## HW and SW Instrument Control at TNG

### A.Ghedina



## Instrument control:TNG specificity



Put yourself in context:

- Subsystems of the '90s
- TNG must observe
- Keep the system working and make proper upgrades, with few money and few time;
- Do not interfere with night ops;
- Everything redundant: old during the night, new during the day.
- Extra work

## Changing the whole TCS

- Encoders  $\rightarrow$  mech+electronics
- Tachos/ sincroresolvers  $\rightarrow$  mech+electronics
- Control electronics/ drivers/  $\rightarrow$  electronics/ software/
- VME/pointing/tracking algorythm  $\rightarrow$  still to be done

#### TNG TCS 1/3: AZ/EL/DER encoders



## TNG TCS 2/3: Sincro/Res y tachimetric (from analog to digital systems)



#### TNG TCS 3/3: Racks





## TNG new TCS core

CompactRIO controller (NI) with Linux RT op system programmed in LabView RT, labview FPGA y slalib (P. Wallace), executing original algorithms of P.Schipani.

Manuel Gonzalez  $\rightarrow$ 



AO(new AO), Derotator A&G(PODER) and Dolores(ARDolor): from Transputers,VME and custom electronics to COTS Arduino and web interfaces



#### ROBODIMM (Cloned also for ING)



Inrmal operation			on an condict call			
	Advanced control					
Dimm data			Selected star	Depek		
			Time:	05:06:08"	LST:	21:24:30"
			Ra:	09:26:36"	Dec:	61º56:22"
			Azimuth:	359º45:10"	Elevation:	00º41:53"
S T			Mean X separation: Std. Deviation X: Fried Trans: Seeing Trans: Airmass: Baricenter 0: Baricenter 1:	: 0.146 1.7615838E-6 11.79 0.857 1.058 30 @ 140.4, 1 52 @ 139.33	Mean Y separatio Std. Deviation Y: Fried Long: Seeing Long: Used images: 58, 28 99, 33	n: 57.316 2.32888461 10.755 0.94 1200/1200 <b>0.898</b>
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Loop Control						
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#### TNG Environment Temp/RH



# SiFAP2(Silicon Fast Astronomical Photometer and Polarimeter)



Coherent optical pulsations of PSR J1023+0038.

#### SiFAP4XP: optics/mechanics/electronics



#### SiFAP2/SiFAP4X GPS-PPS board







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# TNG expertise on HW and SW for instrument controls:

- Wide Opto-mecha-tronics knowledge;
- Optomechanical design, provision and alignment, and CNC mech manufacturing;
- Encoders, Stepper and DC Servos;
- Custom PC boards design, manufacturing, testing (SMD, multilayer and new reworking machine);
- Control logic development, programming from machine level to python, java, web interfaces, GUI interacting with OCS and TCS;
- Team of enthusiast people, smart and devoted to their jobs, able to take decisions under pressure, willing to solve problems and learn new things.





