



Agenzia Spaziale Italiana



Characterizing the spectroscopic selection function for galaxy clustering and application to SC8 **Ben Granett INAF OA Brera**

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Spectroscopic galaxy clustering pipeline

- The LE3 Internal data work package is the interface between LE2 and LE3.
- The *SEL* processing function selects the spectroscopic samples for galaxy clustering and estimates the **purity** and **completeness** of these samples.
- VMSP (spectroscopic visibility mask) characterizes the selection function and builds the random catalog for galaxy clustering.







Internal Data SEL-VMSP team

- The SEL-VMSP processing functions are distributed between UK, Italy and USA.
 - Manager: Sesh Nadathur 💥
 - Validation lead: Lucia F. de la Bella **ﷺ**
 - VMSP developer: Ben Granett
 - SEL developer: Lado Samushia 🗾
 - Active collaborators: Coleman Krawczyk Enzo Branchini, Pierluigi Monaco, Samuele Galeotta
- There are three related prelaunch key project papers.







In collaboration with the SWG E2E galaxy clustering team

• Leads: Michele Moresco, Ben Granett, Sylvain de la Torre

Collaborators: Lucia Pozzetti, Micol Bolzonella, Bianca Garilli, Marco Scodeggio, Claudia Scarlata, Sean Bruton, Maxwell Kuschel, Matthieu Bethermin, Vincent Le Brun, Miguel Delaire, Herve Aussel, Dida Markovic







Challenges for galaxy clustering

- Slitless spectroscopy suffers from high background:
 - Zodi emission, scattered star light and MW extinction make large gradients in SNR on the sky.
 - Spectra overlaps add contamination and confusion.
- Continuum emission will not be detected in the Wide for target galaxies.
- Spectroscopic detection and redshift measurement will be based on a single emission line for most sources.

Our job:

Quantify the probability that a given galaxy would be measured successfully by Euclid if it exists at a given position on the sky.



Fig. 15: The RoI outline (17 354 deg²) with the accepted ranges of the stellar density, dust extinction, and zodiacal light.





E2E simulations and bypass detection model

- End-to-end simulations of the SGS start from mock galaxy catalogs and go to redshift measurements.
- We speed up the process with bypass simulations: skip heavy image processing and work at the catalog level.
- The bypass detection model used in Pypelid and LE3 VMSP is based on SNR. It can be calibrated against simulations.

Survey

simulator

noise

size

af.it

Ζ

flux

NII

Benjan

flux Ha

flux

OIII

flux

HΒ



How do we define bypass SNR?

- The bypass SNR is computed on a simulated 1D spectrum without noise.
- It is the sum of the SNR in quadrature over the extracted 1D spectrum.
- The spectrum is simulated without continuum.
- NB: This is not equivalent to the SNR estimated by SPE or specified in the requirements documents.
- Procedure in VMSP:
 - Simulate 2D images of the emission lines assuming Gaussian profile and double Gaussian PSF model.
 - Extract 1D spectrum
 - Compute SNR





What about the noise?

- We measured the noise for the TU galaxies directly from the SIR science frame variance images.
- Includes all simulated backgrounds including contamination.
- The variance is looked up at the pixel coordinates red and blue of the emission line of the TU galaxies.
- The results here are the result of dedicated work with help from Maxwell Kuschel and Sean Bruton:
 - We downloaded terabytes of TU, MER, SIR, SPE Wide and Deep data products from EAS.
 - Matched the TU catalog with MER detections and SPE measurements.
 - Ran VMSP codes on the SC8 data products.



Cutout of SIR Science frame variance image (e-) with the $\mbox{H}\alpha$ line of a TU galaxy circled.

Thanks to Marco Fumana for help with the SIR location table routines!





Obligatory warning

- Data from SC8 carry many caveats (see Michele's presentation, or speak to anyone working in an OU...)
- The scope here is to model the selection function.
- I am not worried by the absolute values.







Calibration of the detection model with SC8



 SPE success is defined as SPE_Z_PROB > 0.99 & |SPE_Z - z|/(1+z) < 0.003.

> The sample is cut at flux_Ha > 1e-16 erg/cm2/s & 0.9 < z < 1.8

• Fit the success rate as a function of SNR with a sigmoid.

 $y = \frac{c}{1 + \left(\frac{x}{x_0}\right)^{-\alpha}}$

- This is done in redshift bins to capture redshift dependence.
- Does not asymptote to 1 due to line misidentification losses.





Calibration of the detection model with SC8

- Galaxies are lost from the sample due to line misidentification or spurious noise.
 - \circ H α may be mistaken for something else
 - Spurious signal from noise.
- This introduces a complex redshift dependence of the completeness.
 - Measurement success rate and misidentification/spurious rates depend on SPE template priors.





Calibration of the detection model with SC8



Redshift measurement trends in SC8



- We can measure the SPE success rate as a function of any galaxy property.
- Similarly we can use the model p(SNR, z) to predict the success rate as a function of these properties.
 - The dependencies pass through SNR which is a function of flux, size, redshift and noise.

SPE measurements

Model





Redshift measurement trends in SC8



Benjamin.Granett@inaf.it

- Recall the model was fit in redshift bins of size 0.1. This was needed to reproduce the variations in measurement success rate.
- But the model successfully reproduces trends inside the bins.
- Further investigation is needed to understand poor fit at z>1.7.

SPE measurements

Model



Redshift measurement trends in SC8





• $H\alpha/NII$ flux

• Angular size

• Exposure count

The detection model reproduces the trends generally well. A few parameters require checks and deeper investigation.





Proof of concept random catalog



- We build a random catalog by sampling galaxies from TU in SC8 fields.
- Apply the calibrated detection model to the randoms (*VMSP* line).
- This reproduces the N(z) of galaxies in the target sample that were measured correctly (*Correctly measured*).
- The distribution is different from the N(z) of all galaxies (*All measured*) due to incompleteness.
- The randoms are constructed to follow the N(z) of the correctly measured galaxies.





Outline of VMSP function

VMSP performs the following steps to build the random catalog for the Wide.

- 1. Sample galaxies from the CPC/Deep fields to build the random catalog.
- 2. Sample sky coordinates RA, Dec from the Wide survey area.
- 3. Measure noise from SIR pixels at the location of the emission lines of each random galaxy (*RA, Dec, z, wavelength*).
- 4. Compute the bypass SNR for each random.
- Map bypass SNR to the detection probability. The detection model will be calibrated using simulations and the CPC/Deep fields.
- 6. Downsample the random catalog using the detection probability.





Summary

- We are developing algorithms to characterize the spectroscopic selection function for galaxy clustering and digging into SC8 data.
- Provides a proof of concept of the LE3 VMSP pipeline that builds the random catalog for galaxy clustering.
- The density of randoms is modulated by noise through the detection model.
- This work will be written up in the LE3 VMSP pre-launch key project paper.
- The algorithms will continue to be validated and improved as simulations and reduction pipelines are iterated.



