



# CMB lensing X Euclid Gaussian and Numerical covariances

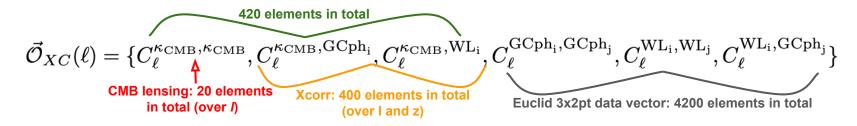
# Sandeep, Pauline, Matteo, Viviana, Melita, Louis, Giulio, Carlo, on behalf of the CMBX Covariance group

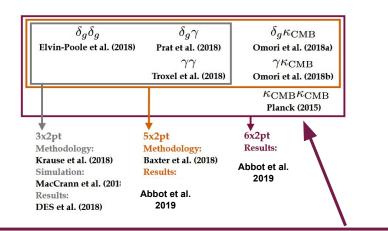
Oct 23 '23, Euclid XCMB SWG meeting, Milan



## **Baseline data vector**





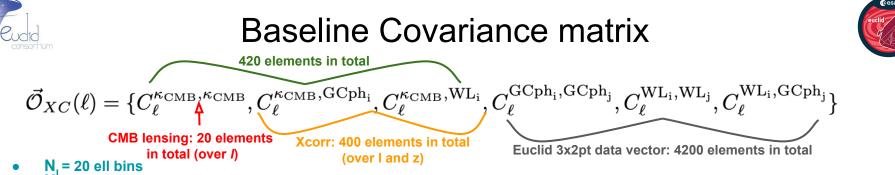


Similar to other works in the literature in CMBX we are neglecting XC with GC<sub>sp</sub>(if not: 10x2pt?? )

- N<sub>1</sub> = 20 ell bins
- N<sub>z</sub> = 10 redshift bins
- No correlation between different ells

Total data vector has 4620 elements

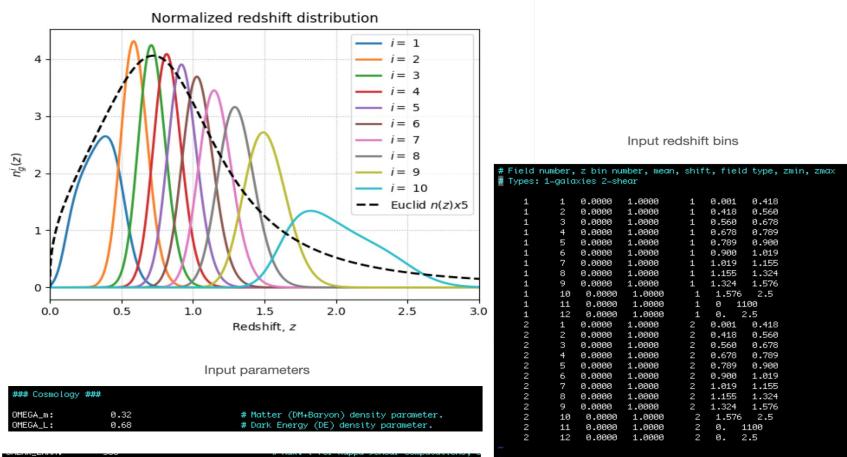
Binning in ell: [ 11, 15, 21, 29, 40, 55, 75, 102, 140, 191, 261, 356, 486, 663, 905, 1235, 1685, 2299, 3137, 4280]



- N<sup>1</sup> =10 redshift bins
- No correlation between different ells

	$C_{\ell}^{\kappa_{ ext{CMB}},\kappa_{ ext{CMB}}}$	$C_\ell^{\kappa_{ m CMB}, { m GCph}_{ m i}}$	$C_\ell^{\kappa_{ m CMB}, { m WL_j}}$	$C_\ell^{{ m GCph}_{ m i},{ m GCph}_{ m j}}$	$C_\ell^{\mathrm{WL_i,WL_j}}$	$C_\ell^{\mathrm{WL}_\mathrm{i},\mathrm{GCph}_\mathrm{j}}$
$C_{\ell}^{\kappa_{ ext{CMB}},\kappa_{ ext{CMB}}}$	Cov( <mark>kk, kk</mark> )	Cov( <mark>kk</mark> , k-GC <sub>i</sub> )	Cov( <mark>kk</mark> , k-WL <sub>j</sub> )	Cov( <mark>kk</mark> , GC <sub>i</sub> -GC <sub>j</sub> )	Cov( <mark>kk</mark> , WL <sub>i</sub> -WL <sub>j</sub> )	Cov( <mark>kk</mark> , WL <sub>i</sub> -GC <sub>j</sub> )
$C_\ell^{\kappa_{ ext{CMB}}, ext{GCph}_ ext{i}}$		Cov(k-GC <sub>j</sub> , k-GC <sub>i</sub> )	Cov( <mark>k-GC</mark> , k-WL <sub>j</sub> )	Cov( <mark>k-GC</mark> ,GC <sub>j</sub> -GC <sub>k</sub> )	Cov( <mark>k-GC</mark> ,,WL <sub>j</sub> -WL <sub>k</sub> )	Cov( <mark>k-GC</mark> ,,WL <sub>j</sub> -GC <sub>k</sub> )
$C_\ell^{\kappa_{ m CMB}, { m WL_j}}$			Cov(k-WL <sub>i</sub> , k-WL <sub>j</sub> )	Cov(k-WL <sub>i</sub> , GC <sub>i</sub> -GC <sub>j</sub> )	Cov(k-WL <sub>i</sub> , WL <sub>i</sub> -WL <sub>j</sub> )	Cov(k-WL <sub>i</sub> , WL <sub>i</sub> -GC <sub>j</sub> )
$C_\ell^{\mathrm{GCph_i},\mathrm{GCph_j}}$				EUCLID 3X2pt COVARIANCE MATRIX		
$C_\ell^{\mathrm{WL_i,WL_j}}$	$Cov(\!AB,A'B') = \frac{\delta^{\mathrm{K}}_{\ell\ell'}}{(2\ell+1)} \left[ \Delta C^{AA'}_{ik}(\ell) \Delta C^{BB'}_{jl}(\ell') + \Delta C^{AB'}_{im}(\ell) \Delta C^{BA'}_{jk}(\ell') \right]$			[N <sub>1</sub> N <sub>z</sub> (2N <sub>z</sub> +1)] X [N <sub>1</sub> N <sub>z</sub> (2N <sub>z</sub> +1)]		
$C_\ell^{\mathrm{WL}_\mathrm{i},\mathrm{GCph}_\mathrm{j}}$	$\Delta C_{ij}^{AB}(\ell) = \frac{1}{\sqrt{f_{\rm sky}\Delta\ell}} \left[ C_{ij}^{AB}(\ell) + N_{ij}^{AB}(\ell) \right]$			4200 X 4200		

10 Euclid redshift bins + 1 CMB lensing bin



512

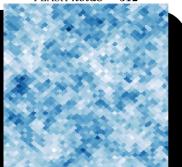
NSIDE:

# Healpix Nside (Npixels = 12\*Nside^2).

FLASK nside = 512

#### **Covariance maps**

- 2500 maps + Cl's auto and cross
- nsdide = 512
- Imax=1500
- DEMNUNi cosmology

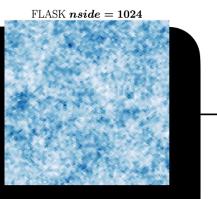


## Gaussian covariance comparison

Binning in ell: [ 11, 15, 21, 29, 40, 55, 75, 102, 140, 191, 261, 356, 486, 663, 905, 1235, 1685, 2299, 3137, 4280]

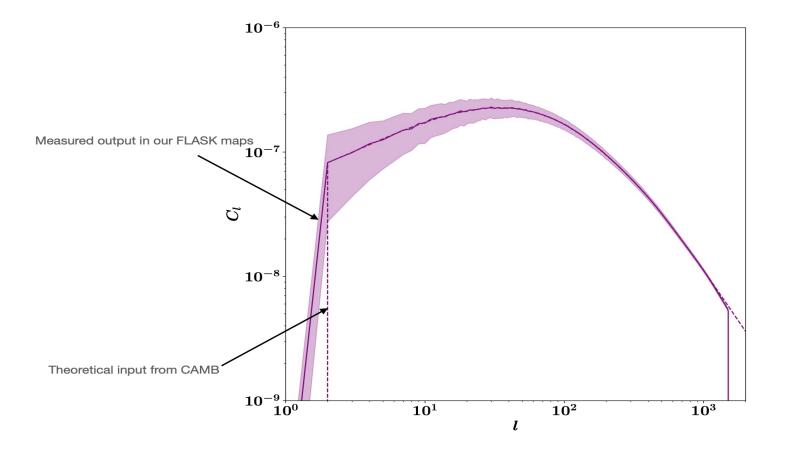
#### Map validation

- 40 maps + Cl's auto and cross
- nsdide = 1024
- Imax=3000
- DEMNUni cosmology



#### DEMNUni comparison

#### Cl\_kk



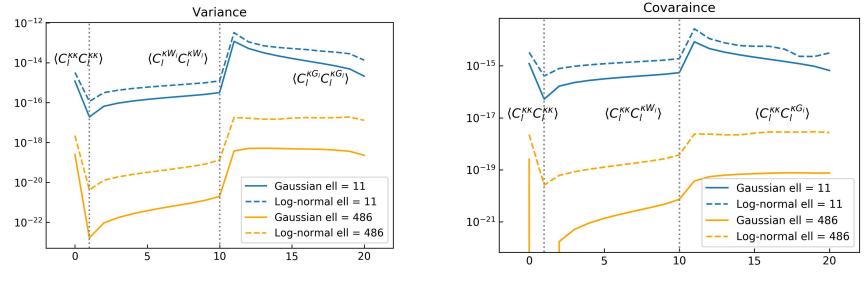


## Log-normal vs Gaussian comparison



#### Variance and Covariances

Recap



Fsky = 1.0

Using the old Flask maps without magnification bias and intrinsic alignment.

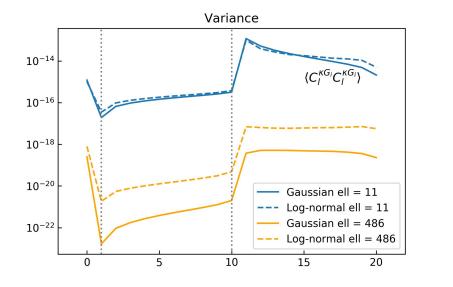


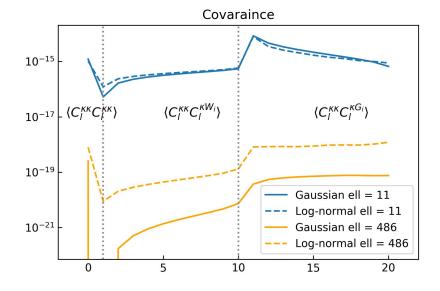
## Log-normal vs Gaussian comparison



#### Variance and Covariances

Recap

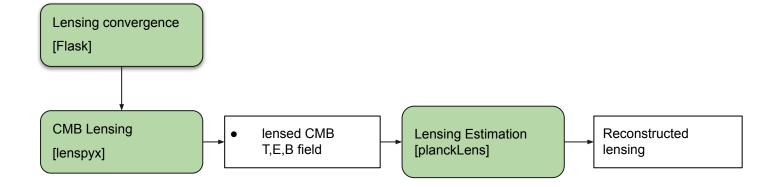




Fsky = 0.36, Nside = 512, Nsims = 2500

### Simulating the CMB observables - Old pipeline

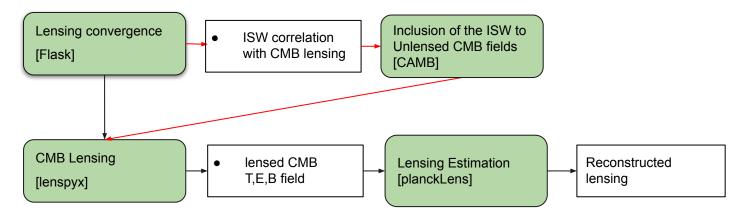
• Simulate lensed CMB observables using the Flask generated lensing potential

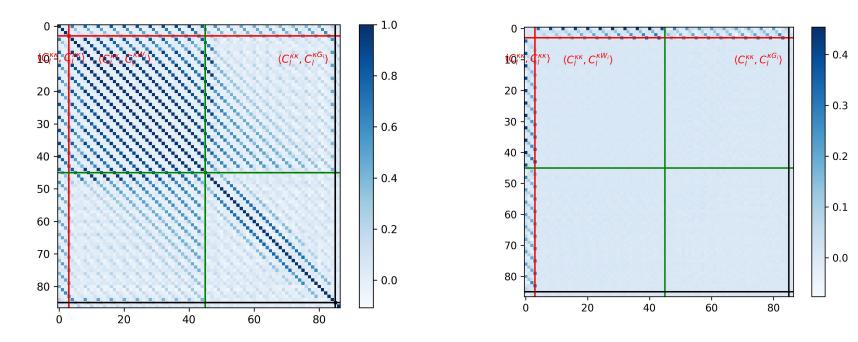


### Update to the covariance pipeline - New pipeline

• Simulate lensed CMB observables using the Flask generated lensing potential

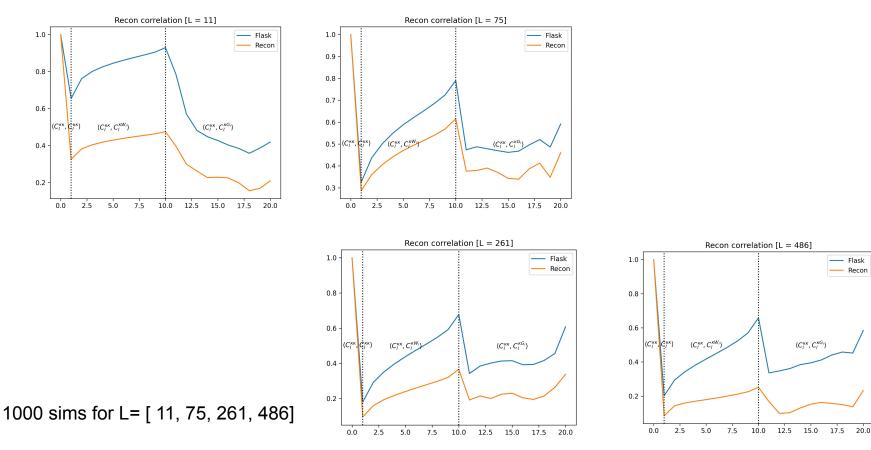
Updated implementation - To include correlated ISW signal



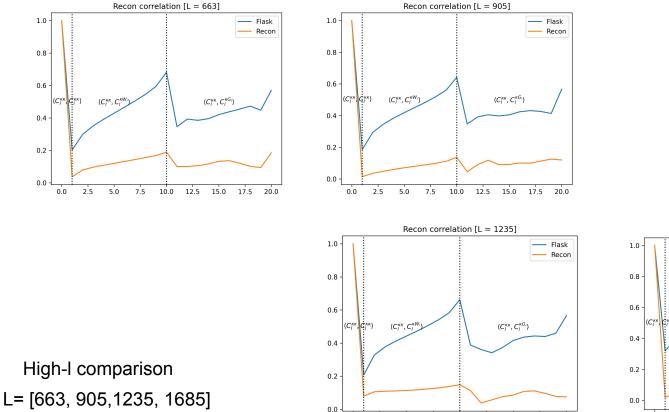


**Reconstructed correlation** 

Recon - Flask



2

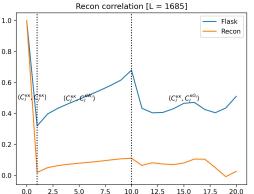


0.0 2.5 5.0

7.5

10.0 12.5

15.0 17.5 20.0



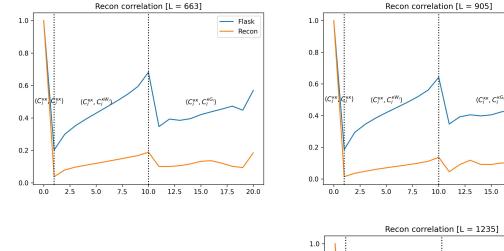
3

- Flask

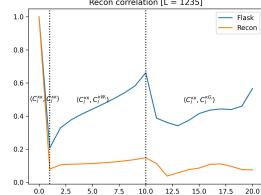
17.5 200

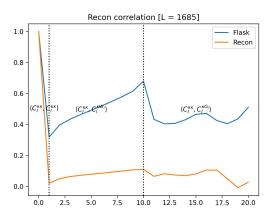
 $\langle C_l^{\kappa\kappa}, C_l^{\kappa G_i} \rangle$ 

Recon



Should be validated against the updated Flask sims





4

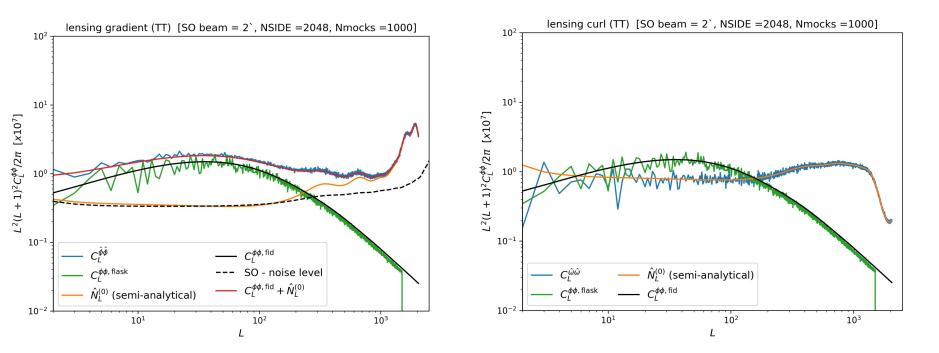
High-I comparison L= [663, 905,1235, 1685]

## UPDATES/On-going - 23/10/2023

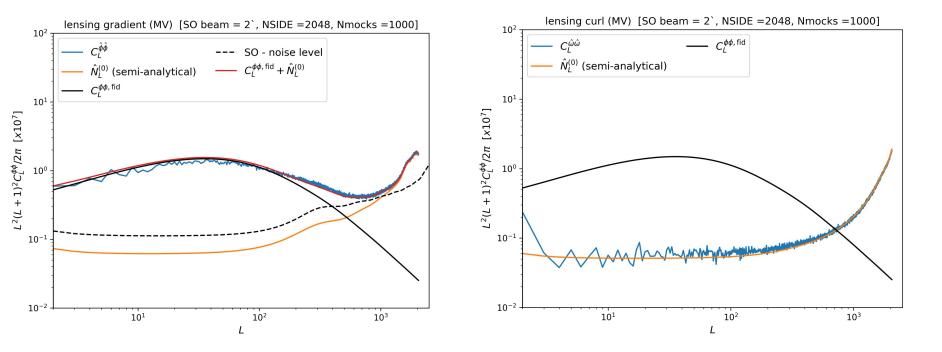
- Modifications to the Flask simulations
  - Validating the higher order statistics discrepancy In progress
- Implementation of ISW- cross- correlation Done
  - To be integrated to the pipeline
- Final numerical covariance
  - Pipeline using TT estimator Done
  - Pipeline extending to MV In progress
  - To implement against the new updated flask simulations To-do

- Definitely some more validations to do !!

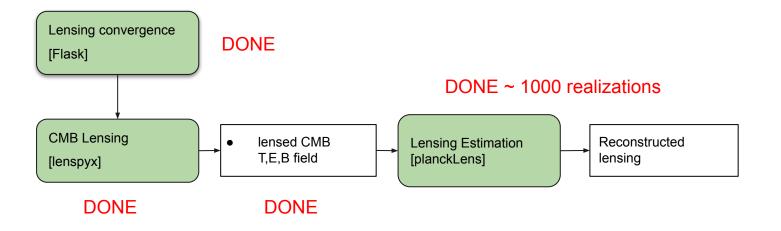
#### Lensing reconstruction using `plancklens' - TT



#### Lensing reconstruction using `plancklens' - MV



## Simulating the CMB observables



- To verify the MV estimator
- Complete with ~2500 realizations
- A few validations to perform !!
- Compute the covariance matrix