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RAMSES GPU

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ICSC Italian Research Center on High-Performance Computing, Big Data and Quantum Computing

Missione 4 • Istruzione e Ricerca









Scientific Rationale

In modern astrophysics, hydrodynamical *N*-body simulations are powerful and versatile tools for **testing theories of galaxy formation and evolution.**

To understand the physical processes involved, simulations with **increasingly high spatial resolution** are required, leading to a dramatic **escalation of computational**.

Solution

Porting and optimization on GPU architecture of specific (time consuming) modules of N-body hydrodynamical codes to cut computational time

Application to (MINI)RAMSES:

RAMSES is an Eulerian code, specifically designed for cosmological simulations. It is written in Fortran90 and it exploits **AMR** (Adaptive mesh refinement), i.e. the spatial resolution is increased in regions where specific criteria are satisfied (e.g. mass density)









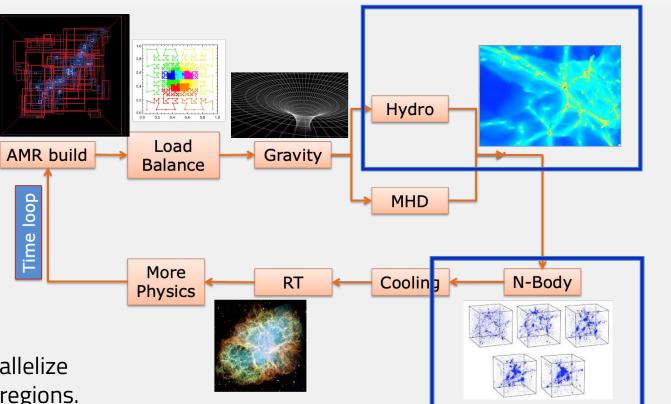
Technical Objectives

Performances enhancement and reduction of computational time: GPU porting of hydrodynamical and N-body modules (with an overall speeding factor >1?)

Methodologies

Profiling methods.

Utilize OpenACC-based directives to parallelize time-consuming loops and critical code regions. Apply optimization techniques such as memory management, kernel optimization, and reduction of communication between CPU and GPU











Timescale, Milestones and KPIs

Analysis and Preparation:

Investigation of MINIRAMSES to identify sections suitable for GPU parallelization - *partially done* (*hydro and Nbody*)

Initial Parallelization (Nbody and Hydro): >3 months (each)

- Identification of suitable modules to port on GPU (<u>partially done Profiling</u>)
- Porting of identified part on GPU based on specific libraries (OpenACC directives)

Testing (Nbody and Hydro): >4 months (each)

- Implementation and run of suitable tests (hydrodynamical sedevo3d test + cosmological simulation).
- Evaluation of initial performance and identification of any issues or bugs
- Optimization of the code on GPU to maximize performance

Integration (Nbody and Hydro):

- Integration in principal version of the code
- Execution of tests to evaluate scalability

Validation and verification of correcteness of results w.r.t. original version of the code.





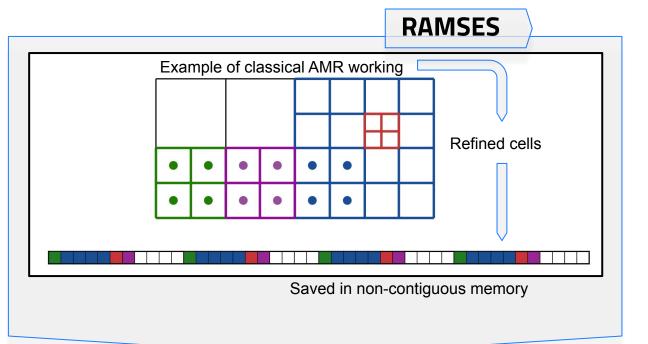




Project started during June 2023, taking advantage of the **hackathon event @ Cineca**

Focus on MINIRAMSES, abridged version of RAMSES.

Designed for GPU parallelization since minimized memory access







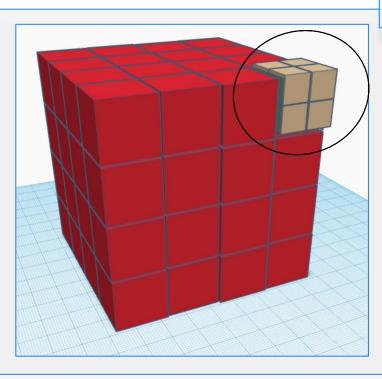




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MINIRAMSES

Super-ocs: groups of adiaject ocs saved in contiguous memory locations

Number of octs per super-octs: 8ⁿ

Designed for GPU parallelization









Project started during June 2023, taking advantage of the **hackathon event @ Cineca**

- Focus on MINIRAMSES, abridged version of RAMSES.
- Profiling of the code based on an hydrodynamical test (sedov 3d)
- Identification of time consuming modules (hydrodynamic solver)

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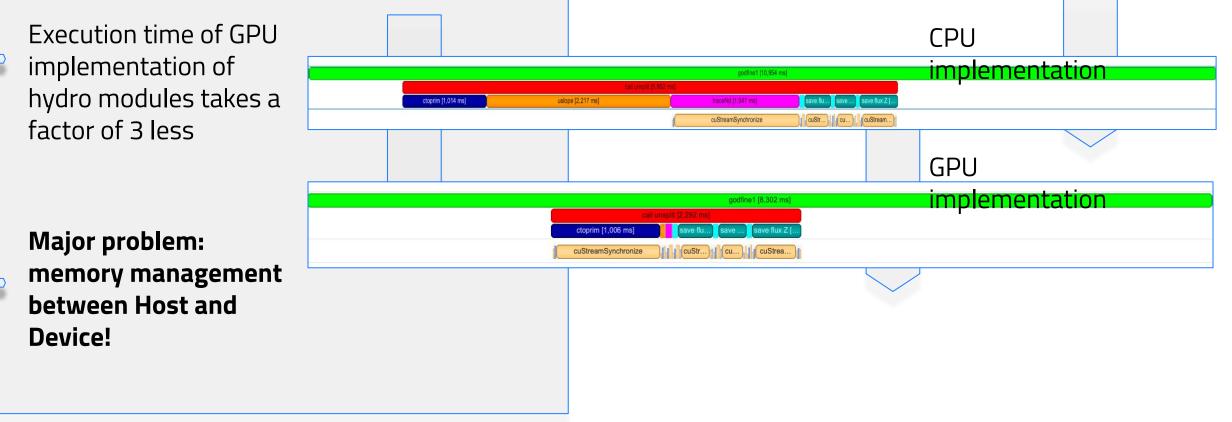
Sedov 3D with 1 task on 1 CPU (about 89 s of execution time)



















Next Steps and Expected Results (by next checkpoint: April 2024)

- Produce a partial documentation of the code.
- get GPU hours. ISCRA C proposal submitted to get GPU hours on Leonardo

Complete optimization of the hydrodynamical modules on GPU: better management of data movements. Change of paradigm: from unified memory to explicit data transfers.