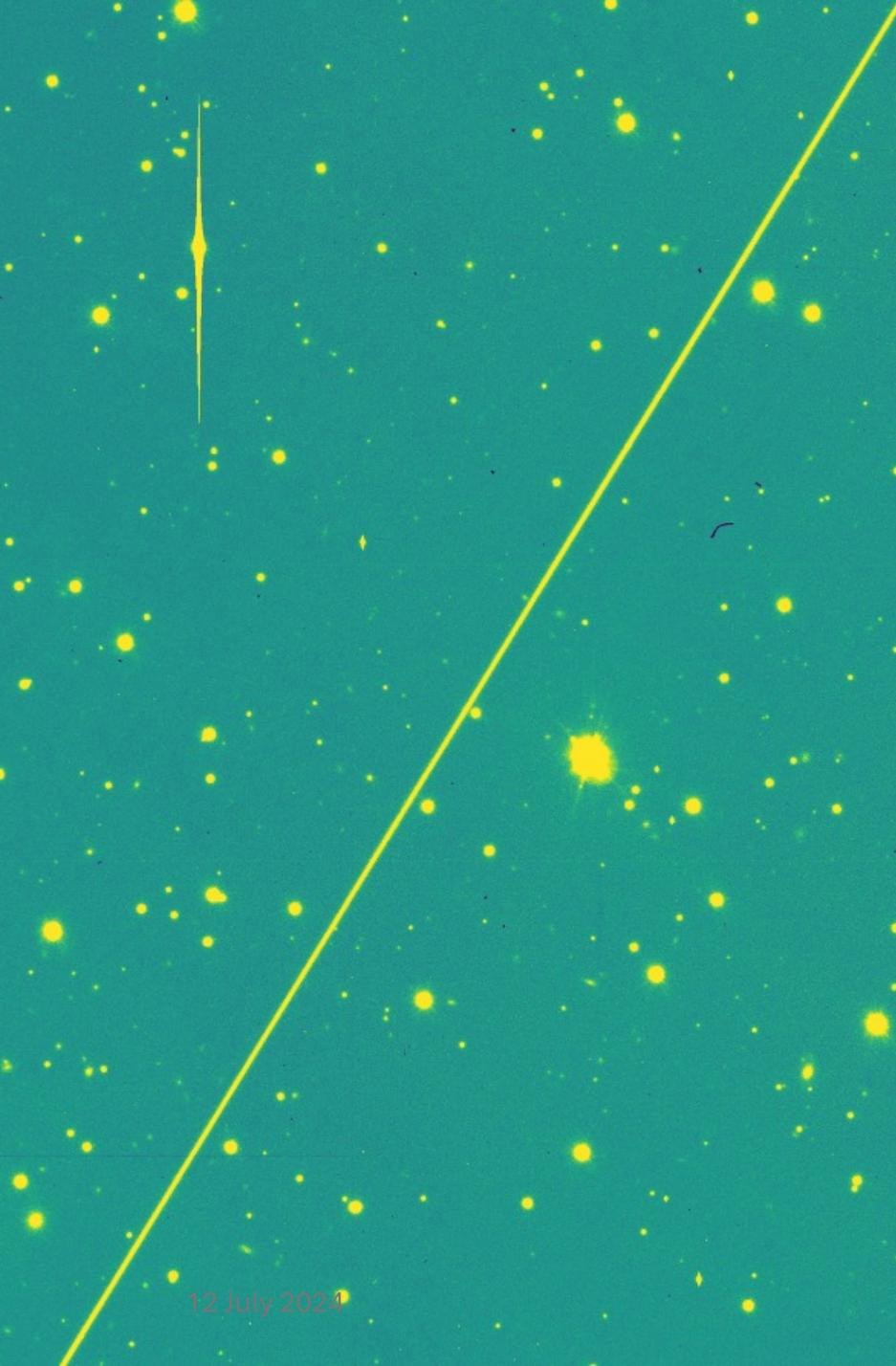
12 July 2024

Belén Yu Irureta-Goyena belen.irureta@epfl.ch

Image credit: Bill Ross

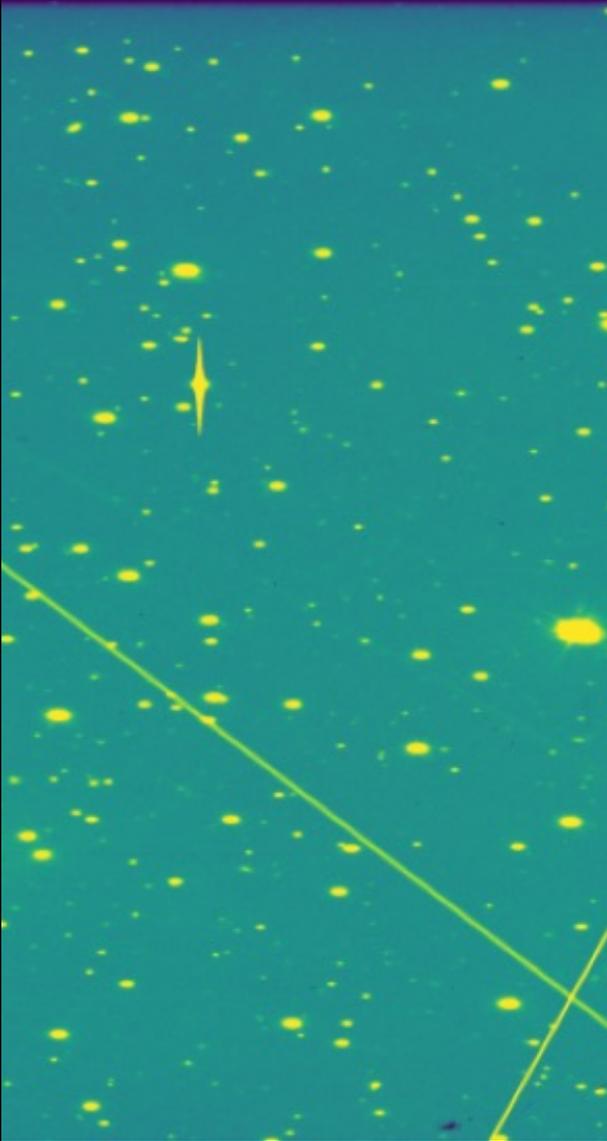
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A vertical panel on the left side of the slide features a green background with numerous small yellow stars. A prominent diagonal yellow line runs from the bottom-left towards the top-right. A single, larger yellow star is visible near the center of the panel.

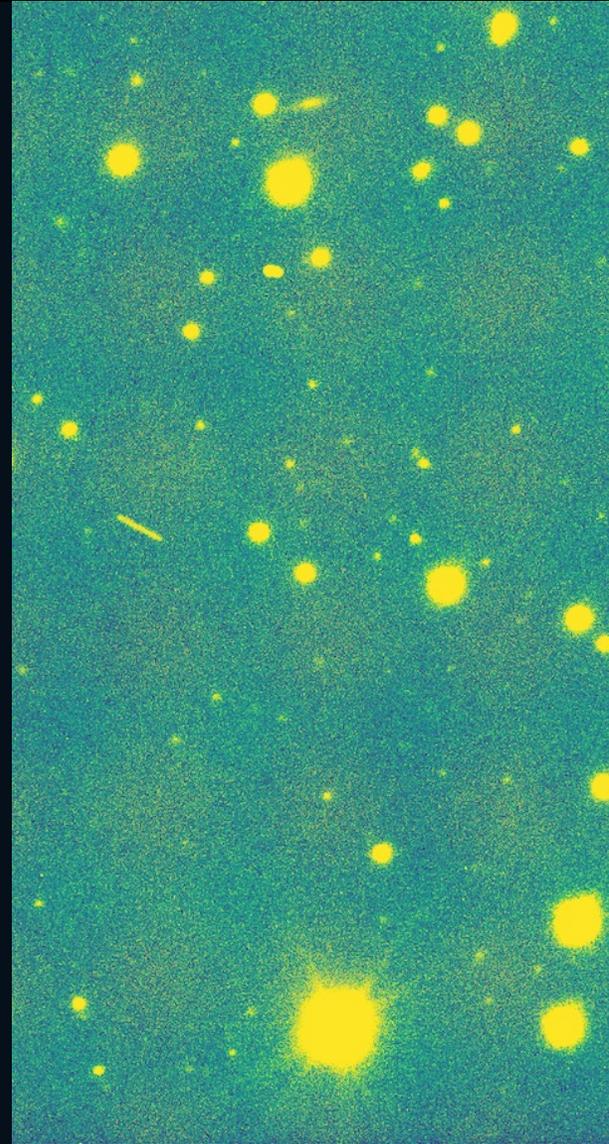
Moving objects in astronomical images

- Objects crossing the sky leave signature tracks in long-exposure astronomical images.
- These objects can be artificial (satellites and space debris) or natural (asteroids and comets).



Satellites and space debris

- moving faster (up to 0.5 deg/s)
- long tracks (cross the whole field)



Asteroids and comets

- moving slower (0.1-1 arcsec/s)
- short tracks (up to 200 pixels)

Insights into the Solar System

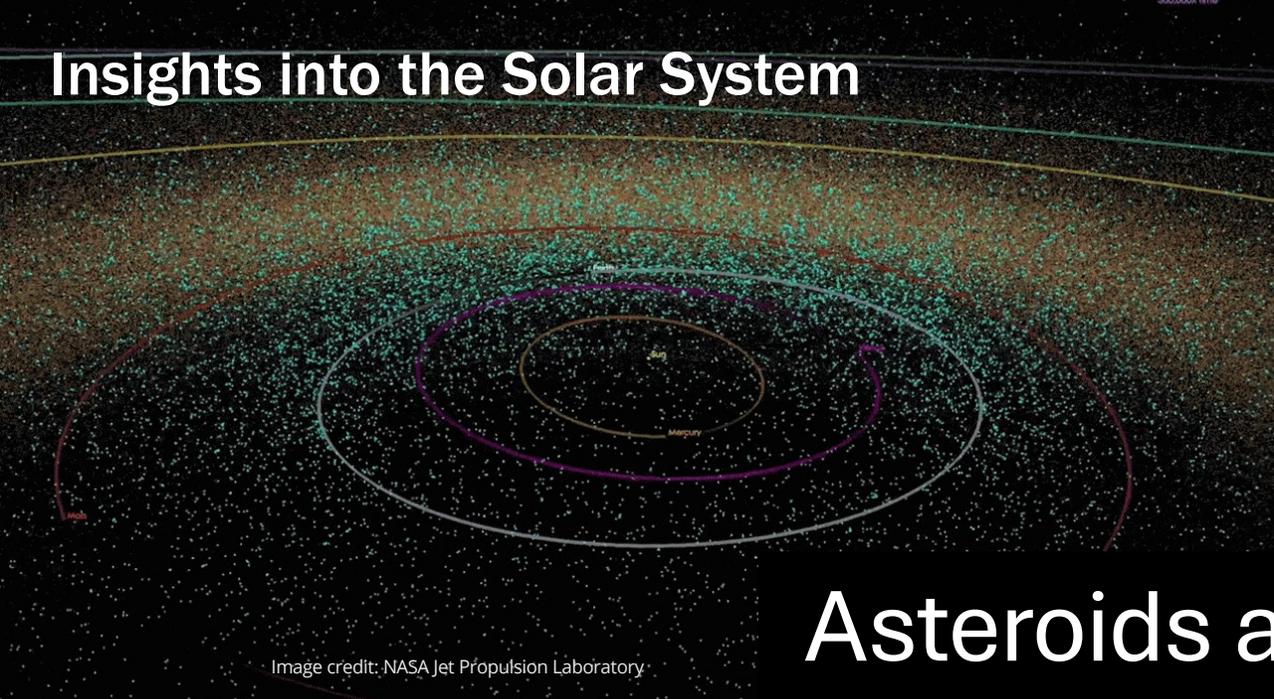


Image credit: NASA Jet Propulsion Laboratory

Threat to Earth

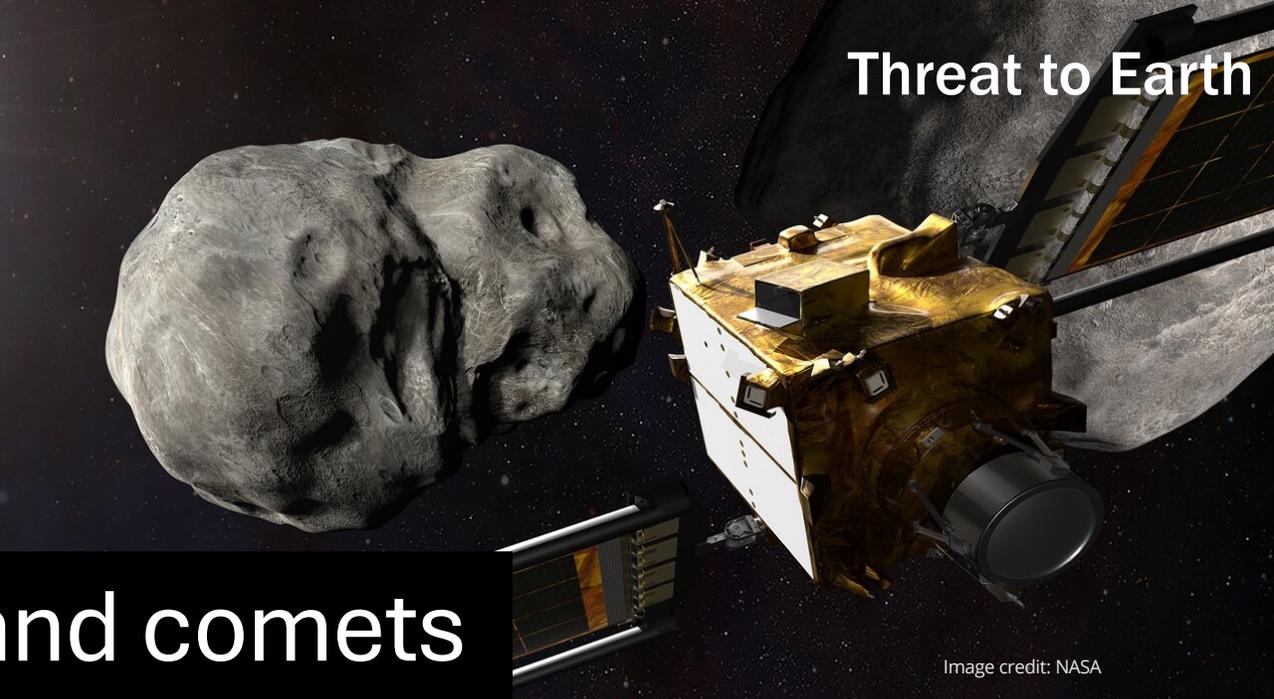


Image credit: NASA

Asteroids and comets

Past events

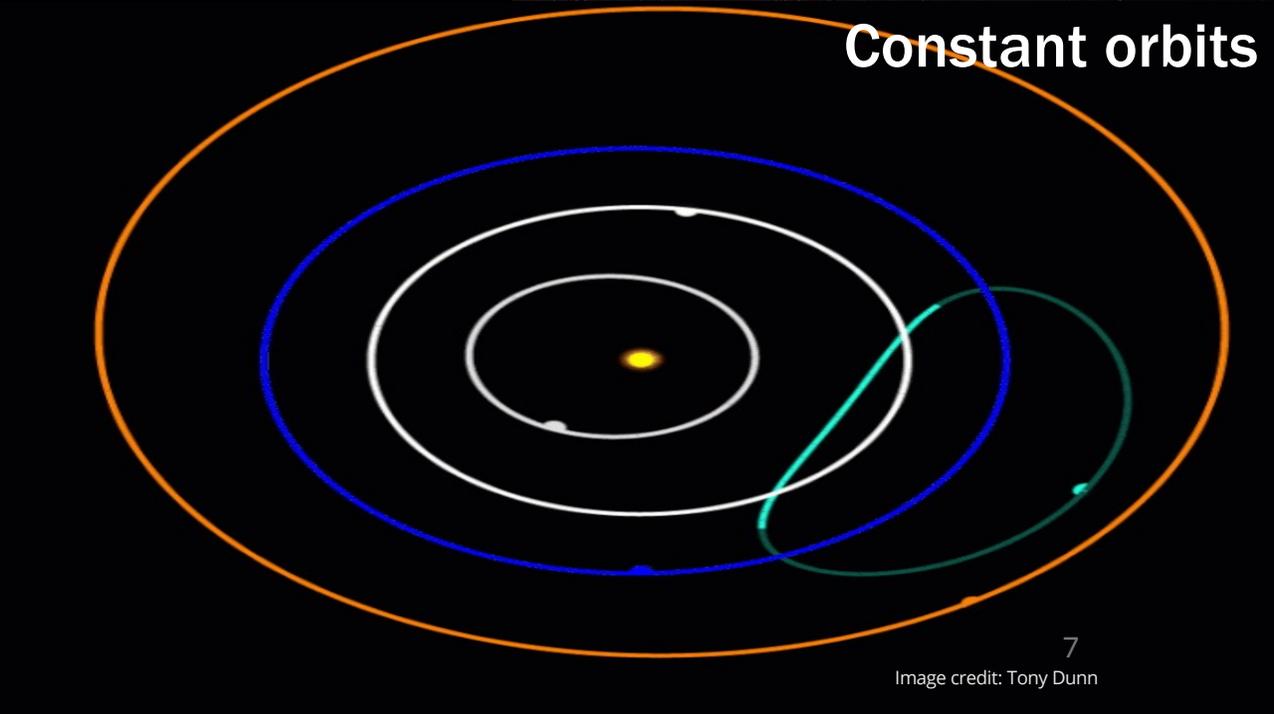


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Image credit: National Museum Scotland

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Constant orbits

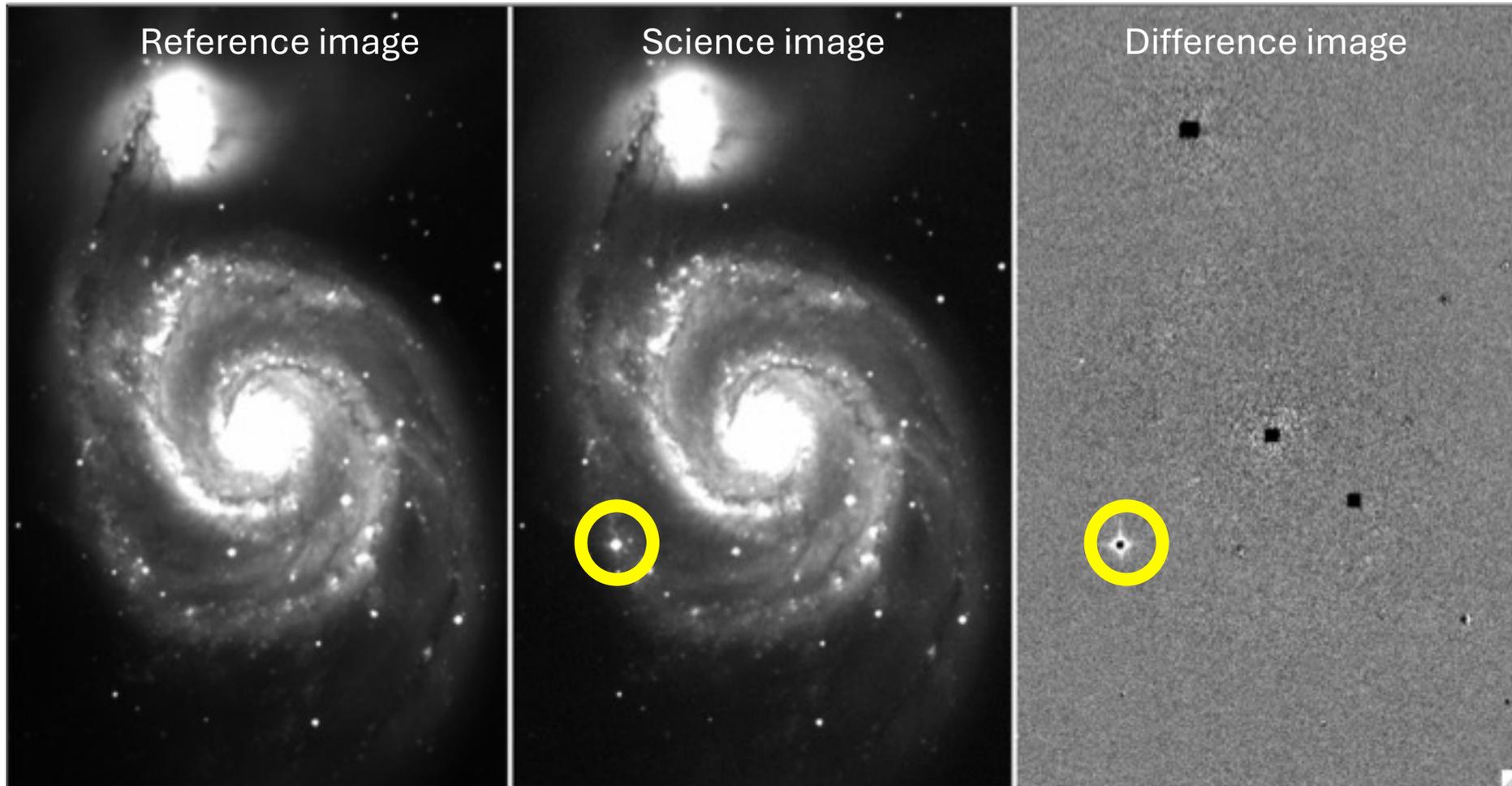


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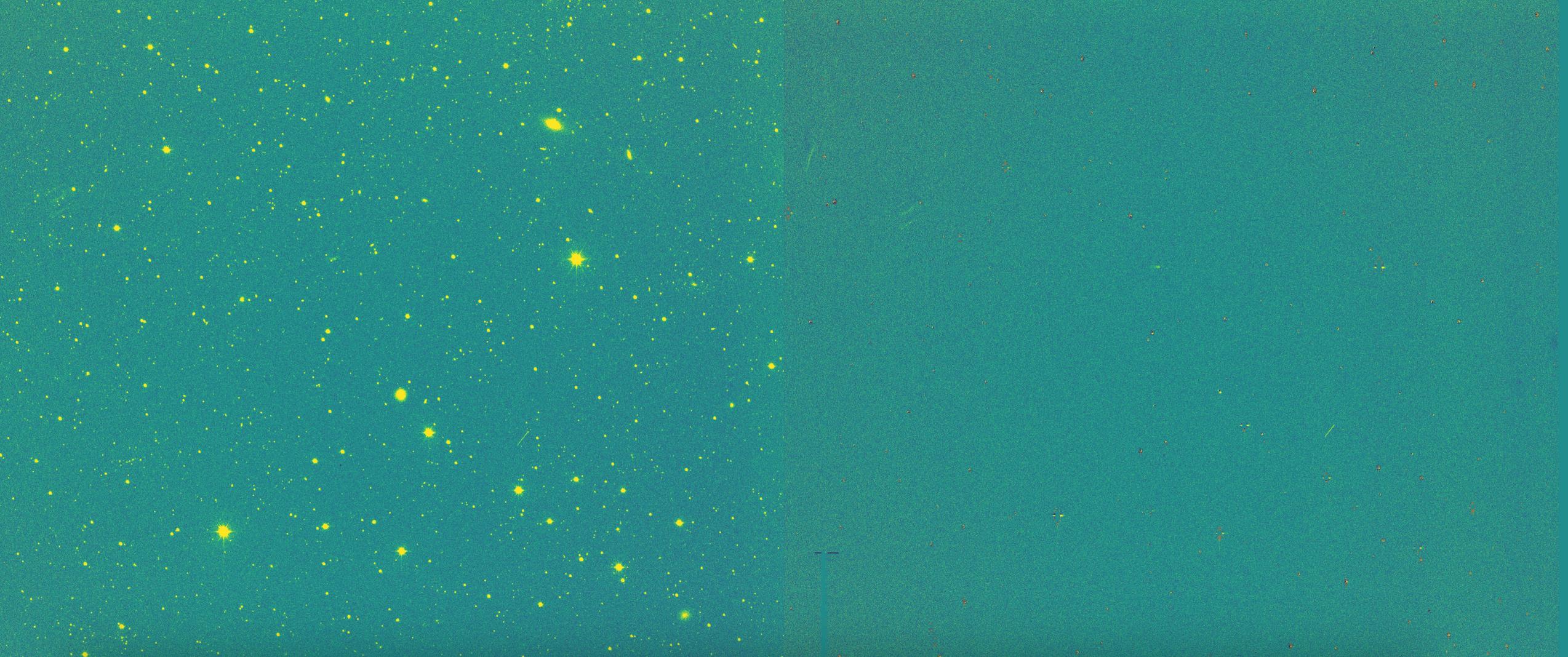
Image credit: Tony Dunn

Zwicky Transient Facility (ZTF)

- extremely large field of view (~47 square degrees)
- 30 s exposures
- difference images



Difference imaging in ZTF images, from Masci (2014).



Difference imaging

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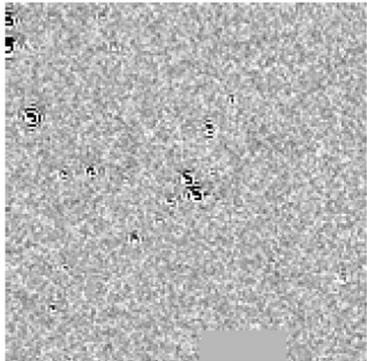
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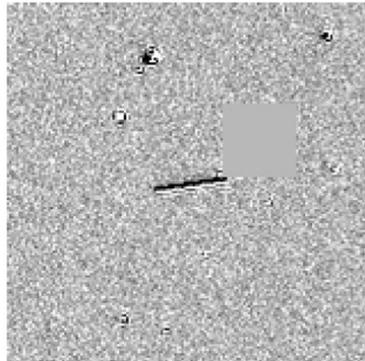
The work of the ZTF near-Earth object group

- More than 200 asteroids and comets discovered.
- The current pipeline consists of
 - an automated streak-detection algorithm ($\sim 10^5$ detections/night)
 - a machine-learning classifier
 - human scanners (≈ 10 detections/night)

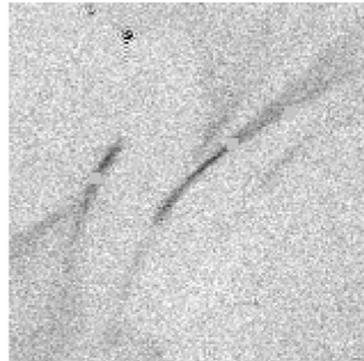
False detections in the current pipeline



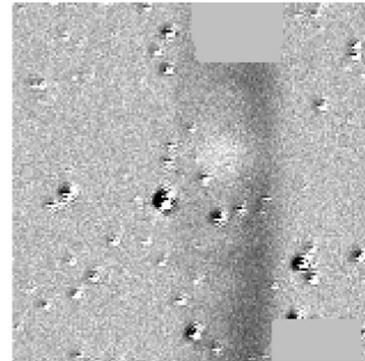
(a) Bad subtraction



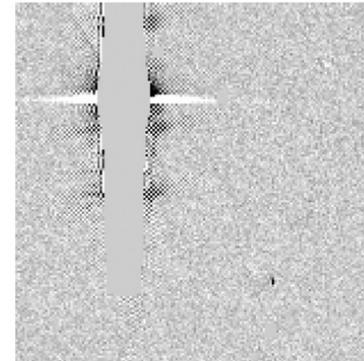
(b) Cosmic ray



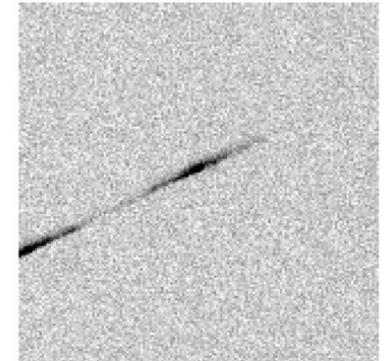
(c) "Dementor"



(d) "Ghost"



(e) Masked star



(f) Satellite trail

Examples of false detections, from Duev et al.

Motivation

Can we make a pipeline that can

1. Find everything that the current algorithms are finding, while
2. Decreasing the rate of false detections, and even
3. Detect additional objects?

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Image credit: Bill Ross

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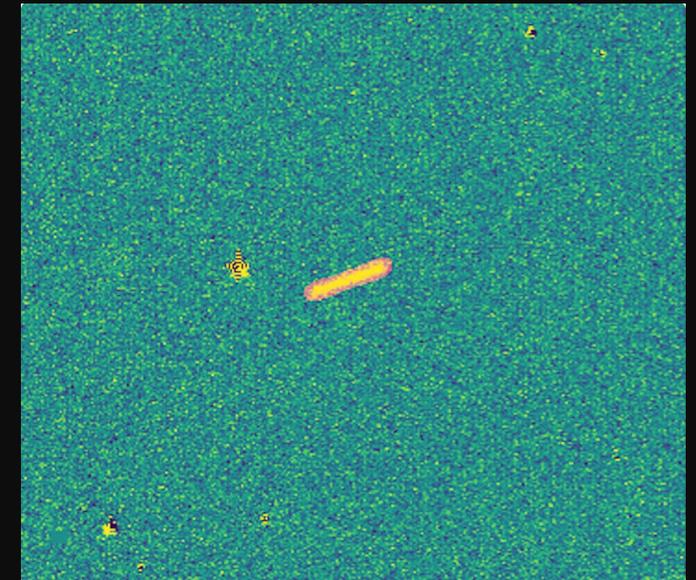
TOPO detection algorithm

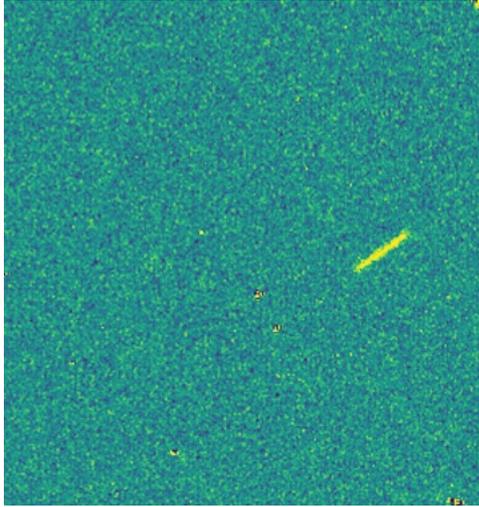
TOPO-Loss for continuity-preserving crack detection using deep learning (Pantoja-Rosero et al., 2022)

- convolutional neural network TernaNet (Iglovikov & Shvets, 2018)
- initially designed to identify cracks in buildings left by earthquakes
- re-trained for streak detection on astronomical images

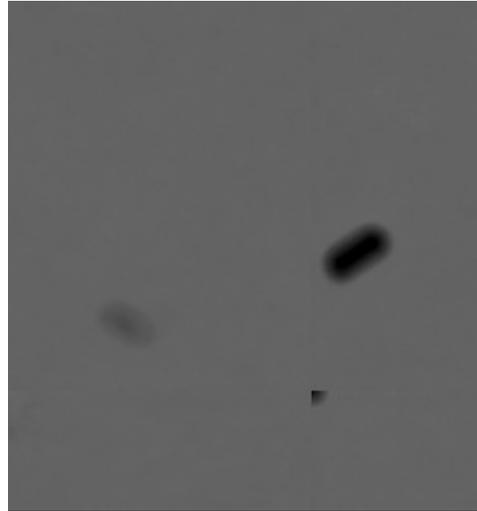


Example of earthquake crack detection, from Pantoja-Rosero et al., 2022

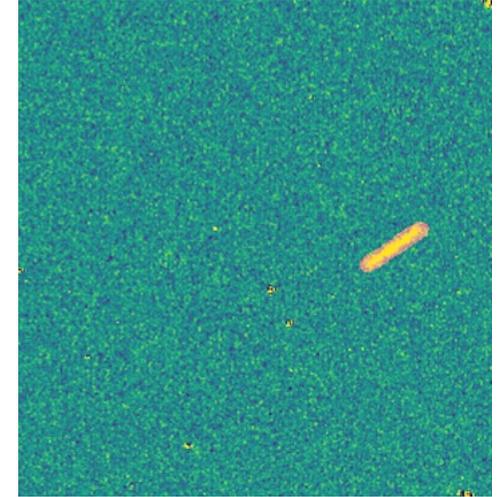




Original image



Detection heatmap



Overlaid detection

Input and output of TOPO

Algorithm training

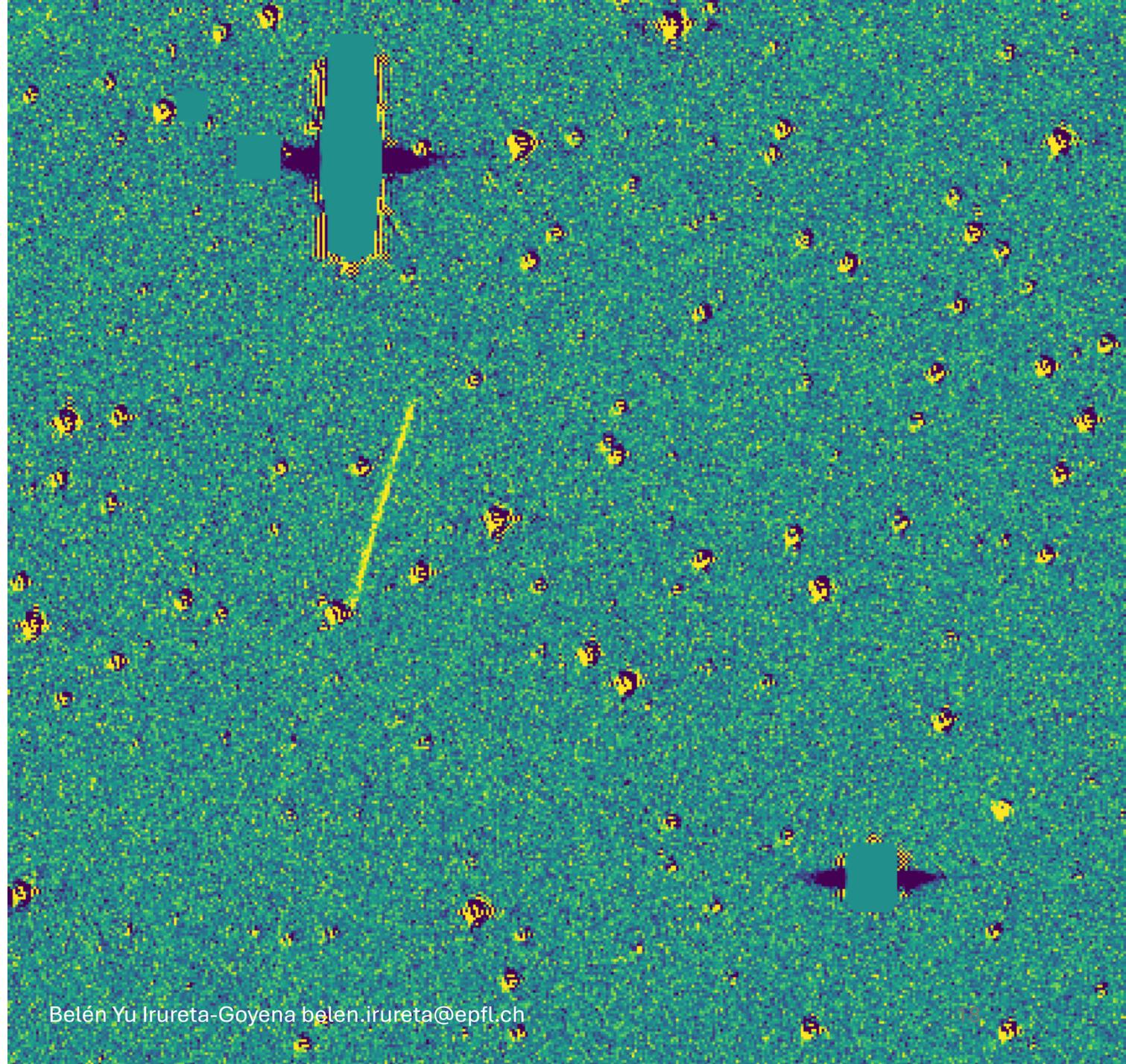
As a supervised-learning algorithm, TOPO was fed with 3 labelled datasets:

- real asteroids
- synthetic asteroids
- mix of both synthetic and real

Real asteroids

- 450 asteroids
- detected by the pipeline currently in operation
- confirmed by the Minor Planet Center

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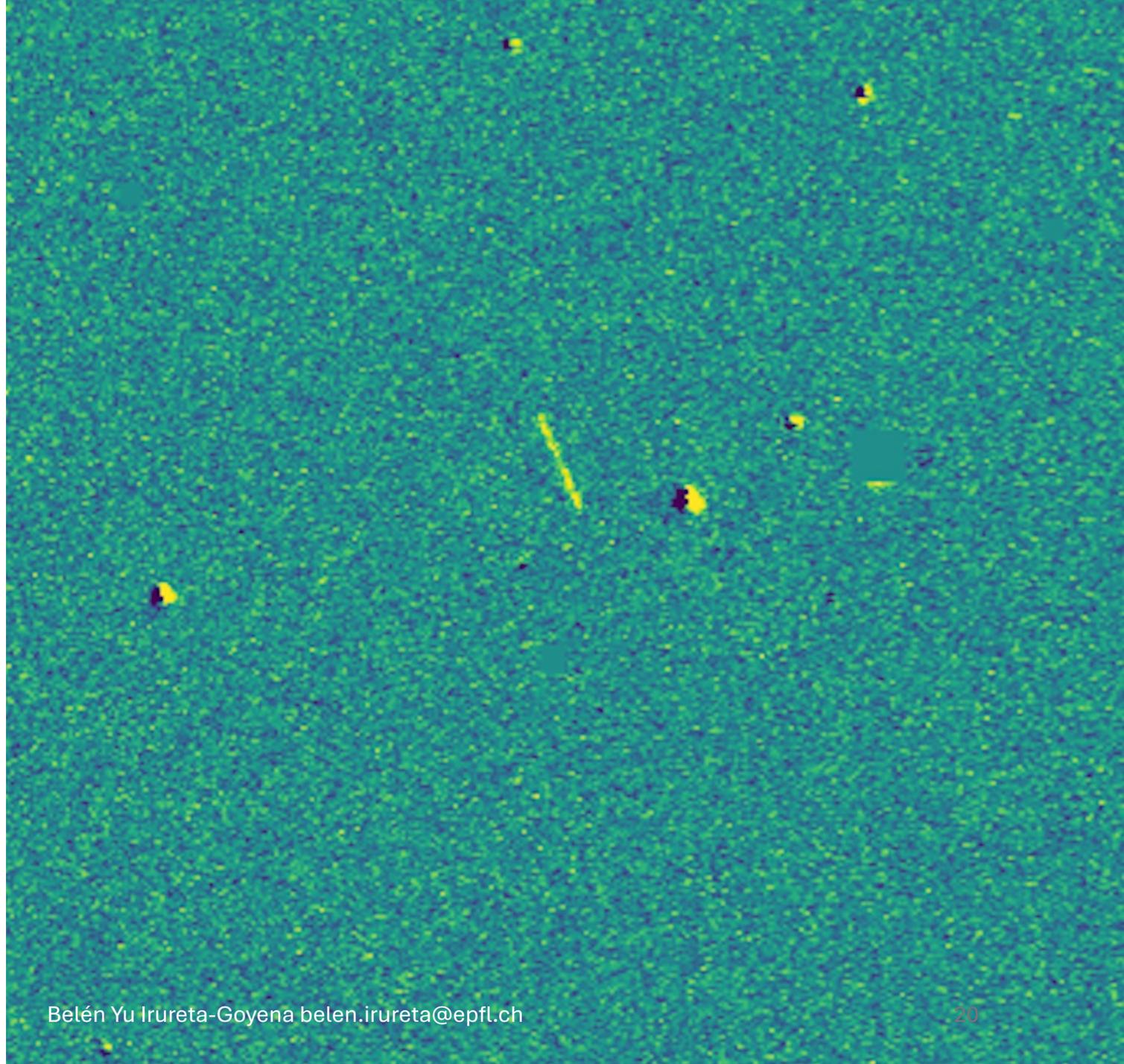
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Synthetic asteroids

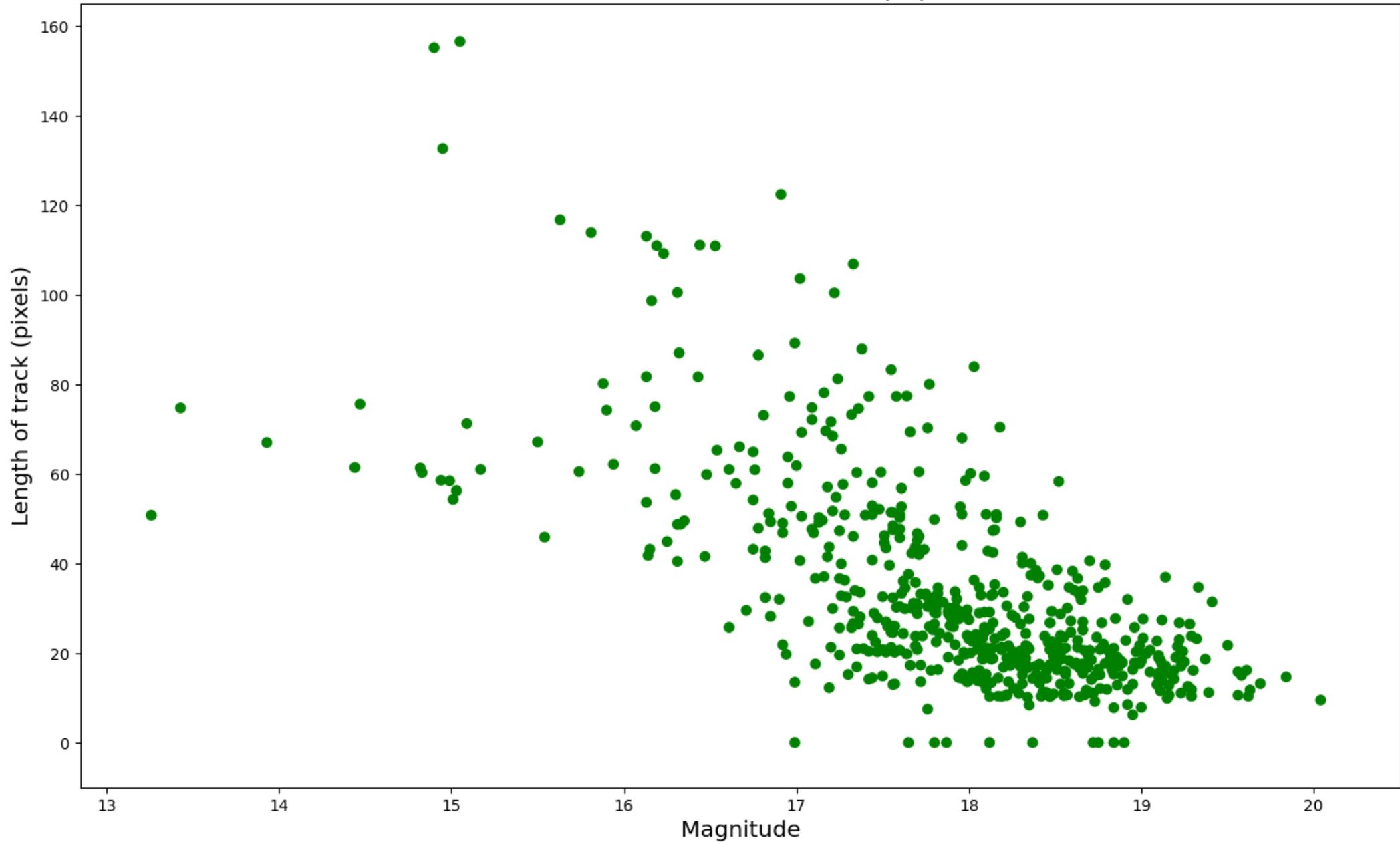
- We are not looking to reproduce the results of the current pipeline, but rather to complement it.
- By training with only detections of the current pipeline, we could be skewing our detections towards asteroids similar to those already found.
- Can we push the algorithm further by creating a new dataset?

Synthetic asteroids

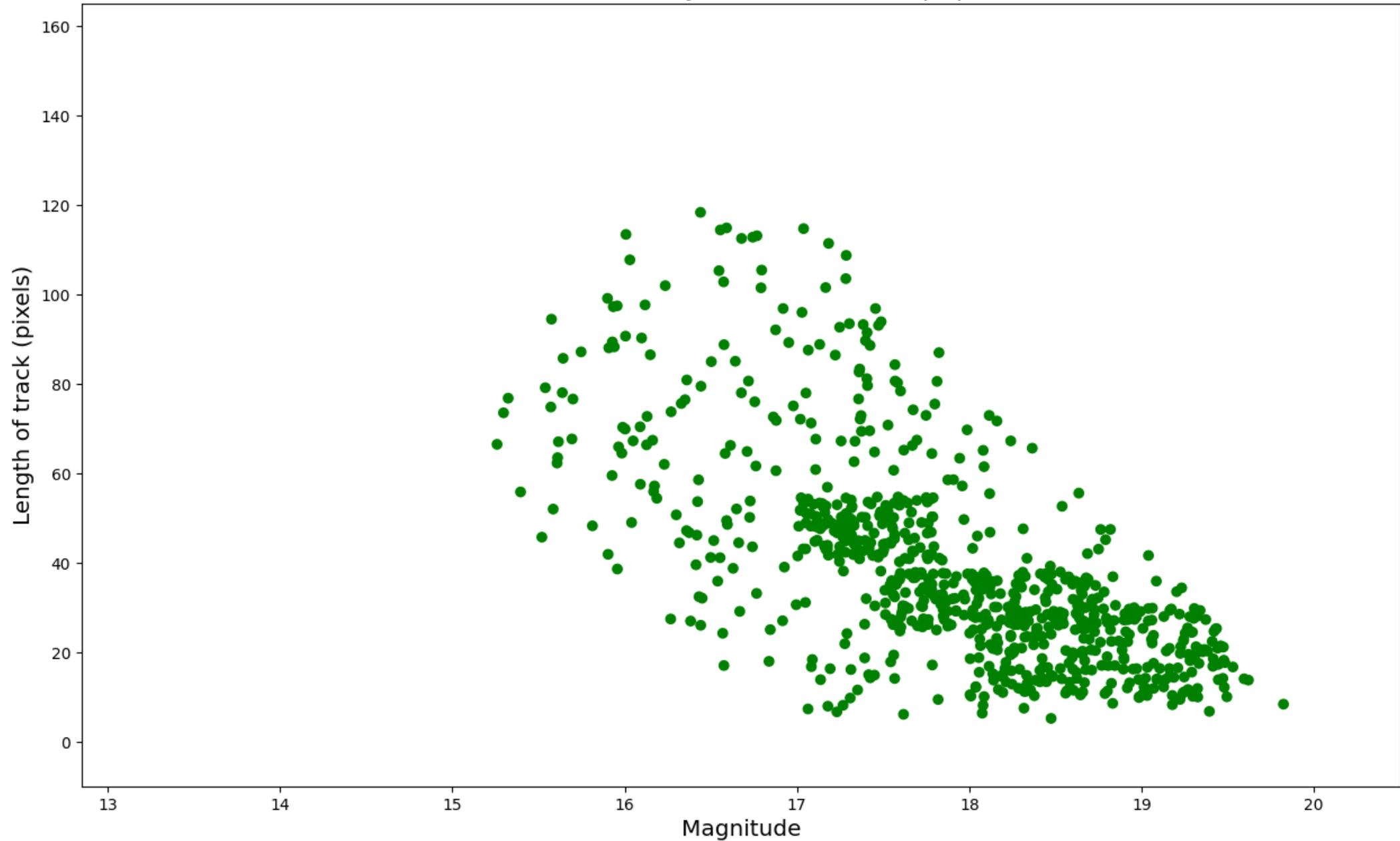
- 20 000 asteroids
- magnitude and track length follow that of real asteroids
- injected streaks convolved with the PSF of each frame



Distribution of the real asteroid population



Distribution of the synthetic asteroid population



Testing the performance of TOPO

- The three models — (1) trained with real streaks, (2) trained with synthetic streaks and (3) trained with the mix — were applied to a test set.
- The test set comprised 115 real asteroid images that had not been ‘seen’ before by the algorithm.
- These detections had been reported by the current ZTF pipeline.

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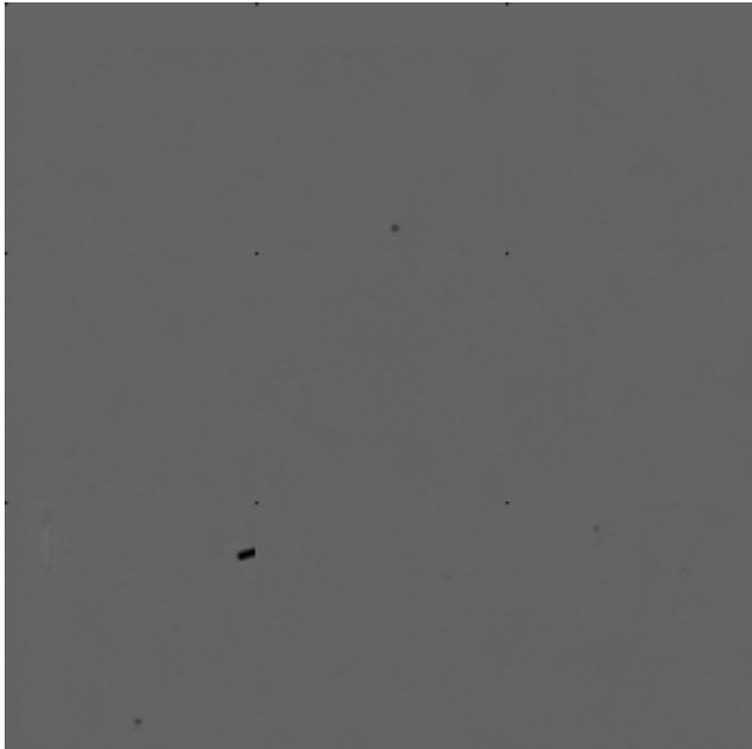
Image credit: Bill Ross

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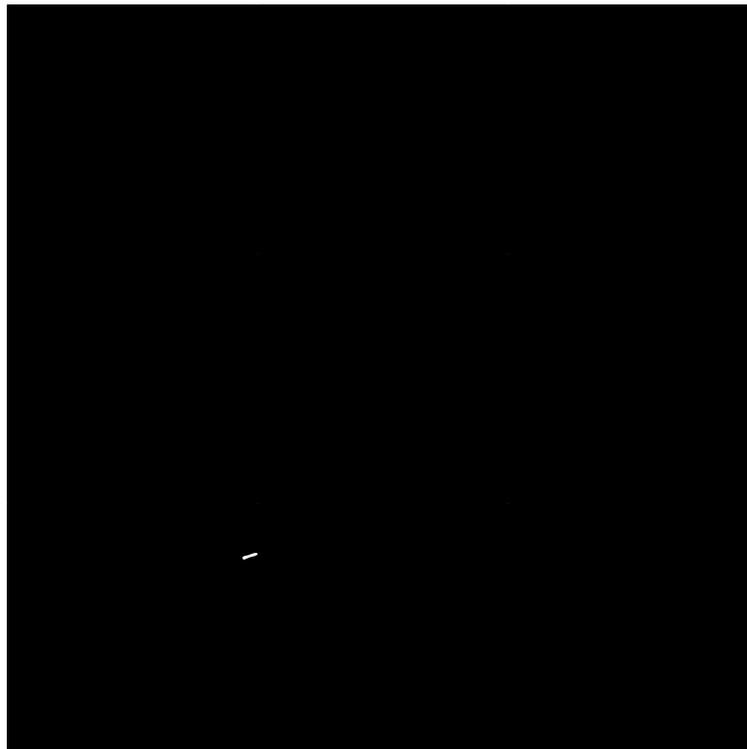


Detection thresholding

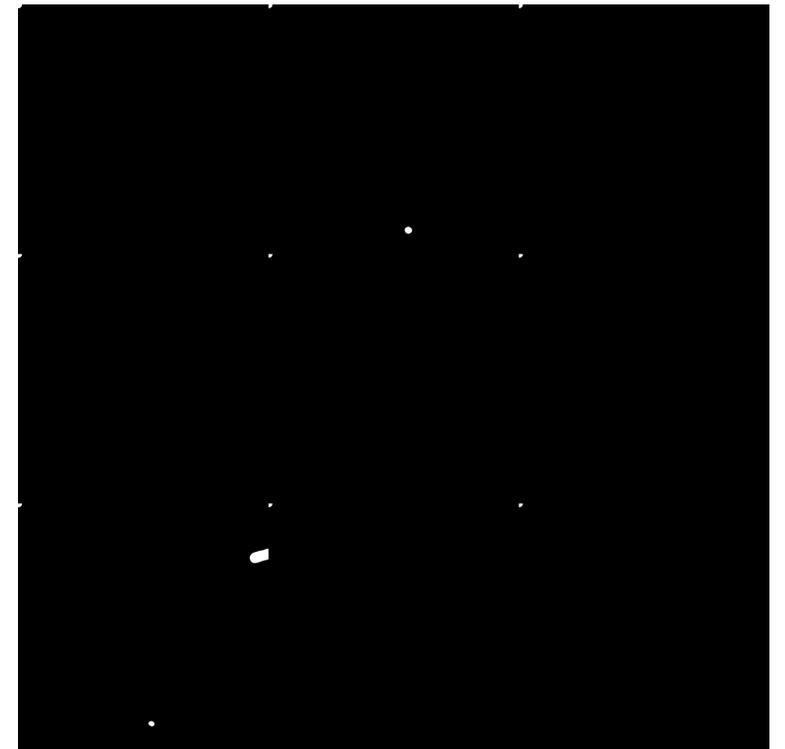
Detection heatmap

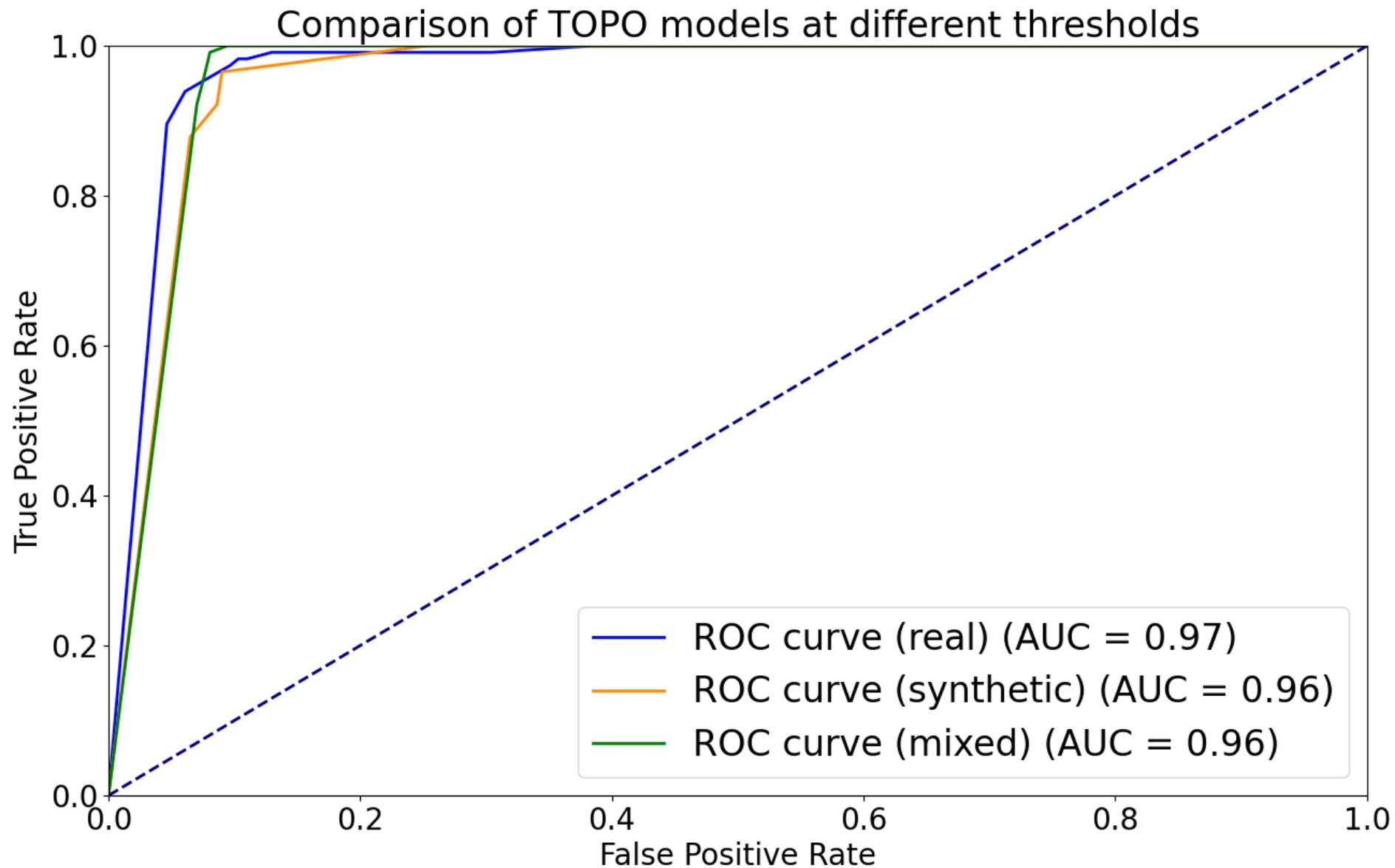


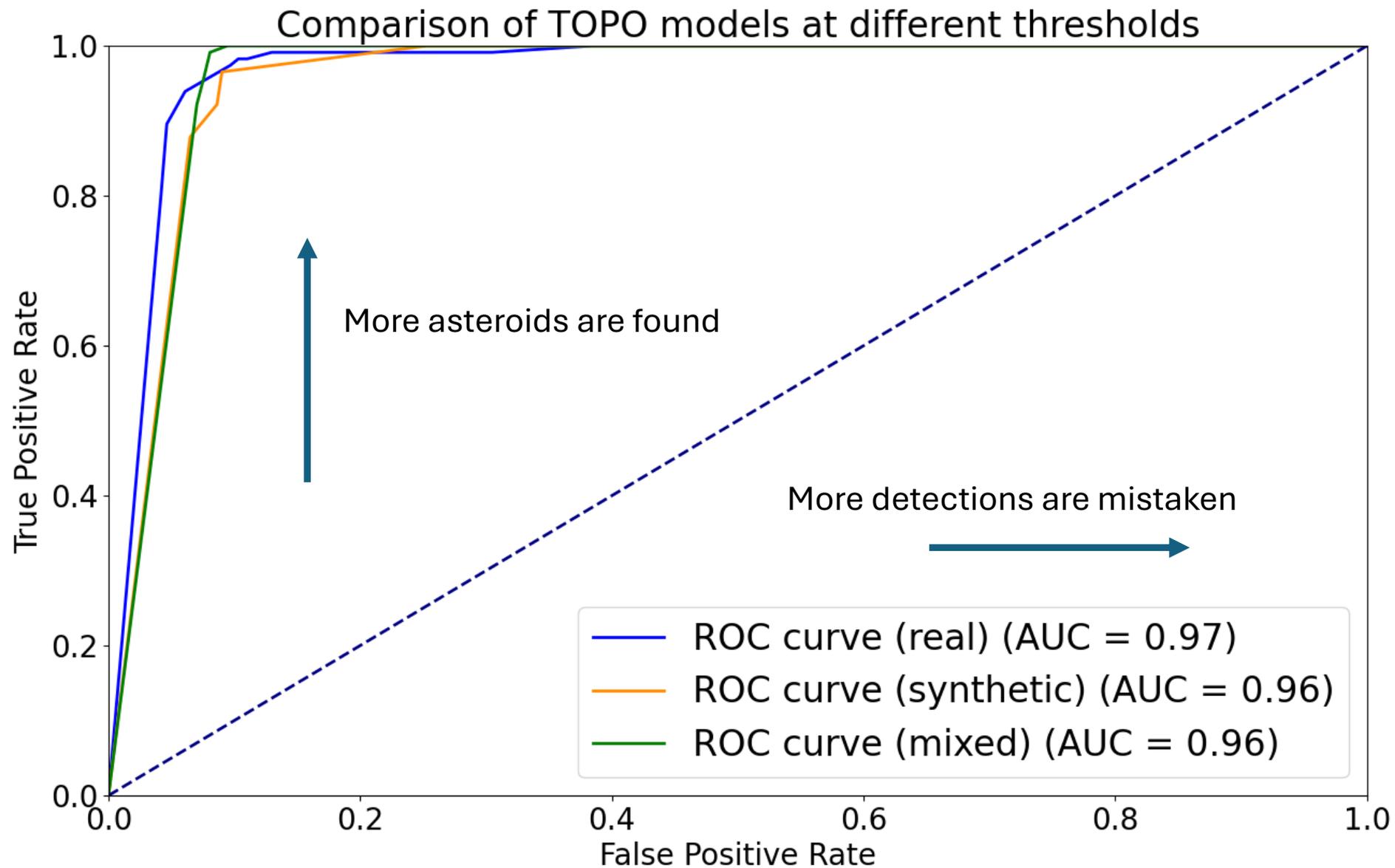
Threshold 1



Threshold 2

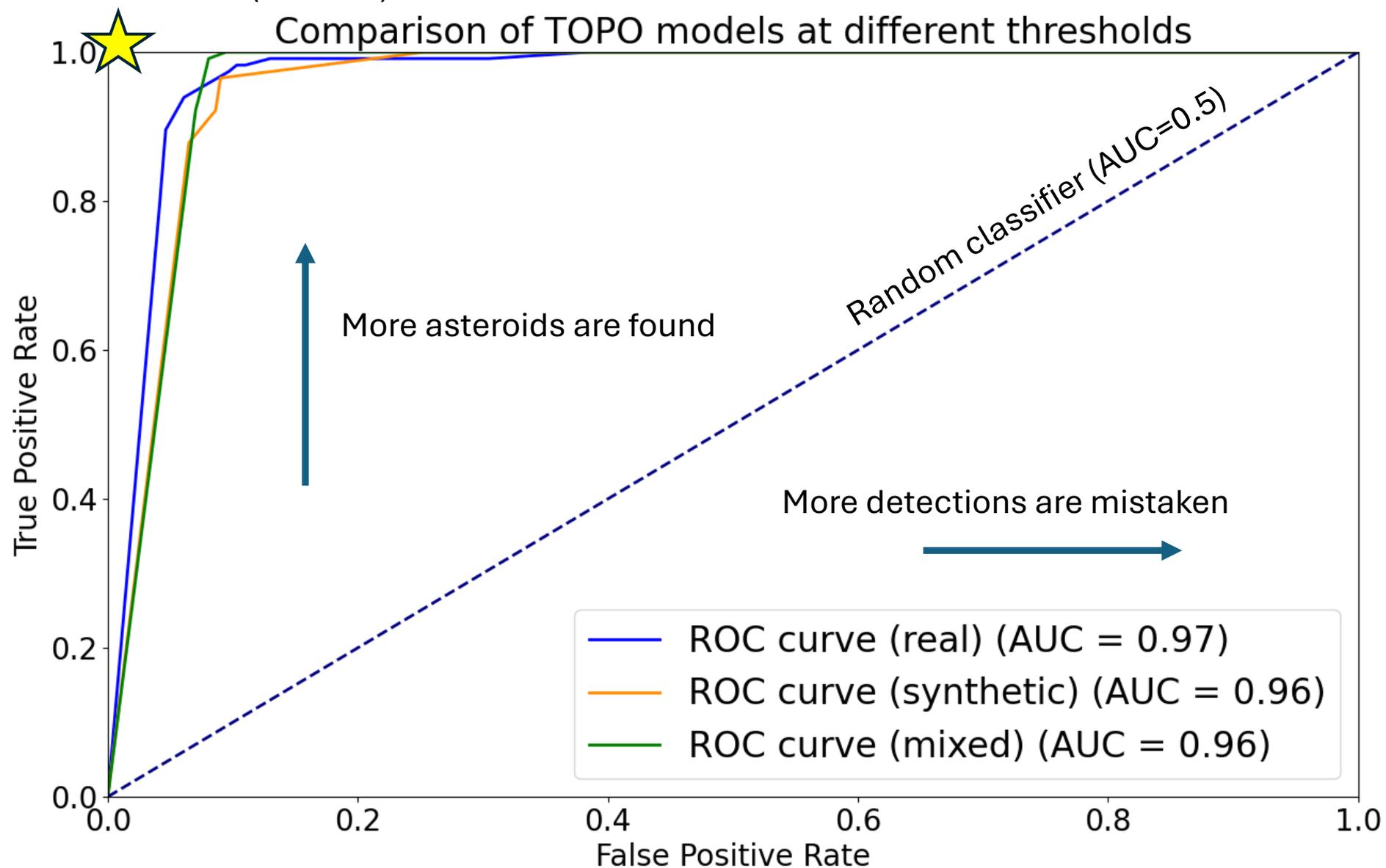




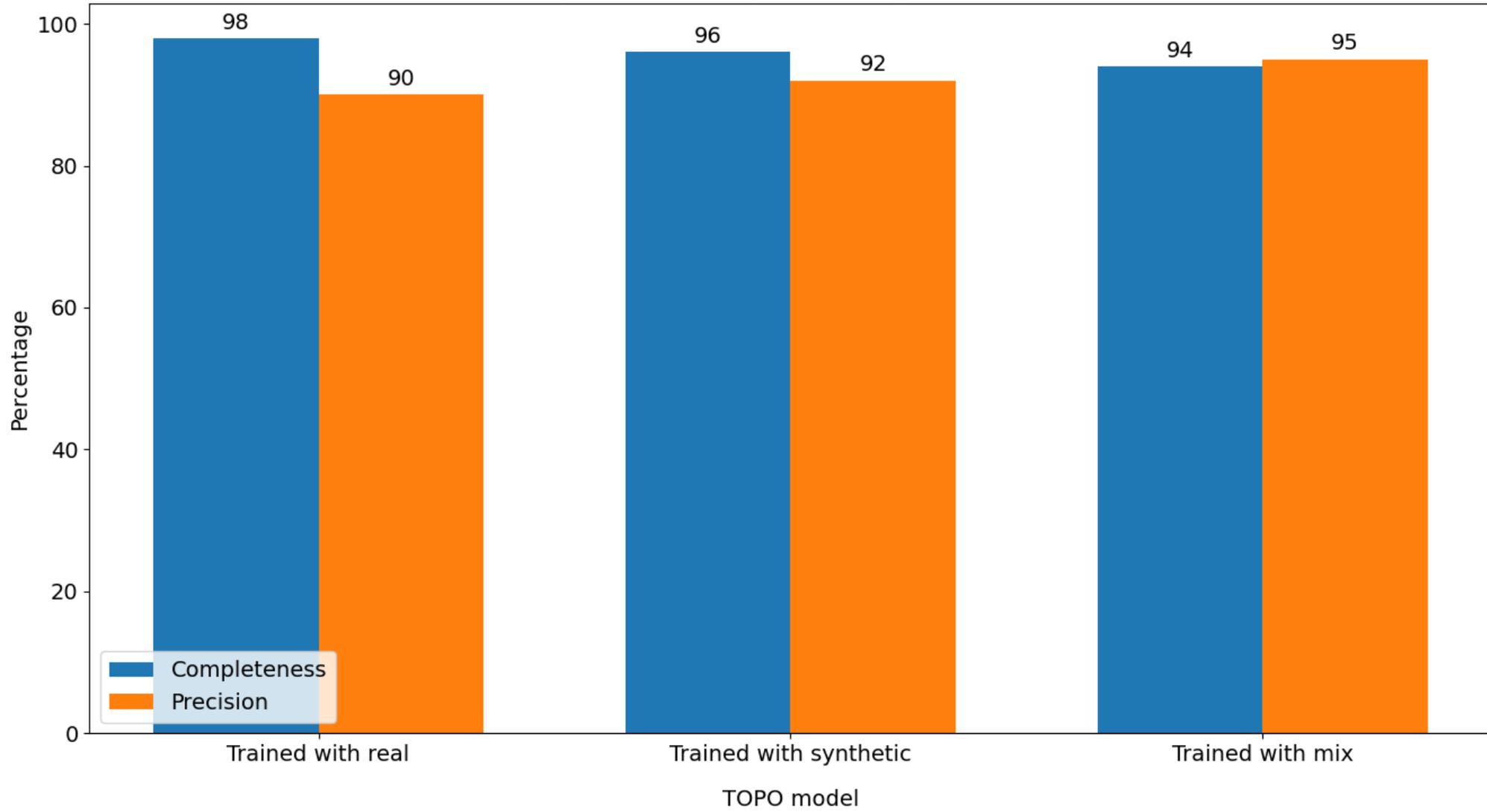


Perfect classifier (AUC = 1)

Comparison of TOPO models at different thresholds

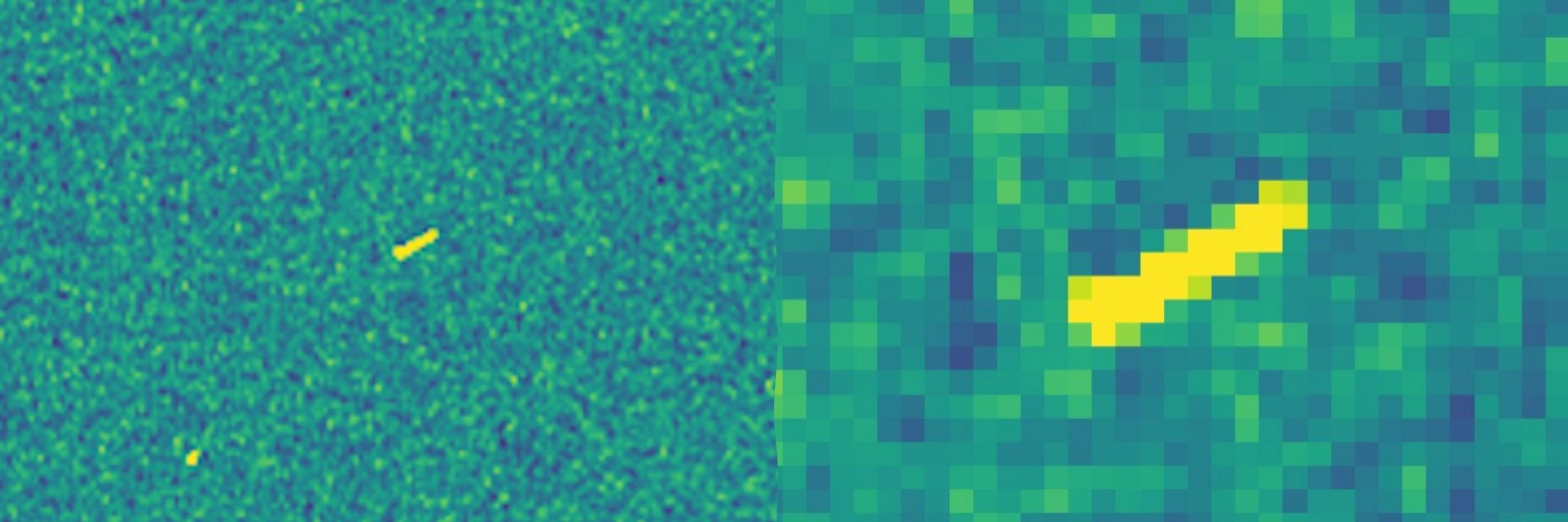


Completeness and precision by TOPO model



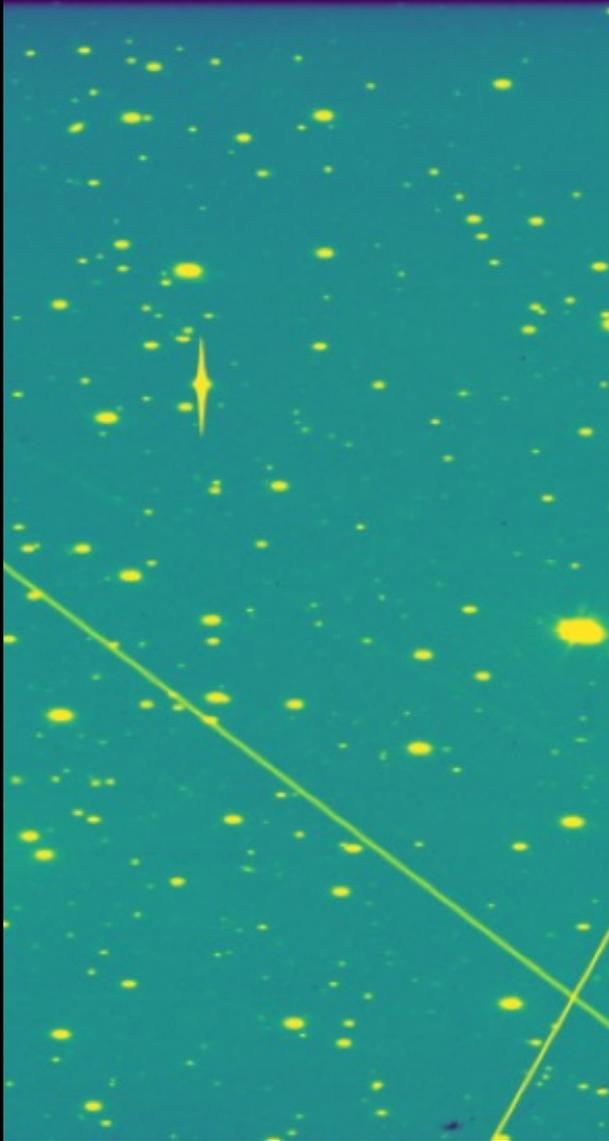
Which model performed best?

- The model trained only with synthetic asteroids performed as well when finding real asteroids as the model trained with real asteroids.
- This implies that the synthetic asteroids are realistic and can be used to enlarge the training set, which is currently small.



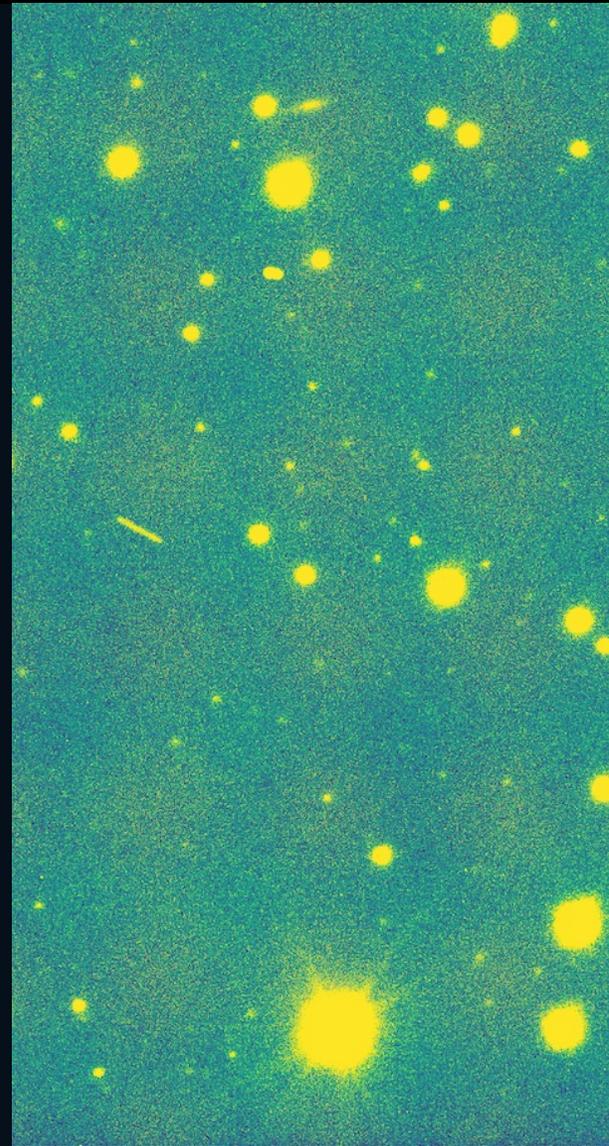
Were there any
new candidates
found?

- In addition to the known asteroids in the images, some potential object candidates were found.
- A larger test set needed to determine whether adding the synthetic asteroids leads to finding new objects.



Satellites and space debris

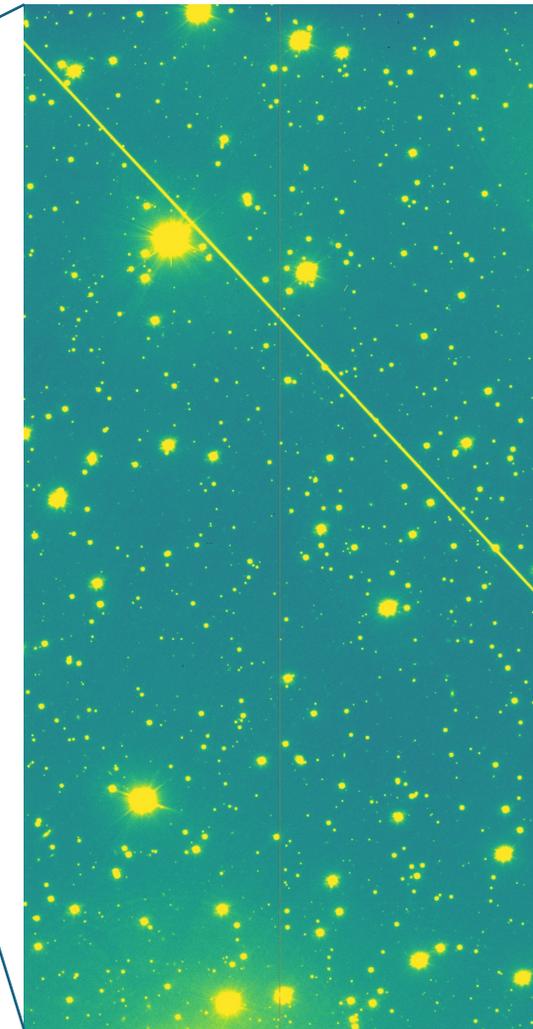
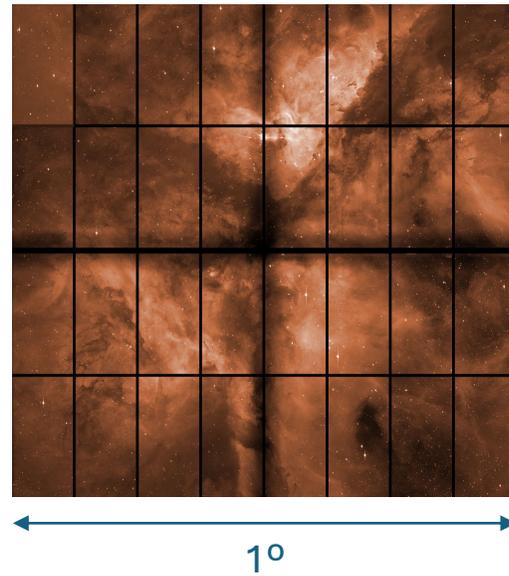
- moving faster (up to 0.5 deg/s)
- long tracks (cross the whole field)



Asteroids and comets

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Detecting satellites and space debris



OmegaCAM *ESO VLT Survey Telescope*

- 2.6 m telescope on Cerro Paranal

Detecting satellites and space debris

- Based on **HT-LCNN** by Lin *et al.* (2020).
 - OmegaCAM dataset of 6176 individual images.
 - Manual annotation of streaks and addition of artificial ones.
- 97.4% average precision on the validation dataset (594 images).

Ground Truth	True Positives	False Positives	False Negatives
1221	1193	71	28

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Image credit: Bill Ross

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Outlook

- On the test set, the new algorithm has recovered as many asteroids as the current pipeline, with much higher precision than the first stage of the ZTF pipeline (line-detection algorithm).
- It should be applied to live data to ensure a fair comparison with the two subsequent stages of the pipeline (machine learning and human scanners).
- These tools could be applied to not only the ZTF data, but also to other wide-field surveys. So far, they have been successful on VST images (Irureta-Goyena, 2024, in prep.), and will be applied to Euclid images.

Thanks!

- In case you have any further questions, please contact me at belen.irureta@epfl.ch.
- I will be graduating at the end of 2025 and looking for postdoc opportunities, please get in touch if interested!

