



PLCs WITHIN ESO ELT FRAMEWORK

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INAF - Osservatorio Astronomico di Trieste

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SUMMARY

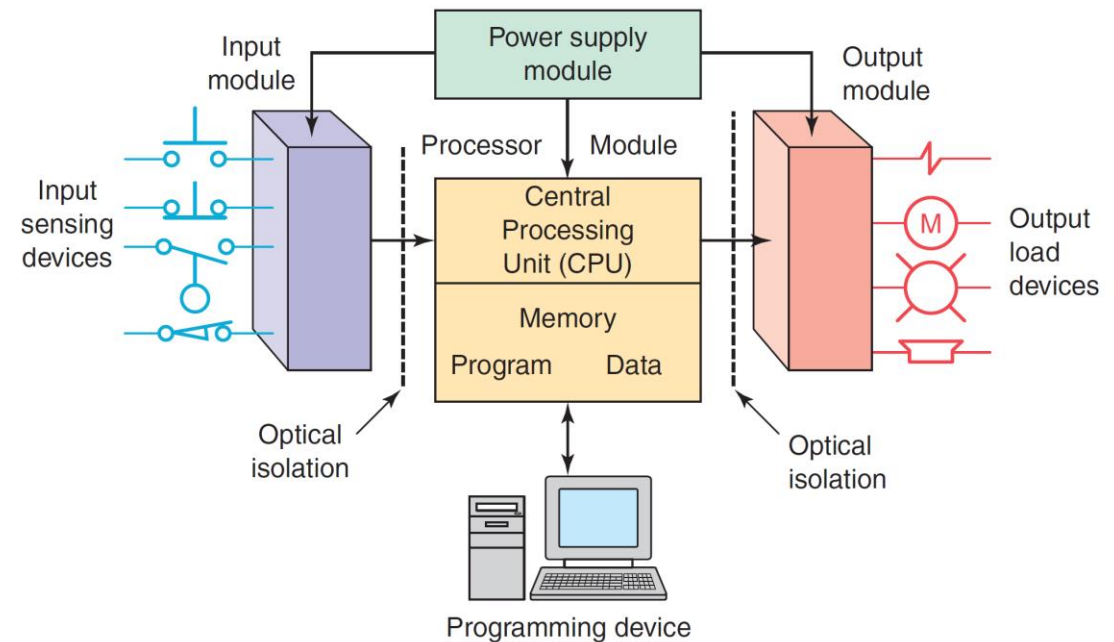
- Programmable logic controller
- The advantages of a PLC control system
- Beckhoff devices and tools
- PLCs at ESO

PROGRAMMABLE LOGIC CONTROLLER

- PLC is an autonomous device capable of controls physical outputs in reaction to physical inputs
- Parameters can be given externally - network, memory cards, HMI
- High level management and coordination of multiple devices
 - SCADA - Supervisory Control and Data Acquisition
 - Coordination of parameters and setup
 - Readout and modification of process data (Process Variables)
 - Remote commands (by means of Process Variables)
- Standardized communication protocol for data exchange
 - OPC-UA - is a cross-platform, vendor independent standard

PROGRAMMABLE LOGIC CONTROLLER

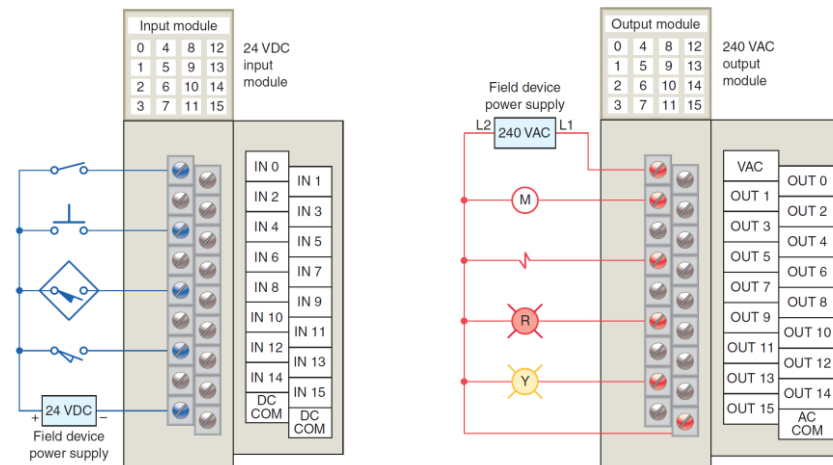
- Main components
 - Power supply
 - CPU
 - I/O modules
 - Communication
 - Human - Machine Interface
 - Programming device



PROGRAMMABLE LOGIC CONTROLLER

Digital I/O modules

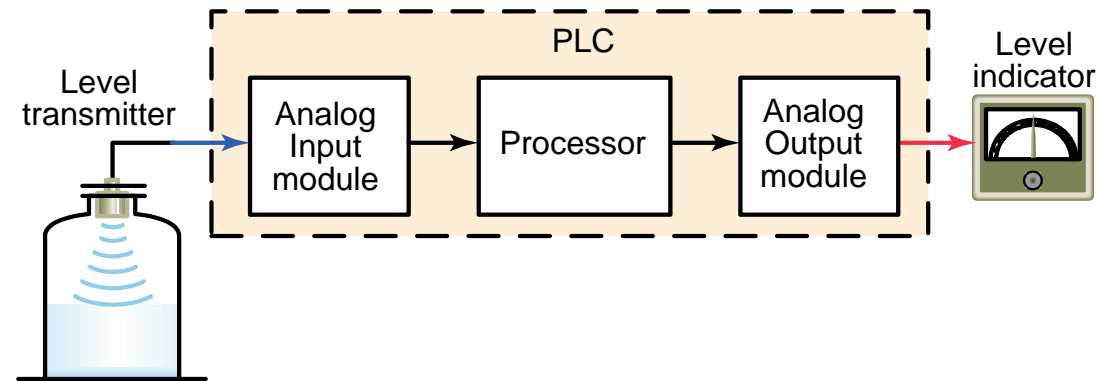
- Power isolated from control unit
- Reference levels 5V, 12V, 24V, 230V
- Digital Inputs
 - Pushbuttons, switches
 - Sensors (limit switches)
- Digital Outputs
 - Lamps
 - Actuators
 - Relays
 - Shutters



PROGRAMMABLE LOGIC CONTROLLER

Analog I/O modules

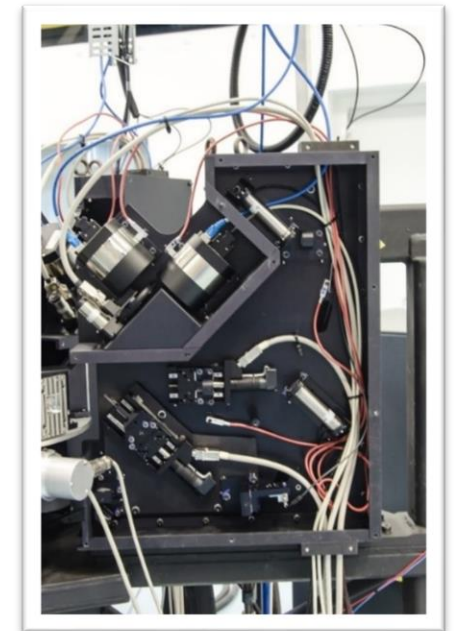
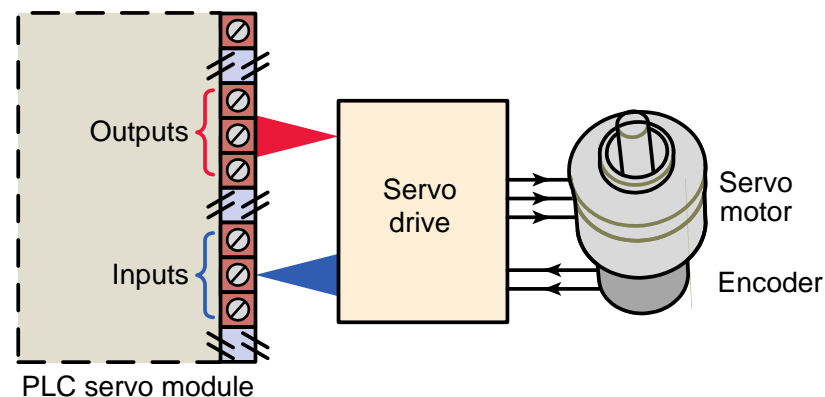
- Voltage, Current
(e.g. 0-10V, 4-20mA, ...)
- Analog Input
 - Measurement device
 - Temperature sensor
- Analog Output
 - Proportional actuator
 - Valves
 - Controllers (piezo)
 - Indicator



PROGRAMMABLE LOGIC CONTROLLER

Special functions

- Motor controllers
 - linear or rotational stages
- Position measurement
- Communication functions
 - Serial
 - Industrial bus



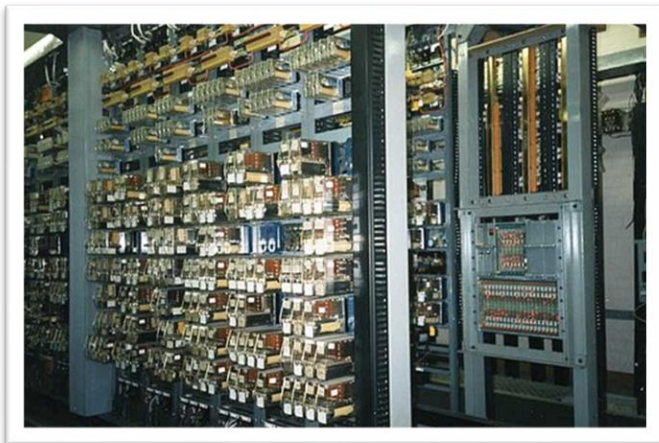
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- PLCs at ESO

THE ADVANTAGES OF A PLC CONTROL SYSTEM

- Convenience:

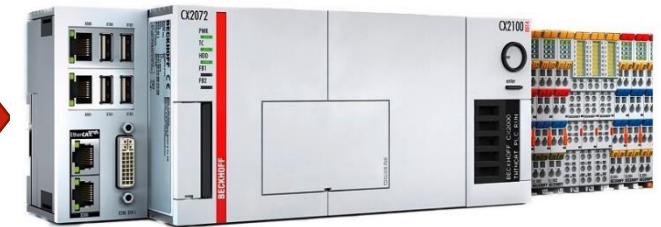
Derived from wired relay logic, a plc-based system means less space, less consumption and rapid diagnostics in the event of faults



Relays control circuit



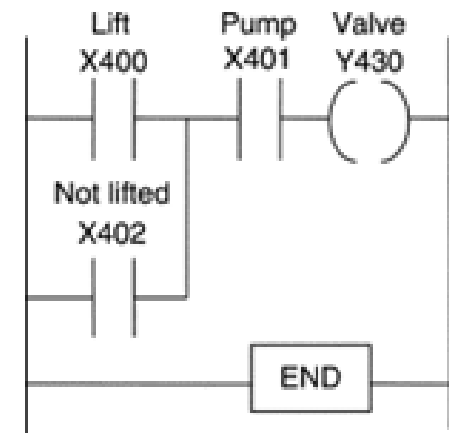
First PLC: Modicon 084 (1968)



Beckhoff CX2030

THE ADVANTAGES OF A PLC CONTROL SYSTEM

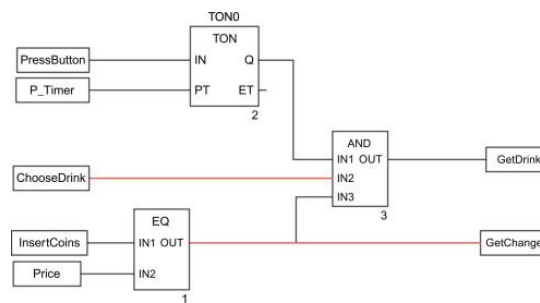
- Initially provided very simple programming
 - Ladder Diagram (resembling wired logic schemes)
 - Instruction List (kind of assembly language)



Ladder

THE ADVANTAGES OF A PLC CONTROL SYSTEM

- Today are very complex and powerful machines
 - Standardized with IEC 61131 (1993), part 3 defines programming languages adding Structured Text, Functional Block Diagram and Sequential Function Chart and support for OOP
 - Extensions for C/C++ , Matlab...



FBD

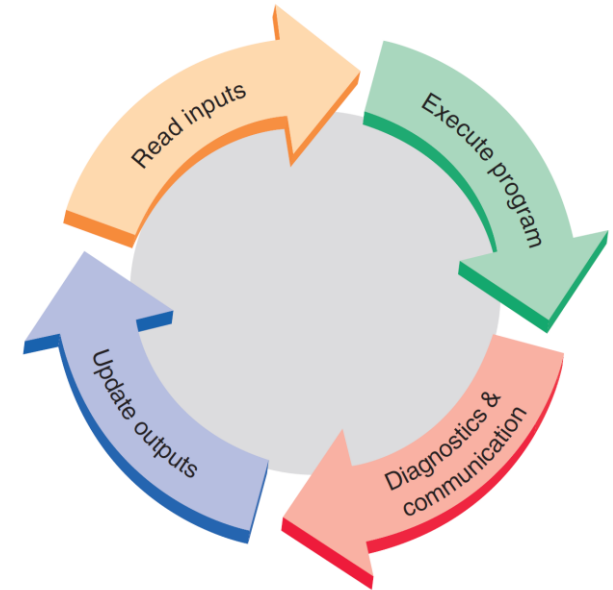
```
1 PROGRAM POU
2 VAR
3 MotorOverload : ARRAY[1..3] OF BOOL;
4 MotorOverCurrent : ARRAY[1..3] OF BOOL;
5 MotorPBStart : ARRAY[1..3] OF BOOL;
6 MotorPBStop : ARRAY[1..3] OF BOOL;
7 MotorCoil : ARRAY[1..3] OF BOOL;
8 i : INT;
9
10 END_VAR
11
12
13 FOR i:=1 TO 3 BY 1 DO
14 IF MotorPBStop[i] OR MotorOverload[i] OR MotorOverCurrent[i] THEN
15     MotorCoil[i]:=0;
16 ELSEIF MotorPBStart[i] THEN
17     MotorCoil[i]:=1;
18 END_IF
19 END_FOR
```

Structured text

THE ADVANTAGES OF A PLC CONTROL SYSTEM

- Real-time

The CPU of a PLC is able to process logics in real time, guaranteeing the time period at each program cycle



THE ADVANTAGES OF A PLC CONTROL SYSTEM

- Flexible

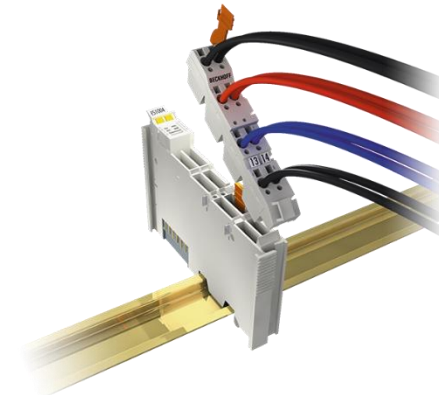
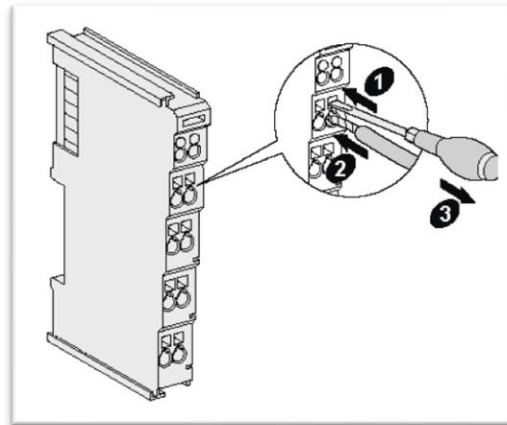
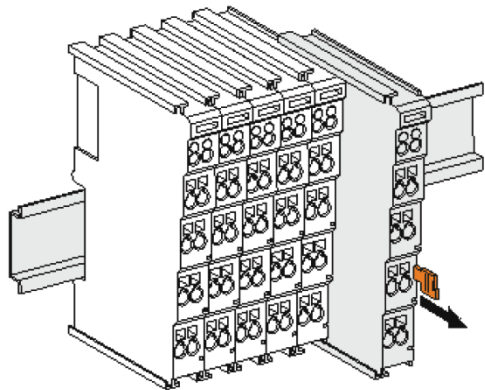
In a control system created with a PLC, it is possible to add or modify the installed modules without redesigning the entire system architecture



THE ADVANTAGES OF A PLC CONTROL SYSTEM

- Easy installation, operation and troubleshooting

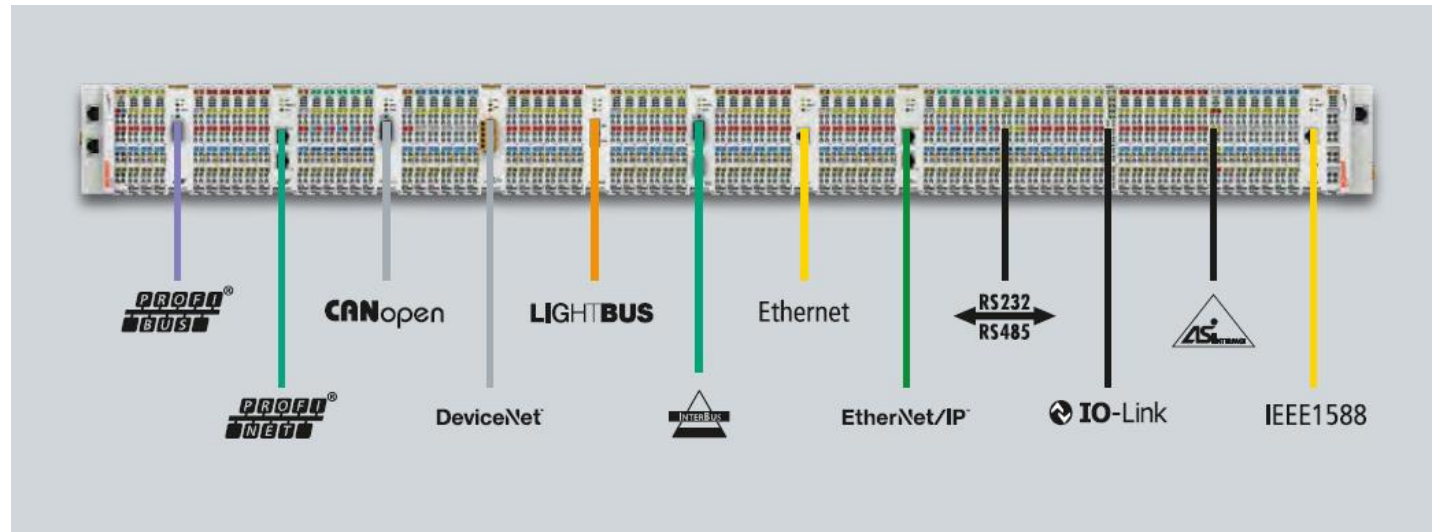
PLCs are designed to be installed and replaced quickly to minimize system downtime



THE ADVANTAGES OF A PLC CONTROL SYSTEM

- Standard communication protocols

PLCs support many communication protocols allowing a connection to many type of device, even between PLCs from different brands



THE ADVANTAGES OF A PLC CONTROL SYSTEM

- Resilient

PLCs can operate in different types of environments or where particular certifications are required

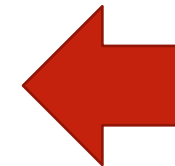
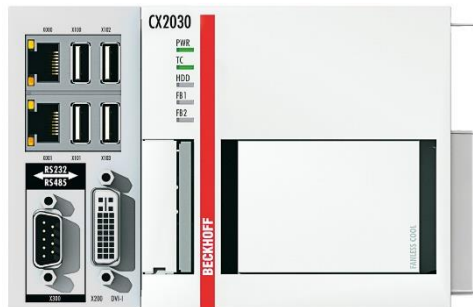


SUMMARY

- Programmable logic controller
- The advantages of a PLC control system
- Beckhoff: devices and tools
- PLCs at ESO

BECKHOFF: DEVICES AND TOOLS

- CPU
 - Open, PC-based control technology
 - Embedded platforms (DIN mount), industrial PCs or standard PCs
 - Based on Windows or Free-BSD



BECKHOFF
TwinCAT®

BECKHOFF: DEVICES AND TOOLS

- Support for all the basic I/O



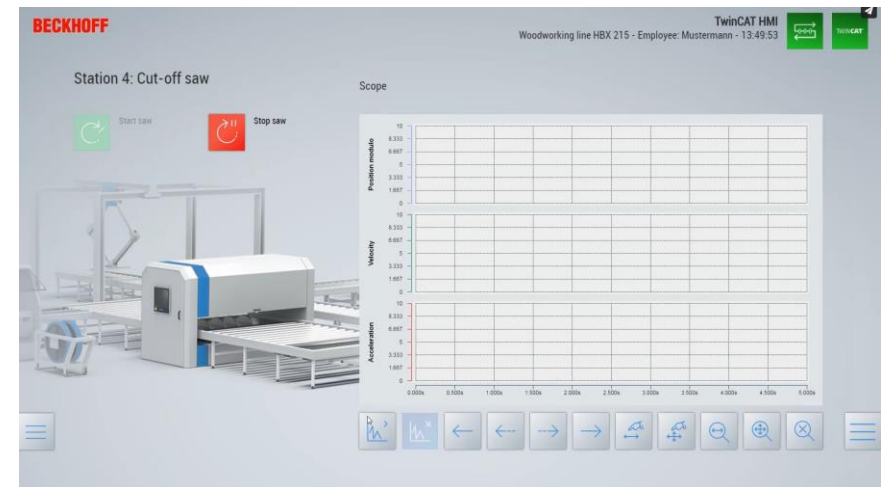
BECKHOFF: DEVICES AND TOOLS

- Motion control is provided by the PLC runtime
- All motor technologies supported with dedicated modules
- Very compact solutions are possible



BECKHOFF: DEVICES AND TOOLS

- HMI
- Basic support on all panels and IDE
- Advanced HMI based on HTML5 available as extension

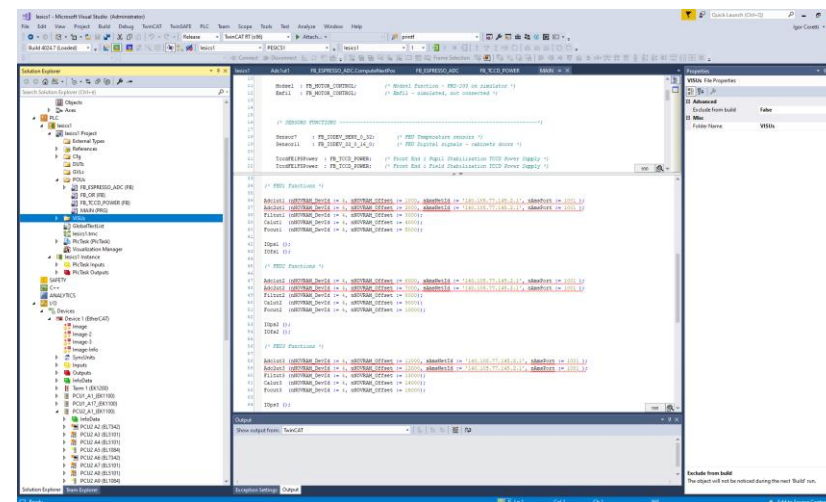


BECKHOFF: DEVICES AND TOOLS

- PLC IDE → TwinCAT3 XAE (eXtended Automation Engineering)

- Based on Visual Studio
- Requires Windows
- Supports all programming options
- Hardware management
- Motion control configuration and management
- HMI design
- Debugging

TwinCAT[®]3



BECKHOFF: DEVICES AND TOOLS

- PLC runtime → TwinCAT 3 - XAR (eXtended Automation Runtime)
 - Communicates with XAE using with ADS protocol
 - Runs on any windows platform with guaranteed real-time
 - Scales seamlessly
 - Has different levels, depending on motion control requirements
 - Many extension available (special functions, communication, HMI, etc.)
 - Licensing costs are tied to CPU power
 - Development licenses are free



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PLCs AT ESO

- In the past: VME based
 - Used in many big physics experiments
 - VME implements the Local Control Unit
 - real-time control
 - Unix - Linux based workstation manages the high-level control



PLCs AT ESO

- Current : PLC based
 - PLC substitutes the VME
 - Brand of choice : Beckhoff
 - ESO provide a list of standard modules
 - Mandatory in all VLT /ELT projects
 - Communication standard
 - OPC-UA
 - Is used for all data exchange between Workstation and PLC
 - Instrument workstation is the supervisor
 - Similar approach to SCADA - it mainly sends commands to PLCs

PLCs AT ESO

- Standardize the PLC also on the software side: the ESO libraries
- Devices include a state machine management
- Some ESO “Standard” device:
 - Lamp
 - Generic digital and analog input and output
 - Motor
 - Includes ADC, Derotator and multi-axis devices
 - Actuator
 - Shutter
 - Communication device
 - Temperature controllers

PLCs AT ESO

Library content:

- Function block (FB) for function control (e.g. FB_LAMP)
 - Some libraries deliver more than one FB (e.g. motor.library)
- Function block for testing when no hardware is available (e.g. FB_SIM_LAMP)
- GUI for local control (e.g. GUI_TEMPLATE_LAMP)
- Enumerations and data structures
 - CFG
 - CTRL
 - INFO
 - STAT

PLCs AT ESO

Inside a ESO standard device function block:

- FB_BASE with common methods to handle the device (most placeholders)
- FB_DEVICE extended from FB_BASE with specific methods
- List of methods to interface to ICS (changes to the state machine)
 - RPC_init
 - RPC_enable
 - RPC_disable
 - RPC_stop
 - RPC_reset
 - Other RPC related to the device (e.g. RPC_On for the Lamp)

PLCs AT ESO

- Examples of template GUI

Grism

SoE Drive
 Clear NOV RAM
 Enable Clear NOV RAM

INIT Sequence Definition

	Action	Value 1	Value 2
1	3	10.000	1.000
2	9	0.000	0.000
3	0	0.000	0.000
4	0	0.000	0.000
5	0	0.000	0.000
6	0	0.000	0.000
7	0	0.000	0.000
8	0	0.000	0.000
9	0	0.000	0.000
10	0	0.000	0.000

Action Legend:

0 - END [0] [0] (e.g. "END,0,0")
 1 - Find Index Switch [fast Vel] [slow Vel] (e.g. "FIND_INDEX,10.0,0.5")
 2 - Find REF Switch Lower Edge [fast Vel] [slow Vel] (e.g. "FIND_REF_LE,8,0.1")
 3 - Find REF Switch Upper Edge [fast Vel] [slow Vel] (e.g. "FIND_REF_UE,8.5,1")
 4 - Find Lower HW Limit [fast Vel] [slow Vel] (e.g. "FIND_LHW,5.0,0.2")
 5 - Find Upper HW Limit [fast Vel] [slow Vel] (e.g. "FIND_UHW,5.0,0.2")
 6 - Delay [ms] [0] (e.g. "DELAY,3000,0")
 7 - Move Absolute [vel] [pos] (e.g. "MOVE_ABS,25.0,360.0")
 8 - Move Relative [vel] [pos] (e.g. "MOVE_REL,25.0,60.0")
 9 - Calibrate Absolute [pos] [0] (e.g. "CALIB_ABS,180.0,0")
 0 - Calibrate Relative [pos] [0] (e.g. "CALIB_REL,5.25,0")
 .1 - Calibrate on Switch [pos] [0.0] (e.g. "CALIB_SWITCH,180.0,0")

User Procs

PRE-INIT

POST-INIT

PRE-MOVE

POST-MOVE

Auto Disable

In-Pos Check

Check

Active Low

Switches Active Low

USTOP

UHW

INDEX

REF

LHW

LSTOP

Brakes

Brakes Used

Active Low

Axis Type

Set Linear

Set Circular

Set Circular-Opt

Timeouts [ms]

INIT:

MOVE:

SWITCH:

SW Limits

Min:

Max:

Backlash

Lock

Position:

Tolerance:

Ver: 4.2.3.5

Grism

 Local Control
User Units: "°"

State OPERATIONAL

Substate STANDSTILL

Status STANDING 2

Status Description OK

Action ActionMoveExecute

Event CMD MOVE

RPC Call Status OK

Status

- Initialised
- Controller Enabled
- Axis Ready
- Brake Used
- Brake Active
- In Position

INIT Step

Switches

- USTOP
- UHW
- INDEX
- REF
- LHW
- LSTOP

RESET

INIT

ENABLE

MOVE ABS

MOVE REL

SET POS

STOP

DISABLE

MOVE VEL+

MOVE VEL-

	Target	Actual
Speed (Pos)	10.00	0.00
Speed (Vel)	10.00	0.00
Position (ABS)	135.00	135.00
Offset (REL)	0.00	
Backlash	0.00	
	ENABLE AXIS	DISABLE AXIS

PLCs AT ESO

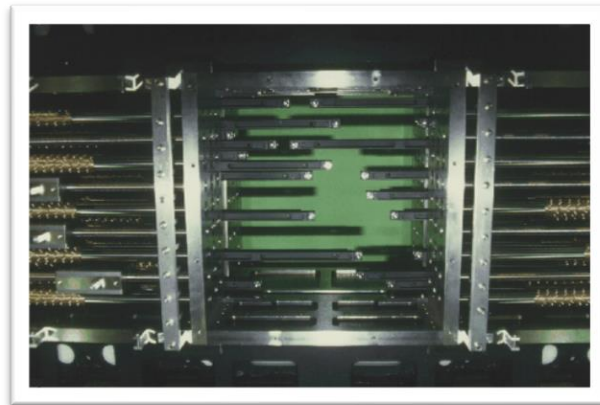
Special devices:

- Control of non-standard hardware
- Control of standard hardware in non-standard way
- Coordination of standard and/or non-standard devices
- Specific applications not related to hardware

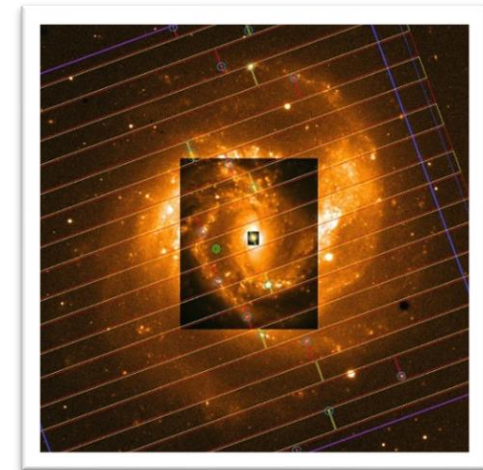
PLCs AT ESO

An example of special device: MOS (Multi-object spectroscopy)

- Used in FORS-Up to observe up to 19 objects simultaneously.
- Every slit obtained by pair of slitlets individually driven by a motor via a precision spindle, controlled by an absolute encoder.



MOS slit jaws



MOS observing technique

PLCs AT ESO

SIEMENS:

- PLC chosen by ESO for special tasks like cryostats and vacuum control systems
- TIA Portal: Innovative simulation tools, seamlessly integrated engineering, energy monitoring and transparent plant operation



PLC S7-1500



TIA PORTAL





THE END

Thank you for your attention